

# Data Structures and Algorithms

## Chapter 5 Sorting Advance Sort

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# Divide and Conquer Sorting Strategy

Merge Sort

Quick Sort

# Divide and Conquer Sorting Strategy

- **Divide**
  - Break into sub-problems that are themselves **smaller instances** of the **same type** of problem
  - **Recursively solving** this problem
- **Conquer** (overcome)
  - The **solution to the original problem** is then formed from the **solutions to the sub-problems**.

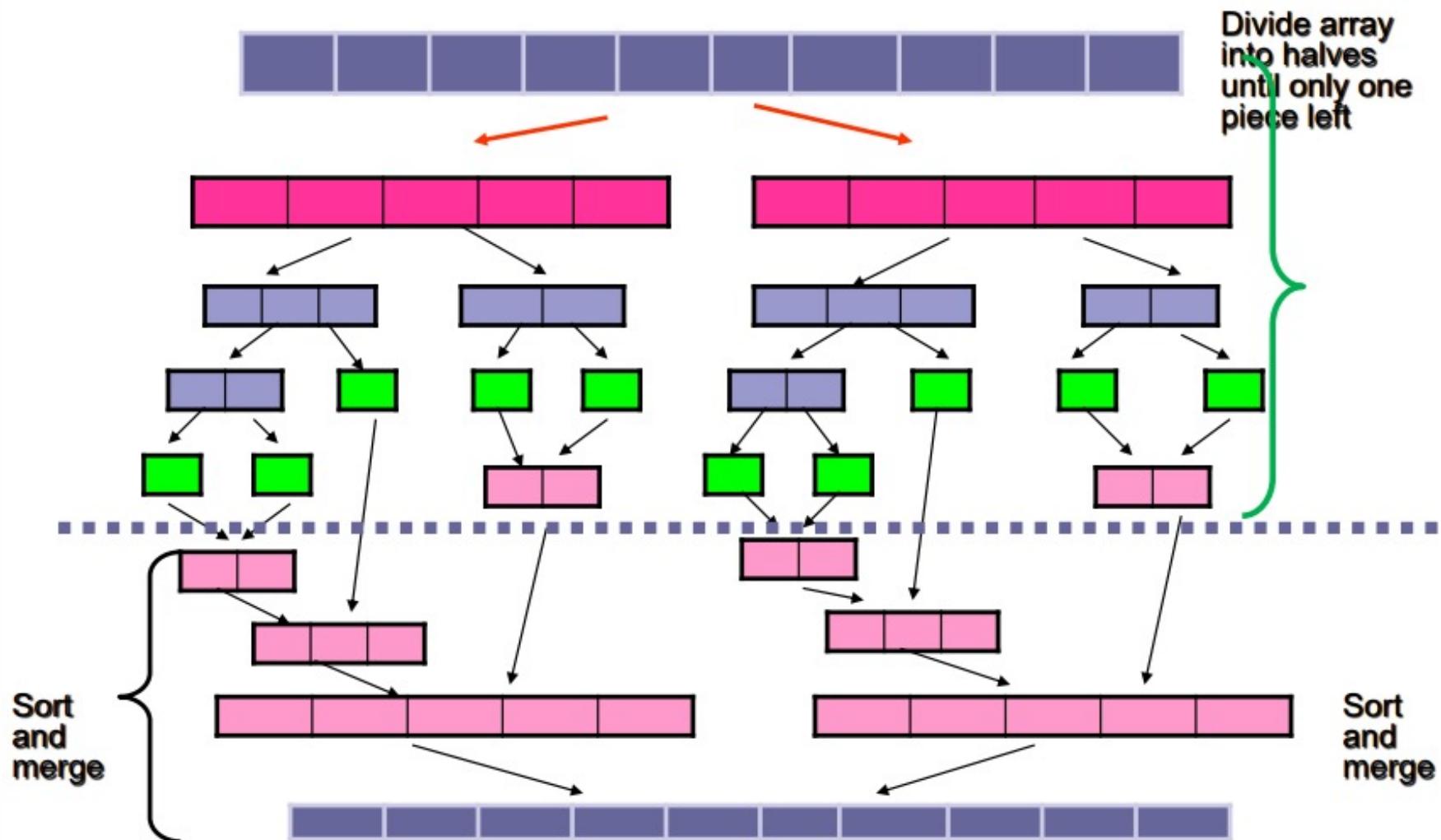
# Merge Sort

6 5 3 1 8 7 2 4

# Merge Sort

- Applies **divide and conquer** strategy.
- **Three main steps** in Merge Sort algorithm:
  - **Divide an array into halves**
  - **Sort each half**
  - **Merge the sorted halves into one sorted array**
- A **recursive** sorting algorithm
- Performance is **independent of the initial order** of the array items

# Merge Sort Operation



# Merge Sort Implementation

Need 2 functions

- **MergeSort()** function
  - A **Recursive** function that **divide the array** into pieces until **each piece contain only one item**.
  - The **small pieces** is merge into **larger sorted pieces** until one **sorted array** is achieved.
- **Merge()** function
  - **Compares an item into one half** of the array with **item in the other half** of the array and **moves the smaller item into temporary array**. Then, the **remaining items** are **simply moved to the temporary array**. The **temporary array** is **copied back into the original array**.

# Merge Sort Operation

theArray: 

Divide the array in half

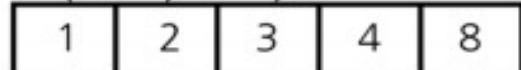


Sort the halves

Temporary array  
tempArray:

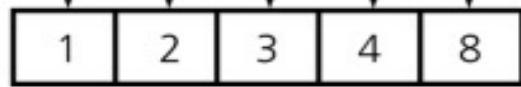
Merge the halves:

- 1 < 2, so move 1 from left half to tempArray
- 4 > 2, so move 2 from right half to tempArray
- 4 > 3, so move 3 from right half to tempArray
- Right half is finished, so move rest of left half to tempArray



theArray:

Copy temporary array back into original array



**Note: A merge sort with an auxiliary temporary array**

# mergeSort() function

```
void mergeSort(DataType theArray[], int first, int last)
{
    if (first < last)
    {
        // sort each half
        int mid = (first + last)/2; // index of midpoint

        // sort left half theArray[first..mid]
        mergesort(theArray, first, mid);

        // sort right half theArray[mid+1..last]
        mergesort(theArray, mid+1, last);

        // merge the two halves
        merge(theArray, first, mid, last);
    } // end if
} // end mergesort
```

while both sub-arrays are not empty, copy the smaller item into the temporary array

