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Points-to Analysis in Almost Linear Time

Presented by Abdul Dakkak

Overview

- * Definitions
- * Steensgaard's Language
- * Steensgaard's Algorithm
- * Results
- * Conclusion

Definitions

Definitions

- * A variable *p points-to* a value *v* if *p*'s value may contain the address of *v*
- * Two values p and q alias if they may point-to the same variable (if $pts(p) \cap pts(q) \neq \{\}$)
- * The *points-to set* for p contains the set of variables which p may point-to ($v \in pts(p)$ iff p may point-to v)

Definitions

- * An analysis is *flow sensitive* if it performs the analysis at each program point and follows the instruction flow (keeps track of branches, definition kills, ...)
- * An analysis is *context sensitive* if keeps flow along different call paths separate (considers calling context when performing the analysis)
- * An analysis if *field sensitive* if it distinguishes between elements in a field (**struct** in C)

Unification

- * A unification algorithm finds a set of replacement rules that make two terms equal
 - * e.x. if f(g) = f(a) then $g \rightarrow a$ is a substitution that makes the two terms equal
- * For Steensgard, unification means union

Pointer Analysis Uses

- * Pointer analysis facilitates compiler optimizations
- * Useful only when you know that two variables *must not* alias

Available Expressions: If p aliases p or p then the second computation of p is not redundant.

$$p = a + b;$$

 $y = a + b;$

Constant Propagation: If p aliases x then we cannot propagate the value of x.

Steensgaard's Language

Bubble Sort

- * Declare a Point structure
- * Swap elements if two points are lexicographically less than each other
- * In main: allocate two lists and perform bubble sort on them

```
typedef struct {
  double x, y;
} Point t;
bool less(Point_t a, Point_t b) {
  return (a.x < b.x) || (a.x == b.x && a.y < b.y);
void swap(Point t * a, Point t * b) {
  Point t tmp = *a;
  *a = *b;
  *b = tmp;
void bubbleSort(Point_t *pts, int len) {
  bool swapped = true;
  while (swapped) {
    int ii = 1;
    swapped = false;
    while (ii < len) {</pre>
      Point_t * prev = &pts[ii - 1];
      Point_t * curr = &pts[ii];
      if (less(*prev, *curr)) {
        swap(prev, curr);
        swapped = true;
      ii++;
int main(void) {
 lenA = 4;
  lenB = 4;
  A = malloc(lenA);
  A = malloc(lenA);
 A = \{\{0,0\}, \{0,1\}, \{1,1\}, \{1,0\}\};
  B = \{\{1,0\}, \{1,1\}, \{0,1\}, \{0,0\}\};
  bubbleSort(A, lenA);
  bubbleSort(B, lenB);
  return 0;
```

Translating into Steensgaard's Language

- Models C language
- * C pointer operations can be desugared

```
typedef struct {
  double x, y;
} Point t;
bool less(Point t a, Point t b) {
  return (a.x < b.x) || (a.x == b.x && a.y < b.y);
void swap(Point_t * a, Point_t * b) {
  Point_t tmp = *a;
                                                               tmp = *a
  *a = *b;
                                                                *a = *b
  *b = tmp;
                                                               void = 0
void bubbleSort(Point_t *pts, int len) {
  bool swapped = true;
  while (swapped) {
    int ii = 1;
                                                                 ii = 1;
    swapped = false;
    while (ii < len) {
      Point t * prev = &pts[ii - 1];
      Point_t * curr = &pts[ii];
      if (less(*prev, *curr)) {
        swap(prev, curr);
        swapped = true;
      ii++;
int main(void) {
  lenA = 4;
  lenB = 4;
  A = malloc(lenA);
                                                               void = 0
  A = malloc(lenA);
                                                             lenA = 4;
  A = \{\{0,0\}, \{0,1\}, \{1,1\}, \{1,0\}\};
                                                             lenB = 4;
  B = \{\{1,0\}, \{1,1\}, \{0,1\}, \{0,0\}\};
  bubbleSort(A, lenA);
  bubbleSort(B, lenB);
  return 0;
                                                             return(0);
```

```
less = fun(a, b) \rightarrow (res)
  tmp0 = fless(a.x, b.x)
  tmp1 = feq(a.x, b.x)
  tmp2 = fless(a.y, b.y)
  tmp3 = and(tmp1, tmp2)
  res = or(tmp0, tmp3)
swap = fun(*a, *b) \rightarrow (void)
bubbleSort = fun(*pts, len) -> (void)
  swapped = true;
  while (swapped) {
    swapped = false;
    while (ii < len) {</pre>
      ptsii_1 = add(pts, subtract(ii, 1));
      ptsii = add(pts, ii);
      prev = &ptsii 1;
      curr = &pts_ii;
      dprev = *prev;
      dcurr = *curr;
      if (less(dprev, dcurr)) {
        swap(prev, curr);
        swapped = true;
      ii = iadd(ii, 1);
A = allocate(lenA);
A = allocate(lenA);
A = \{\{0,0\}, \{0,1\}, \{1,1\}, \{1,0\}\};
B = \{\{1,0\}, \{1,1\}, \{0,1\}, \{0,0\}\};
bubbleSort(A, lenA);
bubbleSort(B, lenB);
```

