

# Quicksort

## References:

*Introduction to Algorithms*

by Cormen, Leiserson, Rivest & Stein [Chapter 7]

*Fundamentals of Algorithmics*

by Gilles Brassard and Paul Bratley [Chapter 10]

$A$ : array to be *in-place* sorted.  
 $p$  and  $r$  are the start and the end indices.  
 $q$  is the final index of the pivot.

QUICKSORT( $A, p, r$ )

1    **if**  $p < r$

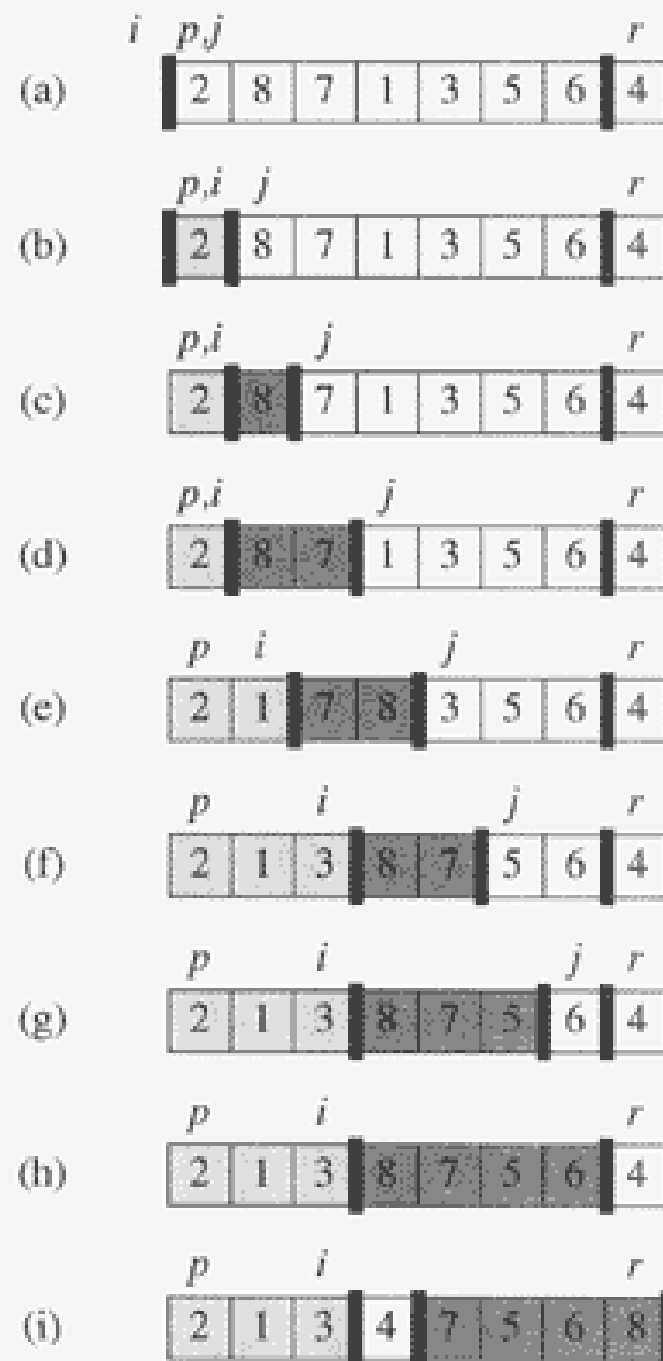
2        **then**  $q \leftarrow \text{PARTITION}(A, p, r)$

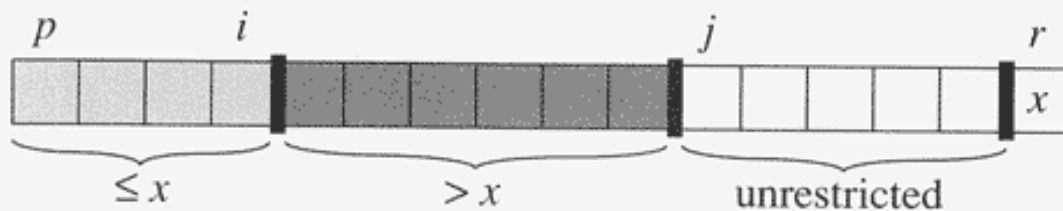
3            QUICKSORT( $A, p, q - 1$ )

