

SoilMind: Real Sensor Integration Guide

Overview

This guide covers transitioning from potentiometer simulation to real agricultural sensors for the Smart Irrigation system. By the end, you'll have a fully functional edge-AI irrigation controller.

1. Hardware Requirements

1.1 Recommended Sensors

Sensor	Model	Purpose	Interface	Price Range
Soil Moisture	Capacitive v1.2/v2.0	Soil moisture level	Analog	\$2-5
Temperature & Humidity	DHT22 / AM2302	Air temp & humidity	Digital (1-wire)	\$3-6
Alternative Temp	DS18B20 (waterproof)	Soil temperature	Digital (1-wire)	\$2-4

 **Avoid resistive soil moisture sensors** - they corrode quickly and give inconsistent readings.

1.2 Bill of Materials

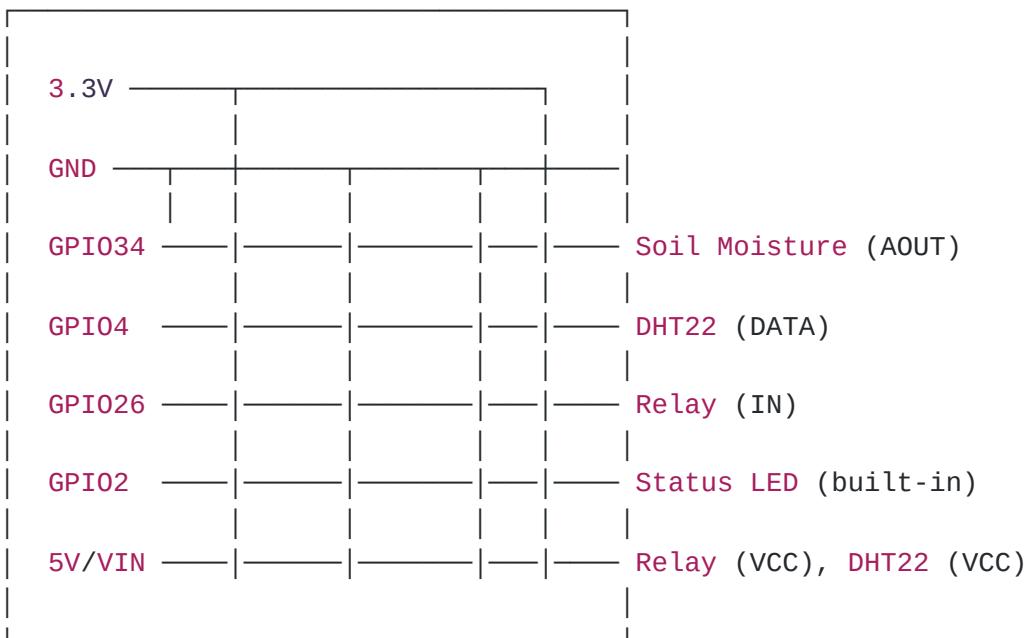
Component	Quantity	Notes
ESP32 DevKit	1	Any variant with ADC pins
Capacitive Soil Moisture Sensor	1	v1.2 or v2.0
DHT22 Sensor	1	With breakout board
5V Relay Module	1	For pump control
Water Pump (5V/12V)	1	Submersible or diaphragm
10kΩ Resistor	1	Pull-up for DHT22
Jumper Wires	~15	Male-to-female recommended

Component	Quantity	Notes
Breadboard	1	For prototyping
Power Supply	1	5V 2A minimum

2. Wiring Diagram

2.1 Pin Connections

ESP32 DevKit V1



2.2 Detailed Connections

Capacitive Soil Moisture Sensor:

Sensor	ESP32
VCC	→ 3.3V (NOT 5V - can damage ADC!)
GND	→ GND
AOUT	→ GPIO34

DHT22 Temperature/Humidity Sensor:

Sensor	ESP32
VCC	→ 5V (or 3.3V)

GND	→	GND
DATA	→	GPIO4 (with 10kΩ pull-up to VCC)

Relay Module:

Relay		ESP32
VCC	→	5V
GND	→	GND
IN	→	GPIO26
COM	→	Pump power (+)
NO	→	Pump (+) terminal

3. Sensor Calibration

3.1 Soil Moisture Calibration

The capacitive sensor outputs analog values. You need to map these to match your training data range (50-450).