Steensgaard's Language

- No aggregate types
- * Function variables are unique to the function
- Struct accessors flattened
- Pointer operations desugared to function calls
- * Malloc converted to allocate
- Void return converted to use a dummy variable

```
less = fun(a, b) \rightarrow (res)
  tmp0 = fless(a, b)
  tmp1 = feq(a, b)
  tmp2 = fless(a, b)
  tmp3 = and(tmp1, tmp2)
  res = or(tmp0, tmp3)
swap = fun(*a, *b) \rightarrow (void)
  tmp = *a
  *b = tmp
  void = 0
bubbleSort = fun(*pts, len) -> (void)
  swapped = true;
  while (swapped) {
    ii = 1;
    swapped = false;
    while (ii < len) {
      ptsii_1 = add(pts, subtract(ii, 1));
      ptsii = add(pts, ii);
      prev = &ptsii 1;
      curr = &pts_ii;
      dprev = *prev;
      dcurr = *curr;
      if (less(dprev, dcurr)) {
         swap(prev, curr);
         swapped = true;
      ii = iadd(ii, 1);
  void = 0
lenA = 4:
lenB = 4;
A = allocate(lenA);
A = allocate(lenA);
A = \{\{0,0\}, \{0,1\}, \{1,1\}, \{1,0\}\};
B = \{\{1,0\}, \{1,1\}, \{0,1\}, \{0,0\}\};
bubbleSort(A, lenA);
bubbleSort(B, lenB);
return(0);
```

Algorithm

Steensgaard's Algorithm

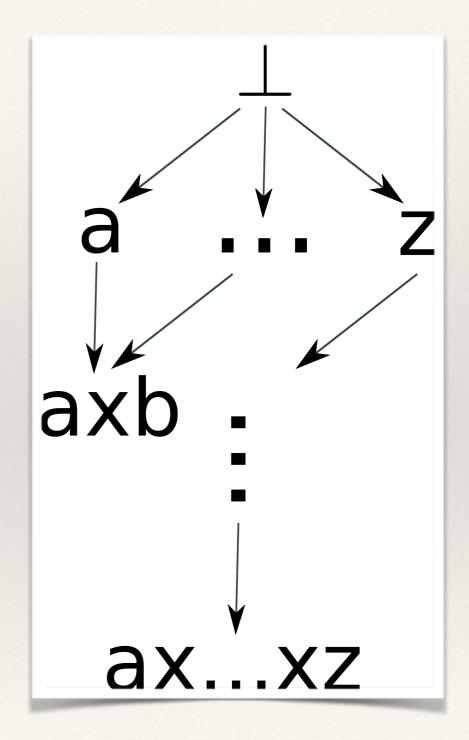
- * Flow insensitive, interprocedural, context insensitive unification based pointer analysis
- * Performs pointer analysis in near linear time
- * Traverse the instructions from top to bottom in a single pass
- * If type information is known then unify them, otherwise delay the unification

Modeling Values

- * Model values as pointers to locations or points to functions
 - * Value types: $\alpha = \tau \times \lambda$
 - * Pointer/Address types: $\tau = ref(\alpha) \mid \bot$
 - * Function signature: $\lambda = lam(\alpha_1,...)(\alpha_k,...) \mid \bot$
- * Keeps space usage to O(n) using this representation
- Impose partial order on memory locations

Partial Ordering

- We define a partial Ordering operator ≤
 such that
 - $(t_1 \leq t_2) \Leftrightarrow (t_1 = \bot) \lor (t_1 = t_2)$
 - $(t_1 \times t_2) \trianglelefteq (t_3 \times t_4) \Leftrightarrow (t_1 \trianglelefteq t_3) \land (t_2 \trianglelefteq t_4)$
- * Type type of each type variable is initially assumed to be $ref(\bot \times \bot)$



