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## Purpose

The purpose of this rework was to modify Assignment 5 to use Station Mode on the Arduino Uno R4 WiFi board instead of Access Point mode. The objective was to enable full control and interaction from a mobile phone browser, allowing the user to access live sensor data and control onboard LEDs wirelessly via a Wi-Fi network.

## Methodology / Approach

In this version of the project, the Arduino connects to a Wi-Fi network in Station Mode and hosts a web server to serve dynamic interfaces. In Part A, the Arduino reads data from the GY-87 (IMU, barometer, magnetometer) and HC-SR04 ultrasonic sensor, then displays temperature, pressure, altitude, heading, and distance in a live HTML page accessed through a phone browser. In Part B, the Arduino serves a different HTML page with controls to toggle the blue LED on/off and a slider to adjust the brightness of the red LED via PWM. Both pages are responsive and controlled entirely through a mobile browser over the same Wi-Fi network, with all inputs processed using HTTP GET requests.

## Results

The wireless system was successful overall. Every action on the website interacted perfectly and quickly with the Arduino board.

## Appendix

Part A:

```
#include <WiFiS3.h>
#include <Wire.h>
#include <Adafruit_MPU6050.h>
#include <Adafruit_BMP085.h>
#include <QMC5883LCompass.h>

#define TRIG_PIN 10
#define ECHO_PIN 9

Adafruit_MPU6050 mpu;
Adafruit_BMP085 bmp;
QMC5883LCompass compass;
```

```
char ssid[] = "Abdullah Khalid";
char pass[] = "QSPS2992@is2992";

WiFiServer server(80);

void setup() {
  Serial.begin(9600);
  Wire.begin();
  mpu.begin();
  bmp.begin();
  compass.init();

  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);

  WiFi.begin(ssid, pass);
  while (WiFi.status() != WL_CONNECTED) {
    delay(1000);
    Serial.print(".");
  }

  Serial.println("\nWiFi connected!");
  Serial.print("IP: ");
  Serial.println(WiFi.localIP());

  server.begin();
}

void loop() {
  WiFiClient client = server.available();
  if (client) {
    String request = client.readStringUntil('\r');
    client.flush();

    String html = "<html><head><title>Sensor Data</title></head><body>";
    html += "<h1>Live Sensor Readings</h1>";
    html += getSensorData();
    html += "</body></html>";

    client.println("HTTP/1.1 200 OK");
    client.println("Content-Type: text/html");
    client.println();
    client.print(html);

    client.stop();
  }
}
```

```

String getSensorData() {
    sensors_event_t a, g, t;
    mpu.getEvent(&a, &g, &t);
    compass.read();
    float temp = bmp.readTemperature();
    float pressure = bmp.readPressure();
    float altitude = bmp.readAltitude();
    float distance = readDistanceCM();
    int heading = compass.getAzimuth();
    char dir[4]; compass.getDirection(dir, heading);

    String data = "";
    data += "Temperature: " + String(temp, 1) + " °C<br>";
    data += "Pressure: " + String(pressure / 100.0, 1) + " hPa<br>";
    data += "Altitude: " + String(altitude, 1) + " m<br>";
    data += "Distance: " + String(distance, 1) + " cm<br>";
    data += "Heading: " + String(heading) + "° (" + String(dir) + ")<br>";
    return data;
}

float readDistanceCM() {
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2);
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW);
    long duration = pulseIn(ECHO_PIN, HIGH);
    return duration * 0.0343 / 2;
}

```

Part B:

```

#include <WiFiS3.h>

const int redLED = 5;    // PWM capable
const int blueLED = 4;

char ssid[] = "Abdullah Khalid";
char pass[] = "QSPS2992@is2992";

WiFiServer server(80);

void setup() {
    Serial.begin(9600);
    pinMode(redLED, OUTPUT);
    pinMode(blueLED, OUTPUT);
}

```

```

WiFi.begin(ssid, pass);
while (WiFi.status() != WL_CONNECTED) {
    delay(1000);
    Serial.print(".");
}

Serial.println("\nWiFi connected!");
Serial.print("IP: ");
Serial.println(WiFi.localIP());

server.begin();
}

void loop() {
    WiFiClient client = server.available();
    if (client) {
        String request = client.readStringUntil('\r');
        client.flush();

        // Handle red LED brightness
        if (request.indexOf("red=") != -1) {
            int valIndex = request.indexOf("red=") + 4;
            int ampIndex = request.indexOf('&', valIndex);
            String valStr = (ampIndex == -1) ? request.substring(valIndex) :
request.substring(valIndex, ampIndex);
            int redValue = valStr.toInt();
            analogWrite(redLED, constrain(redValue, 0, 255));
        }

        // Handle blue LED ON/OFF
        if (request.indexOf("blue=on") != -1) digitalWrite(blueLED, HIGH);
        if (request.indexOf("blue=off") != -1) digitalWrite(blueLED, LOW);

        // HTML Response
        String html = "<html><head><title>LED Control</title></head><body>";
        html += "<h1>Control LEDs</h1>";

        // Red LED Slider
        html += "Red Brightness (0-255):<br>";
        html += "<form method='GET'>";
        html += "<input type='range' name='red' min='0' max='255' value='128'";
onchange='this.form.submit()'><br><br>";
        html += "</form>";

        // Blue LED buttons
        html += "<a href='/?blue=on'>Blue ON</a><br>";
        html += "<a href='/?blue=off'>Blue OFF</a><br>";
    }
}

```

```
html += "</body></html>";

client.println("HTTP/1.1 200 OK");
client.println("Content-Type: text/html");
client.println();
client.print(html);

client.stop();
}
```