

Notes on Coxeter Matroids

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1 Matroids

Definition (Matroid). *The set of basis of a matroid M over a given a ground set $[n]$ is $\binom{\mathcal{B}(M)}{[n],r}$, where r is the rank of the matroid. The set \mathcal{B} must fulfill:*

- $A, B \in \mathcal{B}, a \in A - B \Rightarrow \exists b \in B - A : (A - \{a\}) \cup \{b\} \in \mathcal{B}$

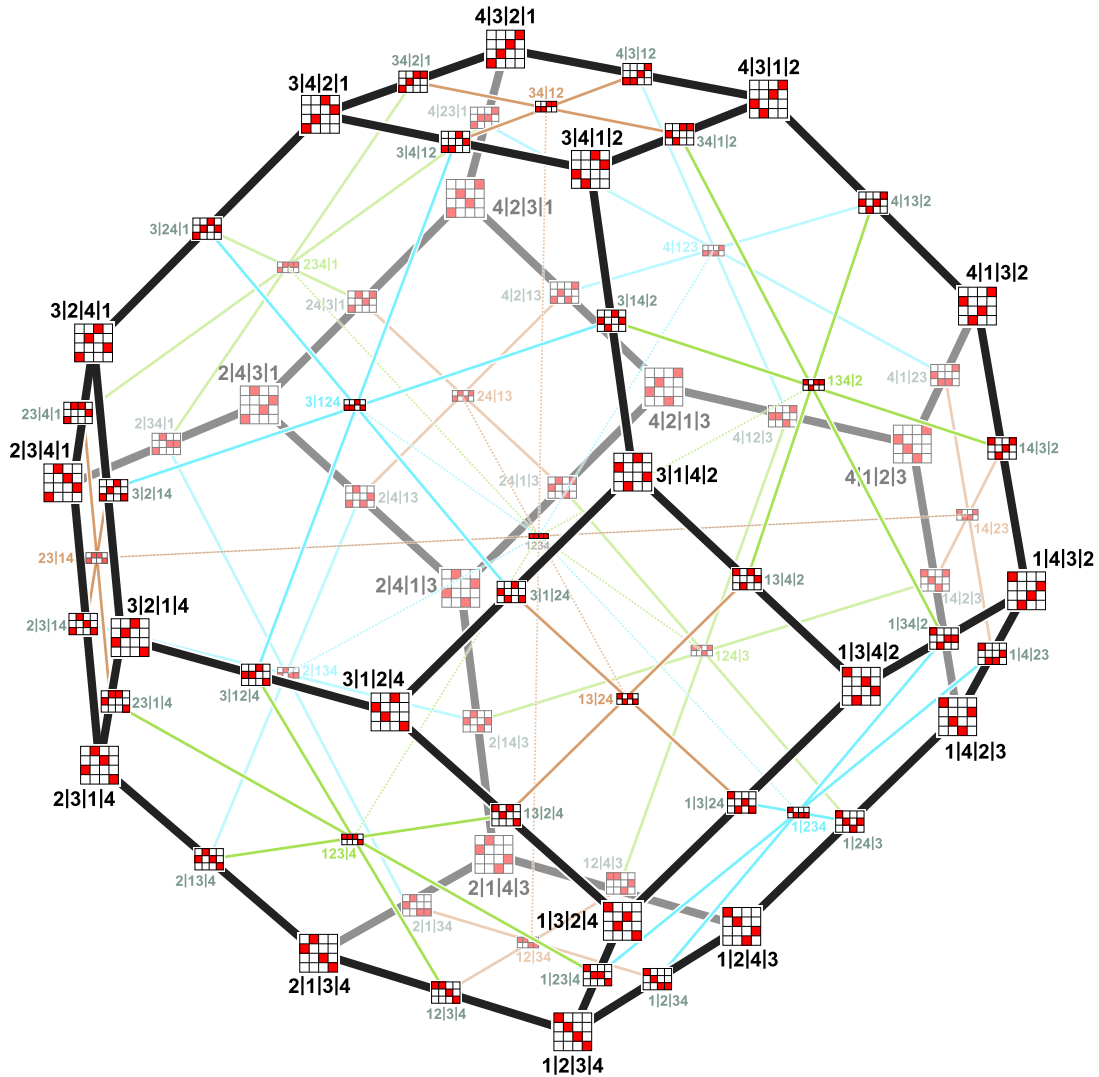
2 Permutahedron

2.1 Regular permutahedron

The permutahedron Π_n is the convex hull of the vertices $V = \{(\sigma(1), \dots, \sigma(n)) : \sigma \in S_n\}$