Use a Simpler Example

```
typedef struct {
     float x, y;
} Point t;
bool lessX(Point_t * a, Point_t * b) {
     return a->x < b->x;
}
Point_t A[1] = \{\{0, 0\}\};
Point_t B = \{0, 1\};
Point_t * pC;
bool g = lessX(&A[0], &B);
if (g) {
     pC = &A[0];
} else {
     pC = \&B;
}
bool k = lessX(\&B, \&A[0]):
```

```
lessX = fun(lessa, lessb) -> (res)
     res = fpless(lessa, lessb)
v00 = 00
v01 = 01
A = allocate(8)
*A = v00
B = v01
A0 = *A
pA0 = &A0
pB = \&B
g = lessX(pA0, pB)
if g then
     pC = &A0
else
     pC = \&B
end
k = lessX(pB, pA0)
```

```
A \vdash \mathbf{x} : \mathbf{ref}(\underline{\phantom{a}} \times \mathbf{lam}(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}))
                                     A \vdash \mathsf{f}_i : \mathsf{ref}(\alpha_i)
                                  A \vdash \mathsf{r}_j : \mathbf{ref}(\alpha_{n+j})
                         \forall s \in S^* : A \vdash welltyped(s)
  A \vdash well typed(x = fun(f_1...f_n) \rightarrow (r_1...r_m) S^*)
```

One can use C's type information

pointer.

to know that the return type is not a

lessX = fun(lessa, lessb) -> (res) res = fpless(lessa, lessb)

fpless :
$$\tau_0 = \mathbf{ref}(_- \times \mathbf{lam}(\alpha_1, \alpha_2)(\alpha_3))$$

lessa :
$$\tau_1 = \mathbf{ref}(\alpha_4)$$

lessb :
$$\tau_2 = \mathbf{ref}(\alpha_5)$$

res :
$$\tau_3 = \mathbf{ref}(\alpha_6) = \mathbf{ref}(\bot \times \bot)$$

less :
$$\tau_4 = \mathbf{ref}(_- \times \mathbf{lam}(\alpha_4, \alpha_5)(\alpha_6))$$

$$\alpha_4 \leq \alpha_1$$

$$\alpha_5 \leq \alpha_2$$

Constrains on the unbound types.

$$\alpha_6 \leq \alpha_3$$

$$v00 = 00$$

$$v01 = 01$$

$$A = allocate(8)$$

$$*A = v00$$

$$A \vdash x : \mathbf{ref}(\mathbf{ref}(\underline{\ }) \times \underline{\ })$$
$$A \vdash welltyped(x = allocate(y))$$

$$A \vdash \mathsf{x} : \mathbf{ref}(\mathbf{ref}(\alpha_1) \times \underline{\hspace{0.5cm}})$$

$$A \vdash \mathsf{y} : \mathbf{ref}(\alpha_2)$$

$$\alpha_2 \unlhd \alpha_1$$

$$A \vdash welltyped(*\mathsf{x} = \mathsf{y})$$

$$v00:\tau_5 = \mathbf{ref}(\bot \times \bot) = \mathbf{ref}(\alpha_7)$$

$$v01:\tau_6 = \mathbf{ref}(\bot \times \bot) = \mathbf{ref}(\alpha_8)$$

Values are assumed to not reference anything.

$$A:\tau_{10}=\mathbf{ref}(\mathbf{ref}(_{-})\times_{-})$$

Underscore matches any symbol

$$A:\tau_{10}=\mathbf{ref}(\mathbf{ref}(\alpha_9)\times _{-})$$



Constraints are added in case values are no longer \(\triangle \)

$$B = v01$$
 $A0 = *A$
 $pA0 = &A0$
 $pB = &B$

B:
$$\tau_{11} = \mathbf{ref}(\alpha_{10})$$

$$\alpha_8 \leq \alpha 10$$
A0: $\tau_{12} = \mathbf{ref}(\alpha_{11})$

$$\alpha_9 \leq \alpha 11$$
pA0: $\tau_{13} = \mathbf{ref}(\tau_{12} \times \beta_{12})$
pB: $\tau_{14} = \mathbf{ref}(\tau_{11} \times \beta_{12})$

$$A \vdash \mathbf{x} : \mathbf{ref}(\alpha_1)$$

$$A \vdash \mathbf{y} : \mathbf{ref}(\mathbf{ref}(\alpha_2) \times \underline{\hspace{1cm}})$$

$$\alpha_2 \trianglelefteq \alpha_1$$

$$A \vdash welltyped(\mathbf{x} = *\mathbf{y})$$

$$A \vdash \mathbf{x} : \mathbf{ref}(\tau \times \underline{\hspace{0.1cm}})$$

$$A \vdash \mathbf{y} : \tau$$

$$A \vdash welltyped(\mathbf{x} = \mathbf{\&y})$$

$$A \vdash \mathsf{x}_{j} : \mathbf{ref}(\alpha'_{n+j})$$

$$A \vdash \mathsf{p} : \mathbf{ref}(_ \times \mathbf{lam}(\alpha_{1} \dots \alpha_{n})(\alpha_{n+1} \dots \alpha_{n+m}))$$

