**Neural Network Computing - Project**

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This project comprised of 3 main parts. In Part 1, the weights and biases after 1 epoch were validated given initial weights and biases. In Part 2, the hyperparameters were varied while using the quadratic cost function whereas in part 3, the hyperparameters were varied while using the cross entropy cost function. The results were analyzed at each step and were found to be in close conformity with the theory.

**Part 1: XOR Weights Validation**

Using the initial weights and biases provided, the following weights and biases were obtained after 1 epoch of training when using a 2-4-1 neural network architecture with the following hyperparameters:

Weights1 = [[ 0.193475, 0.316754, -0.144748, 0.363745],  
 [ 0.306867, 0.188452, -0.033015, -0.488590]]

Weights2 = [[ 0.475348], [0.276428], [-0.383950], [ 0.348013]] T

Biases1 = [[-0.322434, 0.265042, 0.273305, -0.32503622]]

Biases2 = [[-0.080274]]

These values were validated with the GA before moving on to the rest of the experiments.

*Note: Throughout all the experiments, tolerance was kept fixed at 0.05 and max number of epochs was set to 700 after empirically trying several different combinations.*

**Part 2a: Varying (Quadratic Cost Function)**

In this part of the project, the quadratic cost function was used and the following hyperparameter combinations were tested:

Hence, a total of 27 hyperparameter combinations were tried. Note that for this part, the NN architecture was kept fixed at 2-4-1 in order to observe the effect of the different learning rates, weights and bias initializations and slope of the transfer function. The results are summarized below:

Table 1 Effect of the hyperparameters on convergence (quadratic cost function).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
|  |  |  | Final Epoch Error | Convergence | # Training Epochs |
| 0.1 | 0.5 | 0.5 | 0.0496 | Yes | 172 |
| 0.1 | 0.5 | 1 | 0.0499 | Yes | 661 |
| 0.1 | 0.5 | 1.5 | 4.0497 | No | 700 |
| 0.1 | 1 | 0.5 | 0.0495 | Yes | 120 |
| 0.1 | 1 | 1 | 0.0499 | Yes | 535 |
| 0.1 | 1 | 1.5 | 1.3302 | No | 700 |
| 0.1 | 1.5 | 0.5 | 0.0499 | Yes | 109 |
| 0.1 | 1.5 | 1 | 0.0499 | Yes | 478 |
| 0.1 | 1.5 | 1.5 | 0.0852 | No | 700 |
| 0.2 | 0.5 | 0.5 | 0.0496 | Yes | 70 |
| 0.2 | 0.5 | 1 | 4.205 | No | 700 |
| 0.2 | 0.5 | 1.5 | 4.0934 | No | 700 |
| 0.2 | 1 | 0.5 | 0.0493 | Yes | 48 |
| 0.2 | 1 | 1 | 0.05 | Yes | 316 |
| 0.2 | 1 | 1.5 | 0.0515 | No | 700 |
| 0.2 | 1.5 | 0.5 | 0.0498 | Yes | 45 |
| 0.2 | 1.5 | 1 | 0.0499 | Yes | 428 |
| 0.2 | 1.5 | 1.5 | 0.05 | Yes | 517 |
| 0.3 | 0.5 | 0.5 | 0.0487 | Yes | 38 |
| 0.3 | 0.5 | 1 | 4.3105 | No | 700 |
| 0.3 | 0.5 | 1.5 | 4.1365 | No | 700 |
| 0.3 | 1 | 0.5 | 0.0492 | Yes | 28 |
| 0.3 | 1 | 1 | 0.0496 | Yes | 219 |
| 0.3 | 1 | 1.5 | 0.0499 | Yes | 491 |
| 0.3 | 1.5 | 0.5 | 0.0482 | Yes | 32 |
| 0.3 | 1.5 | 1 | 0.0499 | Yes | 129 |
| 0.3 | 1.5 | 1.5 | 0.0499 | Yes | 431 |

We see that 19 out of the 27 hyperparameter combinations tested lead to convergence. With max number of epochs set to 700, the learning rate **α** does not seem to affect how many hyperparameter combinations converge (6-7 convergence results in each set of 9 rows with **α**=0.1, **α**=0.2 and **α**=0.3). However, the learning rate **α** does affect the *rate of convergence* if the experiments converge*.* For instance, consider the hyperparameter combinations indicated by the rows highlighted in yellow. With the same settings for **,** increasing the learning rate decreases the number of training epochs required for convergence. Note however that increasing the learning rate leads to greater risk of skipping minima during the gradient descent process, which may lead to divergence. As a further note, even though have the same values in the rows considered above, they might not necessarily yield the same results every time since the weights and biases are randomly initialized.

Furthermore, it is observed that using relatively low initialization values of the weights and biases (e.g. = 0.5) decreases the chance of convergence. This can be seen from the rows highlighted in green where increasing decreases the number of epochs needed for convergence.

Lastly, it was observed that increasing (slope argument of the transfer function) decreased the rate of convergence. This can be seen, for example, from the rows highlighted in orange. The following graphs for the bipolar sigmoid transfer function help explain why this is the case. The red, blue and green curves represent =0.5**,** =1 and =1.5 respectively. Since the slope of the red curve is greater, this means that lower values of lead to faster rates of convergence as was confirmed empirically by the results above.

