KLPT²: Algebraic isogeny pathfinding in dimension 2

W. Castryck, T. Decru, P. Kutas, A. Laval, C. Petit, Y.B. Ti

September 12, 2025

Definition (Elliptic curve)

An elliptic curve E over a field \mathbb{F}_q is the set of solution of a cubic equation, with a special *point at infinity*.

$$E = \left\{ y^2 = x^3 + ax + b, \quad x, y \in \overline{\mathbb{F}}_q \right\} \cup \{\infty\}$$

with $a, b \in \mathbb{F}_q$ and $4a^3 + 27b^2 \neq 0$.

Definition (Elliptic curve)

An elliptic curve E over a field \mathbb{F}_q is the set of solution of a cubic equation, with a special *point at infinity*.

$$E = \{y^2 = x^3 + ax + b, \quad x, y \in \overline{\mathbb{F}}_q\} \cup \{\infty\}$$

with $a, b \in \mathbb{F}_q$ and $4a^3 + 27b^2 \neq 0$.

E is the elliptic curve; $E(\mathbb{F}_q)$ is the set of rational points over K.

 $E(\mathbb{F}_q)$ is an abelian group. Its neutral element is ∞ .

Definition (Elliptic curve)

An elliptic curve E over a field \mathbb{F}_q is the set of solution of a cubic equation, with a special *point at infinity*.

$$E = \{y^2 = x^3 + ax + b, \quad x, y \in \overline{\mathbb{F}}_q\} \cup \{\infty\}$$

with $a, b \in \mathbb{F}_q$ and $4a^3 + 27b^2 \neq 0$.

E is the elliptic curve; $E(\mathbb{F}_q)$ is the set of rational points over K.

 $E(\mathbb{F}_q)$ is an abelian group. Its neutral element is ∞ .

Example

Let's take $E: y^2 = x^3 + 1$ over \mathbb{F}_5 . It has 6 rational points :

$$E(\mathbb{F}_5) = \{(0,1), (0,4), (2,2), (2,3), (4,0), \infty\}$$

Definition (Isogeny)

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_q .

Definition (Isogeny)

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_q .

An isogeny $\varphi: E_1 \to E_2$ is a group homomorphism with finite kernel.

Definition (Isogeny)

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_q . An isogeny $\varphi: E_1 \to E_2$ is a group homomorphism with finite kernel.

It can be represented with rational maps.

Definition (Isogeny)

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_q .

An isogeny $\varphi: E_1 \to E_2$ is a group homomorphism with finite kernel.

It can be represented with rational maps.

The degree of a (separable) isogeny is the size of it kernel.

Definition (Isogeny)

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_q .

An isogeny $\varphi: E_1 \to E_2$ is a group homomorphism with finite kernel.

It can be represented with rational maps.

The degree of a (separable) isogeny is the size of it kernel.

Example

Over \mathbb{F}_5 , we take :

$$\begin{cases} E_1 : y^2 = x^3 + 1 \\ E_2 : y^2 = x^3 + 2 \end{cases}$$

Definition (Isogeny)

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_q .

An isogeny $\varphi: E_1 \to E_2$ is a group homomorphism with finite kernel.

It can be represented with rational maps.

The degree of a (separable) isogeny is the size of it kernel.

Example

Over \mathbb{F}_5 , we take :

$$\begin{cases} E_1 : y^2 = x^3 + 1 \\ E_2 : y^2 = x^3 + 2 \end{cases}$$

We can consider the isogeny $\varphi: E_1 \to E_2$ given by the map

$$\varphi: (x,y) \mapsto \left(\frac{x^2 + x - 2}{x + 1}, \frac{x^2 + 2x - 2}{x^2 + 2x + 1}y\right)$$

Definition (Isogeny)

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_q .

An isogeny $\varphi: E_1 \to E_2$ is a group homomorphism with finite kernel.

It can be represented with rational maps.

The degree of a (separable) isogeny is the size of it kernel.

Example

Over \mathbb{F}_5 , we take :

$$\begin{cases} E_1 : y^2 = x^3 + 1 \\ E_2 : y^2 = x^3 + 2 \end{cases}$$

We can consider the isogeny $\varphi: E_1 \to E_2$ given by the map

$$\varphi: (x,y) \mapsto \left(\frac{x^2 + x - 2}{x + 1}, \frac{x^2 + 2x - 2}{x^2 + 2x + 1}y\right)$$

The kernel of φ is $\{(4,0),\infty\} \leftrightarrow \deg(\varphi) = 2$.

Isogeny graphs

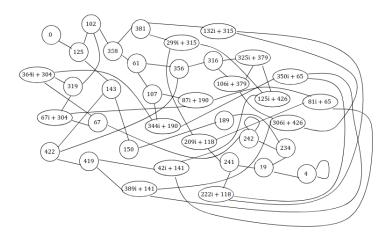


Figure: The ℓ -isogeny graph over $\mathbb{F}_{p^2} \simeq \mathbb{F}_p[i]$, for p = 431 and $\ell = 2$.

[Cos19]: Costello, SIKE for beginners

Definition (The quaternion algebra ramified at p and ∞)

We will make use of the quaternion algebra $B_{p,\infty}$ defined as :

$$B_{p,\infty} = \mathbb{Q} + i\mathbb{Q} + j\mathbb{Q} + k\mathbb{Q}$$

with
$$i^2 = -1$$
, $j^2 = -p$, $ij = -ji$.