$$A \vdash \mathsf{y}_{i} : \mathbf{ref}(\alpha'_{i})$$

$$\forall i \in [1 \dots n] : \alpha'_{i} \trianglelefteq \alpha_{i}$$

$$\forall j \in [1 \dots m] : \alpha_{n+j} \trianglelefteq \alpha'_{n+j}$$

$$A \vdash welltyped(\mathsf{x}_{1} \dots \mathsf{x}_{m} = \mathsf{p}(\mathsf{y}_{1} \dots \mathsf{y}_{n}))$$

g = lessX(pA0, pB)

$$\tau_{13} \leq \alpha_4$$

$$\tau_{14} \leq \alpha_5$$



Constraints from the function call.

$$\tau_{14} \leq \alpha_5$$

$$g:\tau_{15}=\mathbf{ref}(\bot\times\bot)$$

if g then
$$pC = \&A0$$
 else
$$pC = \&B$$
 end

$$A \vdash x : \mathbf{ref}(\tau \times \underline{\hspace{0.1cm}})$$

$$A \vdash y : \tau$$

$$A \vdash welltyped(x = \&y)$$

pC:
$$\tau_{16} = \mathbf{ref}(\tau_{12} \times L)$$
pC: $\tau_{16} = \mathbf{ref}(\tau_{11} \times L)$

$$\tau_{12} = \tau_{11}$$

$$\alpha_{10} = \alpha_{11}$$
Equality

Equality follows from the unifying the types

$$A \vdash \mathsf{x}_{j} : \mathbf{ref}(\alpha'_{n+j})$$

$$A \vdash \mathsf{p} : \mathbf{ref}(_ \times \mathbf{lam}(\alpha_{1} \dots \alpha_{n})(\alpha_{n+1} \dots \alpha_{n+m}))$$

$$A \vdash \mathsf{y}_{i} : \mathbf{ref}(\alpha'_{i})$$

$$\forall i \in [1 \dots n] : \alpha'_{i} \trianglelefteq \alpha_{i}$$

$$\forall j \in [1 \dots m] : \alpha_{n+j} \trianglelefteq \alpha'_{n+j}$$

$$A \vdash welltyped(\mathsf{x}_{1} \dots \mathsf{x}_{m} = \mathsf{p}(\mathsf{y}_{1} \dots \mathsf{y}_{n}))$$

$$k = lessX(pB, pA0)$$

$$\tau_{14} \leq \alpha_4$$

$$\tau_{13} \leq \alpha_5$$



Why is this important?

$$g:\tau_{15}=\mathbf{ref}(\bot\times\bot)$$

Steensgaard Unifies Function Arguments

- * If $t_1 \le C$ and $t_2 \le C$ then $t_1 = t_2$
 - * Recall $(t \le C) \Leftrightarrow (t = \bot) \lor (t = C)$
- * This means that if we call a function with different arguments, then we will unify the arguments

```
memcpy(A, B, sz);
memcpy(B, C, sz);
memset(B, 0, sz);
strcmp(s1, s2);
strcmp(s2, s3);
```

Final Contraint Set

```
fpless :\tau_0 = \mathbf{ref}(\ \times \mathbf{lam}(\alpha_1, \alpha_2)(\alpha_3))
 lessa :\tau_1 = \mathbf{ref}(\alpha_4)
 lessb :\tau_2 = \mathbf{ref}(\alpha_5)
     res :\tau_3 = \mathbf{ref}(\alpha_6) = \mathbf{ref}(\bot \times \bot)
    less : \tau_4 = \mathbf{ref}(\mathbf{x} \times \mathbf{lam}(\alpha_4, \alpha_5)(\alpha_6))
               \alpha_4 \leq \alpha_1
                \alpha_5 \leq \alpha_2
                \alpha_6 \triangleleft \alpha_3
    v00:\tau_5 = \mathbf{ref}(\bot \times \bot) = \mathbf{ref}(\alpha_7)
    v01 : \tau_6 = \mathbf{ref}(\bot \times \bot) = \mathbf{ref}(\alpha_8)
        A:\tau_{10}=\mathbf{ref}(\mathbf{ref}(_{-})\times_{-})
        A : \tau_{10} = \mathbf{ref}(\mathbf{ref}(\alpha_9) \times \underline{\ })
                \alpha_7 \leq \alpha_9
        B:\tau_{11} = \mathbf{ref}(\alpha_{10})
                \alpha_8 \leq \alpha 10
```

