

# Vector Calculus

March 17, 2024

## 1 Motivation

Placeholder

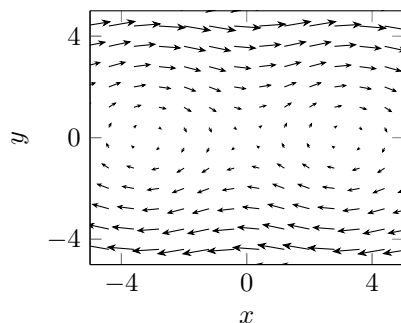
## 2 Introduction

Placeholder

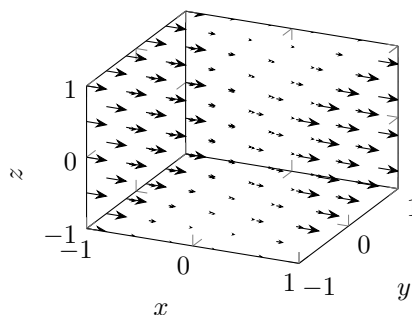
## 3 Vector Field

**Definition 1** A vector field on  $\mathbb{R}^n$  is a function  $\mathbf{F} : D \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$  that assigns to each point  $\mathbf{x}$  in domain<sup>1</sup>  $D$  a vector  $\mathbf{F}(\mathbf{x}) \equiv \langle x_1, \dots, x_n \rangle \in \mathbb{R}^n$

For visualisation of vector fields defined in  $\mathbb{R}^2$  or  $\mathbb{R}^3$  one would plot some vectors samples across the domain to avoid clutter. See plots of vector fields in  $\mathbb{R}^2$  or  $\mathbb{R}^3$  receptively.



(a)  $\mathbf{F} : (x, y) \mapsto \langle y, \sin x \rangle$



(b)  $\mathbf{F} : (x, y, z) \mapsto \langle x^2, 0, 0 \rangle$

A beautiful observation from these plots, that is most vector fields can be seen as flowing fluid, which provide a beautiful and helpful interpretation about their behaviour.

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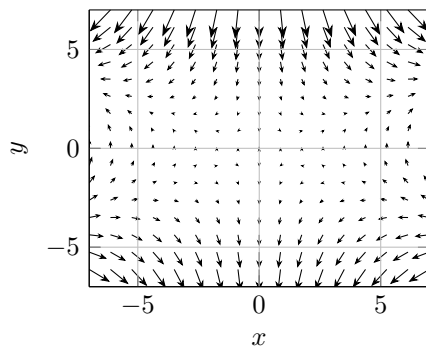
<sup>1</sup>domain could be a subset of  $\mathbb{R}^n$  or all of it

A place where vector field might appear is in the representation of gradient of multivariable scalar function. Lets consider the following example.

**Example 1** Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be a scalar function act on  $\mathbb{R}^2$ , with  $f(x, y) = x^2y - y^3$ . Write out  $\nabla f(x, y)$  and plot it.

$$\nabla f(x, y) = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} = \begin{bmatrix} 2xy \\ x^2 - 3y^2 \end{bmatrix} \equiv 2xy \mathbf{i} + (x^2 - 3y^2) \mathbf{j}$$

The gradient  $\nabla f(x, y)$  is a vector field act on  $\mathbb{R}^2$ , and its visualization



This vector field hold information of the magnitude and direction of the gradient of  $f(x, y)$  at any point  $(x, y) \in \mathbb{R}^2$ . ■

## 4 Line Integrals

Another extension to the concept of integration is computing of the integration of a mathematical form<sup>2</sup> along a curve. This operation is called line integration.

**Definition 2** *Line integration of a mathematical form  $\mathbf{F}$  is the cumulative change of  $\mathbf{F}$  along a path defined by some curve  $C$*

The mathematical forms that we will address in this script, are scalar fields and vector fields

### 4.1 Scalar Fields

**Definition 3** *Line integration of a scalar field  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  along a smooth curve  $C$*

$$\int_C f(\mathbf{x}) ds \quad (1)$$

The definition above is derived from the concept of Riemann summation. To illustrate this, we will take the following toy example.

**Example 2** *Given a scalar valued function  $f(x, y) = 0.6 \cos(\sqrt{x^2 + y^2}) + 3$  and a parametric curve  $C$  defined by following equations*

$$x = 6t \cos(5t) \quad y = 6t^3 - 6$$

*Derive the definition of line integration exploiting the concept of Riemann summation. Graph some Riemann approximation of the line integration of  $f(x, y)$  along curve  $C$  for arbitrary  $n$*

Riemann summation performed on  $f(x, y)$  along curve  $C$  can be achieved by the following steps:

