

# Basic Instructions Addressing Modes

## Assembly Language Programming CS221

Dr. Hedia ZARDI

#### **Presentation Outline**

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

## Three Basic Types of Operands

- **Immediate**
- Constant integer (8, 16, or 32 bits)
- Constant value is stored within the instruction
- Register
- Name of a register is specified
- Register number is encoded within the instruction
- Memory
- Reference to a location in memory
- Memory address is encoded within the instruction, or
- Register holds the address of a memory location

Assembly Language Programming CS 221

## Instruction Operand Notation

Operand	Description
r8	8-bit general-purpose register: AH, AL, BH, BL, CH, CL, DH, DL
r16	16-bit general-purpose register: AX, BX, CX, DX, SI, DI, SP, BP
r32	32-bit general-purpose register: EAX, EBX, ECX, EDX, ESI, EDI, ESP, EBP
reg	Any general-purpose register
sreg	16-bit segment register: CS, DS, SS, ES, FS, GS
imm	8-, 16-, or 32-bit immediate value
imm8	8-bit immediate byte value
imm16	16-bit immediate word value
imm32	32-bit immediate doubleword value
r/m8	8-bit operand which can be an 8-bit general-purpose register or memory byte
r/m16	16-bit operand which can be a 16-bit general-purpose register or memory word
r/m32	32-bit operand which can be a 32-bit general register or memory doubleword
тет	8-, 16-, or 32-bit memory operand

## Next...

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

#### MOV Instruction

Move source operand to destination

```
mov destination, source
```

Source and destination operands can vary

```
mov req, req
mov mem, req
mov reg,
         mem
mov mem, imm
mov reg,
mov r/m16, sreq
mov sreq, r/m16
```

#### Rules

- Both operands must be of same size
- No memory to memory moves
- No immediate to segment moves
- No segment to segment moves
- Destination cannot be CS

Assembly Language Programming CS 221

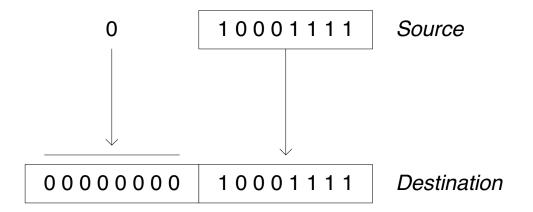
## MOV Examples

```
. DATA
  count BYTE 100
  bVal BYTE 20
  wVal WORD 2
  dVal DWORD 5
CODE
  mov bl, count ; bl = count = 100
  mov ax, wVal ; ax = wVal = 2
  mov count,al ; count = al = 2
  mov eax, dval ; eax = dval = 5
  ; Assembler will not accept the following moves - why?
  mov ds, 45
                  ; immediate move to DS not permitted
  mov esi, wVal
                  ; size mismatch
  mov eip, dVal
                  : EIP cannot be the destination
  mov 25, bVal
                  ; immediate value cannot be destination
  mov bVal, count
                  ; memory-to-memory move not permitted
```

#### **Zero Extension**

- MOVZX Instruction
- Fills (extends) the upper part of the destination with zeros
- Used to copy a small source into a larger destination
- Destination must be a register

```
movzx r32, r/m8
movzx r32, r/m16
movzx r16, r/m8
```

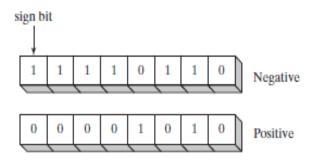


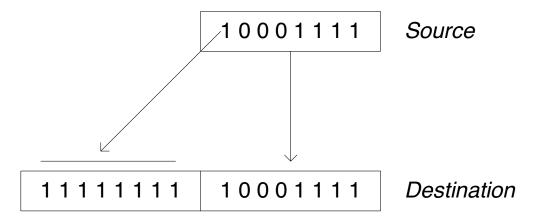
mov bl, 8Fh movzx ax, bl

## Sign Extension

- MOVSX Instruction
- Fills (extends) the upper part of the destination register with a copy of the source operand's sign bit
- Used to copy a small source into a larger destination

```
movsx r32, r/m8
movsx r32, r/m16
movsx r16, r/m8
```





mov bl, 8Fh movsx ax, bl

#### **XCHG** Instruction

XCHG exchanges the values of two operands

```
xchg reg, reg
xchg reg, mem
xchg mem, reg
```