There is a (fancy) bijection between the flags of $[n]$ and the faces of permutahedron Π_n as shown in the picture.

Flags could be interpreted as ordered partitions. One example of the three points of view as follows:
 $F = \{\{3\}, \{1, 2, 3, 4\}\} \iff 3|124 \iff$ "the face whose vertices have a 3 in the first position and the other three are free permutations".



2.2 Generalized permutahedra

Definition (Hypersimplex). $\Delta(n, k) = \{(x_1, \dots, x_n) : x_1 + \dots + x_n = k, 0 \leq x_i \leq 1\}$

The vertices of $\Delta(n, k)$ is formed by vectors with k ones and $n - k$ zeroes.

Definition (Generalized Permutahedron). *Convex polytope with all the edges parallel to $e_i - e_j$*

Vertices of generalized permutahedron came from a subset of the vertices of $\Delta(n, k)$

Definition (Matroid polytope). *Polytope generated by the indicator vectors of the set of basis of the matroid*

3 Coxeter Groups

A Coxeter group is a finite group described by a set of generators $S = \{s_1, \dots, s_n\}$ and a function $m : S \times S \rightarrow \mathbb{N}$ with $m(s_i, s_i) = 1$ and $m(s_i, s_j) = m(s_j, s_i)$ such that the group is described with its presentation:

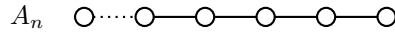
$$G = \{s_i^2 = e; (s_i s_j)^{m(s_i, s_j)} = e\}$$

We can associate every generator with a hyperplane reflection passing through the origin $s_i \leftrightarrow \rho_i$

Suppose we have two generators s_i and s_j . Then we can represent this as two lines in a plane as follows:

If the angle $\angle \rho_i \rho_j = \frac{\pi}{k}$ we have that $s_i s_j$ is a rotation of angle $\frac{2\pi}{k}$. It follows that $m(s_i, s_j) = k$.

Coxeter groups can be represented using a diagram in which each generator is a node and we connect two nodes by a labeled edge with the value of $m(s_i, s_j) \geq 3$. If $m = 3$ it is not needed to label it.



There is a correspondence with each flag selecting one variety(?) to a generator, though it is not a bijection. (define before flag and find a word for variety)

The flag is composed by a vertex, an edge containing the vertex, a 2-face containing the edge ...etc. If we focus on one variety, then the corresponding symmetry is the hyperplane ρ that fixes the lower dimension varieties and keeps invariant the higher ones. (By keep invariant I mean the subspace goes to the same subspace, not necessarily point to point, while fix is point to point)

We will see it more clearly in the next subsection.

3.1 Classification of Platonic Solids

(Probably cut this section idk) There exist 5 platonic solids. We can think all the solids in the projective space to make easier computations.

Tetrahedron A_3

Vertices are the indicator vectors of $\binom{[4]}{1}$

We have a flag $\{V_1, V_2, V_3\}$, where V_i are projective varieties that correspond to a vertex, edge and face respectively and for each V_i we have the induced hyperplane ρ_i associated with the reflection s_i . If we compute the normal vectors of the planes:

$$\rho_1^\perp = \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}, \quad \rho_2^\perp = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}, \quad \rho_3^\perp = \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix} \Rightarrow \angle \rho_1 \rho_2 = \frac{\pi}{3}, \quad \angle \rho_1 \rho_3 = \frac{\pi}{2}, \quad \angle \rho_2 \rho_3 = \frac{\pi}{3}$$

