### Team Contest Reference getRandomNumber(){return 4;}

### Universität zu Lübeck

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### **Inhaltsverzeichnis**

1	Mat	thematische Algorithmen
	1.1	Primzahlen
		1.1.1 Sieb des Eratosthenes
		1.1.2 Primzahlentest
	1.2	Binomial Koeffizient
	1.3	Modulare Arithmetik
		1.3.1 Erweiterter Euklidischer Algorithmus
	1.4	Matrixmultiplikation
2	Date	enstukturen 2
_	2.1	Fenwick Tree (Binary Indexed Tree)
	2.1	Tonwick free (Bindly indexed free)
3	Gra	phenalgorithmen
	3.1	Topologische Sortierung
	3.2	Minimum Spanning Tree
		3.2.1 Prim's Algorithm
		3.2.2 Union and Find: Kruskal's Algorithm
	3.3	Maximaler Fluss (Ford-Fulkerson)
	3.4	Floyd-Warshall
	3.5	Dijkstra
	3.6	Bellmann-Ford
4	Geo	ometrische Algorithmen
	4.1	Rotate a Point
	4.2	Graham Scan (Convex Hull)
	4.3	Maximum Distance in a Point Set
	4.4	Area of a Polygon
	4.5	Punkt in Polygon
5	Vore	schiedenes
J	5.1	Potenzmenge
	5.1	Longest Common Subsequence
	5.3	
	5.5	Longest Increasing Subsequence
6	Eine	e kleine C-Referenz

### 1 Mathematische Algorithmen

### 1.1 Primzahlen

Für Primzahlen gilt immer (aber nicht nur für Primzahlen)

$$a^p \equiv a \mod p$$
 bzw.  $a^{p-1} \equiv 1 \mod p$ .

Ein paar Primzahlen für den Hausgebrauch:  $1000003, 2147483648(2^{31}), 4294967291(2^{32}), \dots (2^{63})$ 

### 1.1.1 Sieb des Eratosthenes

```
static boolean[] sieve(int until) {
boolean[] a = new boolean[until + 1];
Arrays.fill(a, true);
for (int i = 2; i < Math.sqrt(a.length); i++) {
   if (a[i]) {
      for (int j = i * i; j < a.length; j += i) a[j] = false;
   }
}
return a; // a[i] == true, iff. i is prime. a[0] is ignored
}</pre>
```

### 1.1.2 Primzahlentest

```
static boolean isPrim(int p) {
   if (p < 2 || p > 2 && p % 2 == 0) return false;
   for (int i = 3; i <= Math.sqrt(p); i += 2)
   if (p % i == 0) return false;
   return true;
6 }</pre>
```

### 1.2 Binomial Koeffizient

```
1 static int[][] mem = new int[MAX_N][(MAX_N + 1) / 2];
2 static int binoCo(int n, int k) {
3    if (k < 0 || k > n) return 0;
4    if (2 * k > n) binoCo(n, n - k);
5    if (mem[n][k] > 0) return mem[n][k];
6    int ret = 1;
7    for (int i = 1; i <= k; i++) {
8       ret *= n - k + i;
9       ret /= i;
10       mem[n][i] = ret;
11    }
12    return ret;
13 }</pre>
```

### 1.3 Modulare Arithmetik

Bedeutung der größten gemeinsamen Teiler:

$$d = ggT(a, b) = as + bt$$

Verwendung zu Berechnung des inversen Elements b zu a bezüglich einer Restklassengruppe n (a und n müssen teilerfremd sein):

$$ab \equiv 1 \mod n \iff s \equiv b \mod n \quad \text{für } 1 = ggT(a, n)$$

### 1.3.1 Erweiterter Euklidischer Algorithmus

```
1 static int[] eea(int a, int b) {
2    int[] dst = new int[3];
3    if (b == 0) {
4       dst[0] = a;
5       dst[1] = 1;
6       return dst; // a, 1, 0
7    }
8    dst = eea(b, a % b);
9    int tmp = dst[2];
10    dst[2] = dst[1] - ((a / b) * dst[2]);
11    dst[1] = tmp;
12    return dst;
13 }
```

Zur Berechnung des Inversen von n im Restklassenring p gilt: d = eea(p, n).