Definition (The quaternion algebra ramified at p and ∞)

We will make use of the quaternion algebra $B_{p,\infty}$ defined as :

$$B_{p,\infty} = \mathbb{Q} + i\mathbb{Q} + j\mathbb{Q} + k\mathbb{Q}$$

with
$$i^2 = -1$$
, $j^2 = -p$, $ij = -ji$.

We can define "rings of integers" for this algebra :

Definition (The quaternion algebra ramified at p and ∞)

We will make use of the quaternion algebra $B_{p,\infty}$ defined as :

$$B_{p,\infty} = \mathbb{Q} + i\mathbb{Q} + j\mathbb{Q} + k\mathbb{Q}$$

with
$$i^2 = -1$$
, $j^2 = -p$, $ij = -ji$.

We can define "rings of integers" for this algebra :

Definition (Order of an algebra)

Definition (The quaternion algebra ramified at p and ∞)

We will make use of the quaternion algebra $B_{p,\infty}$ defined as :

$$B_{\rho,\infty} = \mathbb{Q} + i\mathbb{Q} + j\mathbb{Q} + k\mathbb{Q}$$

with
$$i^2 = -1$$
, $j^2 = -p$, $ij = -ji$.

We can define "rings of integers" for this algebra :

Definition (Order of an algebra)

An order \mathcal{O} of $B_{p,\infty}$ is a full-rank lattice in B that is also a ring.

Definition (The quaternion algebra ramified at p and ∞)

We will make use of the quaternion algebra $B_{p,\infty}$ defined as :

$$B_{p,\infty} = \mathbb{Q} + i\mathbb{Q} + j\mathbb{Q} + k\mathbb{Q}$$

with
$$i^2 = -1$$
, $j^2 = -p$, $ij = -ji$.

We can define "rings of integers" for this algebra :

Definition (Order of an algebra)

An order \mathcal{O} of $\mathcal{B}_{p,\infty}$ is a full-rank lattice in \mathcal{B} that is also a ring. An order is called *maximal* if not contained in any other order.

Definition (The quaternion algebra ramified at p and ∞)

We will make use of the quaternion algebra $B_{p,\infty}$ defined as :

$$B_{p,\infty} = \mathbb{Q} + i\mathbb{Q} + j\mathbb{Q} + k\mathbb{Q}$$

with
$$i^2 = -1$$
, $j^2 = -p$, $ij = -ji$.

We can define "rings of integers" for this algebra :

Definition (Order of an algebra)

An order \mathcal{O} of $\mathcal{B}_{p,\infty}$ is a full-rank lattice in \mathcal{B} that is also a ring. An order is called *maximal* if not contained in any other order.

Example

$$\mathcal{O} = \mathbb{Z} + i\mathbb{Z} + j\mathbb{Z} + k\mathbb{Z}$$
 is an order.

Definition (The quaternion algebra ramified at p and ∞)

We will make use of the quaternion algebra $B_{p,\infty}$ defined as :

$$B_{p,\infty} = \mathbb{Q} + i\mathbb{Q} + j\mathbb{Q} + k\mathbb{Q}$$

with
$$i^2 = -1$$
, $j^2 = -p$, $ij = -ji$.

We can define "rings of integers" for this algebra :

Definition (Order of an algebra)

An order \mathcal{O} of $\mathcal{B}_{p,\infty}$ is a full-rank lattice in \mathcal{B} that is also a ring. An order is called *maximal* if not contained in any other order.

Example

$$\mathcal{O} = \mathbb{Z} + i\mathbb{Z} + j\mathbb{Z} + k\mathbb{Z}$$
 is an order.

$$\mathcal{O}_0 = \mathbb{Z} + i\mathbb{Z} + \frac{i+j}{2}\mathbb{Z} + \frac{1+k}{2}\mathbb{Z}$$
 is a maximal order.

The Deuring Correspondence in one slide

Theorem (Deuring)

```
Isomorphism classes of (supersingular) elliptic curves over \mathbb{F}_{p^2} and their isogenies \left\{\begin{array}{l} \text{2-to-1} \\ \text{and their connecting ideals} \end{array}\right\}
```

The Deuring Correspondence in one slide

Theorem (Deuring)

$$\left\{ \begin{array}{c} \text{Isomorphism classes of} \\ \text{(supersingular) elliptic curves} \\ \text{over } \mathbb{F}_{p^2} \text{ and their isogenies} \end{array} \right\} \stackrel{\text{2-to-1}}{\longleftrightarrow} \left\{ \begin{array}{c} \text{Maximal orders of } B_{p,\infty} \\ \text{and their connecting ideals} \end{array} \right\}$$

$$\stackrel{-1}{\rightarrow} \left\{ \begin{array}{c} \text{Maximal orders of } B_{p,\infty} \\ \text{and their connecting ideals} \end{array} \right.$$

The canonical example

Take
$$E_0: y^2 = x^3 + x$$
 over \mathbb{F}_{p^2} , with $p = 3 \mod 4$.