And then we deduce the diagram $\textcircled{1} \text{ --- } \textcircled{2} \text{ --- } \textcircled{3}$

Cube B_3

Octahedron B_3

Vertices are the indicator vectors of $\binom{[4]}{2}$

We have a flag $\{V_1, V_2, V_3\}$, where V_i are projective varieties that correspond to a vertex, edge and face respectively and for each V_i we have the induced hyperplane ρ_i associated with the reflection s_i . If we compute the normal vectors of the planes:

$$\rho_1^\perp = \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}, \quad \rho_2^\perp = \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix}, \quad \rho_3^\perp = \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix} \Rightarrow \angle \rho_1 \rho_2 = \frac{\pi}{3}, \quad \angle \rho_1 \rho_3 = \frac{\pi}{2}, \quad \angle \rho_2 \rho_3 = \frac{\pi}{4}$$

And then we deduce the diagram $\textcircled{1} \text{ --- } \textcircled{2} \text{ ---}^4 \textcircled{3}$

Dodecahedron H_3

Icosahedron H_3

4 Description of Coxeter Groups

4.1 Group A_n

$$\circ \longrightarrow \circ \longrightarrow \dots \longrightarrow \circ \longrightarrow \circ$$

We can think type A_n Coxeter Groups as groups generated by the reflections s_1, \dots, s_{n-1} whose associated hyperplanes are defined by

$$\rho_1^\perp = \begin{pmatrix} 1 \\ -1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \quad \rho_2^\perp = \begin{pmatrix} 0 \\ 1 \\ -1 \\ \vdots \\ 0 \end{pmatrix}, \quad \dots \quad \rho_{n-1}^\perp = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ -1 \end{pmatrix},$$

It is easy to see that the angles between the hyperplanes are

$$\angle \rho_i \rho_{i+1} = \frac{\pi}{3}, \quad \angle \rho_i \rho_j = \frac{\pi}{2} \text{ if } i - j \neq \pm 1$$

so that corresponds to the Dynkin diagram, and thus to the Coxeter group

4.2 Group B_n

$$\circ \xrightarrow{4} \circ \longrightarrow \dots \longrightarrow \circ \longrightarrow \circ$$

We can think type B_n Coxeter groups as the group generated by the reflections τ, s_1, \dots, s_n , whose associated hyperplanes are defined by

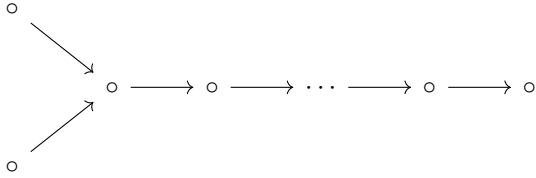
$$\rho_\tau^\perp = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \quad \rho_1^\perp = \begin{pmatrix} 1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \quad \rho_2^\perp = \begin{pmatrix} 0 \\ 1 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \quad \dots \quad \rho_n^\perp = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 1 \end{pmatrix},$$

One can check that the angles between the hyperplanes are

$$\angle \rho_\tau \rho_1 = \frac{\pi}{4}, \quad \angle \rho_\tau \rho_i = \frac{\pi}{2} \text{ if } i > 1, \quad \angle \rho_i \rho_{i+1} = \frac{\pi}{3}, \quad \angle \rho_i \rho_j = \frac{\pi}{2} \text{ if } i - j \neq \pm 1$$

so the construction correspond to the Dynkin diagram, and thus to the coxeter group.

