
NVIDIA/Cal Poly Robotics Teaching Kit with Jet

Module 1: Course Introduction

Lecture Slides

- 1.1 Course Introduction
- 1.2 Introduction to Robotics
- 1.3 Introduction to Jetson TK1/TX1
- 1.4 Jet Overview
- 1.5 Introduction to ROS

Labs

- Lab 1: Building the Robot

Quiz Questions

Module 2: Sensors and Actuators

Lecture Slides

- 2.1 Sonar, Accelerometer, and Gyroscope
- 2.2 Camera, Motors, and Encoders

Labs

- Lab 2: Sense and Avoid

Quiz Questions

Module 3: Computer Vision

Lecture Slides

- 3.1 Introduction to Computer Vision
- 3.2 Image Filtering
- 3.3 Image Moments

Labs

- Lab 3: Computer Vision

Quiz Questions

Module 4: Machine Learning

Lecture Slides

- 4.1 Introduction to Machine Learning
- 4.2 Neural Networks
- 4.3 Caffe

Labs

- NVIDIA DLI Online Elective: [Image Classification with DIGITS](#) (Link)
- NVIDIA DLI Online Elective: [Object Detection with DIGITS](#) (Link)
- NVIDIA DLI Online Elective: [Neural Network Deployment with DIGITS and TensorRT](#) (Link)
- Lab 4: Autonomous Driving

Quiz Questions

Module 5: Dead Reckoning

Lecture Slides

- 5.1 Introduction to Dead Reckoning
- 5.2 Calculating Positions
- 5.3 Sensor Fusion and Kalman Filters

Labs

- Lab 5: Dead Reckoning

Quiz Questions

Module 6: Path Planning

Lecture Slides

- 6.1 Introduction to Path Planning
- 6.2 A* Planning

Labs

- Lab 6: Path Planning

Quiz Questions

Module 7: Control

Lecture Slides

- 7.1 Introduction to Control Systems
- 7.2 PID Control

Labs

- Lab 7: Line Following

Quiz Questions

Module 8: Robot Localization

Lecture Slides

- 8.1 Introduction to Robot Localization
- 8.2 Localization with Particle Filters

Labs

- Lab 8: Localization

Quiz Questions

Module 9: Mapping

Lecture Slides

- 9.1 Introduction to Mapping
- 9.2 SLAM

Labs

- Lab 9: Mapping

Quiz Questions

Module 10: Final Project

- Harvester
 - Capture-the-Flag
 - ColorFollower
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[NVIDIA DLI Online Course with Certification: Fundamentals of Deep Learning for Computer Vision \(link\)](#)