Then, we have

$$\begin{array}{rcl} \mathsf{End}(E_0) & = & \mathbb{Z} + \iota \mathbb{Z} + \frac{\iota + \pi}{2} \mathbb{Z} + \frac{1 + \pi \iota}{2} \mathbb{Z} \\ \mathbb{I}^2 & \mathcal{O}_0 & = & \mathbb{Z} + i \mathbb{Z} + \frac{i + j}{2} \mathbb{Z} + \frac{1 + k}{2} \mathbb{Z} \end{array}$$

Through the Deuring correspondence, we manipulate $\operatorname{End}(E)$ with quaternions. But why do we care so much about $\operatorname{End}(E)$, to begin with ?

Through the Deuring correspondence, we manipulate $\operatorname{End}(E)$ with quaternions. But why do we care so much about $\operatorname{End}(E)$, to begin with ?

Motivating fact

 $\operatorname{End}(E) \simeq \mathcal{O}$ is a non-commutative ring.

■ Its elements correspond to endomorphisms.

Through the Deuring correspondence, we manipulate $\operatorname{End}(E)$ with quaternions. But why do we care so much about $\operatorname{End}(E)$, to begin with ?

Motivating fact

 $\operatorname{End}(E) \simeq \mathcal{O}$ is a non-commutative ring.

- Its elements correspond to endomorphisms.
- Its *left (fractionnal) ideals* correspond to isogenies with domain *E*.

Through the Deuring correspondence, we manipulate $\operatorname{End}(E)$ with quaternions. But why do we care so much about $\operatorname{End}(E)$, to begin with ?

Motivating fact

 $\operatorname{End}(E) \simeq \mathcal{O}$ is a non-commutative ring.

- Its elements correspond to endomorphisms.
- Its *left (fractionnal) ideals* correspond to isogenies with domain *E*.
- Its right (fractionnal) ideals correspond to isogenies with codomain *E*.

Through the Deuring correspondence, we manipulate $\operatorname{End}(E)$ with quaternions. But why do we care so much about $\operatorname{End}(E)$, to begin with ?

Motivating fact

 $\operatorname{End}(E) \simeq \mathcal{O}$ is a non-commutative ring.

- Its elements correspond to endomorphisms.
- Its *left (fractionnal) ideals* correspond to isogenies with domain *E*.
- Its right (fractionnal) ideals correspond to isogenies with codomain *E*.

Knowing $End(E) \rightsquigarrow Knowing everything about E$.

[Wes21]: Benjamin Wesolowski, The supersingular path and endomorphism ring problems are equivalent

Example

1. Fix $\varphi: E_1 \to E_2$

Example

- 1. Fix $\varphi: E_1 \to E_2$
- 2. Define $I_{\varphi} := \operatorname{Hom}(E_2, E_1)\varphi$

Example

- 1. Fix $\varphi: E_1 \to E_2$
- 2. Define $I_{\varphi} := \text{Hom}(E_2, E_1)\varphi$

- \blacksquare I_{φ} is a left-ideal of $\operatorname{End}(E_1)$
- I_{φ} is a right-ideal of End(E_2) (as $I_{\varphi} = \varphi \operatorname{Hom}(E_2, E_1)$).



Example

- 1. Fix $\varphi: E_1 \to E_2$
- 2. Define $I_{\varphi} := \operatorname{Hom}(E_2, E_1)\varphi$

- \blacksquare I_{φ} is a left-ideal of $\operatorname{End}(E_1)$
- I_{φ} is a right-ideal of End(E_2) (as $I_{\varphi} = \varphi \operatorname{Hom}(E_2, E_1)$).



Definition (Connecting ideal)

A connecting ideal $I: \mathcal{O}_1 \to \mathcal{O}_2$ between two maximal orders is an ideal that is a left-order of \mathcal{O}_1 and a right-order of \mathcal{O}_2 .

$$\mathcal{O}_1 \stackrel{I}{\longrightarrow} \mathcal{O}_2$$

The Kohel-Lauter-Petit-Tignol paradigm

Translating the ℓ-isogeny path problem

The ℓ-isogeny path problem

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_{p^2} . Let ℓ be a small prime.

Compute an isogeny $\varphi: E_1 \to E_2$ with degree ℓ^e .

$$E_1 \stackrel{\varphi}{\longrightarrow} E_2$$

The quaternion ℓ -isogeny path problem

Let $\mathcal{O}_1, \mathcal{O}_2$ be two maximal orders in the quaternion algebra $\mathcal{B}_{p,\infty}$.

Compute an ideal I of norm ℓ^e that connects \mathcal{O}_1 to \mathcal{O}_2 .

$$\mathcal{O}_1 \stackrel{l}{\longrightarrow} \mathcal{O}_2$$

Translating the ℓ -isogeny path problem

The ℓ -isogeny path problem

Let E_1 , E_2 be two elliptic curves over \mathbb{F}_{p^2} . Let ℓ be a small prime.

Compute an isogeny $\varphi: E_1 \to E_2$ with degree ℓ^e .

$$E_1 \stackrel{\varphi}{\longrightarrow} E_2$$



The quaternion ℓ -isogeny path problem

Let $\mathcal{O}_1, \mathcal{O}_2$ be two maximal orders in the quaternion algebra $\mathcal{B}_{p,\infty}$.