Move remaining item to temporary array and finish off the second sub-array, if necessary

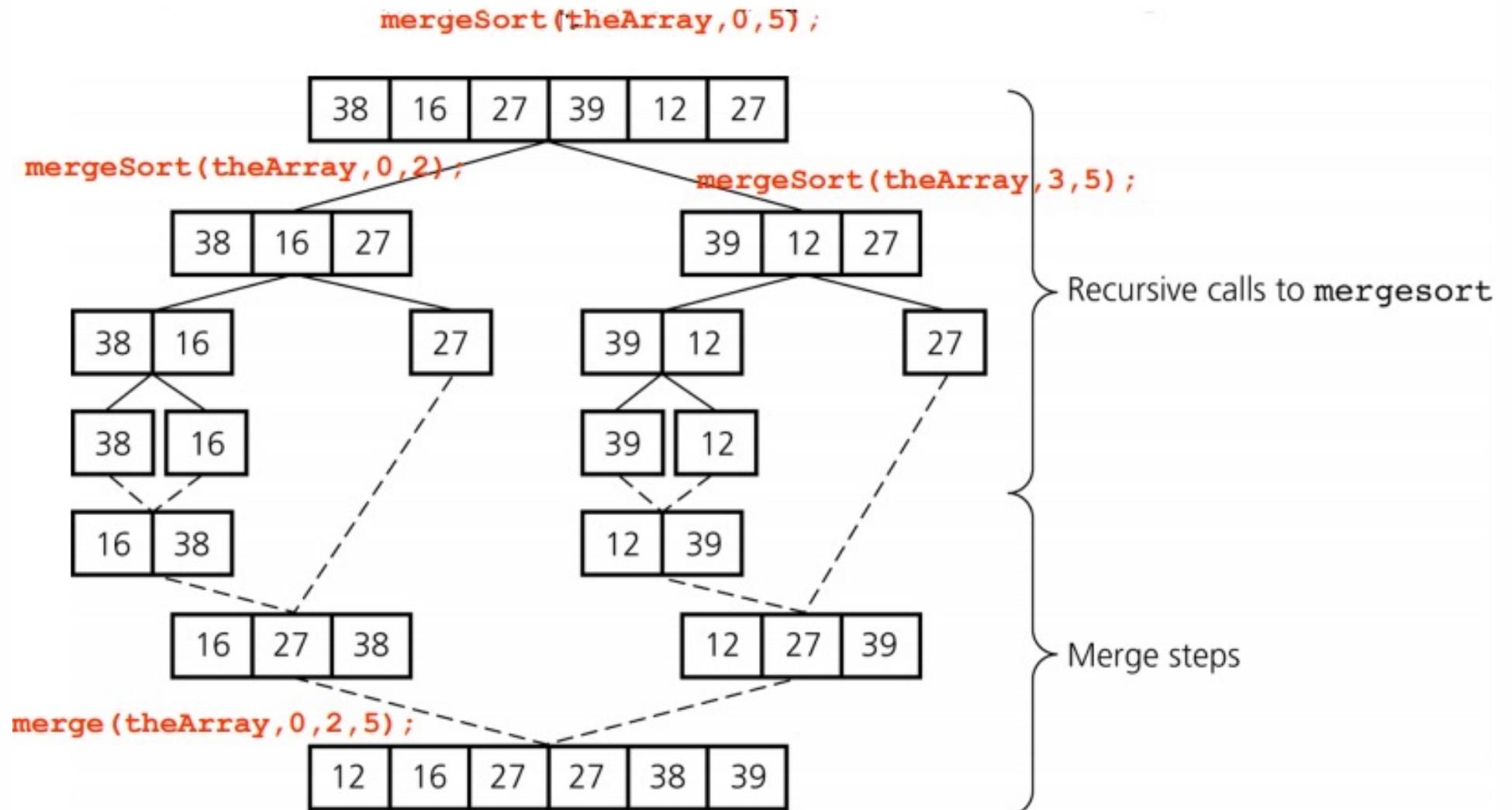
copy the result from temporary array into the original array