$$A0 : \tau_{12} = \mathbf{ref}(\alpha_{11})$$

$$\alpha_9 \leq \alpha 11$$

$$pA0 : \tau_{13} = \mathbf{ref}(\tau_{12} \times \bot)$$

$$pB : \tau_{14} = \mathbf{ref}(\tau_{11} \times \bot)$$

$$\tau_{13} \leq \alpha_4$$

$$\tau_{14} \leq \alpha_5$$

$$g : \tau_{15} = \mathbf{ref}(\bot \times \bot)$$

$$pC : \tau_{16} = \mathbf{ref}(\tau_{12} \times \bot)$$

$$pC : \tau_{16} = \mathbf{ref}(\tau_{11} \times \bot)$$

$$\tau_{12} = \tau_{11}$$

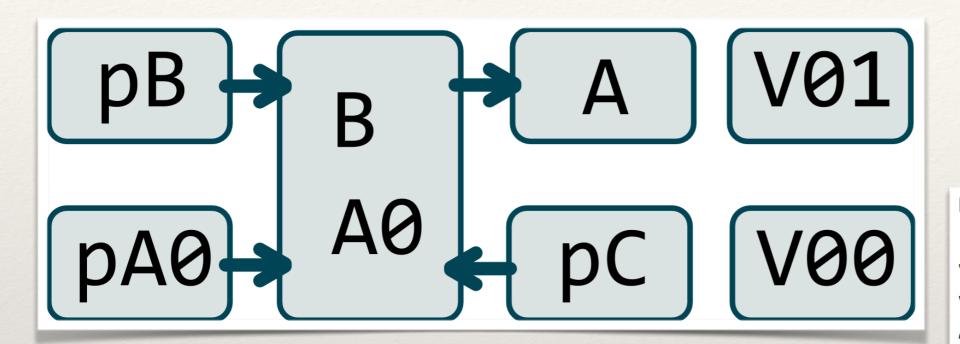
$$\alpha_{10} = \alpha_{11}$$

$$\tau_{14} \leq \alpha_4$$

$$\tau_{13} \leq \alpha_5$$

$$g : \tau_{15} = \mathbf{ref}(\bot \times \bot)$$

The Point-to Set for Our Program



```
lessX = fun(lessa, lessb) -> (res)
     res = fpless(lessa, lessb)
v00 = 00
v01 = 01
A = allocate(8)
*A = v00
B = v01
A^* = 0A
pA0 = &A0
pB = \&B
g = lessX(pA0, pB)
if g then
     pC = &A0
else
     pC = \&B
end
k = lessX(pB, pA0)
```

