**Definition 1** Line integration of a vector field  $\mathbf{F}: \mathbb{R}^n \to \mathbb{R}^n$  along a smooth curve C

 $\int_{C} \mathbf{F} \cdot \mathbf{T} \, ds \tag{1}$ 

where T is the tangent vector to curve C

As the definition of line integration in scalar field, the definition above is derived from the concept of Riemann summation. Let's take the following toy example to illustrate this.

**Example 1** Given a vector field in  $\mathbb{R}^2$  defined by  $\mathbf{F}(x,y) = (x^2 - y^2 - 12) \mathbf{i} + 2xy \mathbf{j}$  and a parametric curve C defined by following equations

$$x = 6t\cos(5t) \qquad \qquad y = 6t^3 - 6$$

Derive the definition of line integration exploiting the concept of Riemann summation. Graph some Riemann approximation of the line integration of  $\mathbf{F}(x,y)$  along curve C for arbitrary n

Riemann summation performed on  $\mathbf{F}(x,y)$  along curve C can be achieve by the following steps:

- 1. Divide the curve C to n small subarcs  $\Delta s_1, \ldots \Delta s_n$ .
- 2. For every subarc i, evaluate  $\mathbf{F}(x,y)$  and the unit tangent vector to the curve direction  $\mathbf{T}(t)$  at some point  $t_i^* \equiv (x_i^*, y_i^*) \in \Delta s_i$ .
- 3. Compute  $[\mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(t_i^*)] \Delta s_i$  for every subarc " i.e. the alignment between the vector field vector  $\mathbf{F}(x_i^*, y_i^*)$  with the unit tangent vector  $\mathbf{T}(t_i^*)$  of subarc i".
- 4. Sum  $[\mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(x_i^*, y_i^*)] \Delta s_i$  over n to approximate how much the vectors of  $\mathbf{F}(x_i^*, y_i^*)$ ; along the path defined by C, align with C.

Work 
$$\approx \sum_{i=1}^{n} [\mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(x_i^*, y_i^*)] \Delta s_i$$

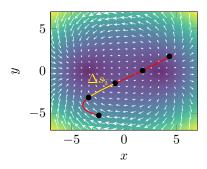
5. Riemann summation imply that n goes to infinity. Hence the Riemann summation gives us the line integration<sup>3</sup> of  $\mathbf{F}(x,y)$  along curve C

$$\int_{C} \mathbf{F} \cdot \mathbf{T} \, ds = \lim_{n \to \infty} \sum_{i=1}^{n} [\mathbf{F}(x_{i}^{*}, y_{i}^{*}) \cdot \mathbf{T}(x_{i}^{*}, y_{i}^{*})] \Delta s_{i}$$

 $<sup>^{1}</sup>$ small arcs

 $<sup>^2{\</sup>rm choice}$  of  $(x_i^*,y_i^*)$  will decide which Riemann sum we have. Either Right, Left, Midpoint Riemann sum

<sup>&</sup>lt;sup>3</sup>recall that  $\int \equiv \lim_{n \to \infty} \sum_{i=1}^{n}$ 



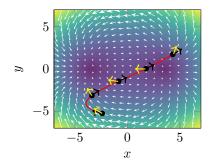


Figure 1: Left: Illustrating  $\Delta s_i$ . Right: Riemann summation for small n where vectors in yellow are  $\mathbf{F}(x_i^*, y_i^*)$  and in black are  $\mathbf{T}(x_i^*, y_i^*)$ 

The plot above is the approximated line integration of  $\mathbf{F}(x,y)$  along curve C using Riemann sum.

In context of parametric curves, it is more convenient<sup>4</sup> to reformulate line integration formula "presented in definition (1)" in terms integration operator for the parametric variable "usually referred as t" rather than the arc length "usually referred as s" hence  $ds \to dt$ .

**Definition 2** Line integration of a vector field  $\mathbf{F}: \mathbb{R}^n \to \mathbb{R}^n$  along a smooth parametric curve C defined by vector function  $\mathbf{r}(t)$ ,  $a \le t \le b$ 

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{a}^{b} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_{C} \mathbf{F} \cdot \mathbf{T} ds$$

**Example 2** Evaluate  $\int_C \mathbf{F} \cdot d\mathbf{r}$ , where C is a quarter-circle defined through  $\mathbf{r}(t) = \cos t \, \mathbf{i} + \sin t \, \mathbf{j}$ ,  $0 \le t \le \pi/2$  and  $\mathbf{F}$  is a vector field  $\mathbf{F}(x,y) = x^2 \, \mathbf{i} - xy \, \mathbf{j}$ .

From the parametric equation  $x = \cos t$  and  $y = \sin t$ , hence we have

$$\mathbf{F}(\mathbf{r}(t)) = \cos^2 t \, \mathbf{i} - \cos t \, \sin t \, \mathbf{j}$$

and

$$\mathbf{r}'(t) = -\sin t \,\mathbf{i} + \cos t \,\mathbf{j}$$

Therefore the line integration reads

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_0^{\pi/2} \left( -\cos^2 t \sin t - \cos^2 t \sin t \right) dt$$
$$= \int_0^{\pi/2} (-2\cos^2 t \sin t) dt$$
$$= \left[ 2\frac{\cos^3 t}{3} \right]_0^{\pi/2} = -\frac{2}{3}$$

<sup>&</sup>lt;sup>4</sup>computationally