

Abstract

Design and build a system capable of monitoring sites
ENGINEERING installed on the robot wheelchair can be controlled
wirelessly using NR waves to control in a radius of 85 meters and
alarm about the presence of rain and provider of solar cells to charge
the battery during the day and through the installation of a camera
Vision day and night can control the angle of vision on the robot can
visually follow the camera through the IP address of the entry of a
laptop or cell phone to see the site.