4            QUICKSORT( $A, q + 1, r$ )

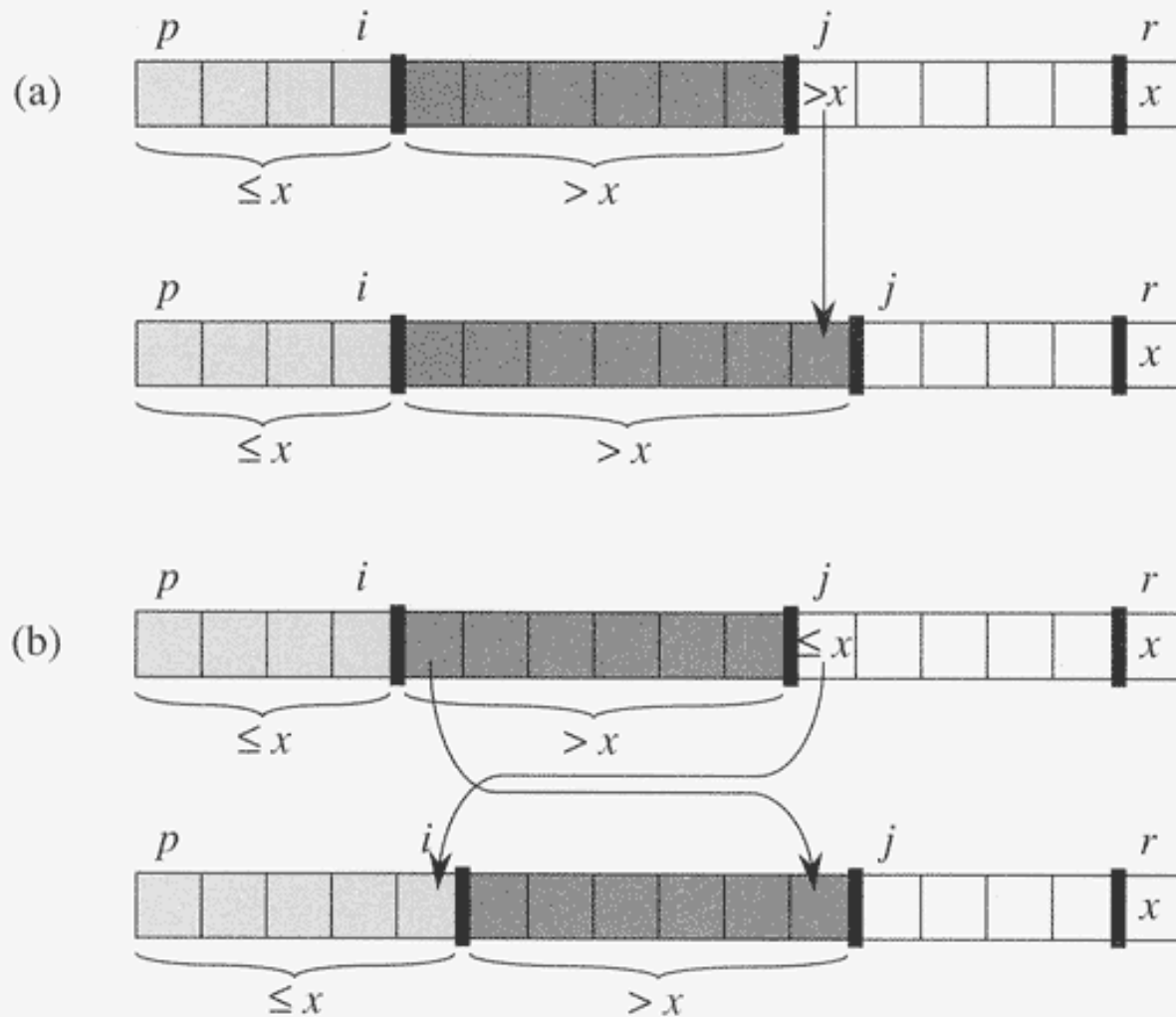
PARTITION( $A, p, r$ )

```
1   $x \leftarrow A[r]$ 
2   $i \leftarrow p - 1$ 
3  for  $j \leftarrow p$  to  $r - 1$ 
4      do if  $A[j] \leq x$ 
5          then  $i \leftarrow i + 1$ 
6              exchange  $A[i] \leftrightarrow A[j]$ 
7  exchange  $A[i + 1] \leftrightarrow A[r]$ 
8  return  $i + 1$ 
```





