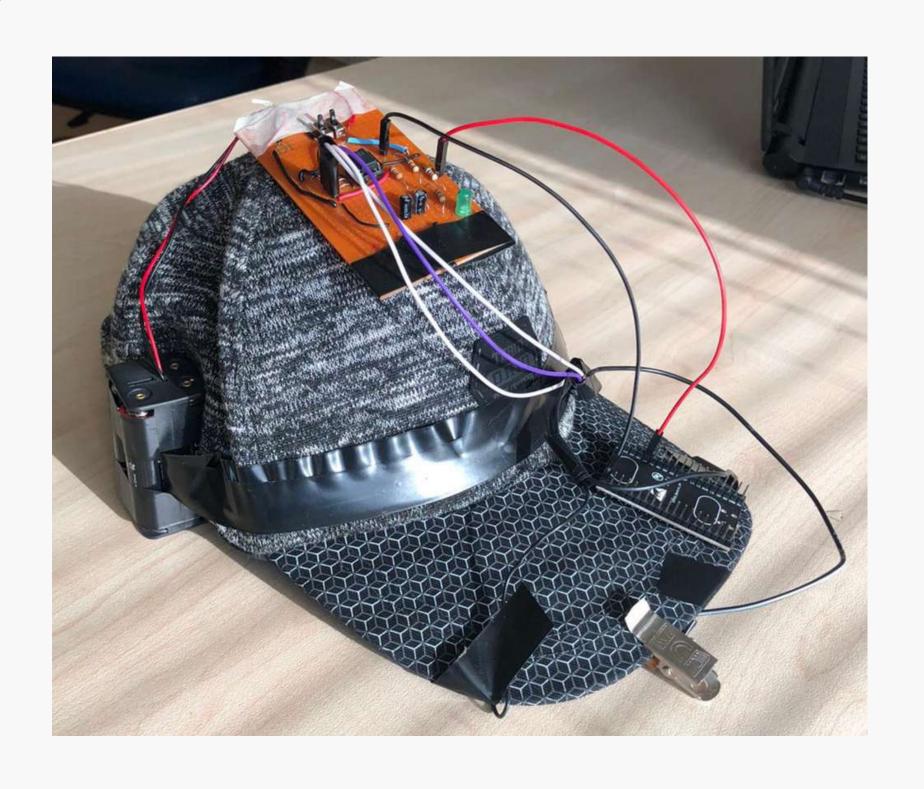


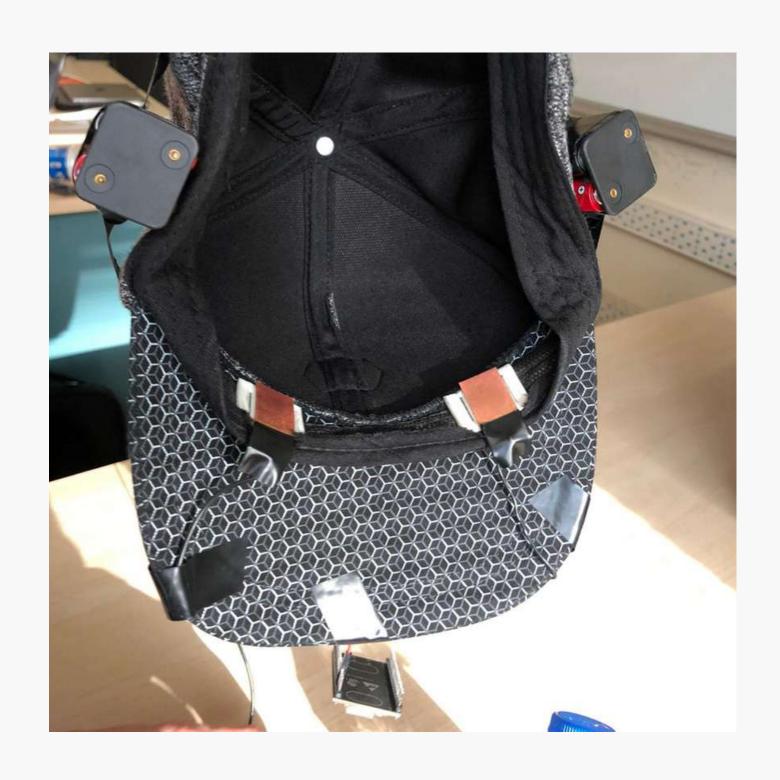
# **CSE396**

Final Presentation

**GENERO** 

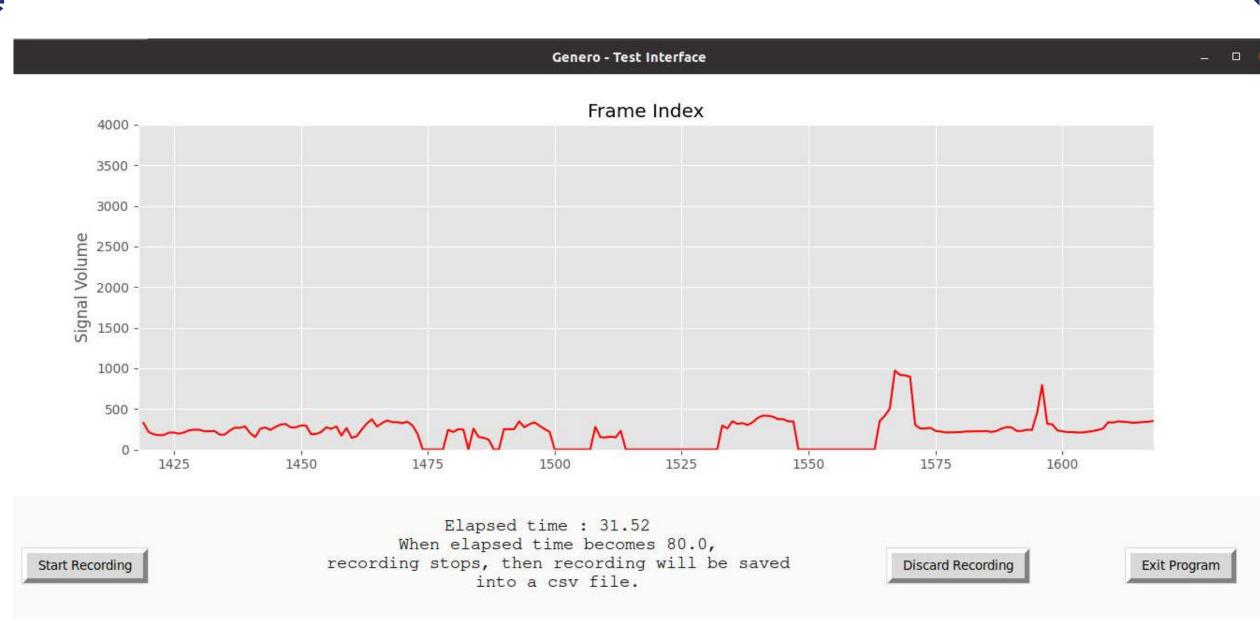
# **HARDWARE**





#### **TEST INTERFACE**

- We used Python to make test interface
- For interactive objects (buttons, frame, etc.) we used Tkinter library.