Compute an ideal I of norm ℓ^e that connects \mathcal{O}_1 to \mathcal{O}_2 .

$$\mathcal{O}_1 \stackrel{l}{\longrightarrow} \mathcal{O}_2$$

[Isogeny Club – S1E4]: **Antonin Leroux**, A new algorithm for the constructive Deuring correspondence: making SQISign faster

Kohel-Lauter-Petit-Tignol (2014)

Instance of the problem

Solution of the problem

Geometric world

$$E_1$$
 E_2

$$E_1 \stackrel{\varphi}{\longrightarrow} E_2$$

Kohel-Lauter-Petit-Tignol (2014)

Instance of the problem

Solution of the problem

Geometric world

$$E_1$$
 E_2

$$E_1 \stackrel{\varphi}{\longrightarrow} E_2$$

Quaternion world

Kohel-Lauter-Petit-Tignol (2014)

Instance of the problem

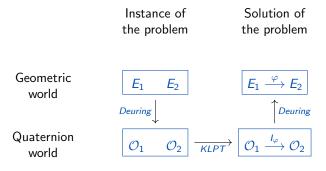
Solution of the problem

Geometric world

$$E_1 \stackrel{\varphi}{\longrightarrow} E_2$$

Quaternion world

$$\mathcal{O}_1$$
 \mathcal{O}_2

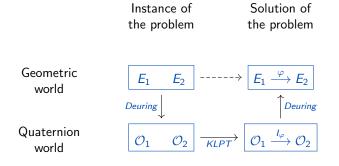


Instance of the problem Solution of the problem $E_1 \quad E_2 \quad ----- \quad E_1 \stackrel{\varphi}{\longrightarrow} E_2$

Geometric world

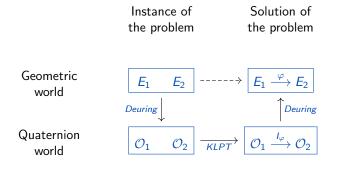
Quaternion world

 $\begin{array}{c|c}
\text{Deuring} & & \uparrow \text{Deuring} \\
\hline
\mathcal{O}_1 & \mathcal{O}_2 & \xrightarrow{\text{KLPT}} & \mathcal{O}_1 \xrightarrow{I_{\varphi}} \mathcal{O}_2
\end{array}$



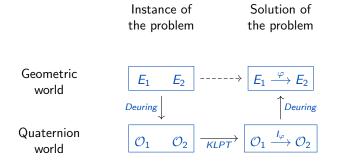
How does KLPT work?

1. We start with a bad ideal I connecting \mathcal{O}_1 to \mathcal{O}_2 .



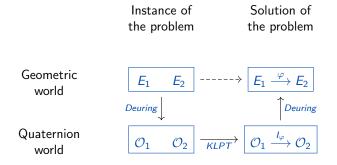
How does KLPT work?

- 1. We start with a bad ideal I connecting \mathcal{O}_1 to \mathcal{O}_2 .
- 2. We find an element $\alpha \in I$ with smooth (reduced) norm.



How does KLPT work?

- 1. We start with a bad ideal I connecting \mathcal{O}_1 to \mathcal{O}_2 .
- 2. We find an element $\alpha \in I$ with smooth (reduced) norm.
- 3. We output $I\alpha$. It still connect \mathcal{O}_1 to \mathcal{O}_2 and has smooth norm.



How does KLPT work?

- 1. We start with a bad ideal I connecting \mathcal{O}_1 to \mathcal{O}_2 .
- 2. We find an element $\alpha \in I$ with smooth (reduced) norm.
- 3. We output $I\alpha$. It still connect \mathcal{O}_1 to \mathcal{O}_2 and has smooth norm.

It requires the knowledge of $End(E_1)$ and $End(E_2)$!

We want an analogue in dimension 2!

Instance of the problem

Solution of the problem

Geometric world

$$(A_1,\lambda_1)$$
 (A_2,λ_2)

$$(A_1,\lambda_1)\stackrel{arphi}{\longrightarrow} (A_2,\lambda_2)$$

- ullet (A_1, λ_1) and (A_2, λ_2) are principally polarized superspecial abelian surfaces.
- → analogue of supersingular elliptic curves in dimension 2.

Instance of the problem

Solution of the problem

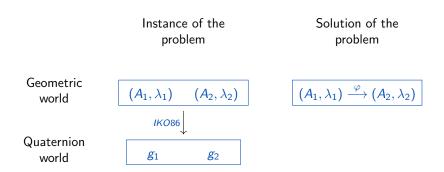
Geometric world

$$(A_1,\lambda_1)$$
 (A_2,λ_2)

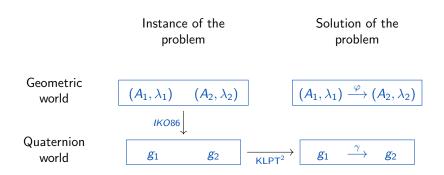
$$(A_1,\lambda_1) \stackrel{arphi}{\longrightarrow} (A_2,\lambda_2)$$

Quaternion world

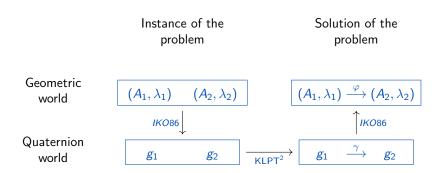
- (A_1, λ_1) and (A_2, λ_2) are principally polarized superspecial abelian surfaces.
- → analogue of supersingular elliptic curves in dimension 2.