**Figure 7.2** The four regions maintained by the procedure PARTITION on a subarray  $A[p..r]$ . The values in  $A[p..i]$  are all less than or equal to  $x$ , the values in  $A[i+1..j-1]$  are all greater than  $x$ , and  $A[r] = x$ . The values in  $A[j..r-1]$  can take on any values.



**Figure 7.3** The two cases for one iteration of procedure PARTITION. (a) If  $A[j] > x$ , the only action is to increment  $j$ , which maintains the loop invariant. (b) If  $A[j] \leq x$ , index  $i$  is incremented,  $A[i]$  and  $A[j]$  are swapped, and then  $j$  is incremented. Again, the loop invariant is maintained.

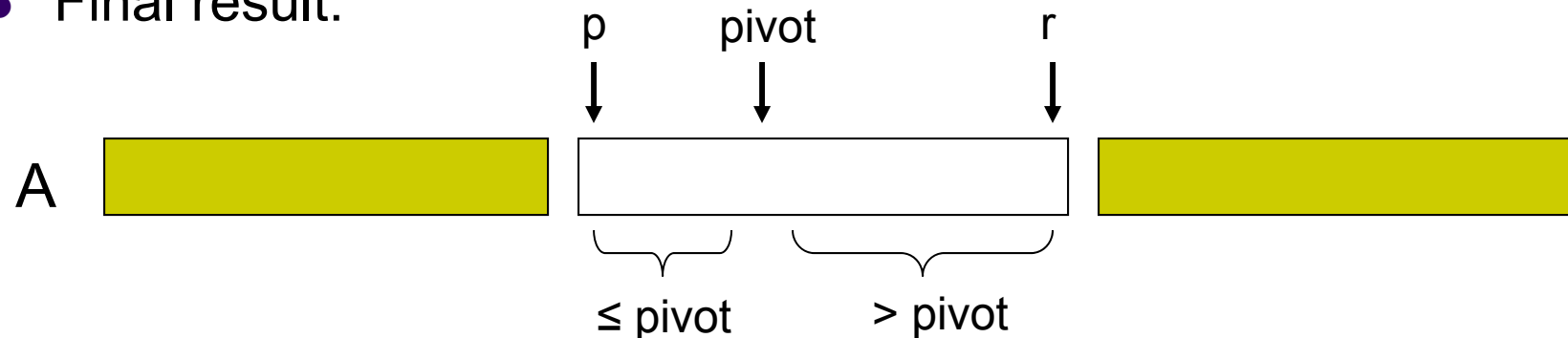
# Trace of Partition



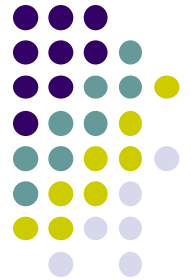
PARTITION( $A, p, r$ )

