

CONTINUE of Previous Lecture

PROOF OF THEOREM A

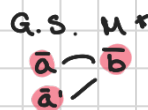
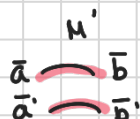
By contradiction, suppose that some " a_i " ends up being matched to a partner other than $\text{best}(a_i)$ in M^*

Since the a 's propose in decreasing order of preference, there must be a time when some " a " gets rejected by one of its valid matches " b " (rejection can happen right after a proposal or when " b " accepts some other proposal)

Let the pair $\{\bar{a}, \bar{b}\}$ be the first pair (during the execution of G-S algorithm) that is valid, and such that \bar{b} rejects \bar{a} .

When this rejection happens, \bar{b} will be paired up with some other \bar{a}' that she likes better than \bar{a} .

Now, since $\{\bar{a}, \bar{b}\}$ is a valid pair there must exist a stable matching M' such that $\{\bar{a}, \bar{b}\} \in M'$. Since M' is a stable matching, it must match \bar{a}' to some \bar{b}' , $\{\bar{a}', \bar{b}'\} \in M'$.



Then observe that $\{\bar{a}', \bar{b}'\}$ is a valid pair. Given that $\{\bar{a}, \bar{b}\}$ was the first valid pair with a rejection, it must be that \bar{a}' was not rejected by a valid partner before \bar{a}' gets engaged with \bar{b} (1st claim)

Now, since \bar{b}' is a valid partner of \bar{a}' ($\{\bar{a}', \bar{b}'\} \in M'$), and since \bar{a}' proposes in decreasing order of preference, it must be that \bar{a}' prefers \bar{b} to \bar{b}' (2nd claim) (3rd claim)

Since \bar{b} prefers \bar{a}' to \bar{a} (she rejected \bar{a} to be with \bar{a}') and since $\{\bar{a}, \bar{b}\}, \{\bar{a}', \bar{b}'\} \in M$. It holds that $\{\bar{a}, \bar{b}\}, \{\bar{a}', \bar{b}'\} \in M'$ is an instability of M' thus M' is unstable. This is a contradiction.

PROOF OF THEOREM B

Suppose that $\exists \{\bar{a}, \bar{b}\} \in M^*$ s.t. $\bar{a} \neq \text{worst}(\bar{b})$.

Then, there exists a stable matching M' s.t. $\{\bar{b}, \bar{a}\} \in M'$ and \bar{b}' likes \bar{a}' less than \bar{a} .

Suppose that in M' , \bar{a} is matched with some $\bar{b}' \neq \bar{b}$ ($\{\bar{a}, \bar{b}'\} \in M'$).

By theorem A, we know that \bar{b} is the best valid partner of \bar{a} thus, \bar{a} likes \bar{b} more than \bar{b}' (or thm A would not hold). that is $\bar{a}: \bar{b} > \bar{b}'$ and $\bar{b}: \bar{a} > \bar{a}'$ but, $\{\bar{a}, \bar{b}'\}, \{\bar{a}, \bar{b}\} \in M'$.

Thus, $=$ form an instability of M' , which is then unstable. **CONTRADICTION**

G-S has given us the opportunity to discuss about a number of questions one encounters when studying algorithm problems.

- ① Formulated the problem in a mathematical precise way
- ② Ask questions about the mathematical problem
- ③ Design an efficient algorithm for your problem
- ④ Prove that your assumption is correct, and bound its runtime

EFFICIENCY

Def (??) "An algorithm is efficient if, after being implemented, it runs quickly on real input instances."

(not a formal definition)

"QUICKLY":

"quick" on which hardware? with which programming language? with which implementation? (each of these questions significantly changes the runtime)

We would like our definition to be independent of details

REAL INPUT INSTANCES

: what does it mean? How to define them?

To prove something about an algorithm, we need mathematical definitions.

WORST-CASE ANALYSIS

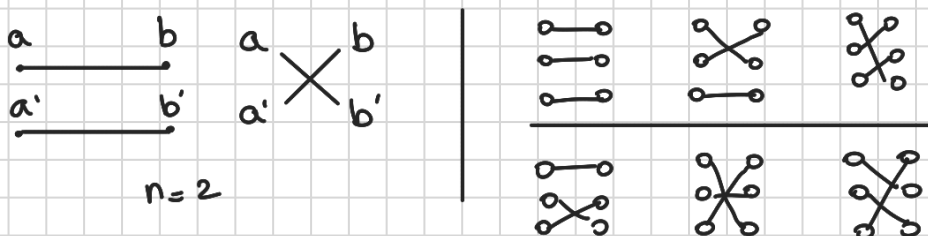
We want the runtime of an algorithm to be bounded in terms of the worst possible input. For instance, in the case of stable matching, we proved that G-S algorithm uses at most n^2 iterations ($n = |A| = |B|$)

Suppose, for instance that we consider inputs in which $|A| = |B| = N$, for $N = 2n$

$$N^2 = (2n)^2 = 4n^2$$

Doubling n changes the runtime by a factor 4

The brute-force algorithm tried each of the $n!$ matches



What would happen to the brute-force algorithm if we doubled the number of people?

$$N! = (2n)! =$$

$$\begin{aligned} &= 2n(2n-1)(2n-2) \dots (n+1) \cdot n(n-1) \cdot 2 \cdot 1 \\ &= 2n(2n-1) \dots (n+1) \cdot n! \\ &\geq (n+1)^n \cdot n! \geq 2^n \cdot n! \end{aligned}$$

Def: An algorithm having a runtime $\leq c \cdot n^d$, where c and d are constants, on inputs of size n is said to be a polynomial time (POLYTIME) algorithm

If I have a polytime algorithm running in time $c \cdot n^d$ on inputs of size n , and I run it on inputs of size $N = b \cdot n$,

$$c \cdot N^d = c (nb)^d = c \cdot n^d \cdot b^d$$

then the blow-up in the runtime is going to be a constant b^d