# Additional Exercises For Convex Optimization Boyd Solutions

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#### **Additional Exercises For Convex Optimization**

This is a collection of additional exercises, meant to supplement those found in the book Convex Optimization, by Stephen Boyd and Lieven Vandenberghe. These exercises were used in several courses on convex optimization, EE364a (Stanford), EE236b (UCLA), or 6.975 (MIT), usually for homework, but sometimes as exam questions.

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2 Convex sets Let c1 be a vector in the plane de ned by a1 and a2, and orthogonal to a2. For example, we can take c1 = a1 aT 1 a2 ka2k2 2 a2: Then x2 S2 if and only if j cT 1 a1j c T 1 x jc T 1 a1j: Similarly, let c2 be a vector in the plane de ned by a1 and a2, and orthogonal to a1, e.g., c2 = a2 aT 2 a1 ka1k2 2 a1: Then x2 S3 if and only if j cT 2 a2j c T 2 x jc T 2 a2j: Putting it all ...

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# Convex Optimization - Boyd and Vandenberghe

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# Assignments | Introduction to Convex Optimization ...

† This set of exercises will be periodically updated as new exercises are added. Many of the exercises and solutions given here were developed as part of my earlier convex optimization book [BNO03] (coauthored with Angelia Nedi´c and Asuman Ozdaglar), and are posted on the internet of that book's web site. The

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