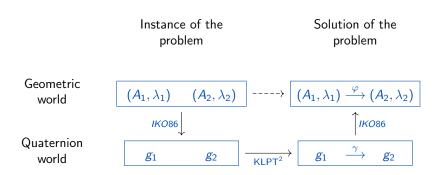
- (A_1, λ_1) and (A_2, λ_2) are principally polarized superspecial abelian surfaces.
- → analogue of supersingular elliptic curves in dimension 2.
- g_1, g_2 are matrices encoding the abelian surfaces.



- ullet (A_1, λ_1) and (A_2, λ_2) are principally polarized superspecial abelian surfaces.
- → analogue of supersingular elliptic curves in dimension 2.
- g_1, g_2 are matrices encoding the abelian surfaces.
- ullet γ is a matrix encoding an isogeny.



- (A_1, λ_1) and (A_2, λ_2) are principally polarized superspecial abelian surfaces.
- → analogue of supersingular elliptic curves in dimension 2.
- g_1, g_2 are matrices encoding the abelian surfaces.
- ullet γ is a matrix encoding an isogeny.



- (A_1, λ_1) and (A_2, λ_2) are principally polarized superspecial abelian surfaces.
- → analogue of supersingular elliptic curves in dimension 2.
- g_1, g_2 are matrices encoding the abelian surfaces.
- ullet γ is a matrix encoding an isogeny.

Setting the frame

For everything that follows, we fix

- A prime $p = 3 \mod 4$ of cryptographic size,
- A small prime ℓ . Typically $\ell \in \{2,3\}$
- $E_0: y^2: x^3 + x$, the curve with j-invariant 1728 over \mathbb{F}_{p^2} ,
- End(E_0) $\simeq \mathcal{O}_0 = \mathbb{Z} + i\mathbb{Z} + \frac{i+j}{2}\mathbb{Z} + \frac{1+k}{2}\mathbb{Z}$,
- $B_{p,\infty} = \mathcal{O}_0 \otimes \mathbb{Q}$, the underlying quaternion algebra,
- Let x be a quaternion. Its norm is $\mathbf{n}(x)$, its trace is $\mathbf{tr}(x)$.

KLPT in dimension 2

Quaternion path problem in dimension 2

Given $g_1, g_2 \in \mathsf{Mat}(\mathcal{O}_0)$, find $\gamma \in \mathsf{M}_2(\mathcal{O}_0)$ such that :

$$\gamma^* g_2 \gamma = \ell^n g_1$$

for some small prime ℓ and with :

$$\quad \mathsf{Mat}(\mathcal{O}_0) = \left\{ \begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}, \quad s,t \in \mathbb{Z}_>, st - \mathsf{n}(r) = 1 \right\}.$$

$$\blacksquare$$
 $-^*: \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mapsto \begin{pmatrix} \overline{a} & \overline{c} \\ \overline{b} & \overline{d} \end{pmatrix}$ is the conjugate-transpose.

KLPT in dimension 2

Quaternion path problem in dimension 2

Given $g_1, g_2 \in \mathsf{Mat}(\mathcal{O}_0)$, find $\gamma \in \mathsf{M}_2(\mathcal{O}_0)$ such that :

$$\gamma^* g_2 \gamma = \ell^n g_1$$

for some small prime ℓ and with :

$$\quad \mathsf{Mat}(\mathcal{O}_0) = \left\{ \begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}, \quad s,t \in \mathbb{Z}_>, st - \mathsf{n}(r) = 1 \right\}.$$

$$\blacksquare$$
 $-^*: \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mapsto \begin{pmatrix} \overline{a} & \overline{c} \\ \overline{b} & \overline{d} \end{pmatrix}$ is the conjugate-transpose.

Theorem (KLPT2)

This problem can be solved in polynomial time with output norm $\ell^n = O(p^{25})$.

Some useful lemmas

Definition (Connecting matrix)

Let $h_1, h_2 \in Mat(A_0)$ and $u \in M_2(\mathcal{O}_0)$.

We say that u is a connecting matrix between h_1 and h_2 if it satisfies

$$u^*h_2u=\mathcal{N}(u)h_1$$

for some integer $\mathcal{N}(u)$ called its norm.

We write $u: h_1 \rightarrow h_2$.

Some useful lemmas

Definition (Connecting matrix)

Let $h_1, h_2 \in Mat(A_0)$ and $u \in M_2(\mathcal{O}_0)$.

We say that u is a connecting matrix between h_1 and h_2 if it satisfies

$$u^* h_2 u = \mathcal{N}(u) h_1$$

for some integer $\mathcal{N}(u)$ called its norm.

We write $u: h_1 \rightarrow h_2$.