#### Rules

Operands must be of the same size

At least one operand must be a register

No immediate operands are permitted

```
No immediate operands are var1 DWORD 10000000h

var2 DWORD 20000000h

.CODE

xchg ah, al ; exchange 8-bit regs
xchg ax, bx ; exchange 16-bit regs
xchg eax, ebx ; exchange 32-bit regs
xchg var1,ebx ; exchange mem, reg
xchg var1,var2 ; error: two memory
operands
```

## **Direct Memory Operands**

- Variable names are references to locations in memory
- Direct Memory Operand:
  - Named reference to a memory location
- Assembler computes address (offset) of named variable

```
.DATA

var1 BYTE 10h
.CODE

mov al, var1 ; AL = var1 = 10h
mov al, [var1] ; AL = var1 = 10h

Alternate Format
```

## Direct-Offset Operands

- Direct-Offset Operand: Constant offset is added to a named memory location to produce an effective address
- Assembler computes the effective address
- Lets you access memory locations that have no name

```
.DATA
arrayB BYTE 10h,20h,30h,40h
.CODE
mov al, arrayB+1 ; AL = 20h
mov al,[arrayB+1] ; alternative notation
mov al, arrayB[1] ; yet another notation
```

Q: Why doesn't arrayB+1 produce 11h?

#### Your Turn . . .

Given the following definition of arrayD.

DATA

arrayD DWORD 1,2,3

Rearrange the three values in the array as: 3, 1, 2

#### Solution:

```
; Copy first array value into EAX
mov eax, arrayD  ; EAX = 1
; Exchange EAX with second array element
xchg eax, arrayD[4]  ; EAX = 2, arrayD = 1,1,3
; Exchange EAX with third array element
xchg eax, arrayD[8]  ; EAX = 3, arrayD = 1,1,2
; Copy value in EAX to first array element
mov arrayD, eax  ; arrayD = 3,1,2
```

## Next...

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

#### ADD and SUB Instructions

- ADD destination, source destination = destination + source
- SUB destination, source destination = destination - source
- Destination can be a *register* or a *memory* location
- Source can be a *register*, *memory* location, or a *constant*
- Destination and source must be of the same size
- Memory-to-memory arithmetic is not allowed

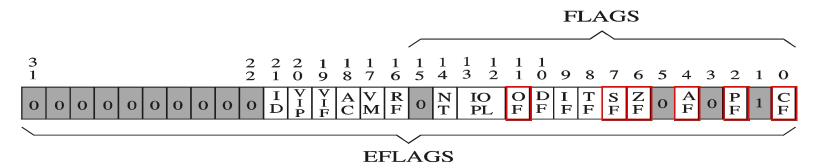
Assembly Language Programming CS 221

#### Evaluate this . . .

Write a program that adds the following three words:

```
. DATA
   array WORD 890Fh, 1276h, 0AF5Bh
Solution: Accumulate the sum in the AX register
  mov ax, array
   add ax, [array+2]
   add ax, [array+4]; what if sum cannot fit in
 AX?
Solution 2: Accumulate the sum in the EAX register
  movzx eax, array ; error to say: mov eax, array
   movzx ebx, array[2] ; use movsx for signed
 integers
   add eax, ebx ; error to say: add eax, array[2]
   movzx ebx, array[4]
   add
         eax, ebx
Basic Instructions & Addressing Modes
```

## Flags Affected



#### ADD and SUB affect all the six status flags:

- Carry Flag: Set when unsigned arithmetic result is out of range
- Overflow Flag: Set when signed arithmetic result is out of range
- Sign Flag: Copy of sign bit, set when result is negative
- Zero Flag: Set when result is zero
- Auxiliary Carry Flag: Set when there is a carry from bit 3 to bit
- Parity Flag: Set when parity in least-significant byte is even

## More on Carry and Overflow

- Addition: A + B
- The Carry flag is the carry out of the most significant bit
- The Overflow flag is only set when . . .
  - Two positive operands are added and their sum is negative
  - Two negative operands are added and their sum is positive
  - Overflow cannot occur when adding operands of opposite signs
- Subtraction: A B
- For Subtraction, the carry flag becomes the borrow flag
- Carry flag is set when A has a smaller unsigned value than B
- The Overflow flag is only set when . . .
  - A and B have different signs and sign of result ≠ sign of A
- Overflow cannot occur when subtracting operands of the same sign

