

# KLPT TWo : Algebraic pathfinding in dimension two

(The capitalization is not a mistake)

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## Setting the frame

For the whole presentation, we fix

- A prime  $p = 3 \bmod 4$  of cryptographic size,
- A small prime  $\ell$ . Typically  $\ell \in \{2, 3\}$
- $E_0 : y^2 : x^3 + x$ , the curve with j-invariant 1728 over  $\mathbb{F}_{p^2}$ ,
- $\text{End}(E_0) \simeq \mathcal{O}_0 = \langle 1, i, \frac{i+j}{2}, \frac{1+k}{2} \rangle$ ,
- $B_{p,\infty} = \mathcal{O}_0 \otimes \mathbb{Q}$ , the underlying quaternion algebra,
- $A_0 := E_0 \times E_0$ , our base abelian surface,
- $\lambda_0$ , the (principal) product polarization of  $A_0$ .

In this presentation, **every** elliptic curve is supersingular

# Introduction : The $\ell$ -isogeny path problem

## The $\ell$ -isogeny path problem

Let  $E_1, E_2$  be two elliptic curves over  $\mathbb{F}_{p^2}$ . Let  $\ell$  be a small prime.

Compute an isogeny  $\varphi : E_1 \rightarrow E_2$  with degree  $\ell^e$ .

$$E_1 \xrightarrow{\varphi} E_2$$

Deuring  
 $\longleftrightarrow$

## The quaternion $\ell^e$ -isogeny path problem

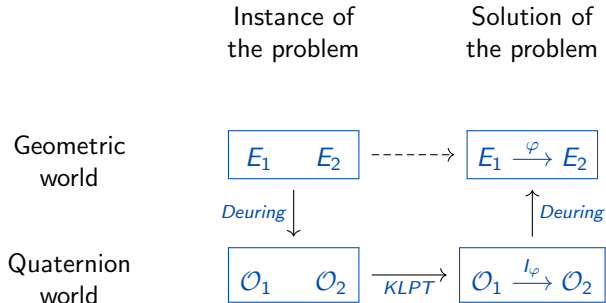
Let  $\mathcal{O}_1, \mathcal{O}_2$  be two maximal orders in the quaternion algebra  $B_{p,\infty}$ .

Compute an ideal  $I$  of norm  $\ell^e$  such that  $\mathcal{O}_L(I) \simeq \mathcal{O}_1$  and  $\mathcal{O}_R(I) \simeq \mathcal{O}_2$ .

$$\mathcal{O}_1 \xrightarrow{I} \mathcal{O}_2$$

[Isogeny Club – S1E4] : **Antonin Leroux**, *A new algorithm for the constructive Deuring correspondence: making SQISign faster*

# Overview of KLPT



## An analogue in dimension 2

- Replace the elliptic curves by *abelian surfaces*
- Replace the maximal orders by matrices
- Replace the Deuring correspondence by the Ibukiyama-Katsura-Oort correspondence.
- **Replace KLPT by KLPT2**

## Organization of the talk

1. Principally polarized superspecial abelian surfaces (Section 2.2)
2. The Ibukiyama-Katsura-Oort correspondence (Section 2.3)
3. KLPT<sup>2</sup> (Section 3)
4. Constructive IKO correspondence and applications (Sections 4 & 5)

## Act I – Understanding the objects we manipulate

Act I : Principally Polarized Superspecial Abelian Surfaces ?

## 1.1 – Abelian surfaces

### Definition (Abelian varieties)

An abelian variety is an algebraic group that can be embedded in a projective space.

It is an abstract object  $\rightsquigarrow$  scary !

### A simple classification of abelian varieties

$$\begin{aligned} \dim = 1 : & \quad E \\ \dim = 2 : & \quad \begin{cases} E_1 \times E_2 \\ \text{Jac}(H) \end{cases}, \text{ or} \\ \dim = 3 : & \quad \dots \end{aligned}$$

with  $H$  an hyperelliptic curve of genus 2

An abelian variety of dimension 2 is called an *abelian surface*.

## 1.1 – It's time to d-d-d-dual !

To any abelian variety, we canonically associate a “mirror” variety called its *dual*. Any isogeny  $\varphi : A \rightarrow B$  induces an isogeny  $\hat{\varphi}$  between the duals.

$$A \xrightarrow{\varphi} B$$

$$A^{\vee} \xleftarrow{\hat{\varphi}} B^{\vee}$$

### Definition (Dual variety)

The dual variety of  $A$  is the *Picard group*  $\text{Pic}^0(A)$ . Its elements are divisors.