- For the graph we used matplotlib library.
- Frame index shows
   which frame is received
   at the moment
- Signal value represents the size of the signal



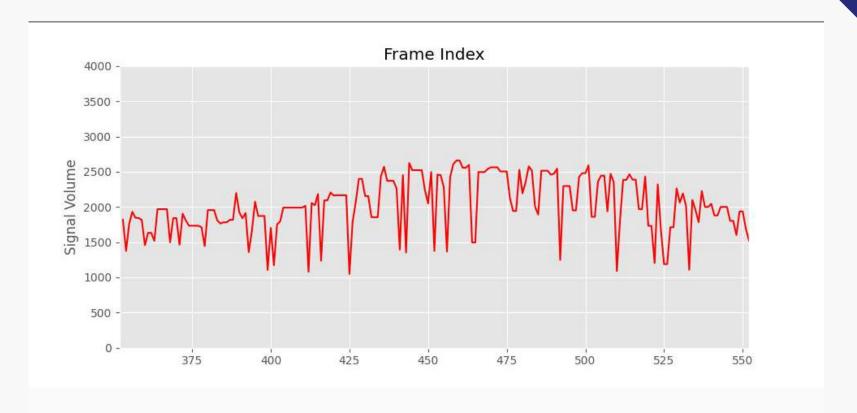
## DATA ACQUISITION

To collect data we used test interface and a video clip from our unity app simultaneously together.