## ADD and SUB Examples

For each of the following marked entries, show the values of the destination operand and the six status flags:

```
mov al, FFh
                 ; AL=-1
add al,1; AL=
                       00h
                            CF=
                                  OF=
                                         SF=
                                               ZF=
                                                     AF=
sub al,1
              ; AL = FFh
                             CF=
                                  OF=
                                         SF=
                                               ZF=
                                                     AF=
                                                           PF=
mov al,26h
sub al,95h
                 ; AL= 91h
                               CF = 1 OF = 1 SF = 1 ZF = 0 AF = 0 PF = 0
                            26h (38)
   0
      0
            0
               0
                        0
                           95h (-107)
      0
         0
               0
                     0
                     0
                           91h (-111)
      0
         0
               0
                  0
```

## INC, DEC, and NEG Instructions

- INC destination
- destination = destination + 1
- More compact (uses less space) than: ADD destination, 1
- **DEC** destination
- destination = destination 1
- More compact (uses less space) than: SUB destination, 1
- **NEG** destination
- destination = 2's complement of destination
- Destination can be 8-, 16-, or 32-bit operand
- In memory or a register
- NO immediate operand

Assembly Language Programming CS 221

## Next...

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

#### **MUL** Instruction

• The MUL (unsigned multiply) instruction multiplies an 8-, 16-, or 32-bit operand by either AL, AX, or EAX.

The instruction formats are:

MUL r/m8

MUL r/m16

MUL r/m32

Implied operands:

Multiplicand	Multiplier	Product
AL	r/m8	AX
AX	r/m16	DX:AX
EAX	r/m32	EDX:EAX

## MUL Examples

100h \* 2000h, using 16-bit operands:

```
data
                      val1 WORD 2000h
                       val2 WORD 100h
                                 . code
                          mov ax, val1
mul val2
             ; DX:AX = 00200000h, CF=1
```

The Carry flag indicates whether or not the upper half of product the significant contains digits.

```
12345h * 1000h, using 32-bit operands:
                                   mov eax, 12345h
                                     mov ebx,1000h
mul ebx
            ; EDX:EAX = 000000012345000h, CF=0
```

#### Your turn . . .

• What will be the hexadecimal values of DX, AX, and the Carry flag after the following instructions execute?

$$DX = 0012h$$
,  $AX = 3400h$ ,  $CF = 1$ 

#### Your turn . . .

 What will be the hexadecimal values of EDX, EAX, and the Carry flag after the following instructions execute?

EDX = 00000012h, EAX = 87650000h, CF = 1

#### **DIV** Instruction

- The DIV (unsigned divide) instruction performs 8-bit, 16-bit, and 32-bit division on unsigned integers
- A single operand is supplied (register or memory operand),
   which is assumed to be the divisor
- Instruction formats:

DIV r/m8

DIV r/m16
DIV r/m32

#### Default Operands:

Dividend	Divisor	Quotient	Remainder
AX	r/m8	AL	АН
DX:AX	r/m16	AX	DX
EDX:EAX	r/m32	EAX	EDX

## DIV Examples

Example 1: The following instructions perform 8-bit unsigned division (83h / 2), producing a quotient of 41h and a remainder of 1:

```
mov ax,0083h; dividend
mov bl,2; divisor
div bl; AL = 41h, AH = 01h
```

## DIV Examples

Example 2: Divide 8003h by 100h, using 16-bit operands:

```
Mov dx, 0
                 ; Clear high dividend,
     Mov ax, 8003h
                      ; low dividend,
           Mov cx, 100h
                           ; divisor
               ; Ax= 0080h, DX=0003
   Div cx
```

## DIV Examples

Example 3: The following instructions perform 32-bit unsigned division using a memory operand as the divisor:

```
.data
```

```
dividend QWORD 000000800300020h
divisor DWORD 00000100h
```

```
mov edx,DWORD PTR dividend; high doubleword
mov eax,DWORD PTR dividend; low doubleword
div divisor; EAX = 08003000h, EDX = 00000020h
```

