

## 0. Introduction

### What is Computer vision?

- computer vision is the use of seen as a major input that control actions.
- computer vision is the science of using image processing to make it useful, extract data or learn something from image.

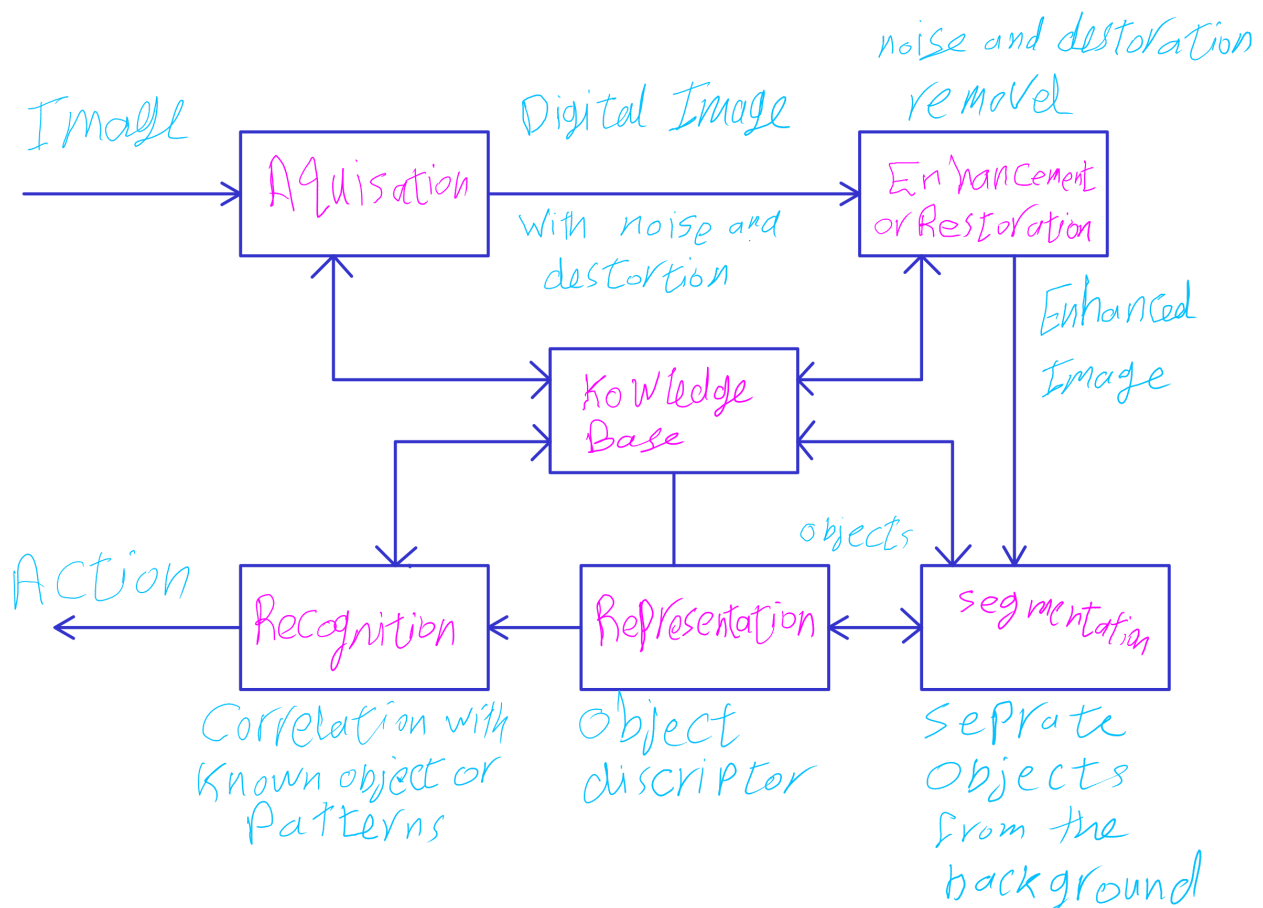
### What is Image Processing?

- Image processing means to perform objective operations on the images, to extract data form it.