Lemma (Inversion lemma)

If $u: h_1 \to h_2$ is invertible in $\mathsf{M}_2(B_{p,\infty})$, then $\mathcal{N}(u)u^{-1} \in \mathsf{M}_2(\mathcal{O}_0)$ and $\mathcal{N}(u)u^{-1}: h_2 \to h_1$.

$$h_1 \underbrace{\overset{u}{\swarrow}}_{\mathcal{N}(u)u^{-1}} h_2$$

Some useful lemmas

Lemma (Composition lemma)

Let h_1, h_2, h_3, u_1, u_2 be matrices such that

$$\left\{
\begin{array}{l}
u_1:h_1\to h_2\\ u_2:h_2\to h_3
\end{array}\right.$$

Then, $u_1u_2: h_1 \rightarrow h_3$.

$$h_1 \xrightarrow{u_1} h_2 \xrightarrow{u_2} h_3$$

The inputs of the algorithm

Two matrices
$$g_1 = \begin{pmatrix} s_1 & r_1 \\ \overline{r}_1 & t_1 \end{pmatrix}$$
 and $g_2 = \begin{pmatrix} s_2 & r_2 \\ \overline{r}_2 & t_2 \end{pmatrix}$.

The strategy

 g_1 g_2

The inputs of the algorithm

Two matrices
$$g_1=\begin{pmatrix} s_1 & r_1 \ \overline{r}_1 & t_1 \end{pmatrix}$$
 and $g_2=\begin{pmatrix} s_2 & r_2 \ \overline{r}_2 & t_2 \end{pmatrix}$.

The strategy

 \blacksquare We note that if the inputs have a certain shape, there exists a connecting matrix τ between them.

$$g_1 \qquad \begin{pmatrix} \ell^f & r_1' \\ \overline{r}_1' & t_1' \end{pmatrix} \stackrel{\tau}{\longrightarrow} \begin{pmatrix} \ell^f & r_2' \\ \overline{r}_2' & t_2' \end{pmatrix} \qquad g_2$$

The inputs of the algorithm

Two matrices
$$g_1 = \begin{pmatrix} s_1 & r_1 \\ \bar{r}_1 & t_1 \end{pmatrix}$$
 and $g_2 = \begin{pmatrix} s_2 & r_2 \\ \bar{r}_2 & t_2 \end{pmatrix}$.

The strategy

- We note that if the inputs have a certain shape, there exists a connecting matrix τ between them.
- We transform our inputs so they have the aforementioned shape.

$$g_1 \xrightarrow{\ u_1 \ } \begin{pmatrix} \ell^f & r_1' \\ \overline{r}_1' & t_1' \end{pmatrix} \xrightarrow{\ \tau \ } \begin{pmatrix} \ell^f & r_2' \\ \overline{r}_2' & t_2' \end{pmatrix} \xleftarrow{\ u_2 \ } g_2$$

The inputs of the algorithm

Two matrices
$$g_1 = \begin{pmatrix} s_1 & r_1 \\ \bar{r}_1 & t_1 \end{pmatrix}$$
 and $g_2 = \begin{pmatrix} s_2 & r_2 \\ \bar{r}_2 & t_2 \end{pmatrix}$.

The strategy

- \blacksquare We note that if the inputs have a certain shape, there exists a connecting matrix au between them.
- We transform our inputs so they have the aforementioned shape.
- We output the product of the three connecting matrices.

$$g_1 \stackrel{u_1}{\longrightarrow} \begin{pmatrix} \ell^f & r_1' \\ \overline{r}_1' & t_1' \end{pmatrix} \stackrel{\tau}{\longrightarrow} \begin{pmatrix} \ell^f & r_2' \\ \overline{r}_2' & t_2' \end{pmatrix} \stackrel{u_2}{\longleftarrow} g_2$$

The output of the algorithm

The composition
$$\gamma := u_1 \cdot \tau \cdot \mathcal{N}(u_2)u_2^{-1}$$
.

The norm of γ is $\mathcal{N}(u_1)\mathcal{N}(u_2)\mathcal{N}(\tau)$.

Connecting matrices between special inputs

Lemma (Step 1: Connecting special matrices)

Let
$$h_1=\begin{pmatrix}\ell^f&r_1'\\ \overline{r}_1'&t_1'\end{pmatrix}$$
 and $h_2=\begin{pmatrix}\ell^f&r_2'\\ \overline{r}_2'&t_2'\end{pmatrix}$ be two "input" matrices such that $\det(h_1)=\det(h_2)$.

Connecting matrices between special inputs

Lemma (Step 1: Connecting special matrices)

Let
$$h_1=\begin{pmatrix}\ell^f&r_1'\\ \bar{r}_1'&t_1'\end{pmatrix}$$
 and $h_2=\begin{pmatrix}\ell^f&r_2'\\ \bar{r}_2'&t_2'\end{pmatrix}$ be two "input" matrices such that $\det(h_1)=\det(h_2)$.

Then, there exists $\tau \in M_2(\mathcal{O}_0)$ connecting h_1 to h_2 .

Connecting matrices between special inputs

Lemma (Step 1: Connecting special matrices)

Let
$$h_1 = \begin{pmatrix} \ell^f & r_1' \\ \overline{r}_1' & t_1' \end{pmatrix}$$
 and $h_2 = \begin{pmatrix} \ell^f & r_2' \\ \overline{r}_2' & t_2' \end{pmatrix}$ be two "input" matrices such that $\det(h_1) = \det(h_2)$.