### 1.4 Matrixmultiplikation

Strassen-Algorithmus: C = AB  $A, B, C \in \mathbb{R}^{2^n \times 2^n}$ 

$$\begin{array}{rcl} \mathbf{C}_{1,1} & = & \mathbf{A}_{1,1}\mathbf{B}_{1,1} + \mathbf{A}_{1,2}\mathbf{B}_{2,1} \\ \mathbf{C}_{1,2} & = & \mathbf{A}_{1,1}\mathbf{B}_{1,2} + \mathbf{A}_{1,2}\mathbf{B}_{2,2} \\ \mathbf{C}_{2,1} & = & \mathbf{A}_{2,1}\mathbf{B}_{1,1} + \mathbf{A}_{2,2}\mathbf{B}_{2,1} \\ \mathbf{C}_{2,2} & = & \mathbf{A}_{2,1}\mathbf{B}_{1,2} + \mathbf{A}_{2,2}\mathbf{B}_{2,2} \end{array}$$

### 2 Datenstukturen

### **2.1** Fenwick Tree (Binary Indexed Tree)

```
class FenwickTree {
   private int[] values;
    private int n;
    public FenwickTree(int n) {
      this.n = n;
      values = new int[n];
    public int get(int i) { //get value of i
     int x = values[0];
      while (i > 0) {
       x += values[i];
11
       i -= i & -i; }
12
13
     return x;
14
    public void add(int i, int x) { // add x to interval [i,n]
15
      if (i == 0) values[0] += x;
16
      else {
17
        while (i < n) {
         values[i] += x;
19
         i += i & -i; }
20
21
22
    }
23
```

### 3 Graphenalgorithmen

### 3.1 Topologische Sortierung

```
static List<Integer> topoSort(Map<Integer, List<Integer>> edges,
     Map<Integer, List<Integer>> revedges) {
    Queue<Integer> q = new LinkedList<Integer>();
    List<Integer> ret = new LinkedList<Integer>();
    Map<Integer, Integer> indeg = new HashMap<Integer, Integer>();
    for (int v : revedges.keySet()) {
     indeg.put(v, revedges.get(v).size());
     if (revedges.get(v).size() == 0)
       q.add(v);
10
   while (!q.isEmpty()) {
11
12
     int tmp = q.poll();
     ret.add(tmp);
13
14
      for (int dest : edges.get(tmp)) {
       indeg.put(dest, indeg.get(dest) - 1);
15
       if (indeg.get(dest) == 0)
16
17
         q.add(dest);
18
     }
   }
19
    return ret;
```

### 3.2 Minimum Spanning Tree

### 3.2.1 Prim's Algorithm

```
#define WHITE 0
  #define BLACK 1
  #define INF INT_MAX
5 int baum( int **matrix, int N){
   int i, sum = 0;
    int color[N];
    int dist[N];
10
     // markiere alle Knoten ausser 0 als unbesucht
11
    color[0] = BLACK;
    for( i=1; i<N; i++){</pre>
13
14
      color[i] = WHITE;
      dist[i] = INF;
15
    }
16
```

```
// berechne den Rand
18
    for( i=1; i<N; i++){</pre>
19
         if( dist[i] > matrix[i][nextIndex]){
20
             dist[i] = matrix[i][nextIndex];
21
22
      }
23
24
    while( 1){
25
      int nextDist = INF, nextIndex = -1;
26
27
28
      /* Den naechsten Knoten waehlen */
      for(i=0; i<N; i++){
29
        if( color[i] != WHITE) continue;
31
        if( dist[i] < nextDist){</pre>
32
         nextDist = dist[i];
         nextIndex = i;
34
35
36
37
38
      /* Abbruchbedingung*/
      if( nextIndex == -1) break;
39
40
41
      /* Knoten in MST aufnehmen */
      color[nextIndex] = RED;
42
43
      sum += nextDist;
44
      /* naechste kuerzeste Distanzen berechnen */
45
46
      for( i=0; i<N; i++){</pre>
47
             if( i == nextIndex || color[i] == BLACK ) continue;
48
             if( dist[i] > matrix[i][nextIndex]){
                 dist[i] = matrix[i][nextIndex];
50
51
52
      }
    }
53
54
    return sum;
55
56 }
  3.2.2 Union and Find: Kruskal's Algorithm
  Amortized time per operation is O(\alpha(n)).
 1 // Only the tree root is stored. The edges must be stored separately.
2 // Path compression and union by rank
4 int *par = (int *) malloc(n * sizeof(int));
5 int *rank = (int *) malloc(n * sizeof(int));
7 // Create new forest of n vertices
8 void init(int n, int *par, int *rank) {
    int i;
    for (i = 1; i \le n; i++) {
10
     par[i] = i; // every vertex is its on root
      rank[i] = 0;
12
    }
13
14 }
15
_{16} // Union two trees which contain x and y respectively, returns new root
int union(int n, int *par, int *rank, int x, int y) {
   y = find(n, par, y);
18
    x = find(n, par, x);
   if (rank[x] > rank[y]) return par[y] = x;
20
   if (rank[x] < rank[y]) return par[x] = y;</pre>
    rank[x]++; // rank[x] == rank[y]
   return par[y] = x;
23
24 }
_{26} // Find the tree root of x
27 int find(int n, int *par, int x) {
   // if parent is not a tree root
   if (par[x] != par[par[x]]) par[x] = find(n, par, par[x]);
29
   return par[x];
```