Calibration Procedure:

1. Dry Reading (Air):

Remove sensor **from** soil, wipe clean, let dry
 Record value: DRY_VALUE = _____ (typically 3200-3600)

2. Wet Reading (Water):

Submerge sensor up to **the** line **in** water
 Record value: WET_VALUE = _____ (typically 1400-1800)

3. Calculate Mapping:

```
// In your code:
const int DRY_VALUE = 3400;    // Your measured dry value
const int WET_VALUE = 1600;    // Your measured wet value

// Map to training data range (50-450)
float mapMoisture(int raw) {
    // Invert because lower ADC = wetter soil
    float normalized = (float)(DRY_VALUE - raw) / (DRY_VALUE - WET_VALUE);
    normalized = constrain(normalized, 0.0f, 1.0f);
```

```
    return MOISTURE_MIN + normalized * (MOISTURE_MAX - MOISTURE_MIN);  
}
```

3.2 Temperature Verification

DHT22 is factory-calibrated, but verify readings:

1. Compare with a known thermometer
2. If offset exists, add correction factor:

```
float temp = dht.readTemperature() + TEMP_OFFSET;
```

4. Software Implementation

4.1 Required Libraries

Install via Arduino Library Manager:

- DHT sensor library (by Adafruit)
- Adafruit Unified Sensor
- ArduTFLite (already installed)

4.2 Code Structure

```
#include <ArduTFLite.h>  
#include <DHT.h>  
#include "irrigation_model.h"  
  
// ===== PIN DEFINITIONS =====  
#define SOIL_MOISTURE_PIN 34  
#define DHT_PIN 4  
#define RELAY_PIN 26  
#define LED_PIN 2  
  
// ===== SENSOR CONFIG =====  
#define DHT_TYPE DHT22  
  
// Calibration values (UPDATE THESE!)  
const int DRY_VALUE = 3400;  
const int WET_VALUE = 1600;  
  
// Mapping ranges (match training data)  
const float MOISTURE_MIN = 50.0f;  
const float MOISTURE_MAX = 450.0f;
```

```
// ===== OBJECTS =====
DHT dht(DHT_PIN, DHT_TYPE);
```

4.3 Sensor Reading Functions

```
float readSoilMoisture() {
    // Average multiple readings for stability
    long sum = 0;
    for (int i = 0; i < 10; i++) {
        sum += analogRead(SOIL_MOISTURE_PIN);
        delay(10);
    }
    int raw = sum / 10;

    // Map to training data range (inverted - lower ADC = wetter)
    float normalized = (float)(DRY_VALUE - raw) / (DRY_VALUE - WET_VALUE);
    normalized = constrain(normalized, 0.0f, 1.0f);

    return MOISTURE_MIN + normalized * (MOISTURE_MAX - MOISTURE_MIN);
}

float readTemperature() {
    float temp = dht.readTemperature();

    // Check for read errors
    if (isnan(temp)) {
        Serial.println("[ERROR] DHT read failed!");
        return -999.0f; // Error indicator
    }

    return temp;
}
```

4.4 Setup Function

```
void setup() {
    Serial.begin(115200);
    delay(1000);

    // Initialize pins
    pinMode(SOIL_MOISTURE_PIN, INPUT);
    pinMode(RELAY_PIN, OUTPUT);
    pinMode(LED_PIN, OUTPUT);
    digitalWrite(RELAY_PIN, LOW);

    // Initialize DHT sensor
    dht.begin();
    Serial.println("[INIT] DHT22 initialized");
```

```

// Initialize ML model
modelReady = modelInit(irrigation_model, tensorArena, kTensorArenaSize);
Serial.printf("[INIT] Model: %s\n", modelReady ? "OK" : "FAILED");

// Initialize history
history.init();

// Wait for DHT to stabilize
delay(2000);
}

```

5. Sampling Strategy

5.1 Recommended Intervals

Parameter	Interval	Reason
Sensor Reading	30-60 seconds	Soil moisture changes slowly
ML Inference	Every 4th reading	Need trend data
Pump Check	After each inference	React to predictions

5.2 Reading Interval Configuration

```

const unsigned long READING_INTERVAL = 30000; // 30 seconds
const unsigned long MIN_PUMP_ON_TIME = 10000; // Minimum 10s pump runtime
const unsigned long PUMP_COOLDOWN = 60000; // Wait 60s before re-checking

```

6. Error Handling

6.1 Sensor Failure Detection

```

bool sensorsOK = true;

void checkSensors() {
    // Check DHT
    float temp = dht.readTemperature();
    if (isnan(temp)) {
        Serial.println("[WARN] DHT not responding!");
        sensorsOK = false;
    }
}