Then, there exists $\tau \in M_2(\mathcal{O}_0)$ connecting h_1 to h_2 .

Proof.

Take
$$\tau = \begin{pmatrix} \ell^f & r_1 - r_2 \\ 0 & \ell^f \end{pmatrix}$$
.



Analyzing the constraints

Let us write

$$u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad g = \begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}, \quad h = \begin{pmatrix} s' & r' \\ \overline{r}' & t' \end{pmatrix} = u^*gu$$

Analyzing the constraints

Let us write

$$u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad g = \begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}, \quad h = \begin{pmatrix} s' & r' \\ \overline{r}' & t' \end{pmatrix} = u^*gu$$

We have two constraints to satisfy:

1. The top-left entry of h must be of the form ℓ^f : $s' = s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) \rightsquigarrow$ only depends on a and c.

Analyzing the constraints

Let us write

$$u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad g = \begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}, \quad h = \begin{pmatrix} s' & r' \\ \overline{r}' & t' \end{pmatrix} = u^*gu$$

We have two constraints to satisfy:

- 1. The top-left entry of h must be of the form ℓ^f : $s' = s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) \rightsquigarrow$ only depends on a and c.
- 2. The norm of u must be of the form ℓ^e : $\mathcal{N}(u) = \mathbf{n}(a)\mathbf{n}(b) + \mathbf{n}(c)\mathbf{n}(d) \mathbf{tr}(\bar{a}b\bar{d}c) \rightsquigarrow$ depends on all variables.

Analyzing the constraints

Let us write

$$u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad g = \begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}, \quad h = \begin{pmatrix} s' & r' \\ \overline{r}' & t' \end{pmatrix} = u^*gu$$

We have two constraints to satisfy:

- 1. The top-left entry of h must be of the form ℓ^f : $s' = s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) \rightsquigarrow$ only depends on a and c.
- 2. The norm of u must be of the form ℓ^e : $\mathcal{N}(u) = \mathbf{n}(a)\mathbf{n}(b) + \mathbf{n}(c)\mathbf{n}(d) \mathbf{tr}(\bar{a}b\bar{d}c) \rightsquigarrow$ depends on all variables.

We fix a and c such that the first constraint is satisfied, Given a and c, we find b and d such that the second constraint is satisfied.

We want to solve :

$$s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) = \ell^f$$

for
$$a, c \in \mathcal{O} = \mathbb{Z} + i\mathbb{Z} + j\mathbb{Z} + k\mathbb{Z} = \mathbb{Z}[i] + j\mathbb{Z}[i]$$
.

We want to solve :

$$s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) = \ell^f$$

for $a, c \in \mathcal{O} = \mathbb{Z} + i\mathbb{Z} + j\mathbb{Z} + k\mathbb{Z} = \mathbb{Z}[i] + j\mathbb{Z}[i].$

1. Restrict $a \in \mathbb{Z}[i]$, $c \in \bar{r}j\mathbb{Z}[i] \rightsquigarrow$ the trace vanishes.

We want to solve :

$$s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) = \ell^f$$
 for $a, c \in \mathcal{O} = \mathbb{Z} + i\mathbb{Z} + j\mathbb{Z} + k\mathbb{Z} = \mathbb{Z}[i] + i\mathbb{Z}[i]$.

- 1. Restrict $a \in \mathbb{Z}[i]$, $c \in \overline{r}j\mathbb{Z}[i] \rightsquigarrow$ the trace vanishes.
- 2. Write $a = a_1 + a_2 i$ and $c = \overline{r} j(c_1 + c_2 i)$. Then, $\mathbf{n}(a) = a_1^2 + a_2^2$ and $\mathbf{n}(c) = p\mathbf{n}(r)(c_1^2 + c_2^2)$.

We want to solve :

$$s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) = \ell^f$$
 for $a, c \in \mathcal{O} = \mathbb{Z} + i\mathbb{Z} + j\mathbb{Z} + k\mathbb{Z} = \mathbb{Z}[i] + i\mathbb{Z}[i]$.

- 1. Restrict $a \in \mathbb{Z}[i]$, $c \in \overline{r}j\mathbb{Z}[i] \rightsquigarrow$ the trace vanishes.
- 2. Write $a = a_1 + a_2 i$ and $c = \overline{r} j(c_1 + c_2 i)$. Then, $\mathbf{n}(a) = a_1^2 + a_2^2$ and $\mathbf{n}(c) = p\mathbf{n}(r)(c_1^2 + c_2^2)$.
- 3. Find (c_1, c_2) such that :

$$\mathbf{n}(a) = \frac{\ell^f - t \cdot \mathbf{n}(c)}{s}$$

We want to solve :

$$s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{a}rc) = \ell^f$$
 for $a, c \in \mathcal{O} = \mathbb{Z} + i\mathbb{Z} + j\mathbb{Z} + k\mathbb{Z} = \mathbb{Z}[i] + j\mathbb{Z}[i]$.

