Team Contest Reference getRandomNumber() {return 4;}

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1 Mathematische Algorithmen

1.1 Primzahlen

Für Primzahlen gilt immer (aber nicht nur für Primzahlen)

```
a^p \equiv a \mod p bzw. a^{p-1} \equiv 1 \mod p.
```

1.1.1 Sieb des Eratosthenes

```
static boolean[] sieve(int until) {
  boolean[] a = new boolean[until + 1];
  Arrays.fill(a, true);
  for (int i = 2; i < Math.sqrt(a.length); i++) {
    if (a[i]) {
      for (int j = i * i; j < a.length; j += i) a[j] = false;
    }
}
return a; // a[i] == true, iff. i is prime. a[0] is ignored
}</pre>
```

1.1.2 Primzahlentest

```
static boolean isPrim(int p) {
   if (p < 2 || p > 2 && p % 2 == 0) return false;
   for (int i = 3; i <= Math.sqrt(p); i += 2)
   if (p % i == 0) return false;
   return true;
}</pre>
```

1.2 Binomial Koeffizient

```
1 static int[][] mem = new int[MAX_N][(MAX_N + 1) / 2];
2 static int binoCo(int n, int k) {
3    if (k < 0 || k > n) return 0;
4    if (2 * k > n) binoCo(n, n - k);
5    if (mem[n][k] > 0) return mem[n][k];
6    int ret = 1;
7    for (int i = 1; i <= k; i++) {
8       ret *= n - k + i;
9       ret /= i;
10       mem[n][i] = ret;
11    }
12    return ret;
13 }</pre>
```

1.3 Modulare Arithmetik

Bedeutung der größten gemeinsamen Teiler:

$$d = ggT(a, b) = as + bt$$

Verwendung zu Berechnung des inversen Elements b zu a bezüglich einer Restklassengruppe n (a und n müssen teilerfremd sein):

```
ab \equiv 1 \mod n \iff s \equiv b \mod n \quad \text{für } 1 = ggT(a, n)
```

1.3.1 Erweiterter Euklidischer Algorithmus

```
static int[] eea(int a, int b) {
   int[] dst = new int[3];
   if (b == 0) {
      dst[0] = a;
      dst[1] = 1;
      return dst; // a, 1, 0
   }
   dst = eea(b, a % b);
   int tmp = dst[2];
   dst[2] = dst[1] - ((a / b) * dst[2]);
   idst[1] = tmp;
   return dst;
}
```

2 Datenstukturen

2.1 Fenwick Tree (Binary Indexed Tree)

```
class FenwickTree {
    private int[] values;
    private int n;
    public FenwickTree(int n) {
      this.n = n;
      values = new int[n];
    public int get(int i) { //get value of i
      int x = values[0];
      while (i > 0) {
10
11
        x += values[i];
        i -= i & -i; }
12
      return x;
13
14
    public void add(int i, int x) { // add x to interval [i,n]
15
      if (i == 0) values[0] += x;
16
17
        while (i < n) {
18
19
          values[i] += x;
          i += i & -i; }
20
```

```
21 }
22 }
```

3 Graphenalgorithmen

3.1 Topologische Sortierung

```
static List<Integer> topoSort(Map<Integer, List<Integer>> edges,
      Map<Integer, List<Integer>> revedges) {
    Queue<Integer> q = new LinkedList<Integer>();
    List<Integer> ret = new LinkedList<Integer>();
    Map<Integer, Integer> indeg = new HashMap<Integer, Integer>();
    for (int v : revedges.keySet()) {
      indeg.put(v, revedges.get(v).size());
      if (revedges.get(v).size() == 0)
        q.add(v);
10
    while (!q.isEmpty()) {
11
      int tmp = q.poll();
      ret.add(tmp);
13
14
      for (int dest : edges.get(tmp)) {
        indeg.put(dest, indeg.get(dest) - 1);
15
        if (indeg.get(dest) == 0)
16
17
          q.add(dest);
18
      }
    }
19
    return ret;
```

3.2 Prim (Minimum Spanning Tree)

```
1 #define WHITE 0
2 #define BLACK 1
3 #define INF INT_MAX
5 int baum( int **matrix, int N){
    int i, sum = 0;
    int color[N];
    int dist[N];
10
       // markiere alle Knoten ausser 0 als unbesucht
    color[0] = BLACK;
12
    for( i=1; i<N; i++){</pre>
13
      color[i] = WHITE;
14
      dist[i] = INF;
15
16
17
       // berechne den Rand
18
    for( i=1; i<N; i++){</pre>
19
           if( dist[i] > matrix[i][nextIndex]){
20
21
               dist[i] = matrix[i][nextIndex];
22
23
      }
    while( 1){
25
      int nextDist = INF, nextIndex = -1;
26
       /* Den naechsten Knoten waehlen */
28
      for(i=0; i< N; i++){
29
         if( color[i] != WHITE) continue;
30
31
32
         if( dist[i] < nextDist){</pre>
           nextDist = dist[i];
33
           nextIndex = i;
34
35
      }
36
37
       /* Abbruchbedingung*/
38
      if( nextIndex == -1) break;
39
       /* Knoten in MST aufnehmen */
41
      color[nextIndex] = RED;
42
      sum += nextDist;
```

```
/* naechste kuerzeste Distanzen berechnen */
45
46
      for( i=0; i<N; i++){
               if( i == nextIndex || color[i] == BLACK ) continue;
47
48
49
               if( dist[i] > matrix[i][nextIndex]){
                   dist[i] = matrix[i][nextIndex];
50
51
52
    }
53
54
55
    return sum;
```