### Remark

The dual isogeny  $\varphi : B^{\vee} \rightarrow A^{\vee}$  is **not** what we call a dual isogenies for elliptic curves !



## 1.2 – Supersingularity vs superspeciality

Let  $A$  be an abelian surface (a Jacobian or a product of elliptic curves).

### Supersingularity

$A$  is supersingular if it is *isogenous* to some  $E_1 \times E_2$ .

The supersingular isogeny graph

Contains infinitely many vertices.  $\times$

### Superspeciality

$A$  is superspecial if it is *isomorphic* to some  $E_1 \times E_2$ .

The superspecial isogeny graph

Contains a single vertex.  $\times$

Theorem (Deligne)

For all  $E_1, E_2, E_3, E_4$ , we have

$$E_1 \times E_2 \simeq E_3 \times E_4$$

## 1.3 – Polarizations

### Informal Definition (Polarization)

A polarization on  $A$  is an isogeny

$$\begin{array}{rcl} \lambda_D & : & A \rightarrow A^\vee \\ & & P \mapsto [t_P^*(D) - (D)] \end{array}$$

where  $D$  is an ample divisor and  $t_P^*$  is the pullback of the translation-by- $P$  map.

### Important properties of polarizations

- Not all isogenies  $A \rightarrow A^\vee$  are polarizations.
- If a polarization has degree 1, it is called *principal*.
- We write  $\text{PPol}(A)$  for the set of principal polarizations of  $A$ .

## 1.3 – Isogenies between polarized varieties

### Definition (Polarized isogeny)

Let  $(A, \lambda_A)$  and  $(B, \lambda_B)$  be two polarized varieties.

An isogeny  $\varphi : (A, \lambda_A) \rightarrow (B, \lambda_B)$  is an isogeny  $\varphi : A \rightarrow B$  between the underlying varieties such that the following diagram commutes.

$$\begin{array}{ccc} A & \xrightarrow{\varphi} & B \\ N\lambda_A \downarrow & & \downarrow \lambda_B \\ A^\vee & \xleftarrow{\hat{\varphi}} & B^\vee \end{array}$$

i.e. we have  $\hat{\varphi}\lambda_B\varphi = N\lambda_A$ , for some integer  $N$  called the *reduced degree*.

# 1 – Wrapping up

Principally polarized



$$\lambda : A \xrightarrow{\sim} A^\vee$$

Superspecial



$$A \simeq E_0 \times E_0$$

**as non-  
polarized  
variety**

Abelian Surface



$$\text{Jac}(H) \text{ or } E_1 \times E_2$$

## The polarized superspecial isogeny graph

The graph of principally polarized superspecial abelian surfaces over  $\mathbb{F}_p$  contains  $O(p^3)$  vertices. ✓

Among which we have :

- $O(p^3)$  Jacobians.
- $O(p^2)$  products of elliptic curves.

## A small sanity check

### Example 1 : $E_0$

$E_0 : y^2 = x^3 + x$ . It is a supersingular curve.

It is equipped with a canonical principal polarization

$$\begin{array}{ccc} \lambda & : & E_0 \rightarrow E_0^\vee \\ & & P \mapsto (P) - (\infty) \end{array}$$

It is the only possible polarization on  $E_0$ .

### Example 2 : $(A_0, \lambda_0)$

$A_0 = E_0^2$ . It is superspecial.

It can be equipped with a natural polarization  $\lambda_0$  called the *product polarization* inherited from  $E_0$ .

There are a lot of non-equivalent polarizations on  $A_0$ .

### Example 3 : $(A, \lambda)$

$A = \text{Jac}(H)$  for  $H/\mathbb{F}_p : y^2 = x^6 + 1$ . It is superspecial if  $p \equiv 5 \pmod{6}$ .

The equation for  $H$  implicitly induces a polarization  $\lambda$ .

### Act II : The Ibukiyama-Katsura-Oort Correspondence

$$\left\{ \begin{array}{l} \text{Abelian surfaces} \\ (A, \lambda_A) \\ \text{up to polarized} \\ \text{isomorphism} \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{Polarizations} \\ \lambda \text{ of } A_0 \\ \text{up to equivalence} \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{Matrices} \\ g \in M_2(\mathcal{O}_0) \\ \text{up to congruence} \end{array} \right\}$$

## 2.1 – From surfaces to polarizations

### Goal

Given an abelian surface  $(A, \lambda_A)$ , encode it as a polarization  $\lambda$  on  $A_0$ .