# merge() function

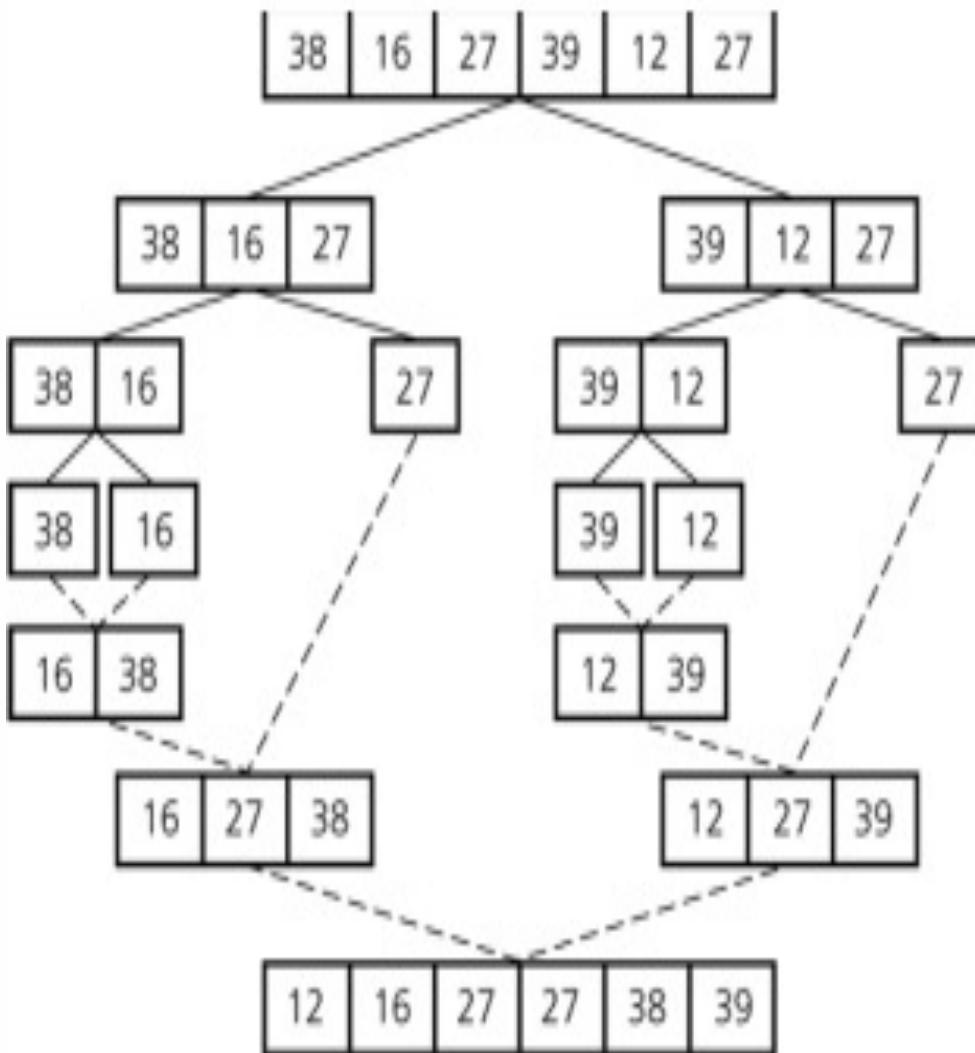
```
const int MAX_SIZE = maxNmbrItemInArry;
void merge(DataType theArray[], int first, int mid, int last)
{
    DataType tempArray[MAX_SIZE]; // temp array
    int first1 = first; // first subarray begin
    int last1 = mid; // end of first subarray
    int first2 = mid + 1; // secnd subarry begin
    int last2 = last; // end of secnd subarry
    int index = first1;

    // next available location in tempArray
    for (; (first1 <= last1) && (first2 <= last2); ++index)
    {
        if (theArray[first1] < theArray[first2])
        {
            tempArray[index] = theArray[first1];
            ++first1;
        }
        else
        {
            tempArray[index] = theArray[first2];
            ++first2;
        }
    } // end for
    for (; first1 <= last1; ++first1, ++index)
        tempArray[index] = theArray[first1];
    for (; first2 <= last2; ++first2, ++index)
        tempArray[index] = theArray[first2];
    // copy the result back into the original array
    for (index = first; index <= last; ++index)
        theArray[index] = tempArray[index];
} // end merge function
```

## mergeSort [38 16 27 39 12 27]



## mergeSort [38 16 27 39 12 27] (continued...)



Content of the array before sorting : 38 16 27 39 12 27  
 Content of sublist 1 -> 38 16 27 39 12 27  
 Content of sublist 2 -> 38 16 27  
 Content of sublist 3 -> 38 16  
 Content of sublist 4 -> 38  
 Content of sublist 5 -> 16  
 Content of merged list 16 38  
 Content of sublist 6 -> 27  
 Content of merged list 16 27 38  
 Content of sublist 7 -> 39 12 27  
 Content of sublist 8 -> 39 12  
 Content of sublist 9 -> 39  
 Content of sublist 10 -> 12  
 Content of merged list 12 39  
 Content of sublist 11 -> 27  
 Content of merged list 12 27 39  
 Content of merged list 12 16 27 27 38 39  
 Content of the array after sorting : 12 16 27 27 38 39

Result AFTER execution

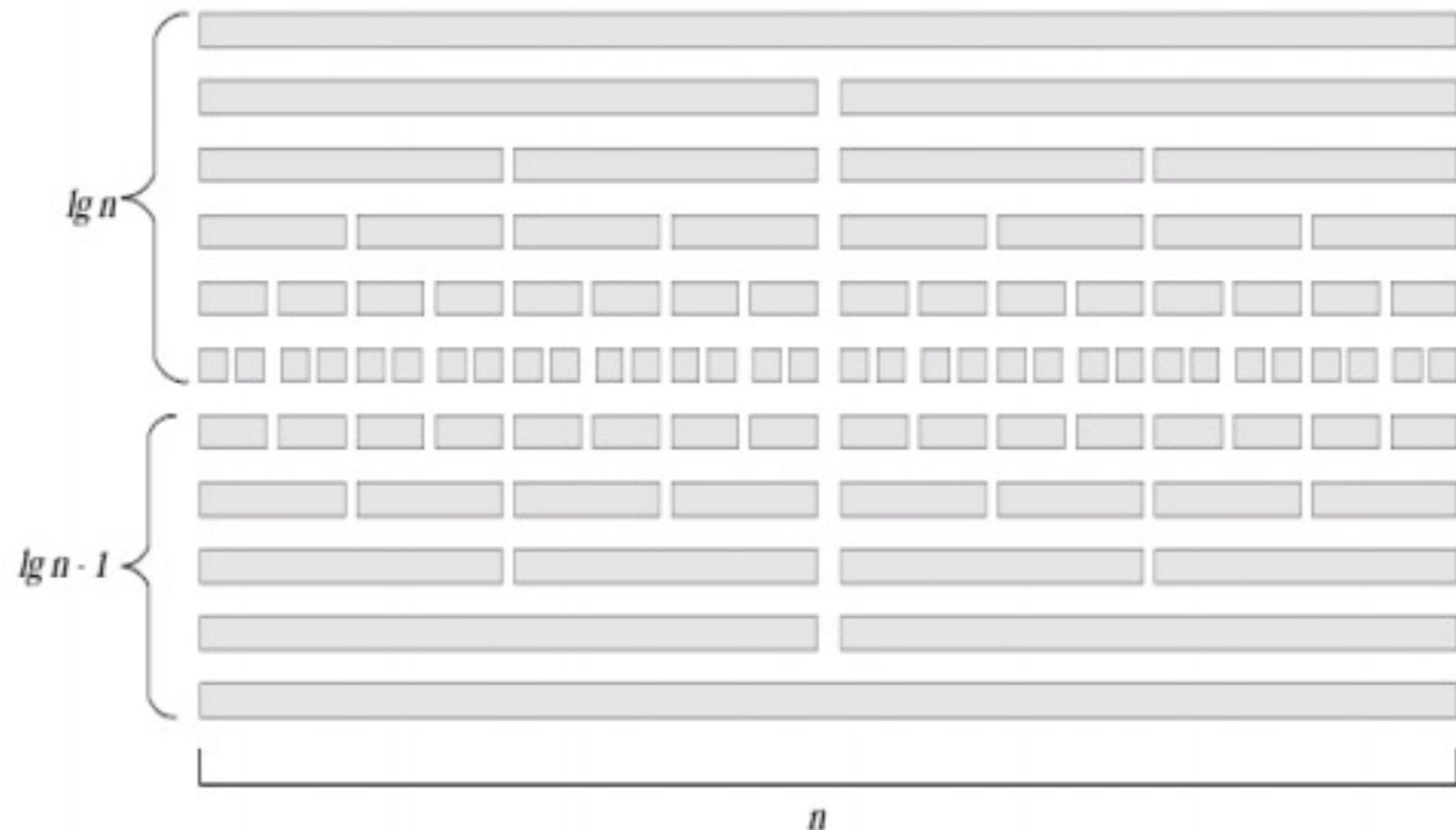
## Merge Sort Analysis

- The list is always divided into two balanced list (or almost balanced for odd size of list)
- The number of calls to repeatedly divide the list until there is one item left in the list is:

$$n + 2 \frac{n}{2} + 4 \frac{n}{4} + 8 \frac{n}{8} + 16 \frac{n}{16} + \dots x \frac{n}{x}$$

- If the **left** segment and the **right** segment of the list have the equal size (or **almost equal** size), then  $x \approx \lg n$ . The **number of iteration** is approximately  $n \lg n$ .
- **The same number of repetition is needed to sort and merge the list.**
- **Thus, as a whole number of steps needed to sort data using merge sort is  $2n \lg n$ , which is  $O(n \lg n)$ .**

## Merge Sort Analysis (continued...)



# Mergesort

- **Analysis**
  - **Worst case:**  $O(n * \log_2 n)$
  - **Average case:**  $O(n * \log_2 n)$ 
    - Performance is independent of the **initial order** of the array items
- **Advantage**
  - Mergesort is an extremely **fast** algorithm
- **Disadvantage**
  - Mergesort requires a second array (**temporary array**) **as large as the original array**

# Quick Sort

6 5 3 1 8 7 2 4

# Quick Sort Operation

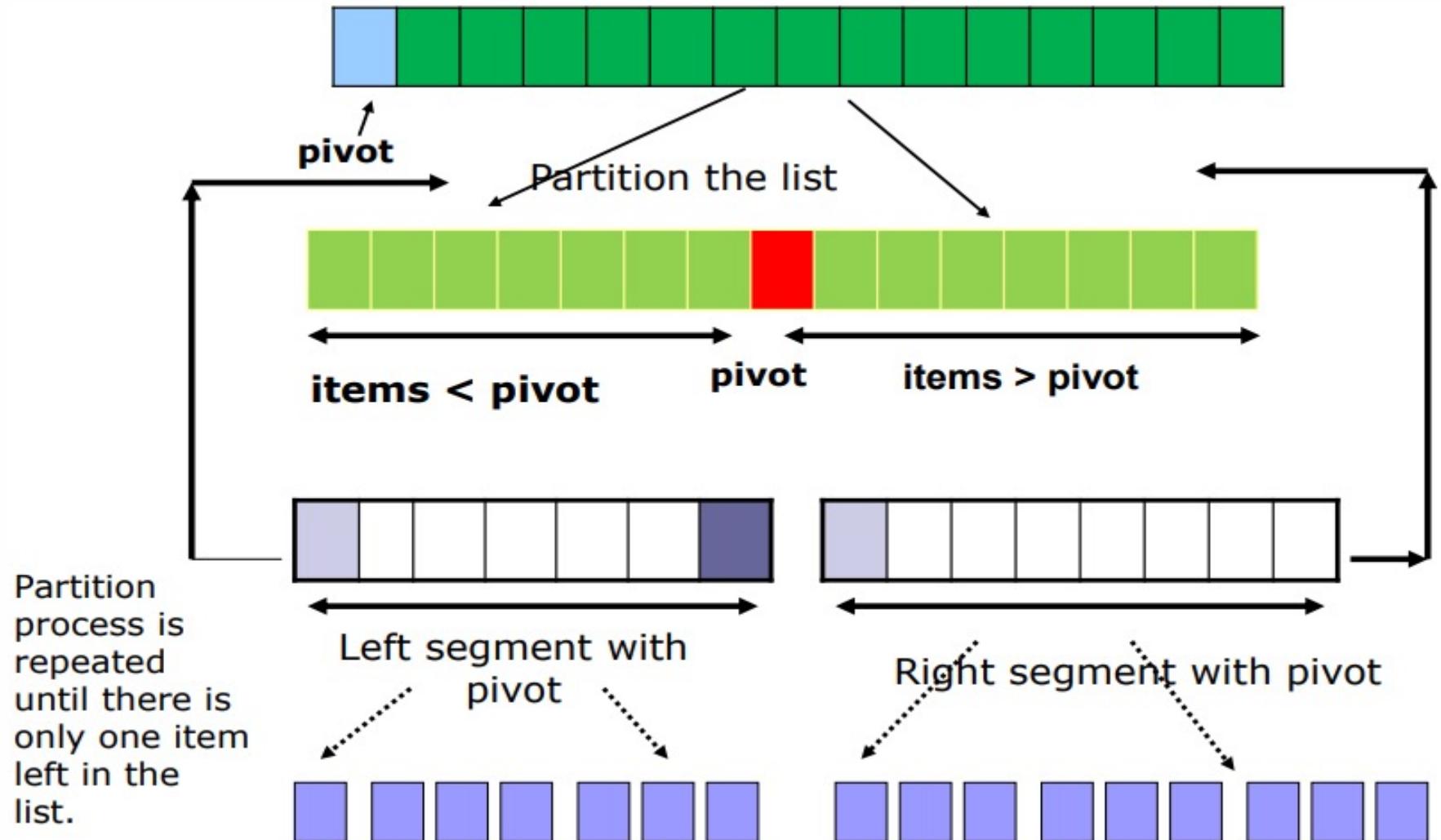
- Quick sort is similar with merge sort in using divide and conquer technique.
- Differences of Quick sort and Merge sort :