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1   $i \leftarrow p - 1$ 
2  for  $j \leftarrow p$  to  $r - 1$ 
3      if  $A[j] \leq A[r]$ 
4           $i \leftarrow i + 1$ 
5          swap  $A[i]$  and  $A[j]$ 
6  swap  $A[i + 1]$  and  $A[r]$ 
7  return  $i + 1$ 
```

- $A[r]$  is called the ***pivot***
- Partitions the elements  $A[p \dots r-1]$  into two sets, those  $\leq$  pivot and those  $>$  pivot
- Operates in place
- Final result:



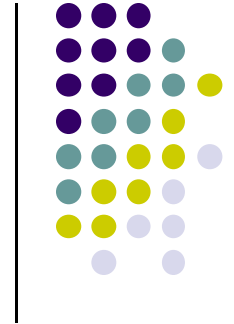
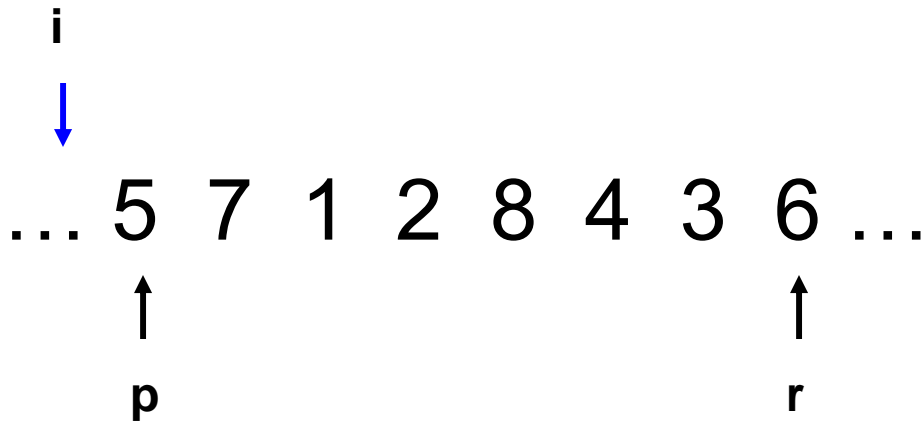




... 5 7 1 2 8 4 3 6 ...  
    ↑          ↑  
    p          r

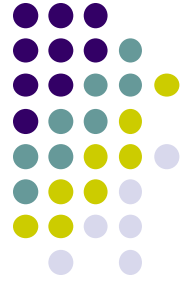
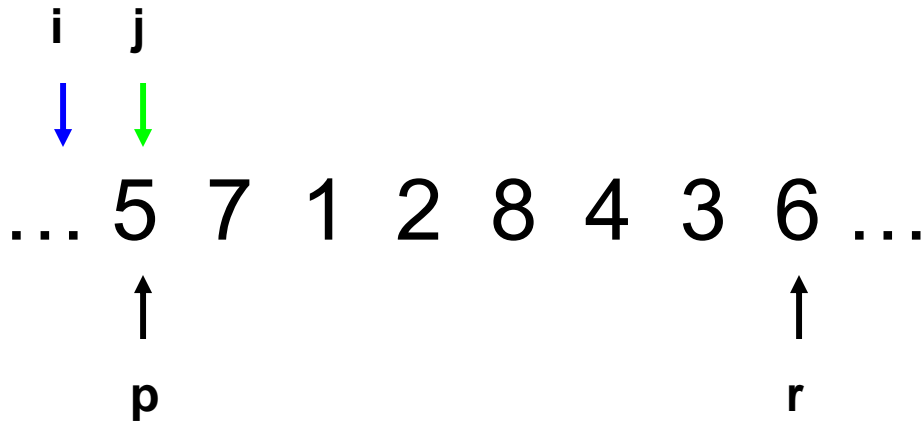
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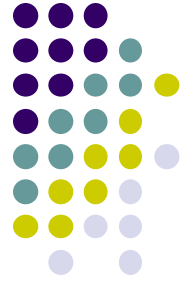
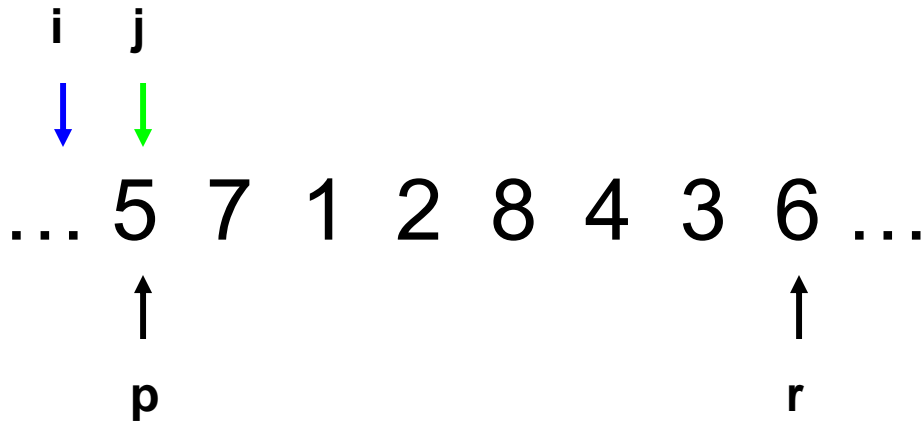
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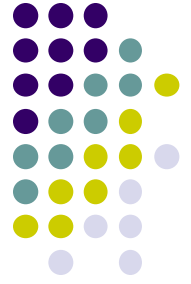
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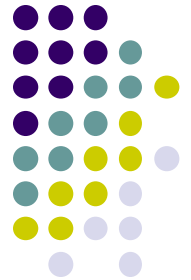