### Polarizations pullbacks

Given  $(A, \lambda_A)$ ,  $A_0$  and an **unpolarized** isomorphism  $\varphi : A_0 \rightarrow A$ , one can compute

$$\lambda = \hat{\varphi} \lambda_A \varphi$$

This is a polarization of  $A_0$ .

$$\begin{array}{ccc} A & \xleftarrow{\varphi} & A_0 \\ \lambda_A \downarrow & & \downarrow \lambda \\ A^\vee & \xrightarrow{\hat{\varphi}} & A_0^\vee \end{array}$$

[GSS25] : **Gaudry-Soumier-Spaenlehauer**, *Isogeny-based Cryptography using Isomorphisms of Superspecial Abelian Surfaces*

## 2.2 – From polarizations to matrices : Deuring for the PPol

### Goal

Given a polarization  $\lambda$  on  $A_0$ , encode it as an endomorphism of  $A_0$ .  
Then, write the endomorphism as a 2x2 matrix with quaternions coefficients.

### Step 1 :

We simply apply the map

$$\begin{array}{ccccc} \mu & : & \text{PPol}(A_0) & \rightarrow & \text{End}(A_0) \\ & & \lambda & \mapsto & \lambda_0^{-1} \lambda \end{array}$$

$$\begin{array}{c} \circlearrowleft \\ \circlearrowright \end{array} A_0 \begin{array}{c} \xrightarrow{\lambda} \\ \xleftarrow{\lambda_0^{-1}} \end{array} A_0^\vee$$

### Step 2 :

By the Deuring correspondence,  $\text{End}(A_0) = M_2(\text{End}(E_0))$  is isomorphic to  $M_2(\mathcal{O}_0)$ .



## 2.2 – From polarizations to matrices : Deuring for the PPol

The image of  $\mu$  (after translating into quaternions) is the set

$$\text{Mat}(A_0) := \left\{ \begin{pmatrix} s & r \\ \bar{r} & t \end{pmatrix}, \quad s, t \in \mathbb{Z}_{>0}, r \in \mathcal{O}_0, st - r\bar{r} = 1 \right\} \subset \text{GL}_2(\mathcal{O}_0)$$

Elements of this set will be the input of  $\text{KLPT}^2$ .

## The IKO correspondence

	Geometric world	Quaternion world
Vertices of the graph	$(A, \lambda_A)$	$g \in \text{Mat}(A_0)$
Edges of the graph	Isogenies $\varphi : (A_1, \lambda_1) \rightarrow (A_2, \lambda_2)$	Connecting matrices $u \in M_2(\mathcal{O}_0)$
Adjoint map	Adjoint isogeny $\tilde{\varphi} = \lambda_1^{-1} \hat{\varphi} \lambda_2$	Conjugate-transpose $u = \begin{pmatrix} \bar{a} & \bar{c} \\ \bar{b} & \bar{d} \end{pmatrix}$
Structure-preserving property	$\hat{\varphi} \lambda_2 \varphi = N \lambda_1$	$u^* g_2 u = N g_1$
Reduced norm	$N$	$\mathcal{N}(u)$

# The quaternion isogeny path problem in dimension 2

Recall : The 2D isogeny path problem

Compute an isogeny  $\varphi : (A_1, \lambda_1) \rightarrow (A_2, \lambda_2)$  with reduced norm  $N = \ell^e$ .

$$\begin{array}{ccc} A_1 & \xrightarrow{\varphi} & A_2 \\ N\lambda_1 \downarrow & & \downarrow \lambda_2 \\ A_1^\vee & \xleftarrow{\hat{\varphi}} & A_2^\vee \end{array}$$

## Theorem

The 2D isogeny path problem reduces to computing  $\psi \in \text{End}(A_0)$  such that the following diagram commutes