## Implementing Arithmetic Expressions

- Some good reasons to learn how to implement expressions:
  - Learn how do compilers do it
  - Test your understanding of MUL and DIV
    - Check for overflow

## Implementing Arithmetic Expressions (1 of 2)

#### Example:

```
var4 = (var1 + var2) * var3
```

```
mov eax, var

add eax, var2

mul var3

jo TooBig ; check for overflow
mov var4, eax ; save product
```

## Implementing Arithmetic Expressions (2 of 2)

```
Example: eax = (-var1 * var2) + var3
                   mov eax, var1
                        neg eax
                       mul var2
                         TooBigeck for overflow
                   jo
     add eax, var3
Example: var4 = (var1 * 5) / (var2 - 3)
                eax, var1
                                           left side
     mov
     mov
                   ebx,5
                                  EDX:EAX = product
     m11 1
                     ebx
                2ebx, var
                                          right side
     mov
                   ebx,3
     sub
                                     final division
     div
                     ebx
               Var4, eax
     mov
```

## Next...

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

## Addressing Modes

- **Two Basic Questions**
- Where are the operands?
- How memory addresses are computed?
- Intel IA-32 supports 3 fundamental addressing modes
- Register addressing: operand is in a register
- Immediate addressing: operand is stored in the instruction itself
- Memory addressing: operand is in memory
- Memory Addressing
- Variety of addressing modes
- Direct and indirect addressing
- Support high-level language constructs and data structures

## Register and Immediate Addressing

- Register Addressing
- Most efficient way of specifying an operand: no memory access
- Shorter Instructions: fewer bits are needed to specify register
- Compilers use registers to optimize code
- Immediate Addressing
- Used to specify a constant
- Immediate constant is part of the instruction
- Efficient: no separate operand fetch is needed
- Examples

# Direct Memory Addressing

- Used to address simple variables in memory
- Variables are defined in the data section of the program
- We use the variable name (label) to address memory directly
- Assembler computes the offset of a variable
  - The variable offset is specified directly as part of the instruction
- Example
  - .data

```
var1 DWORD 100
var2 DWORD 200
sum DWORD ?
```

.code

```
mov eax, var1
add eax, var2
mov sum, eax
```

var1, var2, and sum are direct memory operands

## Register Indirect Addressing

- Problem with Direct Memory Addressing
- Causes problems in addressing arrays and data structures
- Does not facilitate using a loop to traverse an array
- Indirect memory addressing solves this problem
- Register Indirect Addressing
- The memory address is stored in a register
- Brackets [] used to surround the register holding the address
- For 32-bit addressing, any 32-bit register can be used
- Example

EBX contains the address of the operand on the operand of the oper

## Array Sum Example

Indirect addressing is ideal for traversing an array

```
.data
  array DWORD 10000h,20000h,30000h
. code
  mov esi, OFFSET array ; esi = array address
  mov eax, [esi] ; eax = [array] = 10000h
  add esi,4 ; why 4?
  add eax, [esi] ; eax = eax + [array+4]
  add esi,4 ; why 4?
  add eax,[esi] ; eax = eax + [array+8]
```

- Note that ESI register is used as a pointer to array
- ESI must be incremented by 4 to access the next array element

Assembly Language Programming CS 221

Because each array element is 4 bytes (DWORD) in memory

## Ambiguous Indirect Operands

Consider the following instructions:

inc DWORD PTR EDI1

```
mov [EBX], 100
add [ESI], 20
inc [EDI]
   Where EBX, ESI, and EDI contain memory addresses
   The size of the memory operand is not clear to the assembler
      EBX, ESI, and EDI can be pointers to BYTE, WORD, or DWORD
Solution: use PTR operator to clarify the operand size
mov BYTE PTR [EBX], 100; BYTE operand in
memory
add WORD PTR [ESI], 20 ; WORD operand in
memory
```

### Indexed Addressing

- Combines a displacement (name±constant) with an index register
- Assembler converts displacement into a constant offset
- Constant offset is added to register to form an effective address
- Syntax: [disp + index] or disp [index]

```
.data
   array DWORD 10000h,20000h,30000h
.code
   mov esi, 0  ; esi = array index
   mov eax,array[esi]  ; eax = array[0] = 10000h
   add esi,4
   add eax,array[esi]  ; eax = eax + array[4]
   add esi,4
   a
```