31 }

### 3.3 Maximaler Fluss (Ford-Fulkerson)

```
/* die folgende Zeile anpassen! */
3 #define N_MAX 30*30+30
5 /* hier drunter nichts anfassen! */
7 #define SIZE_MAX (N_MAX+2)
8 #define SIZE (N+2)
9 #define QUELLE (N)
10 #define SENKE (N+1)
n extern int capacity[SIZE_MAX][SIZE_MAX];
12 extern int N;
14 int maxFlow();
15 void reset();
#include <stdio.h>
2 #include <limits.h>
3 #include <string.h>
4 #include "flow.h"
6 #define NONE -1
7 #define INF INT_MAX/2
9 int N;
int capacity[SIZE_MAX][SIZE_MAX];
int flow[SIZE_MAX][SIZE_MAX];
int queue[SIZE_MAX], *head, *tail;
int state[SIZE_MAX];
14 int pred[SIZE_MAX];
16 enum { UNVISITED, WAITING, PROCESSED };
18 void enqueue( int x){
      *tail++ = x;
19
20
      state[x] = WAITING;
21 }
22
23 int dequeue(){
      int x = *head++;
24
25
      state[x] = PROCESSED;
      return x;
26
27 }
28
29 void reset(){
30
      int i, j;
      for(i=0; i<SIZE;i++){</pre>
          memset( capacity[i], 0, sizeof(int)*SIZE );
32
33
34 }
35
36 int bfs( int start, int target){
      int u, v;
37
       \begin{tabular}{ll} \textbf{for}( & u=0; & u< SIZE; & u++) \{ \end{tabular} 
38
          state[u] = UNVISITED;
40
      head = tail = queue;
41
      pred[start] = NONE;
42
43
44
      enqueue(start);
45
      while( head < tail){</pre>
46
47
          u = dequeue();
48
          for( v= 0; v< SIZE; v++){</pre>
49
              if( state[v] == UNVISITED &&
50
                 capacity[u][v] \ - \ flow[u][v] \ > \ \emptyset)\{
51
52
                  enqueue(v);
53
                 pred[v] = u;
54
          }
56
      }
57
```

```
return state[target] == PROCESSED;
60 }
61
62 int maxFlow(){
      int max_flow = 0;
63
      int u;
65
66
      int i, j;
      for(i=0; i<SIZE;i++){</pre>
67
         \label{eq:memset} \mbox{memset(flow[i], 0, sizeof(int)*SIZE);}
68
69
70
      while( bfs( QUELLE, SENKE)){
71
72
          int increment = INF, temp;
73
          for( u= SENKE; pred[u] != NONE; u = pred[u]){
74
             temp = capacity[pred[u]][u] - flow[pred[u]][u];
75
             if( temp < increment){</pre>
76
77
                 increment = temp;
78
          }
79
80
          for( u= SENKE; pred[u] != NONE; u = pred[u]){
81
82
             flow[pred[u]][u] += increment;
83
             flow[u][pred[u]] -= increment;
84
85
86
         max_flow += increment;
87
88
      return max_flow;
89
90 }
1 /**
   * Ford Fulkersen
   * @param s source
   * @param d destination
   * @param c capacity
   * @param f flow, init with 0
   * @return
9 static int ff(int s, int d, int[][] c, int[][] f) {
   List<Integer> path = dfs(s, d, c, f, new boolean[c.length]); // find path
10
    if (path.size() < 2) {
      int flow = 0;
12
      for (int i = 0; i < f[s].length; i++) { // leaving flow of source
13
14
        flow += f[s][i];
15
16
     return flow;
17
    int cap = Integer.MAX_VALUE; // capacity of current path
18
    for (int i = 0; i < path.size() - 1; i++) {
      int a = path.get(i), b = path.get(i + 1);
20
      cap = Math.min(cap, c[a][b] - f[a][b]);
21
    }
    for (int i = 0; i < path.size() - 1; i++) { //update flow
23
24
      int a = path.get(i), b = path.get(i + 1);
      f[a][b] += cap;
25
      f[b][a] -= cap;
26
27
    return ff(s, d, c, f); // tail recursion
28
29 }
30
31 /**
32
   * depth first search in flow network
   * @param s source
33
   * @param d destination
34
   * @param c capacity
   * @param f flow
36
   * @param v visited, init with false
37
   * @return
39
40 static List<Integer> dfs(int s, int d, int[][] c, int[][] f, boolean[] v) {
    if (s == d) { // destination found }
42
      LinkedList<Integer> path = new LinkedList<Integer>();
      path.add(d);
```

```
return path;
46
47
    for (int i = 0; i < c[s].length; i++) {
48
      if (!v[i] \&\& c[s][i] - f[s][i] > 0) {
       List<Integer> path = dfs(i, d, c, f, v);
49
       if (path.size() > 0) {
50
         ((LinkedList<Integer>) path).addFirst(s);
51
52
         return path;
53
     }
54
    }
55
    return ((List<Integer>) Collections.EMPTY_LIST);
56
  3.4 Floyd-Warshall
static int n;
2 static int[][] path = new int[n][n];
3 static int[][] next = new int[n][n];
4 static void floyd(int[][] ad) {
    for (int i = 0; i < n; i++)
     path[i] = Arrays.copyOf(ad[i], n);
    for (int i = 0; i < n; i++)
      for (int j = 0; j < n; j++)
       for (int k = 0; k < n; k++)
         if (path[i][k] + path[k][j] < path[i][j]) {
10
           path[i][j] = path[i][k] + path[k][j];
11
12
           next[i][j] = k;
    // there is a negative circle iff. there is a i such that path[i][i] < 0
14
  3.5 Dijkstra
   Funktion Dijkstra(Graph, Startknoten):
       initialisiere(Graph, Startknoten, abstand[], vorgaenger[],Q)
                                             // Der eigentliche Algorithmus
       solange O nicht leer:
          u := Knoten in Q mit kleinstem Wert in abstand[]
          entferne u aus Q
                                                     // fuer u ist der kuerzeste Weg nun bestimmt
          fuer jeden Nachbarn v von u:
              falls v in Q:
                distanz_update(u,v,abstand[],vorgaenger[]) // pruefe Abstand vom Startknoten zu v
       return vorgaenger[]
   Methode initialisiere(Graph, Startknoten, abstand[], vorgaenger[],Q):
11
       fuer jeden Knoten v in Graph:
12
          abstand[v] := unendlich
13
          vorgaenger[v] := null
14
15
       abstand[Startknoten] := 0
       Q := Die Menge aller Knoten in Graph
16
17
   Methode distanz_update(u,v,abstand[],vorgaenger[]):
18
       alternativ := abstand[u] + abstand_zwischen(u, v) // Weglaenge vom Startknoten nach v ueber u
19
       falls alternativ < abstand[v]:</pre>
20
21
          abstand[v] := alternativ
          vorgaenger[v] := u
  3.6 Bellmann-Ford
  Single source all paths, negative weights.
 // returns true iff negative-weight cycle reachable
  private static boolean bellmannford(Node start, int n, List<Edge> edges) {
    start.dist = 0; // others: dist = Integer.MAX_VALUE
    while (n-->0) { // number of nodes --> for all vertices
      for (Edge edge : edges) { // --> for all edges
       if (edge.from.dist < Integer.MAX_VALUE</pre>
           && edge.from.dist + edge.w < edge.to.dist)
         edge.to.dist = edge.from.dist + edge.w; // update predecessor
    } }
    for (Edge edge : edges) {
10
      if (edge.from.dist < Integer.MAX_VALUE</pre>
11
         && edge.from.dist + edge.w < edge.to.dist)
       return true;
13
14
    }
```