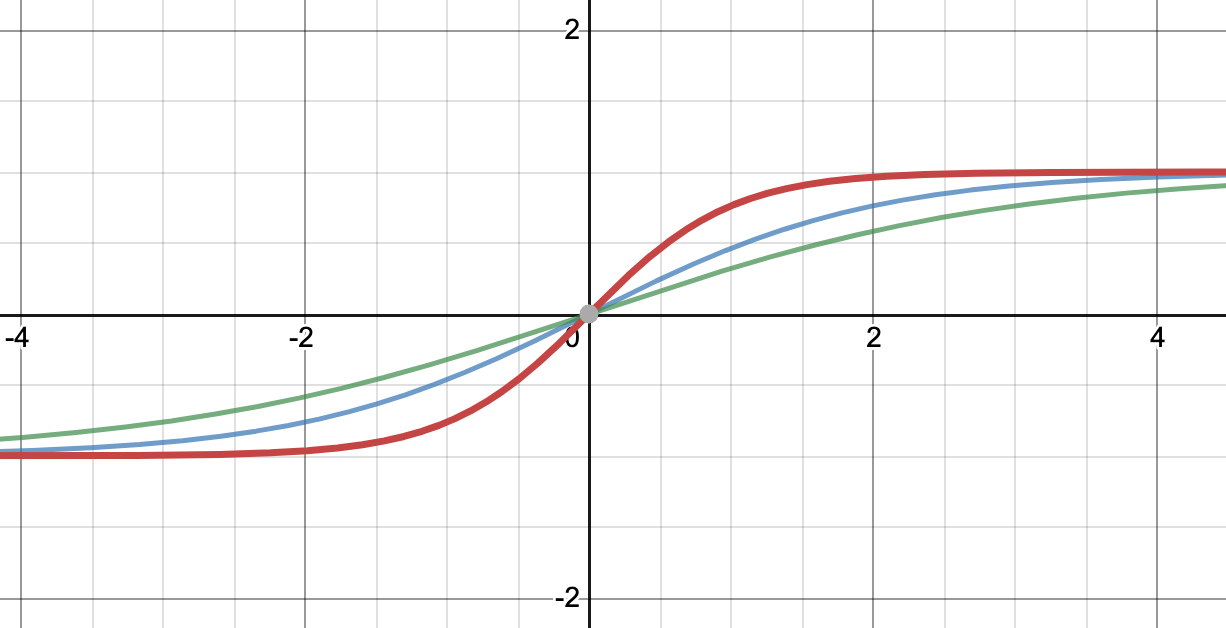


Figure 1 Bipolar sigmoid transfer functions with different values of . The red, blue and green curves represent =0.5**,** =1 and =1.5 respectively.

**Part 2b: Varying (hidden layer neurons) (Quadratic Cost Function)**

In this part of the project, the NN architecture was changed while keeping fixed at 0.2, 1 and 1 respectively. NN architecture of the form 2-N1-1 was used where the following values for N1 were tried (each 100 times):

Table 2 Effect of varying number of hidden neurons on convergence (quadratic cost function).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| N1 | # Iterations Converged | Convergence Epoch Statistics | | | |
| Min | Max | Mean | Median |
| 2 | 84 | 264 | 700 | 406.9 | 353 |
| 4 | 99 | 166 | 700 | 262.75 | 262 |
| 6 | 99 | 160 | 700 | 227.96 | 221.5 |
| 8 | 99 | 142 | 700 | 194.94 | 184.5 |
| 10 | 99 | 135 | 700 | 184.66 | 175 |

As can be seen from the results above, increasing the number of hidden layers increases the number of iterations that converge since it increases the representation power of the NN according to the universality theorem.. However, after N1 = 4, increasing N1 does not increase convergence. In fact, increasing the number of hidden neurons N1 might have the undesired effect of overfitting to the training data. In order to avoid overfitting, we would need to use some form of regularization. However, in this example, since we don’t have any test set, the results can only be reported on the training set and deductions regarding overfitting can’t be made.

When using only 1 hidden neuron (N1=1), none of the 100 iterations converged. This is because the XOR problem is not linearly separable and the representation power of only 1 hidden neuron is not enough to approximate the XOR function. According to the universality theorem, using more neurons in the hidden layer increases the function approximation of the NN, as was observed for the cases where N1>=2.

**Part 3a: Varying (Cross Entropy Cost Function)**

In this part of the project, the cross-entropy cost function was used and the following hyperparameter combinations were tested:

Using the cross-entropy cost function has the effect that only the formula used for the sensitivity of the last layer changes as can be seen from the source code.

