

# Supervised learning

Regression

↳ Output is infinite

Classification

↳ Output is discrete

## Terminology:

$x$  → input / feature

$y$  → output / target

$m$  → Total training examples

$(x^i, y^i) = i^{\text{th}}$  training example  
↳ specific row

Training set



Learning algorithm

new input ↓

↑  
 $x$

→  $f$

model

→  $\hat{y}$

(estimated  $y$ )

↑ target

How to represent  $f$ ?

$$f_{w,b}(x) = wx + b$$



one  $x$  only

linear regression with one variable / Univariate

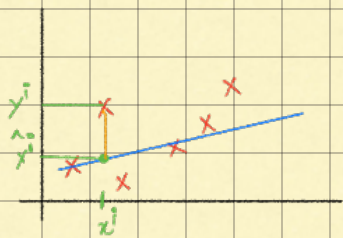
`np.array([x, y])` ⇒ numpy array

`f_wb = np.zeros(0)` → gives 1D array

Cost function:

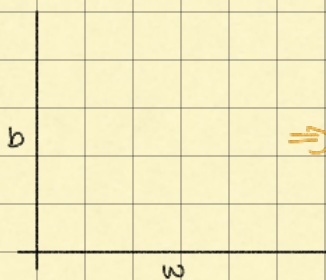
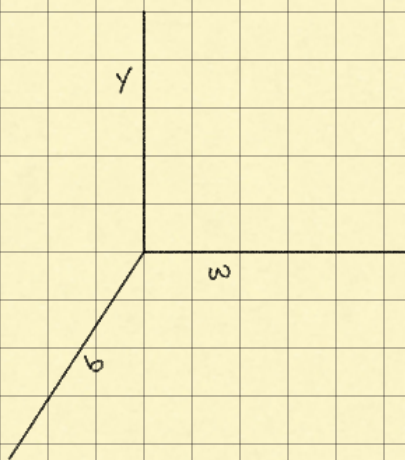
↳ Tells how well your model is doing

$w, b$  : parameters/coefficient

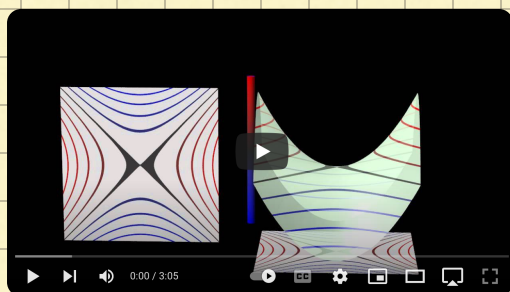


$$J(w, b) = \frac{1}{2m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})^2$$

$$J(w, b) = \frac{1}{2m} \sum_{i=1}^m (f_{w,b}(x^i) - y^i)^2$$



⇒ contours  
visual 3D in 2D

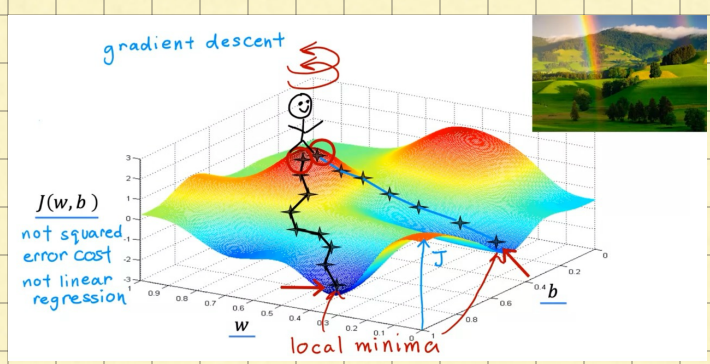


we choose the  $f(w, b)$  which corresponds to the lowest  $J(w, b)$  in the graph.



# Gradient descent:

- start with some  $w, b = 0$
- keep changing  $w, b$  to reduce  $J(w, b)$
- until we settle at or near minimum



mathematically,

$$w = w - \alpha \frac{\partial}{\partial w} J(w, b)$$

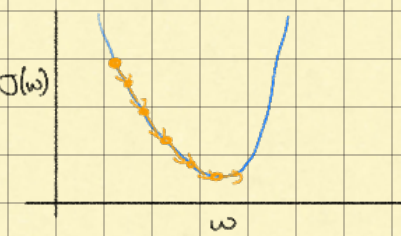
$$b = b - \alpha \frac{\partial}{\partial b} J(w, b)$$

$\alpha$  = learning rate (0-1)  $\rightarrow$  step length

change  $w$  &  $b$  till  $w$  &  $b$  don't change by muc after each computation.

## Learning Rate:

if  $\alpha$  is too small,



$\hookrightarrow$  may be slow

if  $\alpha$  is too large,



$\hookrightarrow$  may overshoot

$$\frac{\partial J(w, b)}{\partial w};$$

$$w = w - \alpha \frac{1}{m} \sum_{i=1}^m (f_{w, b}(x^i) - y^i) x^i$$

$$\frac{\partial J(w, b)}{\partial b};$$

$$b = b - \alpha \frac{1}{m} \sum_{i=1}^m (f_{w, b}(x^i) - y^i)$$