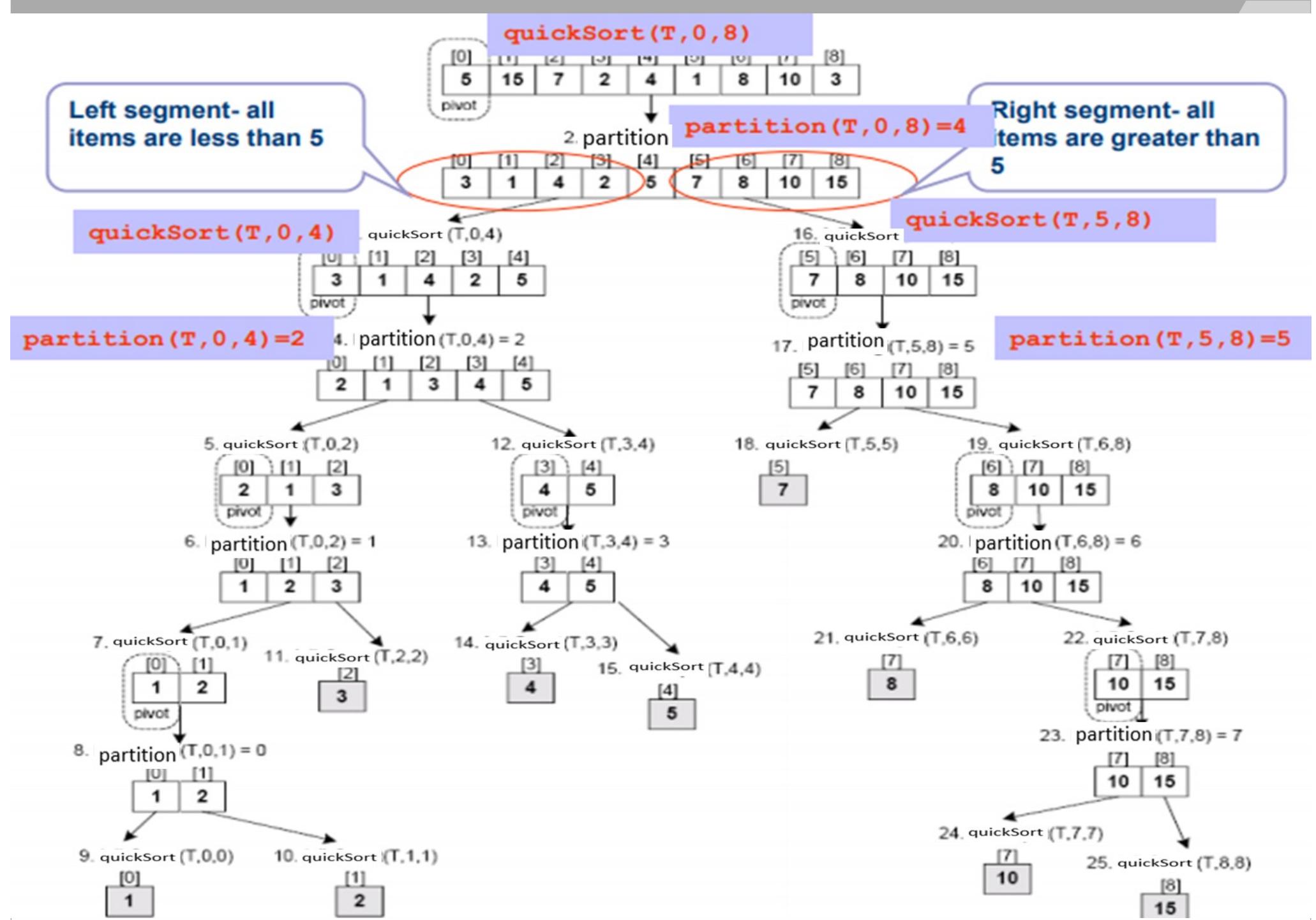
Quick Sort	Merge Sort
Partition the list based on the <b>pivot</b> value	Partition the list by <b>dividing the list into two</b>
<b>No merge operation</b> is needed since when there is only <b>one item left in the list to be sorted</b> , all other items are <b>already in sorted position</b> .	<b>Merge operation</b> is needed to <b>sort and merge</b> the item in the <b>left and right segments</b> .

# Quick Sort

- A divide-and-conquer algorithm
- Strategy
  - Choose a **pivot (first element in the array)**
  - Partition the array about the pivot
    - **items < pivot**
    - **items >= pivot**
    - **Pivot is now in correct sorted position**
  - Sort the left section again until there is one item left
  - Sort the right section again until there is one item left

## Quick Sort Process





# Quick Sort Implementation

2 functions are needed :

- **quickSort() function**

- a **recursive** function that will **partition** the list into several sub lists **until there is one item left** in the sub list.

- **partition() function**

- **organize** the data so that the **items with values less than pivot will be on the left of the pivot**, while the **values at the right pivot contains items that are greater or equal to pivot**.

```
void quickSort(dataType arrayT[], int first , int last)
{
    int cut;
    if (first < last)
    {
        cut = partition(T, first, last);
        quickSort(T, first, cut);
        quickSort(T, cut+1, last);
    }
}
```

# partition() function

```

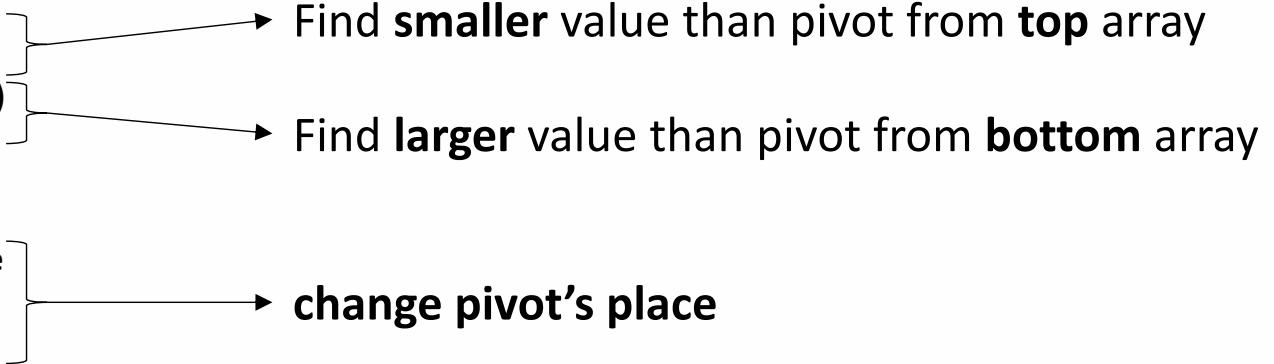
int partition(int T[], int first, int last)
{
  int pivot, temp;
  int loop, cutPoint, bottom, top;
  pivot=T[first]; // identify pivot
  bottom=first; top= last;
  loop=1; //always TRUE

  while (loop)
  {
    while (T[top]>pivot)
    { top--; }

    while(T[bottom]<pivot)
    { bottom++; }

    if (bottom<top)
    {
      // change pivot place
      temp=T[bottom];
      T[bottom]=T[top];
      T[top]=temp;
    }
    else
    {
      loop=0; //loop false
      cutPoint = top;
    }
  } // end while
  return cutPoint;
} // end partition()
    
```

Organize the data so that the items with values **less than pivot** will be on the **left** of the pivot while the values at the **right** of pivot, pivot contains items that are **greater or equal to pivot**.