return false;

```
16 }
17 class Node {}
18 class Edge {
19    Node from, to;
20    int w;
21    public Edge(Node from, Node to, int w) {
22        this.from = from; this.to = to; this.w = w;
23    }
24 }
```

### 4 Geometrische Algorithmen

### 4.1 Rotate a Point

```
static P rotate(P origin, P p, double ccw) {
   double x = (p.x - origin.x) * Math.cos(ccw) - (p.y - origin.y) Math.sin(ccw);
   double y = (p.x - origin.x) * Math.sin(ccw) + (p.y - origin.y) Math.cos(ccw);
   return new P(x, y);
}
```

### 4.2 Graham Scan (Convex Hull)

```
ı class P {
   double x, y;
    P(double x, double y) {
      this.x = x;
      this.y = y;
    // polar coordinates (not used in graham scan)
    double r() { return Math.sqrt(x * x + y * y); }
    double d() { return Math.atan2(y, x); }
10
11 }
13 // turn is counter-clockwise if > 0; collinear if = 0; clockwise else
14 static double ccw(P p1, P p2, P p3) {
   return (p2.x - p1.x) * (p3.y - p1.y) - (p2.y - p1.y) * (p3.x - p1.x);
16 }
18 static List<P> graham(List<P> 1) {
19
   if (l.size() < 3)
20
     return 1;
    P temp = 1.get(0);
21
    for (P p : 1)
23
      if (temp.y > p.y \mid \mid temp.y == p.y \&\& temp.x > p.x)
24
       temp = p;
    final P start = temp; // min y (then leftmost)
26
    Collections.sort(1, new Comparator<P>() {
27
     public int compare(P o1, P o2) {
         \textbf{if (new Double(Math.atan2(o1.y - start.y, o1.x - start.x))} \ / / \ \textit{same angle} 
29
            .compareTo(Math.atan2(o2.y - start.y, o2.x - start.x)) == 0)
30
         return new Double((o1.x - start.x) * (o1.x - start.x)
31
             + (o1.y - start.y) * (o1.y - start.y))
32
             .compareTo((o2.x - start.x) * (o2.x - start.x)
33
             + (o2.y - start.y) * (o2.y - start.y)); // use distance
34
35
       return new Double(Math.atan2(o1.y - start.y, o1.x - start.x))
           .compareTo(Math.atan2(o2.y - start.y, o2.x - start.x));
36
37
38
    });
    Stack<P> s = new Stack<P>();
39
    s.add(start):
40
    s.add(l.get(1));
    for (int i = 2; i < 1.size(); i++) {</pre>
42
      while (s.size() >= 2
43
         && ccw(s.get(s.size() - 2), s.get(s.size() - 1), l.get(i)) \le 0)
       s.pop():
45
46
      s.push(l.get(i));
47
   }
48
   return s:
```