### **Index Scaling**

- Useful to index array elements of size 2, 4, and 8 bytes
- Syntax: [disp + index \* scale] or disp [index \* scale]
- Effective address is computed as follows:
- Disp.'s offset + Index register \* Scale factor

```
.DATA
  arrayB BYTE 10h,20h,30h,40h
  arrayW WORD 100h, 200h, 300h, 400h
  arrayD DWORD 10000h,20000h,30000h,40000h
CODE
  mov esi, 2
  mov al, arrayB[esi]; AL = 30h
  mov ax, arrayW[esi*2] ; AX
                                 = 300h
  mov eax, arrayD[esi*4]; EAX = 30000h
```

Assembly Language Programming CS 221

## Based Addressing

- Syntax: [Base + disp.]
- Effective Address = Base register + Constant Offset
- Useful to access fields of a structure or an object
- ▶ Base Register □ points to the base address of the structure
- Constant Offset 

  | relative offset within the structure

```
mystruct is a structure
.DATA
                                     consisting of 3 fields: a
                        12
                 WORD
   mystruct
       DWORD 1985
                                      word, a double word,
       BYTE
               ' M '
                                          and a byte
. CODE
   mov ebx, OFFSET mystruct
   mov eax, [ebx+2]
                          ; EAX =
                                   1985
   mov al, [ebx+6]
                          ; AL
                                   ' M '
```

#### LEA Instruction

LEA = Load Effective Address

```
LEA r32, mem (Flat-Memory)
```

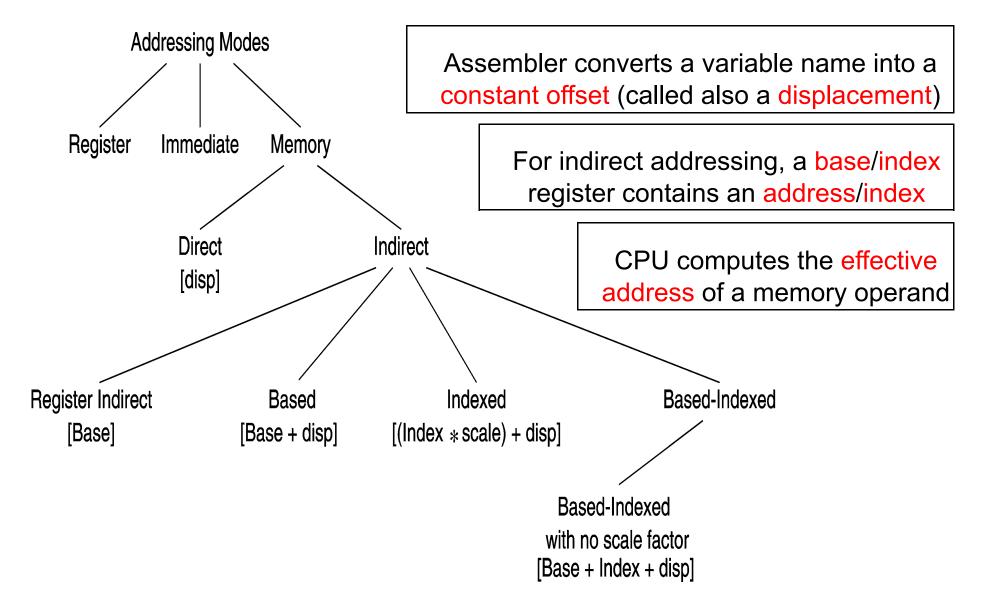
LEA r16, mem (Real-Address Mode)

- Calculate and load the effective address of a memory operand
- Flat memory uses 32-bit effective addresses
  - Real-address mode uses 16-bit effective addresses
- LEA is similar to MOV ... OFFSET, except that:
- OFFSET operator is executed by the assembler
  - Used with named variables: address is known to the assembler
- LEA instruction computes effective address at runtime
- Used with indirect operands: effective address is known at runtime