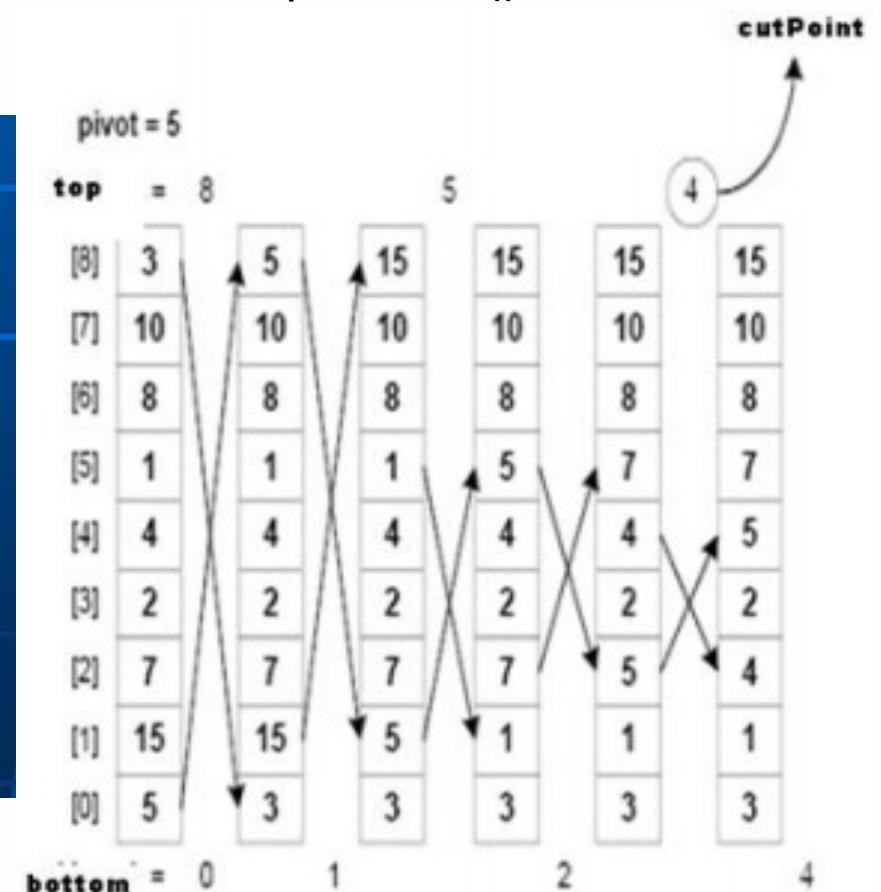

 Find **smaller** value than pivot from **top** array  
 Find **larger** value than pivot from **bottom** array  
 change pivot's place

## Partition process for array: [5 15 7 2 4 1 8 10 3]

After execution of function partition(), **pivot 5** will be placed at **index 4** and the **value 4**, will be returned to function quickSort() for further partition.

```

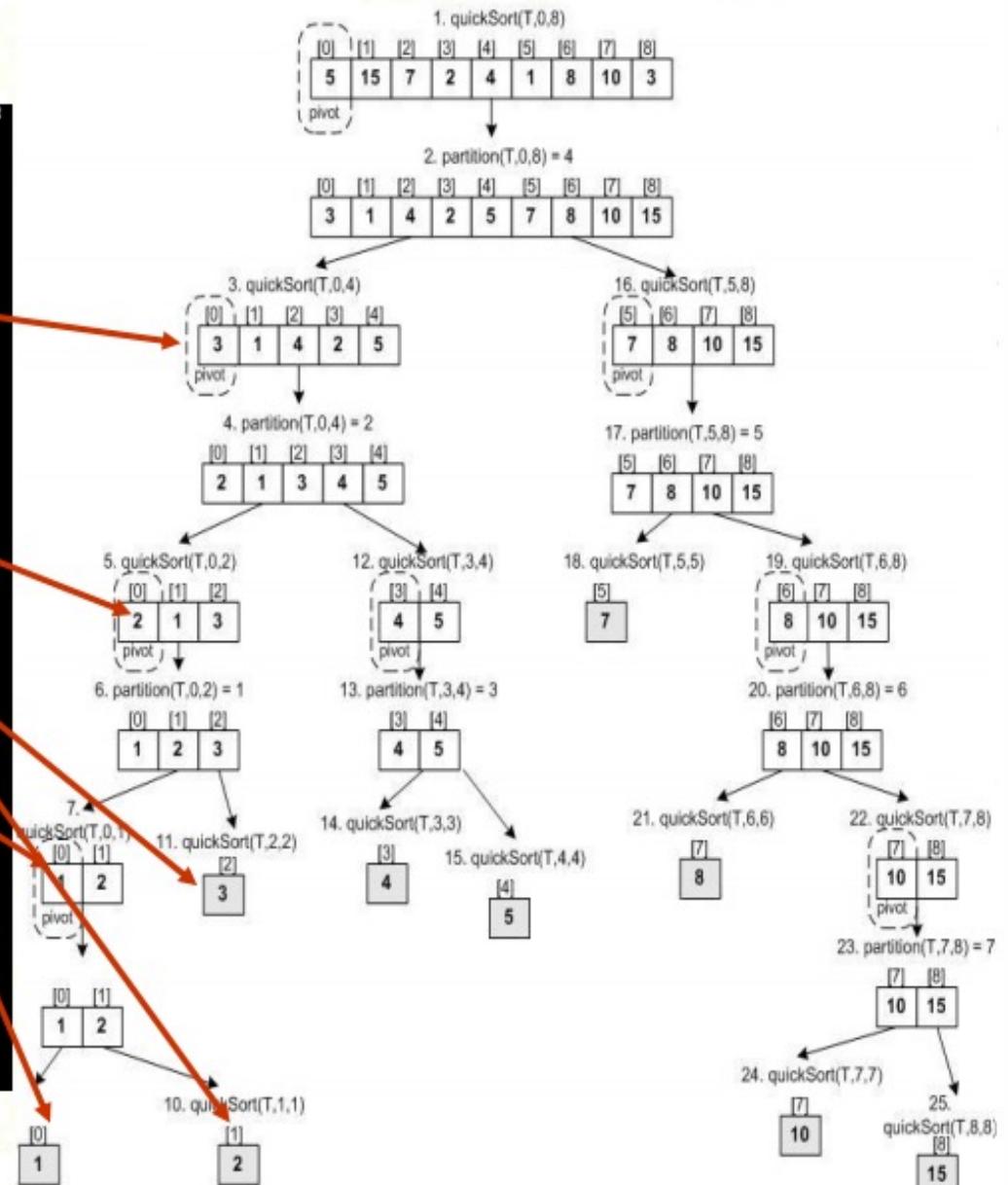
Content of the array before sorting :5 15 7 2 4 1 8 10 3
The sublist with pivot = 5
5 15 7 2 4 1 8 10 3
The sublist with pivot = 3
3 1 4 2 5
The sublist with pivot = 2
2 1 3
The sublist with pivot = 1
1 2
The sublist with pivot = 4
4 5
The sublist with pivot = 7
2 8 10 15
The sublist with pivot = 8
8 10 15
The sublist with pivot = 10
10 15
Content of the array after sorting : 1 2 3 4 5 7 8 10 15 -
  
