

Section 3.5 Numbers; 8, 17, 42, 48, 58, 66(b)
Section 3.6 Numbers; 4, 8, 12, 16, 32, 44, 50.
Section 4.2 Number; 8

3.5.8 Let S be the collection of vectors $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ in \mathbb{R}^3 that satisfy the given property;

$$|x - y| = |y - z|$$

Either prove that S forms a subspace of \mathbb{R}^3 or give a counterexample to show that it does not.

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3.5.17 Give bases for $\text{row}(A)$, $\text{col}(A)$, and $\text{null}(A)$.

$$A = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 1 & 1 \end{bmatrix}.$$

■

3.5.42 *If A is a 4×2 matrix, what are the possible values of $\text{nullity}(A)$?*

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3.5.48 Do $\begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$, and $\begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$ form a basis for \mathbb{R}^4 ?

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3.5.58 *If A and B are $n \times n$ matrices of rank n , prove that AB has rank n .*

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3.5.66(b) Let A be a skew-symmetric $n \times n$ matrix (see page 162). Prove that $I + A$ is invertible. [Hint: Show that $\text{null}(I + A) = \{0\}$].

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3.6.4 Prove that the transformation is linear, using the definition (or the Remark following Example 3.55):

$$T \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x + 2y \\ 3x - 4y \end{bmatrix}$$

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3.6.8 Give a counterexample to show that the transformation is not linear:

$$T \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} |x| \\ |y| \end{bmatrix}$$

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3.6.12 Find the standard matrix of the linear transformation in Exercise 4.

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3.6.16 Show that the transformation from \mathbb{R}^2 to \mathbb{R}^2 is linear by showing that it is a matrix transformation: R rotates a vector 45° counterclockwise about the origin.

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3.6.32 Verify Theorem 3.32 by finding the matrix of $S \circ T$ (a) by direct substitution and (b) by matrix multiplication of $[S][T]$:

$$T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_2 \\ -x_1 \end{bmatrix}$$

,

$$S \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} y_1 + 3y_2 \\ y_1 - y_2 \end{bmatrix}$$

■

3.6.44 Let T be a linear transformation from \mathbb{R}^2 to \mathbb{R}^2 (or \mathbb{R}^3 to \mathbb{R}^3). Prove that T maps a straight line to a straight line or a point. [Hint: use the vector form of the equation of a line.]

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3.6.50 Let $ABCD$ be the square with vertices $(-1, 1)$, $(1, 1)$, $(1, -1)$, and $(-1, -1)$. Use the results in Exercises 44 and 45 to find and draw the image of $ABCD$ under the given transformation:

$$T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 + 2x_2 \\ -3x_1 + x_2 \end{bmatrix}$$

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4.2.8 Compute the determinant using cofactor expansion along any row or column that seems convenient:

$$\begin{vmatrix} 1 & 1 & -1 \\ 2 & 0 & 1 \\ 3 & -2 & 1 \end{vmatrix}$$

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