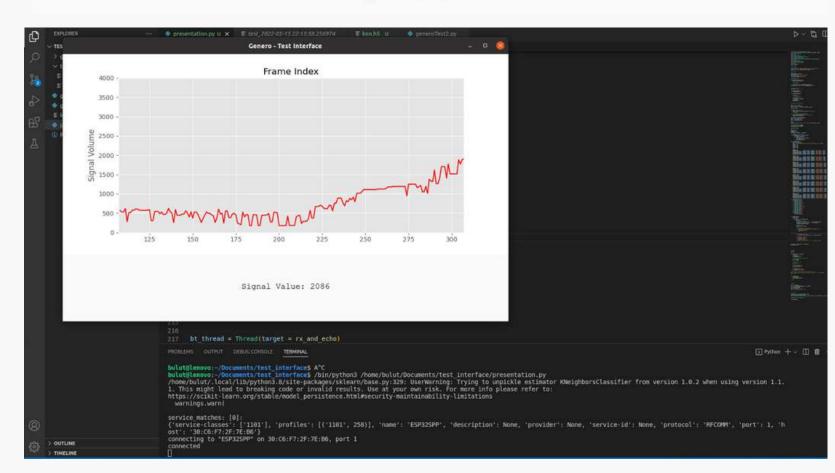
#### SUBJECT GROUP QUALITIES

**AGE:** 19 - 24

**NUMBER:** 115 PEOPLE

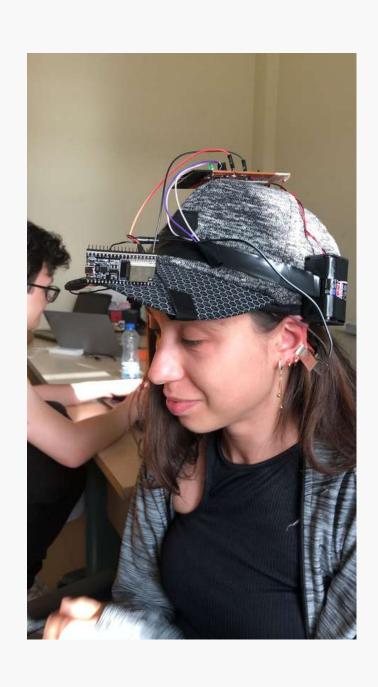


Signal Value: 1521



#### HOW DO WE COLLECT DATA

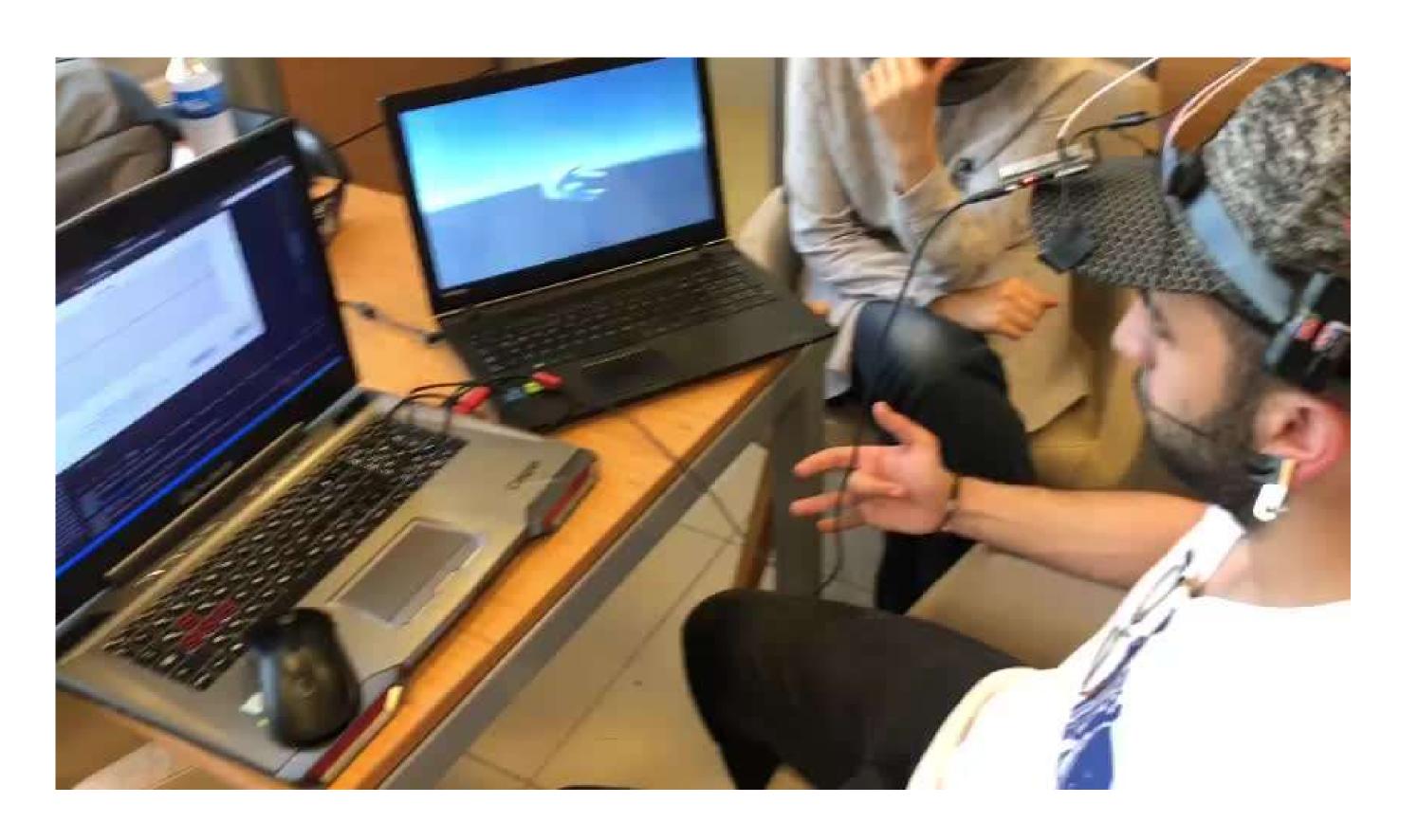
- Put the hat on the head (copper bands must be touching to forehead)
- Reference band must touch to the ear
- Ask people to focus and do some hand movements
- Receive and record the signals formed in the brain with the eeg sensor







### A CLIP FROM DATA COLLECTION



#### DATA PRE PROCESSING

- We used machine learning methods to make the data meaningful
- We used keras python library
- All data from every person is in a file separately and results are labeled as parmakl\_repeat1, parmakl\_repeat2 etc.
- We did a pre-processing to make all the data ready for the learning model

#### DATA PROCESSING MODELS

- We used machine learning models to make the data meaningful
- Z Score Normalization
- test\_size : 0.25
- THESE MODELS:
  - Decision tree
  - K-Nearest Neighbors
  - Best random forest model
  - Deep neural network model

#### RESULTS OF MODELS

DECISION TREE (14.3%)

```
Z Score Normalization
    Bütün özellikler dahil olacak şekilde sınıflandırma
   Decission Tree
   from sklearn.tree import DecisionTreeClassifier
   from sklearn.metrics import (precision_score, recall_score, f1_score, accuracy_score, mean_squared_error, mean_absolute_error, roc_curve,
   model = DecisionTreeClassifier()
   model.fit(x_train, y_train)
  y_pred = model.predict(x_test)
10 accuracy = accuracy_score(y_test, y_pred)
necall = recall_score(y_test, y_pred , average="weighted")
13 f1 = f1_score(y_test, y_pred, average="weighted")
```

```
print("accuracy")
16 print("%.3f" %accuracy)
17 print("precision")
18 print("%.3f" %precision)
19 print("recall")
20 print("%.3f" %recall)
21 print("fiscore")
22 print("%.3f" %f1)
     accuracy
     0.143
     precision
     0.145
     recall
     0.143
     f1score
     0.143
```