```



# quickSort[5 15 7 2 4 1 8 10 3]

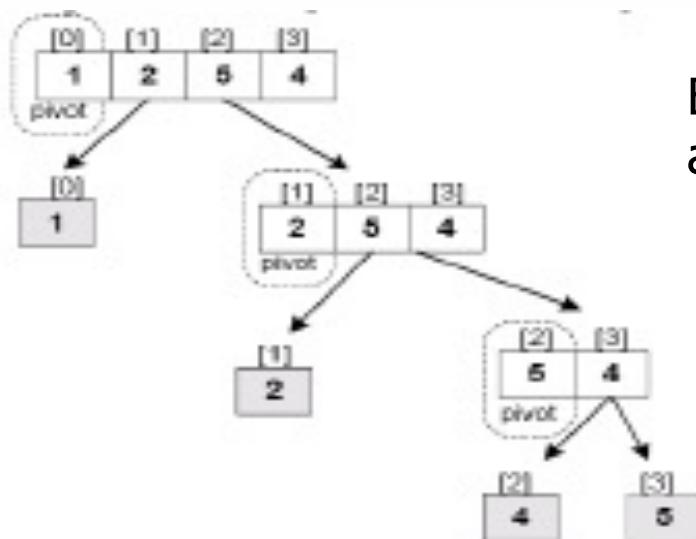
```

Content of the array before sorting :5 15 7 2 4 1 8
The sublist -> 1 with pivot = 5
5 15 7 2 4 1 8 10 3
The sublist -> 2 with pivot = 3
3 1 4 2 5
The sublist -> 3 with pivot = 2
2 1 3
The sublist -> 4 with pivot = 1
1 2
The sublist -> 5 with one piece item = 1
The sublist -> 6 with one piece item = 2
The sublist -> 7 with one piece item = 3
The sublist -> 8 with pivot = 4
4 5
The sublist -> 9 with one piece item = 4
The sublist -> 10 with one piece item = 5
The sublist -> 11 with pivot = 7
7 8 10 15
The sublist -> 12 with one piece item = 7
The sublist -> 13 with pivot = 8
8 10 15
The sublist -> 14 with one piece item = 8
The sublist -> 15 with pivot = 10
10 15
The sublist -> 16 with one piece item = 10
The sublist -> 17 with one piece item = 15
  
```



# Quick Sort Analysis

- The **efficiency** of quick sort depends on the **pivot** value.
- This class chose the **first element in the array** as pivot value.
- However, pivot can also be chosen at **random**, or from the **last element** in the array.
- The **worse case** for quick sort occur when the **smallest item or the largest item always be chosen as pivot** value causing the left partition and the right partition **not balance**.

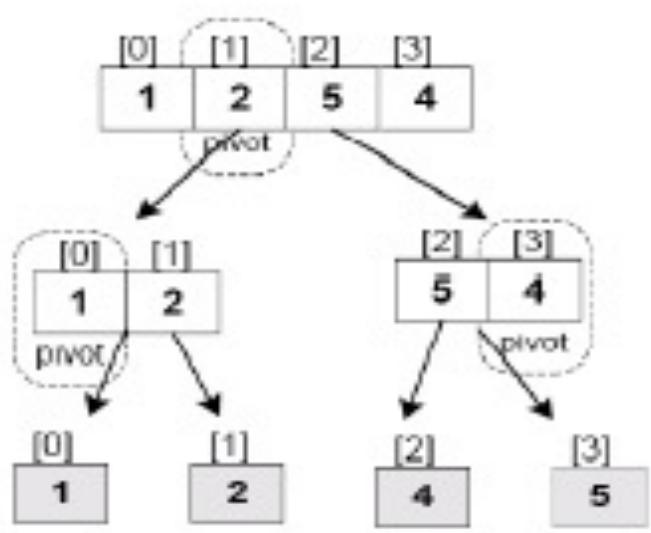


Example of worse case quick sort: sorted array [1 2 5 4] causing imbalance partition.