4.3 Group D_n



We can think type D_n Coxeter groups as the group generated by the reflections $\tau_1, \tau_2, s_1, \dots, s_n$, whose associated hyperplanes are defined by

$$\rho_{\tau_1}^\perp = \begin{pmatrix} 1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \quad \rho_{\tau_2}^\perp = \begin{pmatrix} -1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \quad \rho_1^\perp = \begin{pmatrix} 0 \\ 1 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \quad \dots \quad \rho_n^\perp = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 1 \end{pmatrix},$$

One can check that the angles between the hyperplanes are

$$\angle \rho_{\tau_1} \rho_{\tau_2} = \frac{\pi}{2}, \quad \angle \rho_{\tau_1} \rho_1 = \frac{\pi}{3}, \quad \angle \rho_{\tau_2} \rho_1 = \frac{\pi}{3}, \quad \angle \rho_i \rho_{i+1} = \frac{\pi}{3}, \quad \angle \rho_i \rho_j = \frac{\pi}{2} \text{ if } i - j \neq \pm 1$$

so the construction correspond to the Dynkin diagram, and thus to the coxeter group.

5 Regular Subdivision and height functions

Given a set of points T , we define a height function as $h : T \rightarrow \mathbb{R}$.

The height function h is said to be *M-convex* if the regular subdivisions induced by h are permutahedral.

A subset S of points is a (lower) regular subdivision induced by h if the convex hull of S is described by the lower convex hull of the polytope $T \times h(T)$

Definition (3-Term Plücker Relations). *Let ω be a height function. For each $S \in \binom{[n]}{d-2}$ and $i, j, k, l \notin S$ the minimum*

$$\min(h(S_{ij}) + h(S_{kl}), h(S_{ik}) + h(S_{jl}), h(S_{il}) + h(S_{jk}))$$

is attained at least twice.

Theorem. *A height function induces a permutahedral regular division if the 3-Term Plücker Relations (3TPR) holds.*

Proof

We abbreviate $h_{ij} = h(S_{ij})$

Suppose the 3TPR holds. Given the height function h we fix a linear functional $\varphi = (\varphi_1, \dots, \varphi_n, \varphi_{n+1})$ with $\varphi_{n+1} > 0$ such that the regular division polytope $Q \subseteq P$ is given by

$$Q = \{A \in M : \varphi(A, h(A)) \text{ is minimum}\}$$

We now can relabel the indexes of the elements of Q and φ removing all the terms that are 1 or zero allways (when applying the functional the result is the same inside Q) and relabeling the remaining from 1 to m .

In the cases $m = 2$ and $m = 3$ the subpolytope Q is trivially permutahedral. For case $m \geq 4$ we pick 4 indexes i, j, k, l of elements of Q and φ .

We can assume without loss of generality that $S_{ij}, S_{kl} \in Q$ now we want to prove that exchange axiom is satisfied: i.e. without loss of generality $S_{ik}, S_{jl} \in Q$.

We can express the 3TPR in the following way:

$$3TPR \iff h_{ij} + h_{kl} = h_{ik} + h_{jl} \leq h_{il} + h_{jk}$$

The condition for S_{ij}, S_{kl} to lie in a regular subdivision is that

$$\varphi_i + \varphi_j + \varphi_{n+1}h_{ij} = \varphi_k + \varphi_l + \varphi_{n+1}h_{kl} \leq \begin{cases} \varphi_i + \varphi_k + \varphi_{n+1}h_{ik}(1) \\ \varphi_j + \varphi_l + \varphi_{n+1}h_{jl}(2) \end{cases}$$

This leads to the equations

$$\begin{aligned} \varphi_j - \varphi_k &\leq \varphi_{n+1}(h_{ik} - h_{ij}) \\ \varphi_i - \varphi_l &\leq \varphi_{n+1}(h_{lj} - h_{ij}) \\ \varphi_l - \varphi_i &\leq \varphi_{n+1}(h_{ik} - h_{kl}) \\ \varphi_k - \varphi_j &\leq \varphi_{n+1}(h_{jl} - h_{kl}) \end{aligned}$$

Summing up the equations we get

$$0 \leq 2\varphi_{n+1}(h_{ik} + h_{jl} - h_{ij} - h_{kl}) \Rightarrow h_{ij} + h_{kl} \leq h_{ik} + h_{jl}$$

But this inequality should be an equality under the assumption of 3TPR, so all the above inequalities should be equalities, and (1) and (2) implies $S_{ik}, S_{jl} \in Q$