#### RESULTS OF MODELS

KNN (30%)

```
main.ipynb X
 home > bulut > Desktop > proje_yedek > test > 📳 main.ipynb > 🏺 # setup
+ Code + Markdown | ▶ Run All 

Clear Outputs of All Cells | ■ Outline …
    KNN
        n neighbors = list(range(1,31))
        optimal n neighbors = 0
        for i in n neighbors:
            knn = KNeighborsClassifier(n_neighbors = i)
            knn.fit(x_train, y_train)
            if best acc < knn.score(x test,y test):</pre>
                best acc = knn.score(x test,y test)
                optimal n neighbors = i
        print("Optimal N-Neighbors: {}, Accuracy: {}".format(optimal_n_neighbors,best_acc))
    Optimal N-Neighbors: 3, Accuracy: 0.3
        optimal weights = 'uniform'
        best acc = 0
        weights = ['uniform', 'distance']
        for i in weights:
            knn = KNeighborsClassifier(n_neighbors = 3, p = 2, weights = i)
            knn.fit(x train, y train)
                best acc = knn.score(x test,y test)
                optimal weights = i
        print("Optimal Weights: {}, Accuracy: {}".format(optimal weights, best acc))
     Optimal Weights: uniform, Accuracy: 0.3
    Best K-NN Model
        knn = KNeighborsClassifier(n neighbors = 3, p = 2)
        print("Accuracy: {}".format(knn.score(x test,y test)))
```

#### BEST RANDOM FOREST (20%)

```
File Edit Selection View Go Run Terminal Help
      main.ipynb X
      home > bulut > Desktop > proje_yedek > test > 📳 main.ipynb > 🏺 # setup
     + Code + Markdown | ▶ Run All 

Clear Outputs of All Cells | ■ Outline
              \max depth = [5, 8, 15, 25, 30]
              hyperF = dict(n_estimators = n_estimators, max_depth = max_depth)
              gridF = GridSearchCV(RandomForestClassifier(), hyperF, cv = 3, verbose = 1,
              bestF = gridF.fit(x train, y train)
          Fitting 3 folds for each of 25 candidates, totalling 75 fits
          C:\ProgramData\Anaconda3\lib\site-packages\sklearn\model selection\ split.py:676: UserWarning: The least populated class in
              print(bestF.best params )
              print('\n')
              print(bestF.best_estimator_)
          {'max depth': 5, 'n estimators': 300}
          RandomForestClassifier(max depth=5, n estimators=300)
          Best Random Forest Model
              clf = RandomForestClassifier(max depth=5, n estimators=300)
              clf.score(x test, y test)
```

#### **RESULTS OF MODELS**

#### **DNN (10.78%)**

- activation: 'softmax'
- optimizer : 'adam'
- loss: 'categorical\_crossentropy'
- epochs: 10
- batch\_size : 1024

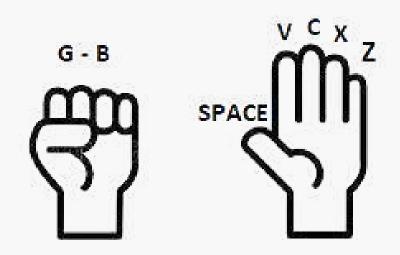
```
Epoch 51/180
3450/3450 [*********************************** - 8s 6us/step - loss: 2.0805 - acc: 0.1342 - val loss: 2.0853 - val acc: 0.1287
Epoch 52/180
                              Output exceeds the size limit. Open the full output data in
a text editor.
2.0776 - acc: 0.1313 - val. loss: 2.0853 - val. acc: 0.1078
<keras.callbacks.History at 0x256cble4940>
y pred = dnn.predict(x test)
y pred= np.argmax(y pred, alls=1)
acc = accuracy score(np.argmax(y test, nmis=1), y pred)
print('DNN Test Accuracy: 5.4f' 3 acc)
DNN Test Accuracy: 0.1078
```

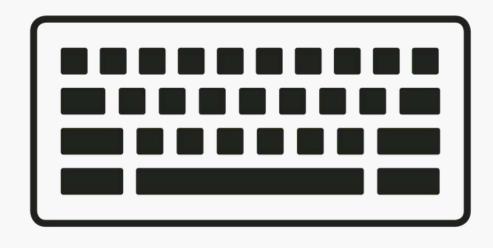
#### RESULT OF DATA PROCESSING

After compiling the model we made a real-time working script that communicates with esp-32 to get signals.