## Quick Sort Analysis (continued...)

- The **best case** for quick sort happen when the list is partition into **balance** segment.
- Must chose the right pivot that can put other items in balance situation.
- The number of comparisons in partition process for base case situation is as follows:

$$n + 2 \frac{n}{2} + 4 \frac{n}{4} + 8 \frac{n}{8} + 16 \frac{n}{16} + \dots + x \frac{n}{x}$$

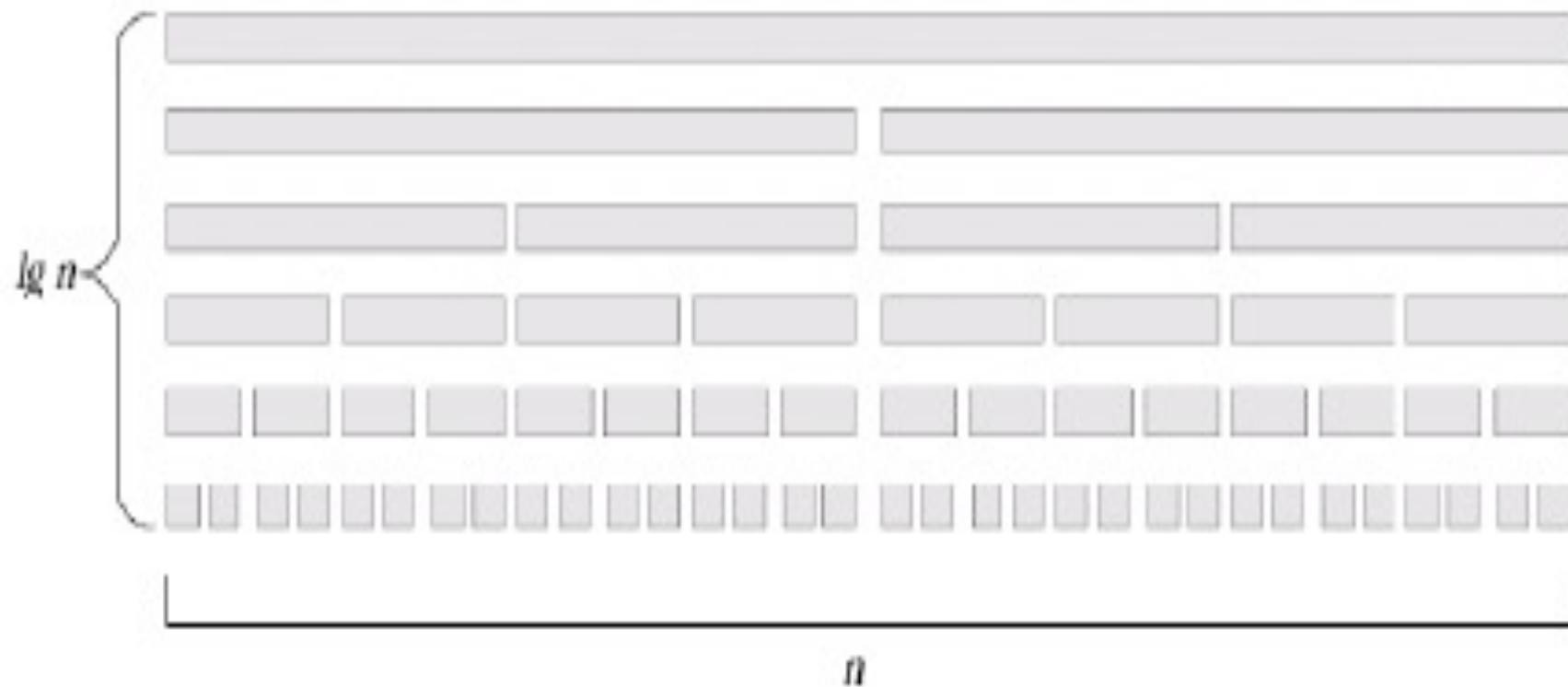


The best case for quick sort happen when the left segment and the right segment is balanced (have the same size) with value  $x \approx \lg n$

Example of best case quick sort: array[1 2 5 4]..

## Quick Sort Analysis

- The number of steps to get the **balance segment** while partitioning the array is  $\lg n$  and the number of comparisons depend on the size list,  $n$ .



# Quick Sort

- **Analysis**
  - **Average case:**  $O(n * \log_2 n)$
  - **Worst case:**  $O(n^2)$ 
    - When the array is already sorted, and the smallest item is chosen as the pivot
    - Quicksort is usually extremely fast in practice
    - Even if the worst case occurs, quicksort's performance is acceptable for moderately large arrays

# A Comparison of Sorting Algorithms

- Approximate growth rates of time required for eight sorting algorithms

	<u>Worst case</u>	<u>Average case</u>
Selection sort	$n^2$	$n^2$
Bubble sort	$n^2$	$n^2$
Insertion sort	$n^2$	$n^2$
Mergesort	$n * \log n$	$n * \log n$
Quicksort	$n^2$	$n * \log n$
Radix sort	$n$	$n$
Treesort rt	$n^2$	$n * \log n$
	$n * \log n$	$n * \log n$

# Order-of-Magnitude Analysis and Big O Notation

- A comparison of growth-rate functions shows that  $O(n \log n)$  algorithm is significantly faster than  $O(n^2)$  algorithm.

Function	$n$					
	10	100	1,000	10,000	100,000	1,000,000
1	1	1	1	1	1	1
$\log_2 n$	3	6	9	13	16	19
$n$	$10$	$10^2$	$10^3$	$10^4$	$10^5$	$10^6$
$n * \log_2 n$	30	664	9,965	$10^5$	$10^6$	$10^7$
$n^2$	$10^2$	$10^4$	$10^6$	$10^8$	$10^{10}$	$10^{12}$
$n^3$	$10^3$	$10^6$	$10^9$	$10^{12}$	$10^{15}$	$10^{18}$
$2^n$	$10^3$	$10^{30}$	$10^{301}$	$10^{3,010}$	$10^{30,103}$	$10^{301,030}$

# Summary

- Order-of-magnitude analysis and Big O notation measure an algorithm's time requirement as a function of the problem size by using a growth-rate function
- To compare the efficiency of algorithms
  - Examine growth-rate functions when problems are large
  - Consider only significant differences in growth-rate functions
- Worst-case and average-case analyses
  - Worst-case analysis considers the maximum amount of work an algorithm will require on a problem of a given size
  - Average-case analysis considers the expected amount of work that an algorithm will require on a problem of a given size
- Order-of-magnitude analysis can be the basis of your choice of an ADT implementation
- Selection sort, bubble sort, and insertion sort are all  $O(n^2)$  algorithms
- Quicksort and mergesort are two very fast recursive sorting algorithms

## Exercise

Show how Quick Sort and Merge Sort algorithm is implemented on the following list of data:

[12 9 20 18 7 5 15 17 11 25 30 35]

Discuss the efficiency of both sorting techniques applying on the data.

Next...