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## Theorem

The 2D isogeny path problem reduces to computing  $\psi \in \text{End}(A_0)$  such that the following diagram commutes

$$\begin{array}{ccccccc} A_1 & \xleftarrow{\varphi_1} & A_0 & \xrightarrow{\psi} & A_0 & \xrightarrow{\varphi_2} & A_2 \\ N\lambda_1 \downarrow & & \lambda_0^{-1} \uparrow \downarrow N\lambda'_1 & & \lambda'_2 \downarrow \uparrow \lambda_0^{-1} & & \downarrow \lambda_2 \\ A_1^\vee & \xrightarrow{\hat{\varphi}_1} & A_0^\vee & \xleftarrow{\hat{\psi}} & A_0^\vee & \xleftarrow{\hat{\varphi}_2} & A_2^\vee \end{array}$$

i.e. such that  $\hat{\psi}\lambda'_2\psi = N\lambda'_1$  ( $\iff \gamma^*g_2\gamma = Ng_1$ ).

We can then output  $\varphi = \varphi_2 \circ \psi \circ \varphi_1^{-1}$ .

### Act III : The $\text{KLPT}^2$ algorithm

#### Main theorem

Let  $g_1, g_2 \in \text{Mat}^0(\mathcal{O}_0)$ . There is a PPT algorithm that computes  $\gamma \in M_2(\mathcal{O}_0)$  such that

$$\gamma^* g_2 \gamma = N g_1$$

with  $N \in O(p^{25})$  is smooth.

### 3.1 – Some useful lemmas

#### Definition (Connecting matrix)

Let  $h_1, h_2, u$  be matrices in  $M_2(\mathcal{O}_0)$ .

We say that  $u$  is a connecting matrix between  $h_1$  and  $h_2$  if it satisfies

$$u^* h_2 u = \mathcal{N}(u) h_1$$

we write  $u : h_1 \rightarrow h_2$ .

#### Lemma (Inversion lemma)

If  $u : h_1 \rightarrow h_2$  is invertible in  $M_2(B_{p,\infty})$ ,  
then  $\mathcal{N}(u)u^{-1} \in M_2(\mathcal{O}_0)$  and  $\mathcal{N}(u)u^{-1} : h_2 \rightarrow h_1$ .

A commutative diagram with  $h_1$  on the left and  $h_2$  on the right. A curved arrow points from  $h_1$  to  $h_2$  and is labeled  $u$ . A curved arrow points from  $h_2$  back to  $h_1$  and is labeled  $\mathcal{N}(u)u^{-1}$ .

## 3.1 – Some useful lemmas

### Lemma (Composition lemma)

Let  $h_1, h_2, h_3, u_1, u_2$  be matrices such that

$$\begin{cases} u_1 : h_1 \rightarrow h_2 \\ u_2 : h_2 \rightarrow h_3 \end{cases}$$

Then,  $u_2 u_1 : h_1 \rightarrow h_3$ .

Proof.

This lemma comes from the fact that  $u_i : h_i \rightarrow h_{i+1}$  corresponds to the identity

$$u_i^* h_{i+1} u_i = \mathcal{N}(u_i) h_i$$

and from the multiplicativity of the reduced norm  $\mathcal{N}$ . □

$$h_1 \xrightarrow{u_1} h_2 \xrightarrow{u_2} h_3$$

## Outline of the strategy

Let  $g_1, g_2 \in \text{Mat}(A_0)$ . A solution is easily computed in the following case :

### Lemma

If  $g_1 = \begin{pmatrix} D & r_1 \\ \bar{r}_1 & t_1 \end{pmatrix}$  and  $g_2 = \begin{pmatrix} D & r_2 \\ \bar{r}_2 & t_2 \end{pmatrix}$ , for some  $D, t_1, t_2 \in \mathbb{Z}$  and  $r_1, r_2 \in \mathcal{O}_0$ , with  $\det(g_1) = \det(g_2)$ , then  $\tau := \begin{pmatrix} D & r_1 - r_2 \\ 0 & D \end{pmatrix}$  satisfies

$$\tau^* g_2 \tau = D^2 g_1$$

if  $D$  is a power of  $\ell$ , we're done.