3.3 Maximaler Fluss (Ford-Fulkerson)

```
#include <stdio.h>
2 #include <limits.h>
4 #define n_MAX 36
5 #define m_MAX 30
6 #define SIZE (m+6+2)
7 #define SIZE_MAX 38
8 #define QUELLE (m+6)
9 #define SENKE (m+7)
10 #define NONE -1
#define INF INT_MAX/2
13 int n, m;
14 int capacity[SIZE_MAX][SIZE_MAX];
int flow[SIZE_MAX][SIZE_MAX];
int queue[SIZE_MAX], *head, *tail;
17 int state[SIZE_MAX];
18 int pred[SIZE_MAX];
19
20 enum { XS, S, M, L, XL, XXL };
  enum { UNVISITED, WAITING, PROCESSED };
23 int strToOffset( char *str);
24 int maxFlow( int quelle, int senke);
26 int main(){
27
      int numOfProps;
28
29
      scanf("%d\n", &numOfProps);
30
       while( numOfProps--){
31
           scanf("%d_{\sim}%d\n", &n, &m);
32
33
34
           int i, j;
35
           /* Matrix initialisieren */
36
37
           for( i=0; i < SIZE; i++){
               for( j=0; j < SIZE; j++){</pre>
38
                    capacity[i][j] = flow[i][j] = 0;
39
40
                    if( i == QUELLE && j < m){</pre>
41
42
                        capacity[i][j] = 1;
43
                        continue;
                   }
44
45
                    if(j == SENKE \&\& i >= m \&\& i < QUELLE){
46
47
                        capacity[i][j] = n/6;
                        continue;
                   }
49
50
               }
51
52
53
           char str[4];
54
           /* Matrix einlesen */
55
           for( i=0; i< m; i++){</pre>
               scanf("%s", str);
57
               capacity[i][m+strToOffset(str)] = 1;
58
59
               scanf("%s", str);
               capacity[i][m+strToOffset(str)] = 1;
```

```
}
62
63
            int foo = maxFlow( QUELLE, SENKE);
64
            printf("%s\n", foo >= m ? "YES" : "NO");
65
66
67
68
69
       return 0;
70 }
71
72 int strToOffset( char *str){
73
       /*snip*/
74 }
75
76 void enqueue( int x){
       *tail++ = x;
       state[x] = WAITING;
78
79 }
80
81 int dequeue(){
82
       int x = *head++;
       state[x] = PROCESSED;
83
84
       return x;
85
86
87 int bfs( int start, int target){
       int u, v;
88
       for( u=0; u < SIZE; u++){
89
            state[u] = UNVISITED;
91
       head = tail = queue;
92
       pred[start] = NONE;
94
95
       enqueue(start);
96
       while( head < tail){</pre>
97
98
            u = dequeue();
99
            for( v= 0; v < SIZE; v++){
100
                if( state[v] == UNVISITED &&
101
                     capacity[u][v] - flow[u][v] > 0){
102
103
104
                     enqueue(v);
                     pred[v] = u;
105
106
                }
107
            }
108
       return state[target] == PROCESSED;
110
111 }
112
int maxFlow( int quelle, int senke){
       int max_flow = 0;
114
115
116
       int u;
117
       while( bfs( quelle, senke)){
118
119
            int increment = INF, temp;
120
            for( u= senke; pred[u] != NONE; u = pred[u]){
121
                temp = capacity[pred[u]][u] - flow[pred[u]][u];
122
                if( temp < increment){</pre>
123
                     increment = temp;
124
            }
126
127
            for( u= senke; pred[u] != NONE; u = pred[u]){
128
                flow[pred[u]][u] += increment;
129
                flow[u][pred[u]] -= increment;
130
131
132
133
            max_flow += increment;
134
135
       return max_flow;
136
```