Why Partial Ordering Matters

$$A \vdash x : \mathbf{ref}(\alpha)$$

$$A \vdash y : \mathbf{ref}(\alpha)$$

$$A \vdash welltyped(x = y)$$

$$v00 = 00$$

v01 = 01



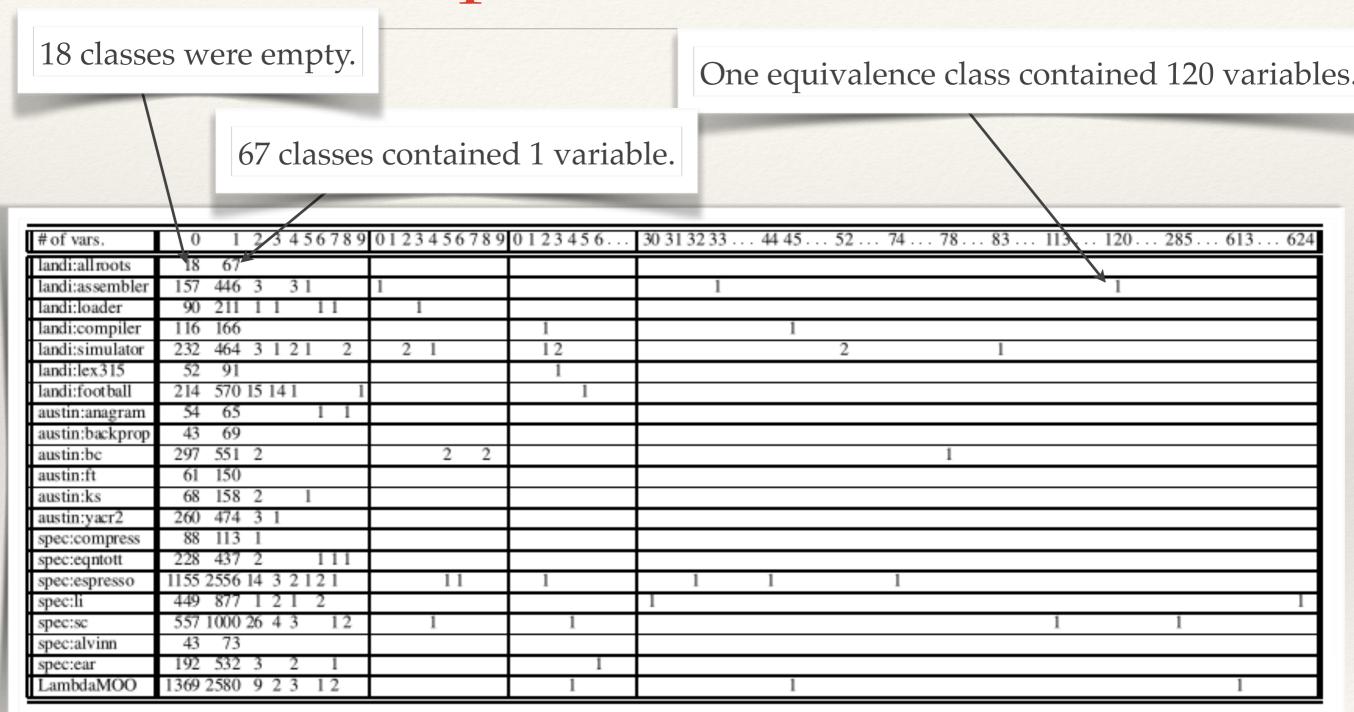
Would incorrectly alias v00 and v01

A = allocate(8)

*A = v00

Results

Unoptimized Results



Conclusion

Author's Conclusions

- * First algorithm to scale to 100kLOC (previous methods only scaled to 10kLOC)
- Uses very little memory and performs the analysis in a reasonable amount of time

Conclusion

- * First algorithm to scale beyond 10kLOC
- * Previous state of the art pointer analysis was O(n^3)
- * Can be used as a first pass for pointer analysis, more precise algorithms can be used on the refined subset
- * SSA provides some flow sensitivity for pointer analysis

Questions

Thank You

Backup Slides

```
A \vdash x : \mathbf{ref}(\alpha_1)
                     A \vdash y : \mathbf{ref}(\alpha_2)
             \alpha_2 \leq \alpha_1
A \vdash welltyped(x = y)
                 A \vdash x : \mathbf{ref}(\tau \times \_)
                           A \vdash \mathbf{y} : \tau
            A \vdash welltyped(x = \&y)
                    A \vdash x : \mathbf{ref}(\alpha_1)
          A \vdash y : \mathbf{ref}(\mathbf{ref}(\alpha_2) \times \_)
            \alpha_2 \leq \alpha_1
A \vdash welltyped(X = *Y)
                      A \vdash x : \mathbf{ref}(\alpha)
                    A \vdash y_i : \mathbf{ref}(\alpha_i)
\forall i \in [1 \dots n] : \alpha_i \leq \alpha

A \vdash welltyped(x = op(y_1 \dots y_n))
```

$$A \vdash \mathsf{x} : \mathbf{ref}(\mathbf{ref}(_) \times _)$$

$$A \vdash \mathsf{welltyped}(\mathsf{x} = \mathsf{allocate}(\mathsf{y}))$$

$$A \vdash \mathsf{x} : \mathbf{ref}(\mathbf{ref}(\alpha_1) \times _)$$

$$A \vdash \mathsf{y} : \mathbf{ref}(\alpha_2)$$

$$\alpha_2 \leq \alpha_1$$

$$A \vdash \mathsf{welltyped}(*\mathsf{x} = \mathsf{y})$$

$$A \vdash \mathsf{x} : \mathbf{ref}(_ \times \mathbf{lam}(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}))$$

$$A \vdash \mathsf{f}_i : \mathbf{ref}(\alpha_i)$$

$$A \vdash \mathsf{f}_i : \mathbf{ref}(\alpha_i)$$

$$A \vdash \mathsf{r}_j : \mathbf{ref}(\alpha_{n+j})$$

$$\forall s \in S^* : A \vdash \mathsf{welltyped}(s)$$

$$A \vdash \mathsf{welltyped}(\mathsf{x} = \mathsf{fun}(\mathsf{f}_1 \dots \mathsf{f}_n) \rightarrow (\mathsf{f}_1 \dots \mathsf{f}_m) S^*)$$

$$A \vdash \mathsf{x}_j : \mathbf{ref}(\alpha'_{n+j})$$

$$A \vdash \mathsf{p} : \mathbf{ref}(_ \times \mathbf{lam}(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}))$$

$$A \vdash \mathsf{y}_i : \mathbf{ref}(\alpha'_i)$$

$$\forall i \in [1 \dots n] : \alpha'_i \leq \alpha_i$$

$$\forall j \in [1 \dots m] : \alpha_{n+j} \leq \alpha'_{n+j}$$

$$A \vdash \mathsf{welltyped}(\mathsf{x}_1 \dots \mathsf{x}_m = \mathsf{p}(\mathsf{y}_1 \dots \mathsf{y}_n))$$

