

# Graphical Models for Decision Making

Lesson 2, week 12, class 24

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## 1 Decision Tables and Decision Trees

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# Graphical Models for Decision Making

## Graphical Models for Decision Making

### under uncertainty

B. Russell

"What men really want is not knowledge but certainty"

# Graphical Models for Decision Making

## Decision Tables: definition

- Most elementary way of representation
- Illustrate simply the basic concepts
- Elements:  $decision(a) + state(\theta) \rightarrow consequence(c(a, \theta) \in C)$

## Decision Tables: **Example:** software development

	0.5 $\theta_1$ =price up	0.3 $\theta_1$ =price stay	0.2 $\theta_1$ =price down
$a_1$ = new staff	$u(a_1, \theta_1) = 90$	$u(a_1, \theta_2) = 30$	$u(a_1, \theta_3) = -50$
$a_2$ = try current	$u(a_2, \theta_1) = 50$	$u(a_2, \theta_2) = 10$	$u(a_2, \theta_3) = -20$
$a_3$ = not to expand	$u(a_3, \theta_1) = 0$	$u(a_3, \theta_2) = 0$	$u(a_3, \theta_3) = 0$

## Decision Tables: evaluation

Discrete case (  $A$  and  $\Theta$  discrete)

- Assign beliefs:  $p(\theta_j) = p_j, (p_j \geq 0, \sum p_j = 1)$
- Assign preferences:  $u(a_i, \theta_j)$
- Compute expected utility of each alternative  $a_i$

$$\sum p_j * u(a_i, \theta_j) = Eu(a_i)$$

- Decision of maximum expected utility  $a^*$

$$\max Eu(a_i = Eu(a^*))$$

Continuous case:

$$Eu(a) = \int u(a, \theta) dP(\theta)$$

, a non linear programming problem

# Graphical Models for Decision Making

## Decision Tables: evaluation

**Example:** software development

	0.5 $\theta_1$ =price up	0.3 $\theta_1$ =price stay	0.2 $\theta_1$ =price down	$Eu(a_i)$
$a_1$ = new staff	$u(a_1, \theta_1) = 90$	$u(a_1, \theta_2) = 30$	$u(a_1, \theta_3) = -50$	<b>44</b>
$a_2$ = try current	$u(a_2, \theta_1) = 50$	$u(a_2, \theta_2) = 10$	$u(a_2, \theta_3) = -20$	24
$a_3$ = not to expand	$u(a_3, \theta_1) = 0$	$u(a_3, \theta_2) = 0$	$u(a_3, \theta_3) = 0$	0



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## Decision Trees: definition

- In practice tables very limited: only 1 moment to make decisions
- Typically, real problems are dynamic, with chained decisions and alternating different outcomes
- Elements :
  - Decision (square), alternatives
  - Chance (circle), states
  - Terminal (end path), Utility of outcome of the scenario

## Decision Trees: construction

- Skeleton (structure): from left to right (time passes), from root node to terminal nodes –Qualitative info–
- Relationships between elements and DM judgments via probabilities and utilities –Quantitative info–

# Graphical Models for Decision Making

## Decision Trees: construction

Conditional probabilities given that events to the left have already happened and previous decisions have been made

$D$	$a_1$ (44)	$P$	up	0.5	90
			–	0.3	30
			down	0.2	-50
	$a_2$ (24)	$P$	up	0.5	50
			–	0.3	10
			down	0.2	-20
	$a_3$ (0)	$P$	up	0.5	0
			–	0.3	0
			down	0.2	0

Software problem,  $\max(u)$ .

## Decision Trees: evaluation

- Tree= set of strategies or policies indicating action plans on what to do at each decision point reached with that plan
- Decision tree is evaluated to find an optimal strategy
- Backward dynamic programming method (optimality principle, Bellman & Dreyfus'62): assume we've made some decisions and nature has taken some outcomes, we'll have arrive at a node that it's:
  - terminal  $\rightarrow$  and we assign it the utility of the consequence;
  - chance node  $\rightarrow$  the max EU, from that node;
  - decision node  $\rightarrow$  the EU of the decision with max EU, from that node

Example: Helicopter (structure, quantitative info, evaluation).

## Decision Trees: properties

- Expressive, intuitive: complete paths
- Doesn't separate quantitative and qualitative info
- Exponential - growth  $\rightarrow$  computational requirements too (since algorithm enumerates when passing through all the paths)
- Schematic trees (generalization)
- Symmetric: all scenarios with same variables and in the same sequence
- Can handle asymmetric problems
- Helicopter: 2 asymmetries: test outcome only if the test is conducted; helicopter state only if it's bought
- Inadequate representation of probabilistic  $\triangleleft$  relationships (ad hoc)
- Preprocess of probabilities for representing the tree (2 trees problem)
- Non local Computations (joint distribution),  $P(A, B, C) = P(A)P(B|A)P(C|A, B)$
- Coalescence (subtree replica) detected ad hoc
- Explicit information constraints, but requires total ordering (not always specified)

# ¿Remarks and Questions?

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