PROBLEM DEFINITION AND DESIGN SPECIFICATIONS

PROJECT TITLE: Mini Robotların Tatlı Dünyası

Definition of the Problem:

The main of the Project design a smart city system that we can apply mechatronics design skills and having a education system that can be used in ME461 project and Romer Internship Project. In addition, the system is going to have graphical user interface which will allow any student or intern to learn and test their algorithms.

Project Requirements:

- The system needs to be portable and re-used. (3D printable parts and electronic components).
- The battery management system needs to be designed.
- Communication system between mini robots and operator must be satisfied.
- Diffrent algorithms should be implamented eaisly.
- The World size proportions (building, road, vehicle, etc.) should be arranged properly.
- The electronic components should be assembled.
- Graphical User Interface should allow users to monitor sensor outcomes and realtime positions of the robot (in a 2-D grid).
- The system should be open source.

| Tasks\Time | 30/03/2023 | 6/4/2023 | 13/4/2023 | 20/4/2023 | 27/4/2023 | 4/5/2023 | 11/5/2023 | 18/5/2023 | 25/05/2023 | 1/6/2023 | 8/6/2023 | 10-11/6/2023 |
|--|------------|----------|-----------|-----------|-----------|----------|-----------|-----------|------------|----------|----------|--------------|
| Mini Robot World Project Assignment by Ahmet Bugra Koku | | | | | | | | | | | | |
| Analysis of project requirements and components | | | | | | | | | | | | |
| Literature Survey | | | | | | | | | | | | |
| Developing multiple conceptual design | | | | | | | | | | | | |
| Real concept presentation and selection | | | | | | | | | | | | |
| Mini Robot World Prototype electronic component selection and order | | | | | | | | | | | | |
| Electronic component arrival | | | | | | | | | | | | |
| Electronic/Mechanical component design and manufacturing | | | | | | | | | | | | |
| Mini Robot World motor actuation, sensor control algorithm development | | | | | | | | | | | | |
| Mini Robot World communication with a basic GUI | | | | | | | | | | | | |
| Developing a ROS firmware | | | | | | | | | | | | |
| Design of ROS environment | | | | | | | | | | | | |
| Calibration and testing | | | | | | | | | | | | |
| Development of sample algorithms | | | | | | | | | | | | |
| Preparation towards the project completion | | | | | | | | | | | | |
| Final Presentation | | | | | | | | | | | | |

Table-1: Gantt Chart of the Project