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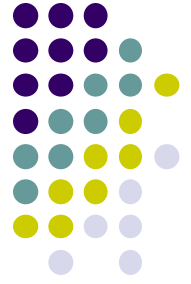
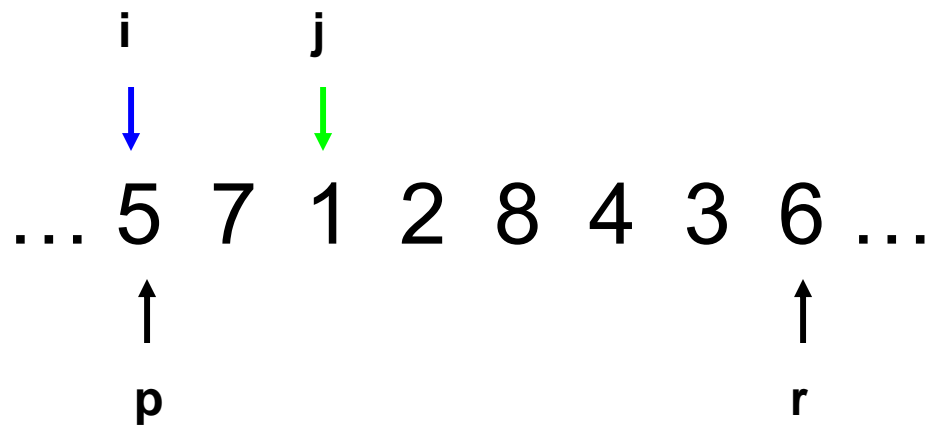
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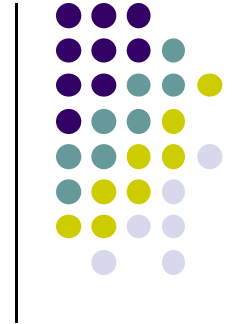
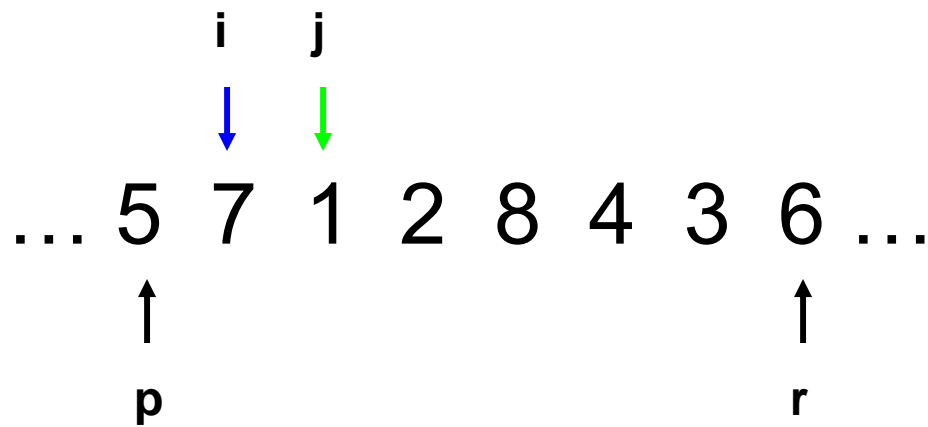
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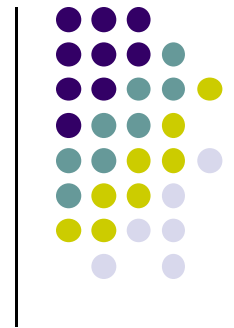
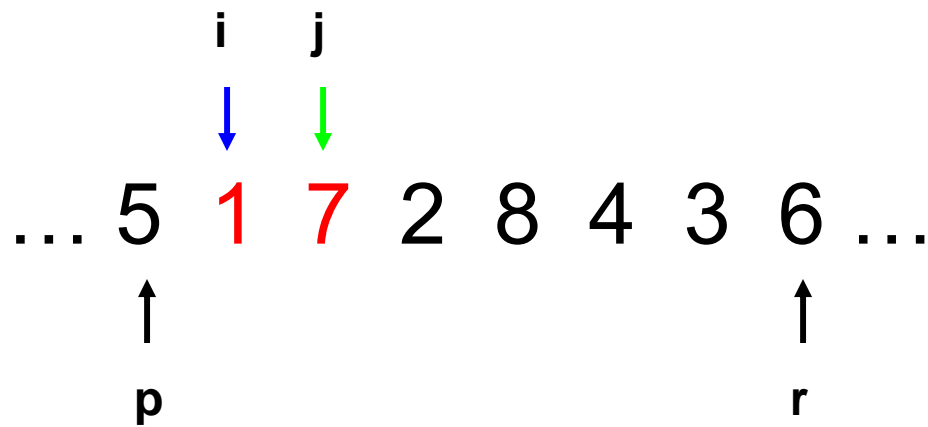
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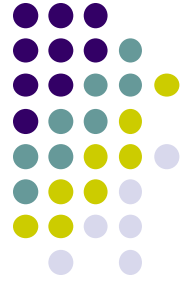