### 4.3 Maximum Distance in a Point Set

```
List<P> hull = graham(list);
2 maxDist(hull);
4 static double dist(P p1, P p2) {
   return Math.sqrt((p1.x - p2.x) * (p1.x - p2.x)
       + (p1.y - p2.y) * (p1.y - p2.y));
7 }
9 static double maxDist(List<P> hull) {
double max = 0, tmp = 0;
11
   int j = 0, n = hull.size();
    for (P p : hull) {
12
13
     while (tmp < dist(p, hull.get((j + 1) % n))) {
       j = (j + 1) \% n;
       tmp = dist(p, hull.get(j));
15
16
     max = Math.max(max, tmp);
   }
18
19
   return max;
20 }
```

### 4.4 Area of a Polygon

```
1 // area of a polygon, e.g. area(graham(list))
2 static double area(List<P> 1) {
3    double sum = 0;
4    // points must be in ccw order, otherwise negative area returned
5    for (int i = 0; i < 1.size(); i++) {
6         sum += 1.get(i).x * 1.get((i + 1) % 1.size()).y;
7         sum -= 1.get(i).y * 1.get((i + 1) % 1.size()).x;
8    }
9    return sum / 2;
10 }</pre>
```

### 4.5 Punkt in Polygon

```
1 /**
   * -1: A liegt links von BC (ausser unterer Endpunkt)
   * 0: A auf BC
   * +1: sonst
6 public static int KreuzProdTest(double ax, double ay, double bx, double by,
      double cx, double cy) {
    if (ay == by && by == cy) {
      if ((bx <= ax && ax <= cx) || (cx <= ax && ax <= bx)) return 0;</pre>
10
      else return +1;
11
   if (by > cy) {
12
13
      double tmpx = bx, tmpy = by;
      bx = cx:
14
15
      by = cy;
      cx = tmpx;
16
      cy = tmpy;
17
   }
19
    if (ay == by && ax == bx) return 0;
    if (ay \leftarrow by \mid \mid ay > cy) return +1;
20
    double delta = (bx - ax) * (cy - ay) - (by - ay) * (cx - ax);
    if (delta > 0) return -1;
22
23
    else if (delta < 0) return +1;</pre>
    else return 0;
25 }
26
27 /**
   * Input: P[i] (x[i],y[i]); P[0]:=P[n]
28
29 * -1: Q ausserhalb Polygon
   * 0: Q auf Polygon
30
  * +1: Q innerhalb des Polygons
31
33 public static int PunktInPoly(double[] x, double[] y, double qx, double qy) {
   int t = -1;
    for (int i = 0; i < x.length - 1; i++)
     t = t * KreuzProdTest(qx, qy, x[i], y[i], x[i + 1], y[i + 1]);
37
    return t;
38 }
```

### 5 Verschiedenes

### 5.1 Potenzmenge

```
static <T> Iterator<List<T>> powerSet(final List<T> 1) {
   return new Iterator<List<T>>() {
      int i; // careful: i becomes 2^1.size()
     public boolean hasNext() {
       return i < (1 << l.size());
     public List<T> next() {
       Vector<T> temp = new Vector<T>();
       for (int j = 0; j < 1.size(); j++)
        if (((i >>> j) \& 1) == 1)
          temp.add(l.get(j));
11
       i++;
12
13
       return temp;
14
     public void remove() {}
16
```