```

```
// Check soil moisture (should be within calibration range)
int raw = analogRead(SOIL_MOISTURE_PIN);
if (raw < WET_VALUE - 500 || raw > DRY_VALUE + 500) {
    Serial.println("[WARN] Soil sensor out of range!");
    sensorsOK = false;
}

sensorsOK = true;
}
```

6.2 Failsafe Logic

```
void controlIrrigation(float probability) {
    // FAILSAFE: If sensors fail, turn OFF pump
    if (!sensorsOK || !modelReady) {
        digitalWrite(RELAY_PIN, LOW);
        irrigationActive = false;
        Serial.println("[SAFETY] Pump OFF - sensor/model error");
        return;
    }

    // Normal ML-based control
    bool shouldIrrigate = (probability >= IRRIGATION_THRESHOLD);
    // ... rest of control logic
}
```

7. Testing Checklist

7.1 Pre-Deployment Tests

- [] **Sensor Readings Stable**
 - Moisture readings vary < ±5 units when stable
 - Temperature readings vary < ±0.5°C when stable
- [] **Calibration Verified**
 - Dry soil → High moisture value (~50-100)
 - Wet soil → Low moisture value (~350-450)
 - Values within training data range
- [] **ML Predictions Sensible**
 - High moisture + stable → NO irrigation
 - Low moisture + dropping → IRRIGATE

- Rising moisture → Eventually stops irrigation

- [] **Relay/Pump Works**

- Relay clicks when activated
- Pump runs when relay closes
- No false triggers

- [] **Long Duration Test (24h)**

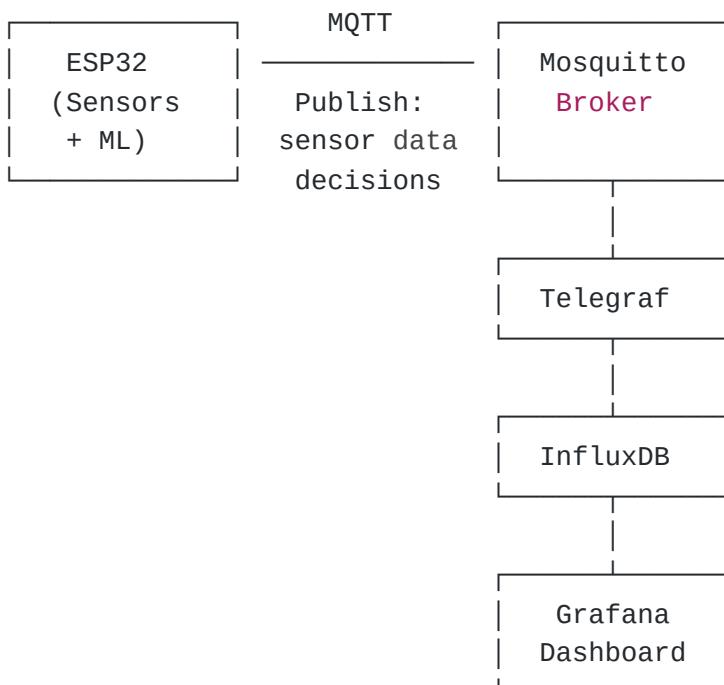
- No crashes or memory leaks
- Reasonable irrigation cycles
- Log data for review

7.2 Field Deployment Checklist

- [] Waterproof enclosure for ESP32
- [] Sensor cables secured and protected
- [] Power supply adequate and weatherproof
- [] Manual override switch installed
- [] Water supply connected and tested

8. Next Steps: MQTT Integration

Once sensors work locally, integrate with your IoT stack:



MQTT Topics Structure:

soilmind/sensors/temperature
 soilmind/sensors/moisture
 soilmind/sensors/moisture_trend
 soilmind/ml/probability
 soilmind/ml/decision
 soilmind/pump/status

9. Troubleshooting

Problem	Possible Cause	Solution
Moisture always 0 or 450	Wrong calibration values	Re-calibrate DRY/WET values
DHT returns NaN	Wiring issue or no pull-up	Check wiring, add 10kΩ pull-up
Model says IRRIGATE always	Values outside training range	Verify mapping matches training data
ESP32 crashes	Arena too small	Increase kTensorArenaSize
Pump never turns off	Threshold too low	Increase IRRIGATION_THRESHOLD
Erratic readings	Power noise	Add 100µF capacitor on sensor VCC

10. Complete Code Template

exist in attached .ino file