1. Divide the curve  $C$  to  $n$  small subarcs<sup>3</sup>  $\Delta s_1, \dots, \Delta s_n$ .
2. For every subarc  $i$ , evaluate  $f(x, y)$  at some point<sup>4</sup>  $(x_i^*, y_i^*) \in \Delta s_i$ .
3. Compute  $f(x_i^*, y_i^*) \Delta s_i$  for every subarc "i.e the area of a rectangle with length  $f(x_i^*, y_i^*)$  and width  $\Delta s_i$  for subarc  $i$ ".
4. Sum  $f(x_i^*, y_i^*) \Delta s_i$  over  $n$  "i.e. the rectangles" to approximate the area under  $f(x, y)$  along path  $C$ .

$$\text{Area under the curve} \approx \sum_{i=1}^n f(x_i^*, y_i^*) \Delta s_i$$

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<sup>2</sup>function

<sup>3</sup>small arcs

<sup>4</sup>choice of  $(x_i^*, y_i^*)$  will decide which Riemann sum we have. Either Right, Left, Midpoint Riemann sum

5. Riemann summation imply that  $n$  goes to infinity "i.e. the rectangles become infinitely small". Hence the Riemann summation gives us the line integration<sup>5</sup> of  $f(x, y)$  along curve  $C$

$$\int_C f(x, y) ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*, y_i^*) \Delta s_i$$

For arbitrary chosen  $n$ , that is not too large; the Riemann sum would look rectangles that cover the area between curve  $C$  and function  $f(x, y)$ . The plot

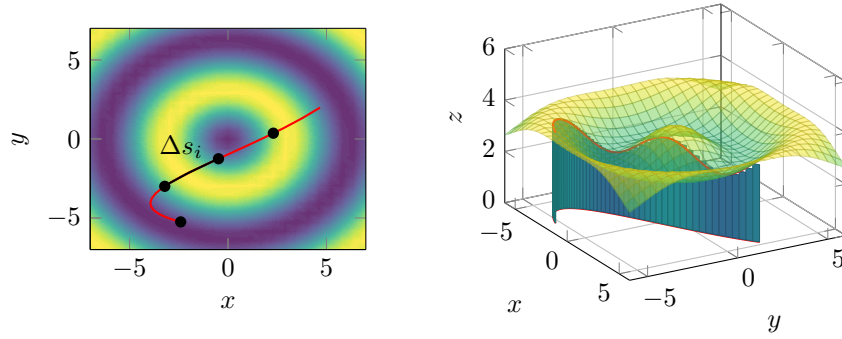


Figure 2: Left: Illustrating  $\Delta s_i$ . Right: Riemann summation for small  $n$

above is the approximated line integration of  $f(x, y)$  along curve  $C$  using Riemann sum. ■

In context of parametric curves, it is more convenient<sup>6</sup> to reformulate line integration formula "presented in definition (5)" in terms integration operator for the parametric variable "usually referred as  $t$ " rather than the arc length "usually referred as  $s$ " hence  $ds \rightarrow dt$ .

**Definition 4** *Line integration of a scalar field  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  along a smooth parametric curve  $C$  that defined by variable  $t$*

$$\int_C f(x, y) ds = \int_a^b f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

given that

$$\frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}$$

This definition can be generalized to  $\mathbb{R}^n$

<sup>5</sup>recall that  $\int \equiv \lim_{n \rightarrow \infty} \sum_{i=1}^n$

<sup>6</sup>computationally

**Example 3** Evaluate  $\int_C (2+x^2y)ds$ , where  $C$  is the upper half of the unit circle  $x^2 + y^2 = 1$ .

The upper half of the unit circle can be expressed using the parametric curve defined by the following equations

$$x = \cos t \qquad y = \sin t$$

Hence the line integral reads

$$\begin{aligned} \int_C (2+x^2y)ds &= \int_0^\pi (2+\cos^2 t \sin t) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt \\ &= \int_0^\pi (2+\cos^2 t \sin t) \sqrt{\sin^2 t + \cos^2 t} dt \\ &= \int_0^\pi (2+\cos^2 t \sin t) dt \\ &= \left[ 2t - \frac{\cos^3 t}{3} \right]_0^\pi = 2\pi + \frac{2}{3} \end{aligned}$$

■

## 4.2 Vector Fields

**Definition 5** Line integration of a vector field  $\mathbf{F} : \mathbb{R}^n \rightarrow \mathbb{R}^n$  along a smooth curve  $C$

$$\int_C \mathbf{F} \cdot \mathbf{T} ds \tag{2}$$

where  $\mathbf{T}$  is the tangent vector to curve  $C$

As the definition of line integration in scalar field, the definition above is derived from the concept of Riemann summation. Let's take the following toy example to illustrate this.