### **5.2** Longest Common Subsequence

```
#include <stdio.h>
2 #include <stdlib.h>
3 #include <string.h>
6 int lcs( char *a, char *b){
      int len = strlen( a);
      int lenb =strlen(b);
      int *zeile = malloc( (len+1) * sizeof(int)), *temp,
          *neue = malloc( (len+1) * sizeof(int)), i, j;
11
12
      for(i=0; i<len+1; i++){</pre>
13
         zeile[i] = neue[i] = 0;
14
15
16
      for(j=0; j<lenb; j++){</pre>
17
18
          for(i=0; i<len; i++){</pre>
             if( a[i] == b[j]){
19
20
                 neue[i+1] = zeile[i] + 1;
             } else {
21
                 neue[i+1] = neue[i] > zeile[i+1] ? neue[i] : zeile[i+1];
22
23
          }
24
         temp = zeile;
25
         zeile = neue;
27
         neue = temp;
28
      int res = zeile[len];
30
31
      free( zeile);
      free( neue);
32
      return res:
33
```

### 5.3 Longest Increasing Subsequence

```
lower = list;
         upper = list + sorted_n;
16
         mid = list + sorted_n / 2;
17
18
19
         while( lower < upper-1){</pre>
             if( list[i] < *mid){
21
                 upper = mid;
22
             } else {
24
                 lower = mid;
             }
25
26
             mid = lower + (upper-lower) / 2;
27
         }
29
    if( mid == list + sorted_n -1 && *mid < list[i]){
30
             *mid = list[i];
             sorted_n++;
32
         }
33
34
         if( list[i] < *mid){
35
             *mid = list[i];
36
37
     }
38
      free( sorted);
40
41
42
      return sorted_n;
43 }
```

### 6 Eine kleine C-Referenz

## C Reference Card (ANSI)

## Program Structure/Functions

TIOSTAIN DU ACCANC/ L'AIRCHOIRS	function declarations external variable declarations main routine local variable declarations	function definition local variable declarations	comments (argv[]) main with args
i rogrami per d	type fuc(type1,)  type name main() { declarations statements	type fnc(arg1,) { declarations statements return value;	/* */ main(int argc, char *argv[])

### C Preprocessor

	#include <flename></flename>	#include "flename"	#define name text	#define name(var) text	((A)>(B)?(A):(B))	+undef $name$	#	##	#if, #else, #elif, #endif	#ifdef, #ifndef	defined(name)	/
4	include library file	include user file	replacement text	replacement macro	Example. #define max(A,B) ((A)>(B) ? (A) : (B))	undefine	quoted string in replace	concatenate args and rescan	conditional execution	is name defined, not defined?	name defined?	line continuation char

### Data Types/Declarations

CIOIIS	char	int	float	double	short	long	signed	unsigned	*int, *float,	ennm	const	extern	register	static	void	struct	typedef typename	sizeof $object$	t) sizeof(type name)
Data 13 pes/ Deciai ations	character (1 byte)	integer	float (single precision)	float (double precision)	short (16 bit integer)	long (32 bit integer)	positive and negative	only positive	pointer to int, float,	enumeration constant	constant (unchanging) value	declare external variable	register variable	local to source file	no value	structure	create name by data type	size of an object (type is size_t)	size of a data type (type is size_t)

### Initialization

$type\ name=value$	type name[]={value1,} char name[]="string"	
initialize variable	initialize array initialize char string	

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### Constants

L or 1	F or f	Φ	0	0x or 0X	'a', '\000', '\xhh'	\n, \r, \t, \b	/., /., //	"abcde"	
long (suffix)	float (suffix)	exponential form	octal (prefix zero)	hexadecimal (prefix zero-ex)	character constant (char, octal, hex)	newline, cr, tab, backspace	special characters	string constant (ends with '\0')	

## Pointers, Arrays & Structures

type *name	type type *f()	type type (*pf)()	void *	NOLL	*pointer	&name	name [ $dim$ ]	$name [dim_1] [dim_2] \dots$		
declare pointer to type	declare function returning pointer to type type *f()	declare pointer to function returning type type (*pf) ()	generic pointer type	null pointer	object pointed to by pointer	address of object name	array	multi-dim array	Structures	

## uctures struct tag { structure template declarations declaration of members

create structure	struct tag name
member of structure from template	name $.$ $member$
member of pointed to structure	pointer -> member
Example. (*p).x and p->x are the same	same
single value, multiple type structure	union
bit field with $b$ bits	member : b

# Operators (grouped by precedence)

structure member operator	name . $member$
structure pointer	pointer->member
increment, decrement	'++
plus, minus, logical not, bitwise not	*, -, +
indirection via pointer, address of object	*pointer, &name
cast expression to type	(type) expr
size of an object	sizeof
multiply, divide, modulus (remainder)	*, /, %
add, subtract	- '+
left, right shift [bit ops]	<<, >>
comparisons	>, >=, <, <=
comparisons	=i, !=
bitwise and	**
bitwise exclusive or	•
bitwise or (incl)	_
logical and	8.8
logical or	
conditional expression exp	expr <sub>1</sub> ? expr <sub>2</sub> : expr <sub>3</sub>
assignment operators	+=, -=, *=,
expression evaluation separator	•

