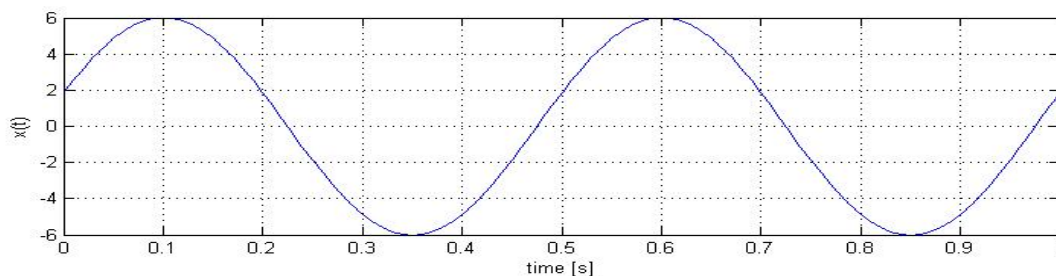


## List 1 Signals and Systems

### Exercise 1 *Sinusoidal Signal.*

Describe the signal  $x(t)$  shown below with three different mathematical expressions using:

- A single cosine function.
- A sum of sine and cosine functions.
- The real part of a complex exponential function.



### Exercise 2 *Phasors (vector rotating about the origin in a complex plane).*

Use the phasor notation to solve the following equations:

- $x(t) = 3 \cdot \cos\left(6\pi t + \frac{\pi}{2}\right) + 2 \cdot \cos\left(6\pi t + \frac{\pi}{4}\right) = ?$
- $x(t) = A \cdot \cos(\omega t + \theta) \quad ; \quad \frac{dx(t)}{dt} = ?$

### Exercise 3 *Signalbeschreibung.*

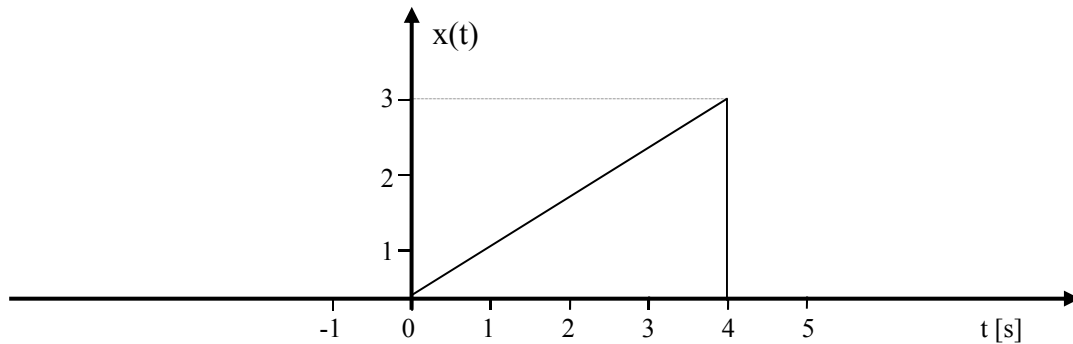
Describe the following signals with a mathematical equation:

- A time limited sine signal from  $t_1 = 1$  s until  $t_2 = 5$  s, with a period length of  $T = 0.5$  s.  
Hint: Use the Heaviside or unit step function.
- An infinite sequence of unit impulses (Dirac deltas) with a spacing of  $T_s$  and a weight (or amplitude)  $A$ .
- Determine for the signals above (items a and b) the following characteristics: power/energy signals, symmetric (even/odd) or not, periodic or not.
- Which kind of signal do you get in Matlab with the command:  
➤ `sig_d = randn(1, 100)`  
Calculate the average value and the standard deviation of `sig_d`.

**Exercise 4** *Signal Conversions.*

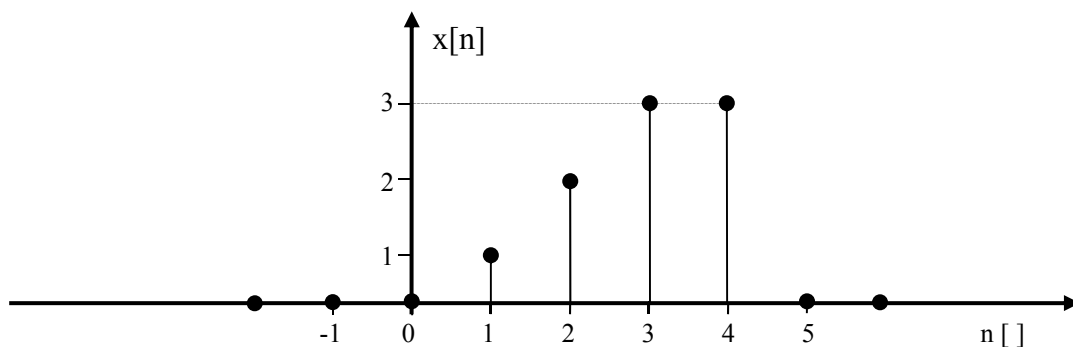
Given the continuous time signal  $x(t)$  shown below, prepare a sketch for each of the following signals (conversions of  $x(t)$ ):

- a)  $x(t-2)$
- b)  $x(2t)$
- c)  $x(t/2)$
- d)  $x(-t)$

**Exercise 5** *Signal Conversions.*

Given the discrete time signal  $x[n]$  shown below, prepare a sketch for each of the following signals (conversions of  $x[n]$ ):

- a)  $x[n-2]$
- b)  $x[2n]$
- c)  $x[-n]$
- d)  $x[-n+2]$



- e) Describe the signal  $x[n]$  as a sum of weighted and shifted unit impulses  $\delta[n]$ .