### Sample Computer vision Systems:

- Smart bombs / Smart missiles
- Security systems (face recognition, finger prints)
- Material analysis
- Machine Control
- Medical (X-ray, Sonar, Radiation and analysis)
- Auto-Drive
- Robotics
- Motion Detection

### Image processing-based system / computer vision system structure and stages



# The Basic Elements of computer vision system

- Acquisition
- Enhancement
- Restoration
- Segmentation
- Description
- Feature extraction
- Detection
- Recognition
- Encoding/Decoding

## Acquisition

is the process of converting a scene to a digital image through **Sampling** and **Quantization**

## Sampling

- is Dividing the image into samples  $N$  in  $x$  and  $M$  in  $y$  as result we will have  $M \times N$  picture elements which is called pixels

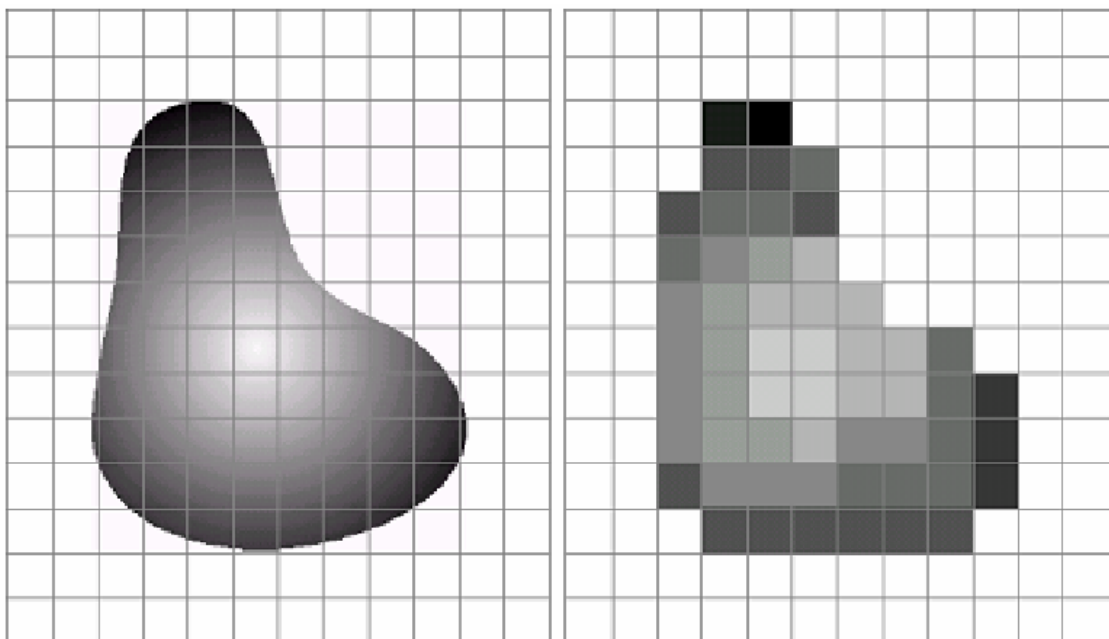
## Quantization

- is the process of converting analog image to digital image grouping a set of grays/colors into gray value or a specific color as result will have matrix at dimension  $M \times N$ .
- Number of possible colors/grays are  $2^q$
- **#note** Image resolution is  $M \times N \times q$

## False contouring / Coarse sampling

- Insufficient number of intensity levels in smooth areas of digital image

# Samples and Quantization



| Fine sampling                   | Coarse sampling          |
|---------------------------------|--------------------------|
| Good image                      | poor image               |
| Precise description             | false contouring         |
| High memory requirements        | low memory requirements  |
| need a lot of processing power  | low processing power     |
| Transmit require high bandwidth | low bandwidth sufficient |

## Image resolution

- refers to the number of pixels in an image
- identified by the width and height of the image and number of colors in an image #note  $R = M \times N \times q$

## Digital image

- is an Image matrix which is finite matrix of integer values or 3 image matrices of color images

## Image Matrix

|                   |                         |                      |                |
|-------------------|-------------------------|----------------------|----------------|
| if max gray level | 130 --> Dark Image      | 255 --> no meaning   |                |
| if min gray level | 170 --> bright          | 0 --> no meaning     |                |
| (max & min)       | (100, 150) low contrast | (0, 255) no meaning  |                |
| Average           | 50 Dark                 | 200 Bright           | 127 no meaning |
| stander deviation | big --> high contrast   | low --> low contrast |                |

## Histogram :

count the number of occurrences per gray/color/color component value within the image matrix/matrices.

## Importance applications of histogram

- Analysis of image, image brightness
- using histogram to equalize an image

#Example Calculate the Following for the following Matrix: Find histogram

$$\begin{pmatrix} 5 & 5 & 4 & 5 \\ 10 & 20 & 5 & 4 \\ 10 & 20 & 5 & 10 \\ 20 & 4 & 5 & 100 \end{pmatrix}$$

#Answer

| Grey Value  | Count |
|-------------|-------|
| 4           | 3     |
| 5           | 6     |
| 10          | 3     |
| 20          | 3     |
| 100         | 1     |
| Total count | 16    |

## Neighboring

Relation between pixels in some way.