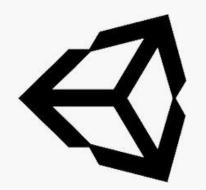
Puts all 50 inputs to the model and redirects the output to the unity simulation and simulation shows the finger movements.

# HARDWARE - UNITY COMMUNICATION





- OUTPUTS AFTER DATA PROCESSING
- ACCORDING TO THE DATA WE HAVE CLASSIFIED, DIFFERENT KEYS ARE PRESSED.
- FOR THE NECESSARY HAND MOVEMENTS.

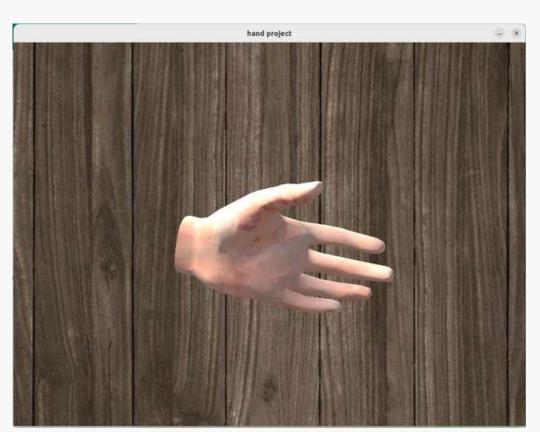


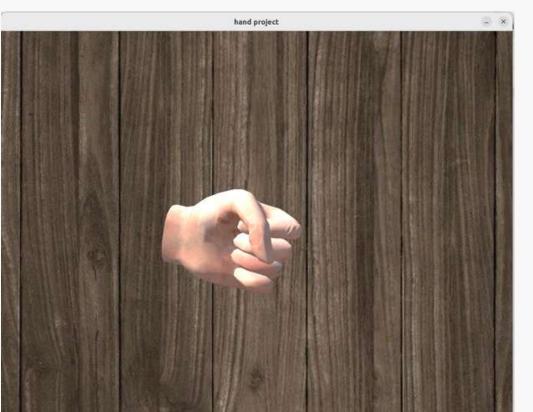


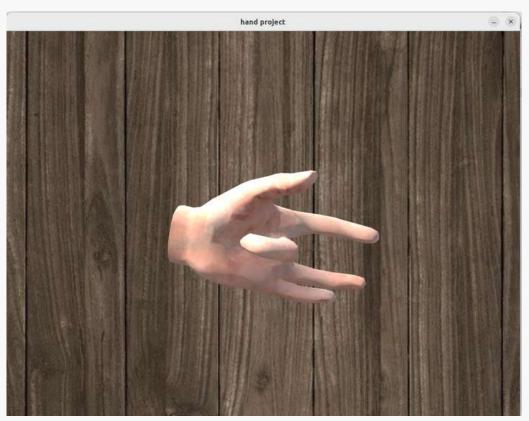
## UNITY

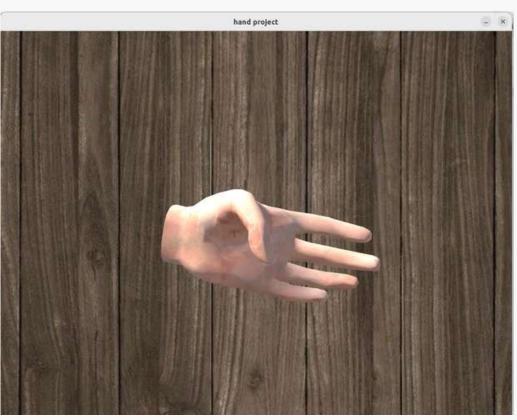
DIFFERENT HAND
COMBINATIONS ARE
SHOWN IN UNITY

USED FOR EACH HAND MOVEMENT









#### **OUR TEAM**

- Abdurrahman Bulut
- Ahmet Tuğkan Ayhan
- Buse Elbirgiç
- Doğukan Güler
- Mehmet Hüseyin Yıldız
- Muhammet Fikret Atar

- Salih Tangel
- Ömer Faruk Erol
- Özlem Sevri
- Yusuf Fatih Şişman
- Yusuf Talha Altun
- Yunus Emre Yumşak



# THANKYOU