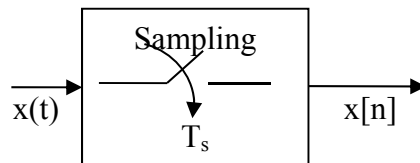
**Exercise 6** *Sampling and Discrete Signals.*

The time continuous signal  $x(t)$  is described as:

$$x(t) = \begin{cases} 1 - |t| & \text{for } -1 \leq t \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

- a) Draw a sketch representing  $x(t)$ .

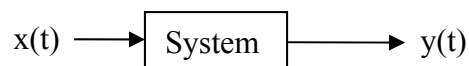
The signal  $x(t)$  is then sampled with different sampling intervals (also called sampling period  $T_s$ ). Prepare sketches of the resulting discrete signals  $x[n]$  for the following values of  $T_s$ :



- b)  $T_s = 0.25$  s  
 c)  $T_s = 0.5$  s  
 d)  $T_s = 1$  s

**Exercise 7** *System Classification.*

Consider a system with a single input signal  $x(t)$  and a single output signal  $y(t)$  as shown below:



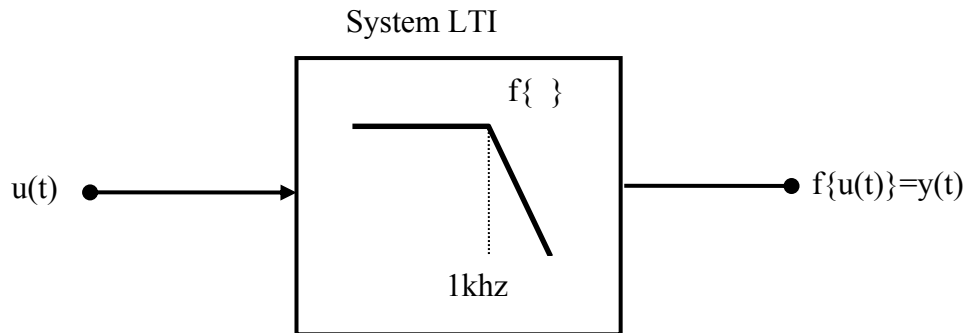
Which of the following functions describe then a linear system? Justify your answer with an equation or a short sentence.

- a)  $y(t) = 0.2 \cdot x(t) - 1.5$   
 b)  $y(t) = x(t) + \int x(t) dt$   
 c)  $y(t) + \dot{y}(t) = 0.4 \cdot x(t) + 0.2 \cdot \dot{x}(t)$   
 d)  $y(t) + \dot{y}(t) = 0.4 \cdot x(t) + 0.2 \cdot x^2(t)$

**Exercise 8** *Linear time invariant System (LTI).*

The following LTI system is a low pass filter, it let through low frequencies unchanged and attenuates high frequencies. Check its effect on test signals  $u_1(t)$  und  $u_2(t)$  and determine then the output signals  $y_3(t)$  und  $y_4(t)$  for the input signals  $u_3(t)$  und  $u_4(t)$  .

Hint: consider the properties of a LTI system.

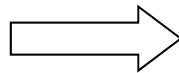
**a) Simplified LTI (only amplitude effect)**

$$u_1(t) = 3 \cdot \cos(2\pi \cdot 100t)$$

$$u_2(t) = 3 \cdot \cos(2\pi \cdot 10kt)$$

$$u_3(t) = 2 \cdot \sin\left(2\pi \cdot 100t + \frac{\pi}{4}\right)$$

$$u_4(t) = 8 \cdot \sin\left(2\pi \cdot 10kt + \frac{\pi}{10}\right) + 4 \cdot \cos\left(2\pi \cdot 100t + \frac{\pi}{6}\right)$$



$$y_1(t) = 3 \cdot \cos(2\pi \cdot 100t)$$

$$y_2(t) = 0,3 \cdot \cos(2\pi \cdot 10kt)$$

$$y_3(t) = ?$$

$$y_4(t) = ?$$

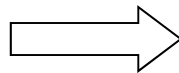
**b) LTI with Amplitude and Phase Effect**

$$u_1(t) = 3 \cdot \cos(2\pi \cdot 100t)$$

$$u_2(t) = 3 \cdot \cos(2\pi \cdot 10kt)$$

$$u_3(t) = 2 \cdot \sin\left(2\pi \cdot 100t + \frac{\pi}{4}\right)$$

$$u_4(t) = 8 \cdot \sin\left(2\pi \cdot 10kt + \frac{\pi}{10}\right) + 4 \cdot \cos\left(2\pi \cdot 100t + \frac{\pi}{6}\right)$$



$$y_1(t) = 3 \cdot \cos(2\pi \cdot 100t)$$

$$y_2(t) = 0,3 \cdot \cos\left(2\pi \cdot 10kt - \frac{\pi}{2}\right)$$

$$y_3(t) = ?$$

$$y_4(t) = ?$$