Type Rules

Implementation

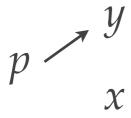
```
X = Y:
                                                                                            x = \text{fun}(f_1 \dots f_n) \rightarrow (r_1 \dots r_m) S^*:
    let ref(\tau_1 \times \lambda_1) = type(ecr(x))
                                                                                                let \mathbf{ref}(\_ \times \lambda) = \mathbf{type}(\mathbf{ecr}(\mathsf{x}))
         ref(\tau_2 \times \lambda_2) = type(ecr(y)) in
                                                                                                   if type(\lambda) = \bot then
       if \tau_1 \neq \tau_2 then cjoin(\tau_1, \tau_2)
                                                                                                       settype(\lambda, lam(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}))
       if \lambda_1 \neq \lambda_2 then cjoin(\lambda_1, \lambda_2)
                                                                                                            ref(\alpha_i) = type(ecr(f_i)), for i \le n
x = &v:
                                                                                                            ref(\alpha_i) = type(ecr(r_{i-n})), for i > n
    let ref(\tau_1 \times \underline{\hspace{0.1cm}}) = type(ecr(x))
         \tau_2 = \mathbf{ecr}(y) in
                                                                                                       let \operatorname{lam}(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}) = \operatorname{type}(\lambda) in
       if \tau_1 \neq \tau_2 then join(\tau_1, \tau_2)
                                                                                                          for i \in [1 \dots n] do
X = *Y:
                                                                                                             let \tau_1 \times \lambda_1 = \alpha_i
    let ref(\tau_1 \times \lambda_1) = type(ecr(x))
                                                                                                                   ref(\tau_2 \times \lambda_2) = type(ecr(f_i)) in
         ref(\tau_2 \times \underline{\hspace{0.1cm}}) = type(ecr(y)) in
                                                                                                                if \tau_1 \neq \tau_2 then join(\tau_2, \tau_1)
       if type(\tau_2) = \bot then
                                                                                                                if \lambda_1 \neq \lambda_2 then join(\lambda_2, \lambda_1)
           settype(\tau_2, ref(\tau_1 \times \lambda_1))
                                                                                                          for i \in [1 \dots m] do
       else
                                                                                                             let \tau_1 \times \lambda_1 = \alpha_{n+i}
          let ref(\tau_3 \times \lambda_3) = type(\tau_2) in
                                                                                                                   ref(\tau_2 \times \lambda_2) = type(ecr(r_i)) in
             if \tau_1 \neq \tau_3 then cjoin(\tau_1, \tau_3)
                                                                                                                if \tau_1 \neq \tau_2 then join(\tau_1, \tau_2)
             if \lambda_1 \neq \lambda_3 then cjoin(\lambda_1, \lambda_3)
                                                                                                                if \lambda_1 \neq \lambda_2 then join(\lambda_1, \lambda_2)
X = op(y_1 \dots y_n):
                                                                                            x_1 \dots x_m = p(y_1 \dots y_n):
    for i \in [1 \dots n] do
                                                                                                let ref(_\times \lambda) = type(ecr(p)) in
       let ref(\tau_1 \times \lambda_1) = type(ecr(x))
                                                                                                   if type(\lambda) = \bot then
             ref(\tau_2 \times \lambda_2) = type(ecr(y_i)) in
                                                                                                       settype(\lambda, lam(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}))
          if \tau_1 \neq \tau_2 then cjoin(\tau_1, \tau_2)
                                                                                                       where
          if \lambda_1 \neq \lambda_2 then cjoin(\lambda_1, \lambda_2)
                                                                                                            \alpha_i = \tau_i \times \lambda_i
                                                                                                             [\tau_i, \lambda_i] = MakeECR(2)
x = allocate(y):
                                                                                                   let lam(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}) = type(\lambda) in
   let ref(\tau \times \underline{\ }) = type(ecr(x)) in
                                                                                                      for i \in [1 \dots n] do
       if type(\tau) = \bot then
                                                                                                         let \tau_1 \times \lambda_1 = \alpha_i
          let [e_1, e_2] = MakeECR(2) in
                                                                                                               ref(\tau_2 \times \lambda_2) = type(ecr(y_i)) in
              settype(\tau, ref(e_1 \times e_2))
                                                                                                             if \tau_1 \neq \tau_2 then cjoin(\tau_1, \tau_2)