## Types of Neighboring :

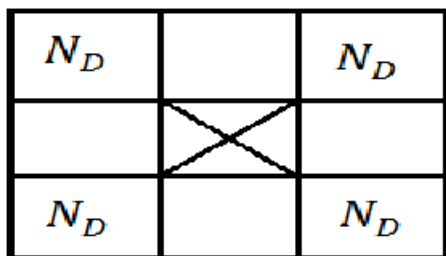
- four neighboring

$$N_4(f(x, y)) = \{f(x-1, y), f(x+1, y), f(x, y-1), f(x, y+1)\}$$



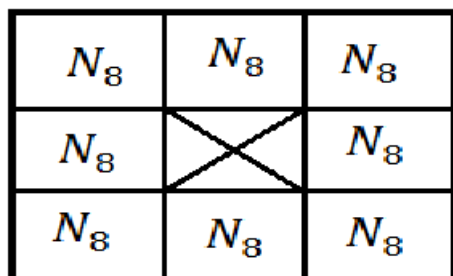
- diagonal neighboring

$$N_D(f(x, y)) = \{f(x-1, y-1), f(x-1, y+1), f(x+1, y-1), f(x+1, y+1)\}$$



- Eight neighboring

$$N_8(f(x, y)) = \{N_D \cup N_4\}$$



## Connectivity:

Pixels are considered connected if and only if

- They're neighbors
- $f(x_1, y_1), f(x_2, y_2) \in \xi \rightarrow$  Where  $\xi$  is the gray levels connectivity set  $\xi = \{\dots, \dots, \dots\}$

**#Example** : find connected pixels for  $f(1, 1)$  using  $N_4$  and connectivity set  $\xi = \{3, 4, 5, 6, 7, 8, 9, 10\}$  . Redo using  $N_D, N_8$

|           |            |            |
|-----------|------------|------------|
| <b>2</b>  | <b>4</b>   | <b>7</b>   |
| <b>6</b>  | <b>5</b>   | <b>100</b> |
| <b>13</b> | <b>120</b> | <b>9</b>   |

**#Answer**

In case of,  $N_4$  5 is connected with  $f(1, 0) = 4$  and  $f(0, 1) = 6$

In case of,  $N_D$  5 is connected with  $f(2, 0) = 7$  and  $f(2, 2) = 9$

In case of,  $N_4$  5 is connected with  $f(1, 0) = 4$ ,  $f(0, 1) = 6$ ,  $f(2, 0) = 7$  and  $f(2, 2) = 9$

## Image Path

The Image path is a sequence of connected pixels starts at the first pixel  $f(x_1, y_1)$  and ends at  $f(x_n, y_n)$

#Example Find the Image Path Between  $f(1, 1)$  and  $f(3, 5)$

- Giving the connectivity set  $\xi = \{3, 4, 5, 6, 7, 8, 9, 10\}$

|   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|
| 6 | 3 | 8 | 7 | 5 | 4 | 2 |
| 2 | 2 | 5 | 6 | 9 | 8 | 7 |
| 4 | 5 | 2 | 3 | 0 | 1 | 2 |
| 3 | 2 | 1 | 7 | 1 | 2 | 1 |
| 1 | 1 | 1 | 8 | 0 | 5 | 5 |
| 8 | 8 | 8 | 6 | 7 | 9 | 8 |
| 7 | 7 | 7 | 8 | 6 | 7 | 5 |

## Connected Regions

A set of pixels of an image such that

- Between any two pixels inside there exist at least one image path
- There exists no image path between any other pixel outside and an inside one
- #note An object within an image is a connected region

Region: is the group of connected pixels.

Labeling is a mean to find out the regions that exist within an image matrix

#Example get the labels for the pixels satisfying the rule of  $\xi = \{0 - - > 20\}$  and neighbor  $N_8$

|     |     |     |     |     |
|-----|-----|-----|-----|-----|
| 100 | 100 | 100 | 110 | 120 |
| 110 | 90  | 5   | 7   | 100 |
| 5   | 100 | 6   | 110 | 120 |
| 7   | 100 | 100 | 120 | 10  |
| 110 | 5   | 70  | 110 | 8   |
| 111 | 110 | 7   | 10  | 120 |

finally, the found labels are  $L1, L2$

$L1 = \{f(2, 1), f(3, 1), f(2, 2)\}$

$L2 = \{f(0, 2), f(0, 3), f(1, 4), f(2, 5), f(3, 5), f(4, 3), f(4, 4)\}$

## Distance Metrics

- Euclidian:  $\Delta(f(x_1, y_1), f(x_2, y_2)) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$
- City Blocks:  $\Delta(f(x_1, y_1), f(x_2, y_2)) = |x_1 - x_2| + |y_1 - y_2|$
- Chess Board:  $\Delta(f(x_1, y_1), f(x_2, y_2)) = \max(|x_1 - x_2|, |y_1 - y_2|)$