# Unary operators, conditional expression and assignment operators group right to left; all others group left to right.

### Flow of Control

; { } or break		$egin{array}{c} { m goto} & label : \end{array}$	return $expr$	<pre>if (expr) statement else if (expr) statement else statement</pre>	$\begin{array}{c} \mathtt{while} \ (expr) \\ statement \end{array}$	<pre>for (expr<sub>1</sub>; expr<sub>2</sub>; expr<sub>3</sub>) statement</pre>	$\begin{array}{ll} {\tt do} & statement \\ {\tt while}(expr); \end{array}$	<pre>switch (expr) {   case const; statement_1 break;   case const_2: statement_2 break;   default: statement</pre>	
statement terminator block delimeters exit from switch, while, do, for	next iteration of while, do, for	go to label	return value from function Flow Constructions	if statement if (e else else else	while statement while $stat$	for statement for (	do statement do while	switch statement switc ca ca de	

### ANSI Standard Libraries

<pre><li><li><li><li><li><li><li><li><li><li< th=""><th></th><th></th></li<></li></li></li></li></li></li></li></li></li></pre>		
<pre><float.h> <signal.h> <string.h> <ctvpe.h></ctvpe.h></string.h></signal.h></float.h></pre>	<b>~.</b>	conbberco
. 2 2	alphanumeric? alphabetic? control character? decimal digit? printing character (not incl space)? printing character (incl space)	
<pre>cassert.h&gt; <ctype.h> <ermo.h> <locale.h> <math.h> <setjmp.h< <td=""><stdim.h> <stdim.h></stdim.h></stdim.h></setjmp.h<></math.h></locale.h></ermo.h></ctype.h></pre> <pre>cstddef.h&gt; <stdio.h> <stdlib.h< pre=""> Character Class Tests</stdlib.h<></stdio.h></pre>	alphanumeric? alphabetic? control character? decimal digit? printing character (not incl space)? printing character (incl space)? printing character (incl space)? printing character (incl space) epiriting character (incl space, formfeed, newline, cr, tab, vt upper case letter? hexadecimal digit? convert to lower case?	pper case:
<pre><assert.b> <locale.b> <stddef.b> Charact</stddef.b></locale.b></assert.b></pre>	alphanumeric? alphabetic? control character? decimal digit? printing character (no lower case letter? printing character (inc printing character (inc printing character) character (inc printing chare except space, formfeed, newlitupper case letter? hexadecimal digit? convert to lower case?	convert to upper case:

### String Operations <string.h>

ngs	strlen(s)	strcpy(s,ct)	strncpy(s,ct,n)	strcat(s,ct)	strncat(s,ct,n)	strcmp(cs,ct)	strncmp(cs,ct,n)	strchr(cs,c)	strrchr(cs,c)	memcpy(s,ct,n)	memmove(s,ct,n)	memcmp(cs,ct,n)	memchr(cs,c,n)	memset(s,c,n)
s,t are strings, cs,ct are constant strings	length of s	copy ct to s	up to n chars	concatenate ct after s	up to n chars	compare cs to ct	only first n chars	pointer to first c in cs	pointer to last c in cs	copy n chars from ct to s	copy n chars from ct to s (may overlap)	compare n chars of cs with ct	pointer to first c in first n chars of cs	put c into first n chars of cs

(4,294,967,295)(65,536)

 $(10^{37})$  $(10^{-37})$ 

> maximum floating point number minimum floating point number

maximum exponent

FLT\_MAX\_EXP

FLT\_MAX FLT\_MIN

number of digits in mantissa smallest  $x \text{ so } 1.0 + x \neq 1.0$ 

FLT\_MANT\_DIG

qsort(array,n,size,cmp())

FLT\_EPSILON

FLT\_ROUNDS

FLT\_RADIX FLT\_DIG

 $(10^{-5})$ 

floating point rounding mode

radix of exponent rep

decimal digits of precision

Float Type Limits <float.h>

max value of unsigned short

 $(10^{-9})$ 

(10)

 $(10^{37})$  $(10^{-37})$ 

max double floating point number min double floating point number

maximum exponent

minimum exponent

DBL MIN EXP

number of digits in mantissa

smallest  $x \text{ so } 1.0 + x \neq 1.0$ 

DBL\_EPSILON DBL\_MANT\_DIG

DBL\_MAX DBL\_MAX\_EXP

decimal digits of precision

minimum exponent

FLT\_MIN\_EXP DBL\_DIG

(+32,767)(-32,768)

(255)(65,535)

max value of unsigned char max value of unsigned long max value of unsigned int

(-128)