A total of 27 hyperparameter combinations were tried. Note that for this part, the NN architecture was kept fixed at 2-4-1 in order to observe the effect of the different learning rates, weights and bias initializations and slope of the transfer function. The results are summarized below:

Table 3 Effect of the hyperparameters on convergence (cross entropy cost function).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
|  |  |  | Final Epoch Error | Convergence | # Training Epochs |
| 0.1 | 0.5 | 0.5 | 0.0478 | Yes | 75 |
| 0.1 | 0.5 | 1 | 4.205 | No | 700 |
| 0.1 | 0.5 | 1.5 | 4.1366 | No | 700 |
| 0.1 | 1 | 0.5 | 0.0486 | Yes | 51 |
| 0.1 | 1 | 1 | 0.0493 | Yes | 153 |
| 0.1 | 1 | 1.5 | 0.0493 | Yes | 275 |
| 0.1 | 1.5 | 0.5 | 0.0483 | Yes | 25 |
| 0.1 | 1.5 | 1 | 0.0497 | Yes | 114 |
| 0.1 | 1.5 | 1.5 | 0.0497 | Yes | 181 |
| 0.2 | 0.5 | 0.5 | 0.0495 | Yes | 52 |
| 0.2 | 0.5 | 1 | 4.4182 | No | 700 |
| 0.2 | 0.5 | 1.5 | 4.2751 | No | 700 |
| 0.2 | 1 | 0.5 | 0.0472 | Yes | 26 |
| 0.2 | 1 | 1 | 0.0481 | Yes | 93 |
| 0.2 | 1 | 1.5 | 0.0484 | Yes | 187 |
| 0.2 | 1.5 | 0.5 | 0.0427 | Yes | 12 |
| 0.2 | 1.5 | 1 | 0.0484 | Yes | 34 |
| 0.2 | 1.5 | 1.5 | 0.0497 | Yes | 177 |
| 0.3 | 0.5 | 0.5 | 5.3024 | No | 700 |
| 0.3 | 0.5 | 1 | 4.638 | No | 700 |
| 0.3 | 0.5 | 1.5 | 4.4182 | No | 700 |
| 0.3 | 1 | 0.5 | 0.047 | Yes | 9 |
| 0.3 | 1 | 1 | 0.05 | Yes | 58 |
| 0.3 | 1 | 1.5 | 0.0478 | Yes | 114 |
| 0.3 | 1.5 | 0.5 | 0.0381 | Yes | 9 |
| 0.3 | 1.5 | 1 | 0.0476 | Yes | 42 |
| 0.3 | 1.5 | 1.5 | 0.0492 | Yes | 96 |

With the cross-entropy cost function, 20 out of the 27 hyperparameter combinations tested lead to convergence compared to the quadratic cost function case where 19 hyperparameter combinations converged.

The cross-entropy cost function has the property that the derivative of the cost function is very large when the predicted value is far from the ground truth, which makes learning fast. Hence, we observe that some of the iterations converge very rapidly (e.g. the rows highlighted in gray) in comparison to the same iterations with the quadratic cost function.

Similar to the quadratic cost function case, we see that increasing the learning rate **α** increases the rate of convergence or it may lead to divergence as in the case highlighted in blue. Increasing from 0.5 – 1.5 decreases the number of epochs needed for convergence as was also observed for the quadratic cost function before. Similarly, it was also observed that lower values of lead to faster rates of convergence.

**Part 3b: Varying (hidden layer neurons) (Cross Entropy Cost Function)**

In this part of the project, the NN architecture was changed while keeping fixed at 0.2, 1 and 1 respectively. NN architecture of the form 2-N1-1 was used where the following values for N1 were tried (each 100 times):

Table 4 Effect of varying number of hidden neurons on convergence (cross entropy cost function).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| N1 | # Iterations Converged | Convergence Epoch Statistics | | | |
| Min | Max | Mean | Median |
| 2 | 61 | 59 | 700 | 325.99 | 110 |
| 4 | 89 | 48 | 700 | 148.01 | 77 |
| 6 | 94 | 39 | 700 | 105.86 | 64.5 |
| 8 | 100 | 35 | 162 | 56.73 | 52.5 |
| 10 | 100 | 34 | 92 | 49.83 | 49 |

Again, like Part 2a, increasing the number of hidden layers increases the number of iterations that converge since it increases the representation power of the NN according to the universality theorem.

When using only 1 hidden neuron (N1=1), none of the 100 iterations converged. This is because the XOR problem is not linearly separable and the representation power of only 1 hidden neuron is not enough to approximate the XOR function. According to the universality theorem, using more neurons in the hidden layer increases the function approximation of the NN, as was observed for the cases where N1>=2.

**Remarks regarding iterations that did not converge**

For most of the runs that did not converge, the main problems were that either the number of hidden layers was too low (e.g. N1=0), the learning rate was too high, the scale parameter of the bipolar sigmoid transfer function was too high or the weights and biases were initialized to very low values (e.g. =0.5).

**Weights and biases for N1 = 4, α = 0.2, ζ = 1.0, and x0 = 1.0 after 1 epoch**

Weights1 = [[-0.659339, -0.305067, 0.864314, 0.968217]  
 [ 0.560623, -0.368451, -0.418328, -0.705848]]

Weights2 = [[0.71485572], [0.03575514], [0.56310025], [0.48140105]] T

Biases1 = [[ 0.35943, -0.608297, 0.574848, -0.299499]]

Biases2 = [[0.038751]]