### The high-level approach

1. Find  $u_i : h_i \rightarrow g_i$  for some  $h_i$  of the form  $\begin{pmatrix} \ell^{e_2} & r'_i \\ \bar{r}'_i & t'_i \end{pmatrix}$ , with  $\mathcal{N}(u_i) = \ell^{e_1}$ .
2. Compute  $\tau : h_1 \rightarrow h_2$ . Its norm is  $\ell^{2e_2}$ .
3. Output  $\gamma = \mathcal{N}(u_1)u_2\tau u_1^{-1}$ . Its norm is  $\ell^{2(e_1+e_2)}$ .

$$\begin{array}{ccc} & h_1 & \xrightarrow{\tau} & h_2 \\ & \swarrow u_1 & & \searrow u_2 \\ g_1 & \xrightarrow{\gamma = \mathcal{N}(u_1)u_2\tau u_1^{-1}} & & g_2 \end{array}$$



## 3.2 – Computing the $u : h \rightarrow g$

### Strategy for computing $u$

Given  $g = \begin{pmatrix} s & r' \\ \bar{r} & t \end{pmatrix} \in \text{Mat}(A_0)$ , compute  $u \in M_2(\mathcal{O}_0)$  such that

1.  $h = u^* g u$  is of the form  $\begin{pmatrix} \ell^{e_2} & r' \\ \bar{r}' & t' \end{pmatrix}$
2.  $\mathcal{N}(u) = \ell^{e_1}$
3.  $e_1$  and  $e_2$  don't depend on  $g$ .

For  $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ , an explicit computation yields

$$u^* g u = \begin{pmatrix} s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \text{tr}(\bar{c}\bar{r}a) & r' \\ \bar{r}' & s \cdot \mathbf{n}(b) + t \cdot \mathbf{n}(d) + \text{tr}(\bar{b}\bar{r}d) \end{pmatrix}$$

The top-left entry only depends on  $a$  and  $c$  !

↳ Fix  $a$  and  $c$  to satisfy 1.

↳ Fix  $b$  and  $d$  to satisfy 2.

## 3.2 – Computing the $u : h \rightarrow g$

Strategy for computing  $u$

Let  $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  and  $h := u^* g u = \begin{pmatrix} s' & r' \\ \bar{r}' & t' \end{pmatrix}$ .

1. Find  $a, c \in \mathcal{O}_0$  such that  $s'$  equals some  $\ell^{e_2}$ .  
↳ Solve a diophantine equation.

## 3.2 – Computing the $u : h \rightarrow g$

Strategy for computing  $u$

Let  $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  and  $h := u^* g u = \begin{pmatrix} s' & r' \\ \bar{r}' & t' \end{pmatrix}$ .

1. Find  $a, c \in \mathcal{O}_0$  such that  $s'$  equals some  $\ell^{e_2}$ .  
↳ Solve a diophantine equation.
2. Given  $a, c$ , find values  $b, d \in \mathcal{O}_0$  such that  $\mathcal{N}(u) = \ell^{e_1}$ .  
↳ Solve a pathfinding problem in 1D  $\rightarrow$  KLPT !

We actually start with step 2.

## Finding $b$ and $d$ : We put KLPTs in your KLPT<sup>2</sup>

Here, we assume we have  $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  with  $a$  and  $c$  fixed and with coprime norm. We want to find a pair  $(b, d) \in \mathcal{O}_0^2$  such that

$$\mathcal{N}(u) = \mathbf{n}(a)\mathbf{n}(d) + \mathbf{n}(b)\mathbf{n}(c) - \mathbf{tr}(\bar{a}b\bar{d}c)$$

Reducing the problem to a pathfinding problem in 1D

1. View  $\mathcal{O}_0^2$  as a free right  $\mathcal{O}_0$ -module of rank 2.
2. Compute Bézout's coefficients  $ua + cv = 1$ .
3. Let  $M_1 = (a, c)\mathcal{O}_0$  and  $M_2 = (u \cdot \mathbf{n}(c)a, -v \cdot \mathbf{n}(a)c)B_{p,\infty} \cap \mathcal{O}_0^2$  be two submodules.
4. Note that  $\mathcal{O}_0^2 = M_1 \oplus M_2$ .

### Theorem

The submodule  $M_2$  is isomorphic to the right  $\mathcal{O}_0$ -ideal  $I = \mathbf{n}(c)\mathcal{O}_0 + a\bar{c}\mathcal{O}_0$

## Finding $b$ and $d$ : We put KLPTs in your KLPT

The isomorphism  $f : M_2 \rightarrow I$  is a  $\mathbf{n}(c)$ -homothety.

### Finding $b$ and $d$ from KLPT1

5. Using KLPT, we can find some  $\omega \in I$  with norm  $\mathbf{n}(c)\ell^{e_0} \in O(p^3)$
6. We translate  $\omega$  into an element  $(b, d) = f^{-1}(\omega)$  of  $M_2$  with norm  $\mathbf{n}(\omega)/\mathbf{n}(c) = \ell^{e_0}$ .