**Example 4** Given a vector field in  $\mathbb{R}^2$  defined by  $\mathbf{F}(x, y) = (x^2 - y^2 - 12) \mathbf{i} + 2xy \mathbf{j}$  and a parametric curve  $C$  defined by following equations

$$x = 6t \cos(5t) \qquad y = 6t^3 - 6$$

Derive the definition of line integration exploiting the concept of Riemann summation. Graph some Riemann approximation of the line integration of  $\mathbf{F}(x, y)$  along curve  $C$  for arbitrary  $n$

Riemann summation performed on  $\mathbf{F}(x, y)$  along curve  $C$  can be achieve by the following steps:

1. Divide the curve  $C$  to  $n$  small subarcs<sup>7</sup>  $\Delta s_1, \dots, \Delta s_n$ .
2. For every subarc  $i$ , evaluate  $\mathbf{F}(x, y)$  and the unit tangent vector to the curve direction  $\mathbf{T}(t)$  at some point<sup>8</sup>  $t_i^* \equiv (x_i^*, y_i^*) \in \Delta s_i$ .
3. Compute  $[\mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(t_i^*)] \Delta s_i$  for every subarc " i.e. the alignment between the vector field vector  $\mathbf{F}(x_i^*, y_i^*)$  with the unit tangent vector  $\mathbf{T}(t_i^*)$  of subarc  $i$ ".
4. Sum  $[\mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(x_i^*, y_i^*)] \Delta s_i$  over  $n$  to approximate how much the vectors of  $\mathbf{F}(x_i^*, y_i^*)$ ; along the path defined by  $C$ , align with  $C$ .

$$\text{Work} \approx \sum_{i=1}^n [\mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(x_i^*, y_i^*)] \Delta s_i$$

5. Riemann summation imply that  $n$  goes to infinity. Hence the Riemann summation gives us the line integration<sup>9</sup> of  $\mathbf{F}(x, y)$  along curve  $C$

$$\int_C \mathbf{F} \cdot \mathbf{T} ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n [\mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(x_i^*, y_i^*)] \Delta s_i$$

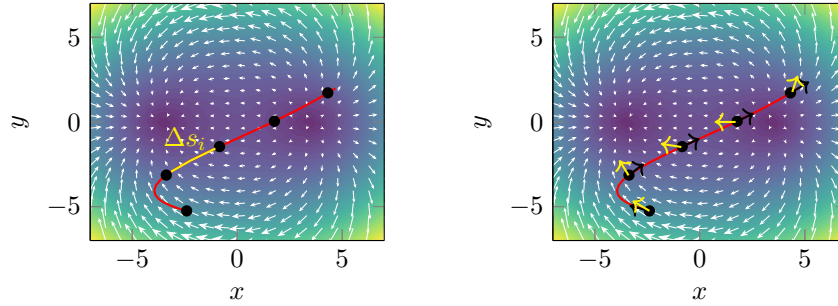


Figure 3: Left: Illustrating  $\Delta s_i$ . Right: Riemann summation for small  $n$  where vectors in yellow are  $\mathbf{F}(x_i^*, y_i^*)$  and in black are  $\mathbf{T}(x_i^*, y_i^*)$

The plot above is the approximated line integration of  $\mathbf{F}(x, y)$  along curve  $C$  using Riemann sum. ■

In context of parametric curves, it is more convenient<sup>10</sup> to reformulate line integration formula "presented in definition (5)" in terms integration operator for the parametric variable "usually referred as  $t$ " rather than the arc length "usually referred as  $s$ " hence  $ds \rightarrow dt$ .

<sup>7</sup>small arcs

<sup>8</sup>choice of  $(x_i^*, y_i^*)$  will decide which Riemann sum we have. Either Right, Left, Midpoint Riemann sum

<sup>9</sup>recall that  $\int \equiv \lim_{n \rightarrow \infty} \sum_{i=1}^n$

<sup>10</sup>computationally

**Definition 6** *Line integration of a vector field  $\mathbf{F} : \mathbb{R}^n \rightarrow \mathbb{R}^n$  along a smooth parametric curve  $C$  defined by vector function  $\mathbf{r}(t)$ ,  $a \leq t \leq b$*

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_C \mathbf{F} \cdot \mathbf{T} ds$$

**Example 5** *Evaluate  $\int_C \mathbf{F} \cdot d\mathbf{r}$ , where  $C$  is a quarter-circle defined through  $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j}$ ,  $0 \leq t \leq \pi/2$  and  $\mathbf{F}$  is a vector field  $\mathbf{F}(x, y) = x^2 \mathbf{i} - xy \mathbf{j}$ .*

From the parametric equation  $x = \cos t$  and  $y = \sin t$ , hence we have

$$\mathbf{F}(\mathbf{r}(t)) = \cos^2 t \mathbf{i} - \cos t \sin t \mathbf{j}$$

and

$$\mathbf{r}'(t) = -\sin t \mathbf{i} + \cos t \mathbf{j}$$

Therefore the line integration reads

$$\begin{aligned} \int_C \mathbf{F} \cdot d\mathbf{r} &= \int_0^{\pi/2} (-\cos^2 t \sin t - \cos^2 t \sin t) dt \\ &= \int_0^{\pi/2} (-2 \cos^2 t \sin t) dt \\ &= \left[ 2 \frac{\cos^3 t}{3} \right]_0^{\pi/2} = -\frac{2}{3} \end{aligned}$$

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## References