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enth Vector Mechanics for Engineers: Dynamics dition Principle of Work and Energy for a Rigid Body 17 - 6 •Work and kinetic energy are scalar quantities. •Assume that the rigid body is made of a large number of particles. T 1 U 1o 2 T 2 T1,T2 U1o 2 initial and final total kinetic energy of particles forming body total work of internal and ...

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Ferdinand P. Beer & E. Russell Johnston Jr. Vector Mechanics for Engineers ( Dynamics ) McGraw-Hill Book Company Inc. 1977 ( N.B.; book page numbering follows on from companion volume 'Statics' )

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Seventh Vector Mechanics for Engineers: Dynamics Edition 16 - 7 Axioms of the Mechanics of Rigid Bodies • The forces act at different points on a rigid body but but have the same magnitude, direction, and line of action.  $\mathbf{F} = F\mathbf{r}$  and • The forces produce the same moment about any point and are therefore, equipollent external forces.

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h Vector Mechanics for Engineers: Dynamics dition 2 - 30 Sample Problem 11.12 Rotation of the arm about O is defined by  $\theta = 0.15t^2$  where  $\theta$  is in radians and  $t$  in seconds. Collar B slides along the

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