(+127)

max value of signed char min value of signed char

max value of long

INT\_MIN LONG\_MAX

min value of long

LONG\_MIN SCHAR\_MIN

SCHAR\_MAX

max value of short min value of short

SHRT\_MAX SHRT\_MIN UCHAR\_MAX

UINT\_MAX ULONG\_MAX

USHRT\_MAX

## C Reference Card (ANSI)

### Input/Output <stdio.h>

stdin stdout stderr EOF	<pre>getchar()     putchar(chr)     putchar(chr)     printf("format", avg1)     scanf("format", kname1)     sscanf(s, "format", kname1)     dhars)     gets(s,max)     puts(s)</pre>	FILE *fp fopen("name", "mode")  te), a (append)     getc(fp)     putc(cfn,fp)     fprintf(fp,"format", avg1,)     fscanf(fp,"format", avg1,)     fclose(fp)	ferror(fp) feof(fp) chars) fgers(s,max,fp) fpurs(s,fp) : "%-+ 0w.pmc"
Standard I/O standard input stream standard output stream standard error stream end of file	get a character print a character print formatted data print to string s read formatted data scr read from string s read from string s print string s print string s	declare file pointer  pointer to named file  modes: r (read), w (write), a (append) get a character  write a character  p write a character  read from file fscanf (fp," close file	non-zero if error non-zero if EOF read line to string s (< max chars) fgs write string s Codes for Formatted I/O: "%-+ 0w.pmc" - left instify

L long double n number of chars written p pointer n number of chars writt g,G same as f or e,E depending on exponent x,X hexadecimal e, E exponential char string u unsigned 1 long, pad with leading zeros conversion character: space print space if no sign conversion character: h short, d,i integerc single charf double print with sign min field width precision o octal 0 adc

# Variable Argument Lists <stdarg.h>

va\_list name;

initialization of argument pointer va\_start(name, lastarg) access next unamed arg, update pointer va\_arg(name,type)  $\mathtt{va\_end}(name)$ lastarg is last named parameter of the function declaration of pointer to arguments call before exiting function

# Standard Utility Functions <stdlib.h>

 $\begin{array}{c}
(8) \\
(127 \text{ or } 255) \\
(-128 \text{ or } 0)
\end{array}$ 

The numbers given in parentheses are typical values for the constants on a 32-bit Unix system.

CHAR\_BIT bits in char (8

max value of char

min value of char

CHAR\_MIN CHAR\_MAX INT\_MAX

max value of int min value of int

Integer Type Limits inits.h>

(-32,768)(+2,147,483,647)(-2,147,483,648)

(+32,767)

abs(n)	labs(n)	div(n,d)	nd div_t.rem	ldiv(n,d)	and ldiv_t.rem	rand()	srand(n)	exit(status)	system(s)		atof(s)	atoi(s)	atol(s)	strtod(s,endp)	strtol(s,endp,b)	strtoul(s,endp,b)		(orin idon) oollee (orin) oollem
absolute value of int n	absolute value of long n	quotient and remainder of ints n,d	returns structure with div_t.quot and div_t.rem	quotient and remainder of longs n,d	returns structure with ldiv_t.quot and ldiv_t.rem	pseudo-random integer [0, RAND_MAX]	set random seed to n	terminate program execution	pass string s to system for execution	Conversions	convert string s to double	convert string s to integer	convert string s to long	convert prefix of s to double	convert prefix of s (base b) to long	same, but unsigned long	Storage Allocation	(original original original

bsearch(key, array, n, size, cmp()) malloc(size), calloc(nobj,size) realloc(pts,size) free(ptr) change size of object search array for key Array Functions deallocate space

# Time and Date Functions <time.h>

sort array ascending order

difftime(time2,time1) processor time used by program clock() Example. clock()/GLOCKS\_PER\_SEC is time in seconds clock\_t,time\_t time() months since January structure type for calendar time comps seconds after minute hours since midnight days since January 1 minutes after hour days since Sunday arithmetic types representing times years since 1900 time2-time1 in seconds (double) day of month current calendar time tm\_hour tm\_mday tm\_year tm\_wday tm\_sec tm\_min tm\_mon

strftime(s,smax,"format",tp) localtime(tp) asctime(tp) mktime(tp) gmtime(tp) convert calendar time in tp to local time ctime(tp) convert calendar time to GMT convert calendar time to local time Daylight Savings Time flag convert local time to calendar time convert time in tp to string format date and time info tm\_isdst tm\_yday

# Mathematical Functions <math.h>

tp is a pointer to a structure of type tm

Arguments and returned values are double

asin(x), acos(x), atan(x)
atan2(y,x) sinh(x), cosh(x), tanh(x)
exp(x), log(x), log10(x) sin(x), cos(x), tan(x)ldexp(x,n), frexp(x,\*e) modf(x,\*ip), fmod(x,y) pow(x,y), sqrt(x)
ceil(x), floor(x), fabs(x) exponentials & logs (2 power) hyperbolic trig functions inverse trig functions division & remainder exponentials & logs trig functions arctan(y/x)rounding

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