- 1. Restrict $a \in \mathbb{Z}[i]$, $c \in \bar{r}j\mathbb{Z}[i] \rightsquigarrow$ the trace vanishes.
- 2. Write $a = a_1 + a_2 i$ and $c = \overline{r} j(c_1 + c_2 i)$. Then, $\mathbf{n}(a) = a_1^2 + a_2^2$ and $\mathbf{n}(c) = p\mathbf{n}(r)(c_1^2 + c_2^2)$.
- 3. Find (c_1, c_2) such that :

$$\mathbf{n}(a) = \frac{\ell^f - t \cdot \mathbf{n}(c)}{s}$$

4. Use Cornacchia's algorithm to solve $a_1^2 + a_2^2 = \frac{\ell^f - t \cdot \mathbf{n}(c)}{s}$

Fixing the norm of u

We want to solve :

$$\mathbf{n}(a)\mathbf{n}(b) + \mathbf{n}(c)\mathbf{n}(d) - \mathbf{tr}(\bar{a}b\bar{d}c) = \ell^e$$

for $b, d \in \mathcal{O}_0$, a and c fixed.

We want to solve :

$$\mathbf{n}(a)\mathbf{n}(b) + \mathbf{n}(c)\mathbf{n}(d) - \mathbf{tr}(\bar{a}b\bar{d}c) = \ell^e$$

for $b, d \in \mathcal{O}_0$, a and c fixed.

1. Define the ideal $I = \langle \mathbf{n}(c), a\bar{c} \rangle \subset \mathcal{O}_0$.

We want to solve :

$$\mathbf{n}(a)\mathbf{n}(b) + \mathbf{n}(c)\mathbf{n}(d) - \mathbf{tr}(\bar{a}b\bar{d}c) = \ell^e$$

for $b, d \in \mathcal{O}_0$, a and c fixed.

- 1. Define the ideal $I = \langle \mathbf{n}(c), a\bar{c} \rangle \subset \mathcal{O}_0$.
- 2. Note that our equation corresponds to a norm equation in 1.

We want to solve :

$$\mathsf{n}(a)\mathsf{n}(b) + \mathsf{n}(c)\mathsf{n}(d) - \mathsf{tr}(\bar{a}b\bar{d}c) = \ell^e$$

for $b, d \in \mathcal{O}_0$, a and c fixed.

- 1. Define the ideal $I = \langle \mathbf{n}(c), a\bar{c} \rangle \subset \mathcal{O}_0$.
- 2. Note that our equation corresponds to a norm equation in 1.
- 3. Use KLPT to solve the norm equation in I. It outputs b and d directly.

We want to solve :

$$\mathsf{n}(a)\mathsf{n}(b) + \mathsf{n}(c)\mathsf{n}(d) - \mathsf{tr}(\bar{a}b\bar{d}c) = \ell^e$$

for $b, d \in \mathcal{O}_0$, a and c fixed.

- 1. Define the ideal $I = \langle \mathbf{n}(c), a\bar{c} \rangle \subset \mathcal{O}_0$.
- 2. Note that our equation corresponds to a norm equation in 1.
- 3. Use KLPT to solve the norm equation in I. It outputs b and d directly.

We obtain
$$u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
 with all the desired properties !

Why do we do this?

Why do we do this?

1. Because it's an obvious question.

Why do we do this?

- 1. Because it's an obvious question.
- 2. It's a piece of the constructive IKO correspondence.

Why do we do this?

- 1. Because it's an obvious question.
- 2. It's a piece of the constructive IKO correspondence.
- 3. It's a cryptanalytic tool for niche theoretical hash functions based on isogenies (2D CGL).

Why do we do this?

- 1. Because it's an obvious question.
- 2. It's a piece of the constructive IKO correspondence.
- 3. It's a cryptanalytic tool for niche theoretical hash functions based on isogenies (2D CGL).

Future work:

Why do we do this?

- 1. Because it's an obvious question.
- 2. It's a piece of the constructive IKO correspondence.
- 3. It's a cryptanalytic tool for niche theoretical hash functions based on isogenies (2D CGL).

Future work:

1. Optimize the algorithm. Lower the bound $\ell^{2(e+f)} = O(p^{25})$.

Why do we do this?

- 1. Because it's an obvious question.
- 2. It's a piece of the constructive IKO correspondence.
- 3. It's a cryptanalytic tool for niche theoretical hash functions based on isogenies (2D CGL).

Future work:

- 1. Optimize the algorithm. Lower the bound $\ell^{2(e+f)} = O(p^{25})$.
- 2. Complete the work on the constructive IKO correspondence.

Why do we do this?

- 1. Because it's an obvious question.
- 2. It's a piece of the constructive IKO correspondence.
- It's a cryptanalytic tool for niche theoretical hash functions based on isogenies (2D CGL).

Future work:

- 1. Optimize the algorithm. Lower the bound $\ell^{2(e+f)} = O(p^{25})$.
- 2. Complete the work on the constructive IKO correspondence.
- 3. Some constructive applications? Another SQIsign??

Why do we do this?

- 1. Because it's an obvious question.
- 2. It's a piece of the constructive IKO correspondence.
- 3. It's a cryptanalytic tool for niche theoretical hash functions based on isogenies (2D CGL).

Future work:

- 1. Optimize the algorithm. Lower the bound $\ell^{2(e+f)} = O(p^{25})$.
- 2. Complete the work on the constructive IKO correspondence.
- 3. Some constructive applications? Another SQIsign??

Thank you for your attention!