COMP 4900 Assignment 3

March 5, 2023

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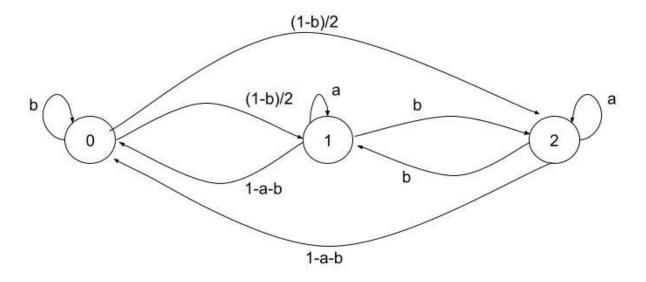
Abdulaah Emin

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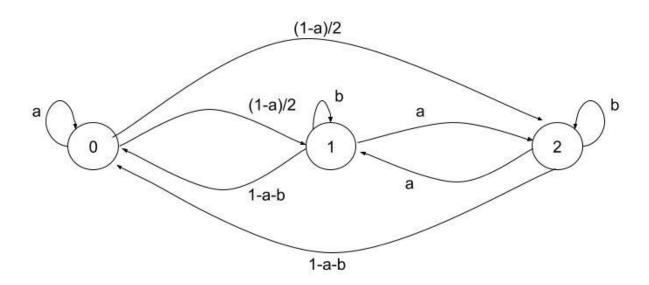


a.

β=0



β=1



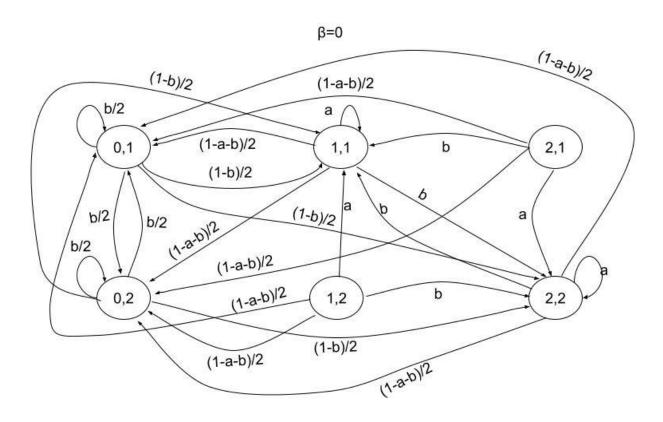
$$F^0 = \begin{bmatrix} b & \frac{1-b}{2} & \frac{1-b}{2} \\ 1-a-b & a & b \\ 1-a-b & b & a \end{bmatrix} \\ F^1 = \begin{bmatrix} a & \frac{1-a}{2} & \frac{1-a}{2} \\ 1-a-b & b & a \\ 1-a-b & a & b \end{bmatrix} \\ G = \begin{bmatrix} 0.5 & 0.5 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

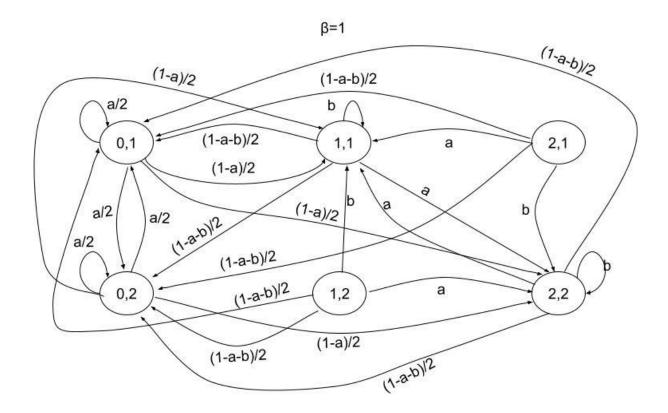
b. New states are:

$$0 \rightarrow (0,1) & (0,2)$$

$$1 \rightarrow (1,1) & (1,2)$$

$$2 \rightarrow (2,1) & (2,2)$$





Using this formula,

$$F^{0,1}_{< i,j>< k,l>} = F^{0,1}_{i,k} \, {}^{\text{old}} * G_{k,l}$$

 F^0 and F^1 can be generated as follow:

$$F^{0} = \begin{bmatrix} \frac{b}{2} & \frac{1-b}{2} & 0 & \frac{b}{2} & 0 & \frac{1-b}{2} \\ \frac{1-a-b}{2} & a & 0 & \frac{1-a-b}{2} & 0 & b \\ \frac{b}{2} & \frac{1-b}{2} & b & 0 & \frac{1-a-b}{2} & 0 & a \\ \frac{b}{2} & \frac{1-b}{2} & 0 & \frac{b}{2} & 0 & \frac{1-b}{2} \\ \frac{1-a-b}{2} & a & 0 & \frac{1-a-b}{2} & 0 & b \\ \frac{1-a-b}{2} & a & 0 & \frac{1-a-b}{2} & 0 & b \end{bmatrix}$$

$$F^{1} = \begin{bmatrix} \frac{a}{2} & \frac{1-a}{2} & 0 & \frac{a}{2} & 0 & \frac{1-a-b}{2} & 0 & a \\ \frac{1-a-b}{2} & a & 0 & \frac{1-a-b}{2} & 0 & b \\ \frac{a}{2} & \frac{1-a}{2} & 0 & \frac{a}{2} & 0 & \frac{1-a}{2} \\ \frac{a}{2} & \frac{1-a-b}{2} & 0 & 0 & a \\ \frac{1-a-b}{2} & b & 0 & \frac{1-a-b}{2} & 0 & a \end{bmatrix}$$

G will become deterministic, therefore when in state $S_{i,j}$ choose action j with probability 1

$$G = \begin{pmatrix} (0,1) \\ (1,1) \\ (1,2) \\ (0,2) \\ (1,2) \\ (2,2) \end{pmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 1 \end{bmatrix}$$

This new machine does not need to have 6 states, it can have only 4, since from old G matrix, state 1 action 2 (1,2) never occurs and state 2 action 1 (2,1) never occurs. As can be seen in our new matrix F^0 and F^1 , columns for (2,1) and (1,2) are all zero entries.

c.(See code for calculations)

Using these formulas,

$$F_{i,j}^{-} = F_{i,j}^{0} [G_{i,1} * (1-C_{1}) + G_{i,2} * (1-C_{2})] + F_{i,j}^{1} [G_{i,1} * C_{1} + G_{i,2} * C_{2})]$$

$$\pi(n) = (F^{-})^{T*} \pi(n-1)$$

$$P(n) = G^{T*} \pi(n)$$

Given a=0.3, b=0.7 and c=[0.4, 0.6], F^{\sim} can be generated as follow:

$$F^{\sim} = \begin{bmatrix} 0.5 & 0.25 & 0.25 \\ 0 & 0.46 & 0.54 \\ 0 & 0.46 & 0.54 \end{bmatrix}$$

Given $\pi(0) = [0.2, 0.4, 0.4]$

We can find P(0), $\pi(1)$ and P(1)

$$P(0) = G^{T*} \pi(0) = [0.5, 0.5]$$

$$\pi(1) = (F^{\sim})^{T*} \; \pi(0) = [0.1 \; , \, 0.418, \, 0.482]$$

$$P(1) = G^{T_*} \pi(1) = [0.468, 0.532]$$

d. (See code for calculations)

Using same formulas and same $\pi(0)$, a,b and c values from question c,

F can be generated as follow:

$$F^{\sim} = \begin{bmatrix} 0.27 & 0.23 & 0 & 0.27 & 0 & 0.23 \\ 0 & 0.46 & 0 & 0 & 0 & 0.54 \\ 0 & 0.54 & 0 & 0 & 0 & 0.46 \\ 0.23 & 0.27 & 0 & 0.23 & 0 & 0.27 \\ 0 & 0.54 & 0 & 0 & 0 & 0.46 \\ 0 & 0.46 & 0 & 0 & 0 & 0.54 \end{bmatrix}$$

Given
$$\pi(0) = [0.2, 0.4, 0.4]$$

We can convert to our new $\pi(0)$ using the old G, following this formula:

$$\pi(0)_{s=(i,j)}^{\text{new}} = \pi(0)_{s=i}^{\text{old}} * G_{i,j}^{\text{old}}$$

States order: (0,1),(1,1),(2,1),(0,2),(1,2),(2,2)

$$\pi(0) = [0.1, 0.4, 0.0, 0.1, 0.0, 0.4]$$

We can find P(0), $\pi(1)$ and P(1)

$$P(0) = (G)^{T*} \pi(0) = [0.5, 0.5]$$

$$\pi(1) = (F^{\sim})^{T*} \pi(0) = [0.05, 0.418, 0, 0.05, 0, 0.482]$$

$$P(1) = G^{T*} \pi(1) = [0.468, 0.532]$$