The resulting matrix  $u$  has norm  $\ell^{e_1} \in O(p^6)$  and can be written as

$$u = \begin{pmatrix} a & v \cdot \mathbf{n}(c)x + v\bar{c}y \\ c & -u\bar{a}x - u \cdot \mathbf{n}(a)y \end{pmatrix}$$

where the quaternion  $\omega$  equals  $\mathbf{n}(c)x + a\bar{c}y$  and  $e_1 = 2e_0$ .

### Remark

$u$  can be rewritten as  $\begin{pmatrix} a & x \\ c & -y \end{pmatrix} \begin{pmatrix} 1 & -u\bar{a}x + v\bar{c}y \\ 0 & 1 \end{pmatrix}$ .

Since the second matrix has determinant 1, we can work with the left one only.

## 3.2 – Computing the $u : h \rightarrow g$

Strategy for computing  $u$

Let  $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  and  $h := u^* g u = \begin{pmatrix} s' & r' \\ \bar{r}' & t' \end{pmatrix}$ .

1. Find  $a, c \in \mathcal{O}_0$  such that  $s'$  equals some  $\ell^{e_2}$ .  
↳ Solve a diophantine equation.
2. Given  $a, c$ , find values  $b, d \in \mathcal{O}_0$  such that  $\mathcal{N}(u) = \ell^{e_1}$  ✓.  
↳ Solve a pathfinding problem in 1D  $\rightarrow$  KLPT !

## Finding $a$ and $c$ : Finalising the algorithm

We want to find  $a, c \in \mathcal{O}_0$  such that

$$s' := s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{c}\bar{r}a) = \ell^{e_2}$$

↳ Similar to KLPT1

### The strategy

1. Use the fact that  $\mathcal{O}_0$  contains the suborder  $\mathbb{Z} + \mathbb{Z}i + \mathbb{Z}j + \mathbb{Z}k$
2. Restrict  $a$  and  $c$  to subspaces of so the trace vanishes.
3. Fix  $c$  and use Cornacchia to compute a suitable value for  $a$ .

With some pre-processing on  $g$ , we can bound its entries and guarantee that  $s' = \ell^{e_2} \in O(p^{6.5})$  and  $\mathbf{n}(a)$  and  $\mathbf{n}(c)$  are coprime.

### 3 – Wrapping up

We showed how to compute  $u_i : h_i \rightarrow g_i$  such that

- $u_i \in \mathcal{O}_0$
- $\mathcal{N}(u_i) = \ell^{e_1} \in O(p^6)$
- $h_i = \begin{pmatrix} \ell^{e_2} & r'_i \\ \bar{r}'_i & t'_i \end{pmatrix}$  with  $\ell^{e_2} \in O(p^{6.5})$ .

The output matrix

The output  $\gamma \in \mathcal{O}_0$  of the algorithm comes from the composition

$$\begin{array}{ccccc} & h_1 & \xrightarrow{\tau} & h_2 & \\ u_1 \swarrow & & & & \searrow u_2 \\ g_1 & \xrightarrow{\gamma = \mathcal{N}(u_1) \tau u_2 u_1^{-1}} & & & g_2 \end{array}$$

Its norm is  $\mathcal{N}(\gamma) = \ell^{e_1} \cdot \ell^{e_1} \cdot \ell^{2e_2} \in O(p^{25})$ .



## Act IV – Constructive IKO Correspondence & Applications

# Act IV – Constructive IKO Correspondence & Applications

## Constructive IKO Correspondence

- Variety-to-Matrix :
  - ↳ Products of elliptic curves : [GSS25] ✓,
  - ↳ Jacobians : “Aurel knows something.”
- Isogeny-to-Matrix :
  - ↳ For (2,2)-isogenies : This work ✓
- Matrix-to-Isogeny :
  - ↳ For powersmooth degrees : [Chu21] ✓

## Applications

- Cryptanalysis of 2D CGL without trusted setup
- Relaxed constraints for isogeny representations in 2D
- A brand new SQISign2D ???

[Chu21] : **Hao-Wei Chu**, *Algorithms for abelian surfaces over finite fields and their applications to cryptography* Phd thesis

Thank you for your attention !

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**KLPT TWO**