137 }

4 Geometrische Algorithmen

4.1 Graham Scan (Convex Hull)

```
static List<P> graham(List<P> 1) {
    if (1.size() < 3)
      return 1;
    P \text{ temp} = 1.get(0);
    for (P p : 1)
      if (temp.y > p.y \mid \mid temp.y == p.y \&\& temp.x > p.x)
        temp = p;
    final P start = temp; // min y (then leftmost)
    {\tt Collections.sort(1, \ \textbf{new} \ \texttt{Comparator} < P > () \ \{}
10
      public int compare(P o1, P o2) {
11
        if (new Double(Math.atan2(o1.y - start.y, o1.x - start.x)) // same angle
12
             .compareTo(Math.atan2(o2.y - start.y, o2.x - start.x)) == 0)
13
           return new Double(Math.sqrt((o1.x - start.x)
               * (o1.x - start.x) + (o1.y - start.y)
15
               * (o1.y - start.y))).compareTo((o2.x - start.x)
16
               * (o2.x - start.x) + (o2.y - start.y)
17
               * (o2.y - start.y)); // use distance
18
19
        return new Double(Math.atan2(o1.y - start.y, o1.x - start.x))
             .compareTo(Math.atan2(o2.y - start.y, o2.x - start.x));
20
      }
21
    });
    Stack<P> s = new Stack<P>();
23
24
    s.add(start);
    s.add(1.get(1));
    for (int i = 2; i < 1.size(); i++) {</pre>
26
27
      while (s.size() >= 2
         && ccw(s.get(s.size() - 2), s.get(s.size() - 1), l.get(i)) <= 0)
28
29
        s.pop();
      s.push(l.get(i));
30
31
32
    return s;
33 }
35 // turn is counter-clockwise if > 0; collinear if = 0; clockwise else
36 static double ccw(P p1, P p2, P p3) {
   return (p2.x - p1.x) * (p3.y - p1.y) - (p2.y - p1.y) * (p3.x - p1.x);
37
38 }
39
40 public static class P {
    double x, y;
42.
43
    P(double x, double y) {
44
      this.x = x;
      this.y = y;
45
46
    // polar coordinates (not used)
47
    // double r() { return Math.sqrt(x * x + y * y); }
48
    // double d() { return Math.atan2(y, x); }
  4.2 Punkt in Polygon
  * -1: A liegt links von BC (ausser unterer Endpunkt)
   * 0: A auf BC
   * +1: sonst
```

```
6 public static int KreuzProdTest(double ax, double ay, double bx, double by,
      double cx, double cy) {
    if (ay == by && by == cy) {
      if ((bx <= ax && ax <= cx) || (cx <= ax && ax <= bx)) return 0;</pre>
10
      else return +1;
11
    if (by > cy) {
12
      double tmpx = bx, tmpy = by;
13
14
      bx = cx;
15
      by = cy;
      cx = tmpx;
```

```
cy = tmpy;
18
    if (ay == by && ax == bx) return 0;
19
    if (ay \le by \mid \mid ay > cy) return +1;
20
    double delta = (bx - ax) * (cy - ay) - (by - ay) * (cx - ax);
21
    if (delta > 0) return -1;
    else if (delta < 0) return +1;</pre>
23
24
    else return 0;
25 }
26
27 /**
28
   * Input: P[i] (x[i],y[i]); P[0]:=P[n]
   * -1: Q ausserhalb Polygon
29
   * 0: Q auf Polygon
   * +1: Q innerhalb des Polygons
31
32
33 public static int PunktInPoly(double[] x, double[] y, double qx, double qy) {
    int t = -1;
34
    for (int i = 0; i < x.length - 1; i++)
35
      t = t * KreuzProdTest(qx, qy, x[i], y[i], x[i + 1], y[i + 1]);
37
    return t;
```

5 Verschiedenes

5.1 Potenzmenge

```
static <T> Iterator<List<T>> powerSet(final List<T> 1) {
    return new Iterator<List<T>>() {
      int i; // careful: i becomes 2^1.size()
      public boolean hasNext() {
        return i < (1 << 1.size());
      public List<T> next() {
        Vector < T > temp = new Vector < T > ();
        for (int j = 0; j < 1.size(); j++)
          if (((i >>> j) & 1) == 1)
10
            temp.add(l.get(j));
11
12
        return temp;
13
14
      }
      public void remove() {}
15
16
      };
    }
```

5.2 Longest Common Subsequence

```
#include <stdio.h>
2 #include <stdlib.h>
3 #include <string.h>
6 int lcs( char *a, char *b){
      int len = strlen( a);
      int lenb =strlen(b);
      int *zeile = malloc( (len+1) * sizeof(int)), *temp,
10
           *neue = malloc((len+1) * sizeof(int)), i, j;
11
      for(i=0; i<len+1; i++){</pre>
13
14
           zeile[i] = neue[i] = 0;
15
16
      for(j=0; j<lenb; j++){
17
           for(i=0; i<len; i++){</pre>
18
               if( a[i] == b[j]){
19
                   neue[i+1] = zeile[i] + 1;
20
               } else {
21
                   neue[i+1] = neue[i] > zeile[i+1] ? neue[i] : zeile[i+1];
22
23
           }
24
25
           temp = zeile;
26
           zeile = neue;
          neue = temp;
27
      }
```

```
29
30     int res = zeile[len];
31     free( zeile);
32     free( neue);
33     return res;
34 }
```