*X = Y:
                                                                                                             if \lambda_1 \neq \lambda_2 then cjoin(\lambda_1, \lambda_2)
    let ref(\tau_1 \times \underline{\hspace{0.1cm}}) = type(ecr(x))
                                                                                                      for i \in [1 \dots m] do
         ref(\tau_2 \times \lambda_2) = type(ecr(y))
                                                                                                          let \tau_1 \times \lambda_1 = \alpha_{n+1}
       if type(\tau_1) = \bot then
                                                                                                               \operatorname{ref}(\tau_2 \times \lambda_2) = \operatorname{type}(\operatorname{ecr}(\mathsf{x}_i)) in
           settype(\tau_1, ref(\tau_2 \times \lambda_2))
                                                                                                             if \tau_1 \neq \tau_2 then cjoin(\tau_2, \tau_1)
       else
                                                                                                             if \lambda_1 \neq \lambda_2 then cjoin(\lambda_2, \lambda_1)
           let ref(\tau_3 \times \lambda_3) = type(\tau_1) in
             if \tau_2 \neq \tau_3 then cjoin(\tau_3, \tau_2)
             if \lambda_2 \neq \lambda_3 then cjoin(\lambda_3, \lambda_2)
```

```
settype(e, t):
                                                                                                                    join(e_1, e_2):
    type(e) \leftarrow t
                                                                                                                        let t_1 = type(e_1)
    for x \in \mathbf{pending}(e) do \mathbf{join}(e, x)
                                                                                                                             t_2 = \mathbf{type}(e_2)
                                                                                                                             e = \operatorname{ecr-union}(e_1, e_2) in
                                                                                                                           if t_1 = \bot then
cjoin(e_1, e_2):
                                                                                                                               type(e) \leftarrow t_2
    if type(e_2) = \bot then
                                                                                                                              if t_2 = \bot then
       pending(e_2) \leftarrow \{e_1\} \cup pending(e_2)
                                                                                                                                  pending(e) \leftarrow pending(e_1) \cup
    else
                                                                                                                                                           pending(e_2)
       \mathbf{join}(e_1, e_2)
                                                                                                                               else
                                                                                                                                  for x \in \mathbf{pending}(e_1) do \mathbf{join}(e, x)
unify(ref(\tau_1 \times \lambda_1), ref(\tau_2 \times \lambda_2)):
                                                                                                                           else
    if \tau_1 \neq \tau_2 then join(\tau_1, \tau_2)
                                                                                                                               type(e) \leftarrow t_1
    if \lambda_1 \neq \lambda_2 then join(\lambda_1, \lambda_2)
                                                                                                                              if t_2 = \bot then
                                                                                                                                  for x \in \mathbf{pending}(e_2) do \mathbf{join}(e, x)
unify(lam(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}),
lam(\alpha'_1 \dots \alpha'_n)(\alpha'_{n+1} \dots \alpha'_{n+m}))
                                                                                                                               else
                                                                                                                                  \mathbf{unify}(t_1, t_2)
    for i \in [1 \dots (n+m)] do
    let \tau_1 \times \lambda_1 = \alpha_i
         \tau_2 \times \lambda_2 = \alpha_i' in
       if \tau_1 \neq \tau_2 then join(\tau_1, \tau_2)
       if \lambda_1 \neq \lambda_2 then join(\lambda_1, \lambda_2)
```

Unification

Flow Sensitive vs Insensitive Analysis

Flow Sensitive: Pointer analysis follows the CFG. Computes the points-to set at all program points.



Flow Insensitive: Pointer analysis ignores the order of statements in the program.

$$p < \frac{y}{x}$$

SSA Remedies Some Flow Insensitivity

Flow Sensitive: Pointer analysis follows the CFG. Computes the points-to set at all program points.

$$p1 \longrightarrow y$$

$$p0 \longrightarrow x$$

Flow Insensitive: Pointer analysis ignores the order of statements in the program.

$$p1 \longrightarrow y$$
$$p0 \longrightarrow x$$

Context Sensitive vs Insensitive Analysis

Context Sensitive: Considers calling context when performing *points-to* analysis.

$$pX \xrightarrow{x} a$$

$$pY \longrightarrow y$$

Context Insensitive: Produces spurious aliases.

```
pX \xrightarrow{x} a
pY \xrightarrow{y} y
```

```
void * id(void * a) {
   return a;
void fa() {
   int x = 1;
   pX = &x;
   id(pX);
void fb() {
   int y = 1;
   pY = &y;
   id(pY);
```