### LEA Examples

```
Nb of elements
data
  array WORD 1000 DUP(?)
                          ?= default value: 0
           Duplicate
. code
       ; <del>Equivarent</del> to .
 lea eax, array[esi] ; mov eax, esi
    ; add eax, OFFSET array
 ; add eax, eax
    ; add eax, OFFSET array
 lea eax, [ebx+esi*2] ; mov eax, esi
    ; add eax, eax
    ; add eax, ebx
```

# Summary of Addressing Modes



#### Next...

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

#### JMP Instruction

- JMP is an unconditional jump to a destination instruction
- Syntax: JMP destination
- JMP causes the modification of the EIP register *EIP* □ *destination address*
- A label is used to identify the destination address
- Example:

```
top:
```

- JMP provides an easy way to create a loop
- Loop will continue endlessly unless we find a way to terminate it

Assembly Language Programming CS 221

#### LOOP Instruction

- The LOOP instruction creates a counting loop
- Syntax: LOOP destination
- Logic: ECX ∏ ECX 1 if ECX != 0, jump to destination label
- ECX register is used as a counter to count the iterations
- Example: calculate the sum of integers from 1 to 100

```
eax, 0; sum
  mov
  mov ecx, 100 ; count = ecx
L1:
      eax, ecx ; accumulate sum in eax
  add
             ; decrement ecx until 0
  loop L1
```

Assembly Language Programming CS 221

#### Your turn . . .

What will be the final value of EAX?

Solution: 10

What will be the final value of EAX?

Solution: same value 1

mov eax,1
mov ecx,0
L2:
dec eax
loop L2

### Nested Loop

If you need to code a loop within a loop, you must save the outer loop counter's ECX value

```
. DATA
  count DWORD ?
. CODE
  mov ecx, 100 ; set outer loop count to 100
L1:
  mov count, ecx ; save outer loop count
  mov ecx, 20 ; set inner loop count to 20
L2: .
  mov ecx, count ; restore outer loop count
```

#### Next...

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

# Copying a String

The following code copies a string from source to target

```
. DATA
   source BYTE "This is the source string", 0
   target BYTE SIZEOF source DUP(0)
. CODE
                 Good use of SIZEOF
main PROC
   mov esi,0
                  ; index register
   mov ecx, SIZEOF source ; loop counter
L1:
   mov al,source[esi] ; get char from source
   mov target[esi],al ; store it in the target
                ; increment index
   inc esi
                 loop for entire string
ESI is used to
   loop L1
   exit
                 index source &
main ENDP
                  target strings
END main
```

#### Next...

- Operand Types
- Data Transfer Instructions
- Addition and Subtraction
- Multiplication and division
- Addressing Modes
- Jump and Loop Instructions
- Copying a String
- Summing an Array of Integers

## Summing an Integer Array

This program calculates the sum of an array of 16-bit integers

```
. DATA
intarray WORD 100h, 200h, 300h, 400h, 500h, 600h
. CODE
main PROC
  mov ecx, LENGTHOF intarray ; loop counter
  mov ax, 0; zero the accumulator
L1:
   add ax, [esi] ; accumulate sum in ax
               ; point to next integer
            ; \repeat until ecx = 0
  loop L1
  exit
                esi is used as a pointer
main ENDP
END main
          contains the address of an array element
```

## Summing an Integer Array – cont'd

This program calculates the sum of an array of 32-bit integers

```
. DATA
intarray DWORD 10000h,20000h,30000h,40000h,50000h,60000h
. CODE
main PROC
  mov esi, 0 ; index of intarray
   mov ecx, LENGTHOF intarray ; loop counter
  mov eax, 0 ; zero the accumulator
L1:
   add eax, intarray[esi*4] ; accumulate sum in eax
   inc esi ; increment index
  exit
main ENDP
                  esi is used as a scaled index
END main
```

### Summary

- Data Transfer
- MOV, MOVSX, MOVZX, and XCHG instructions
- **Arithmetic**
- ADD, SUB, INC, DEC, NEG, ADC, SBB, STC, and CLC
- Carry, Overflow, Sign, Zero, Auxiliary and Parity flags
- Mul, div
- Addressing Modes
- Register, immediate, direct, indirect, indexed, based-indexed
- Load Effective Address (LEA) instruction
- JMP and LOOP Instructions
- Traversing and summing arrays, copying strings

Assembly Language Programming CS 221