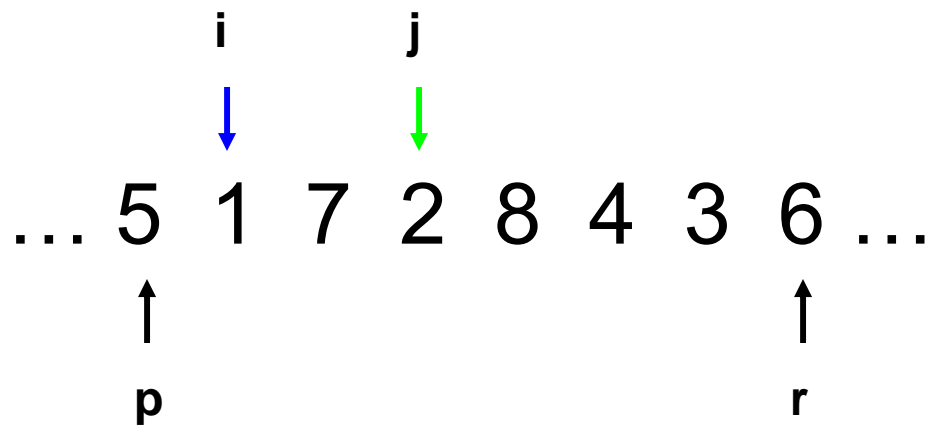
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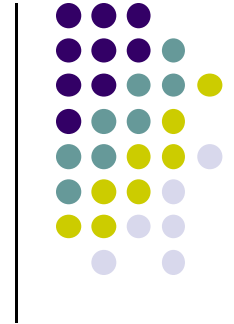
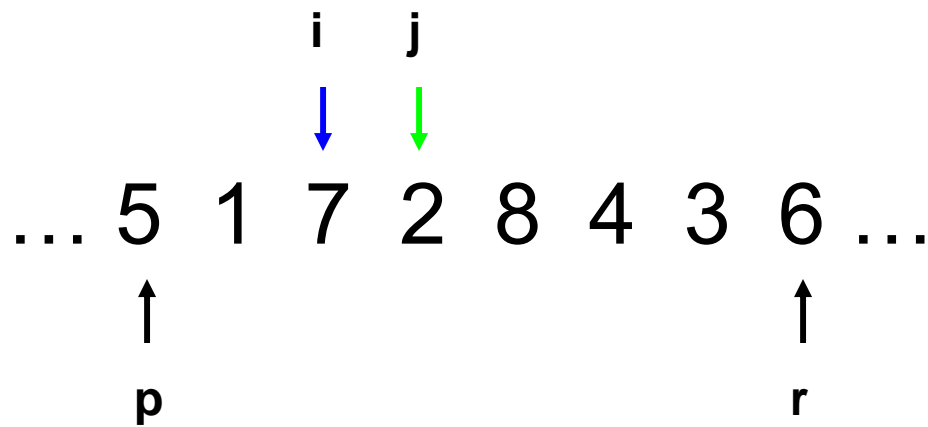
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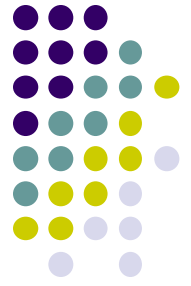
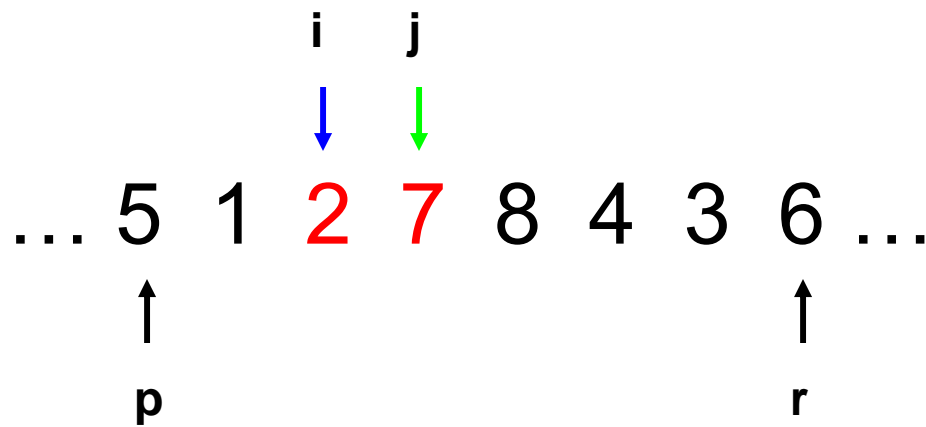
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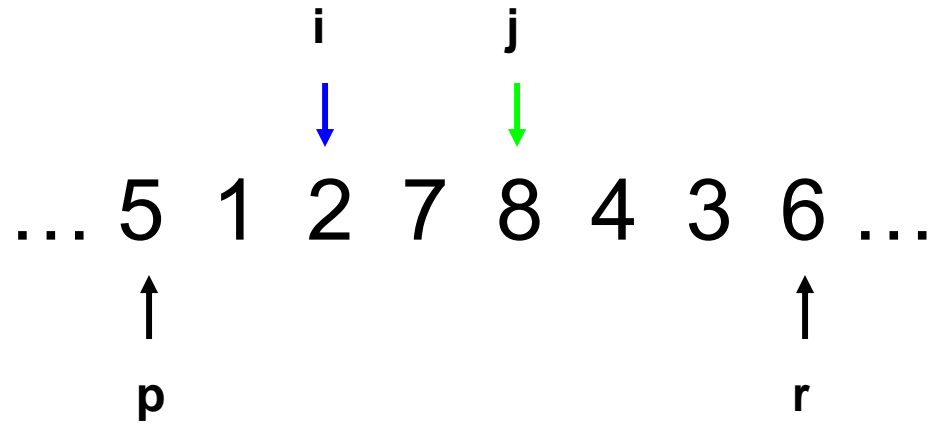
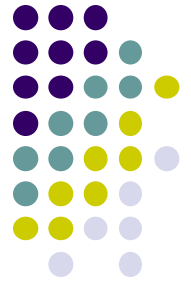
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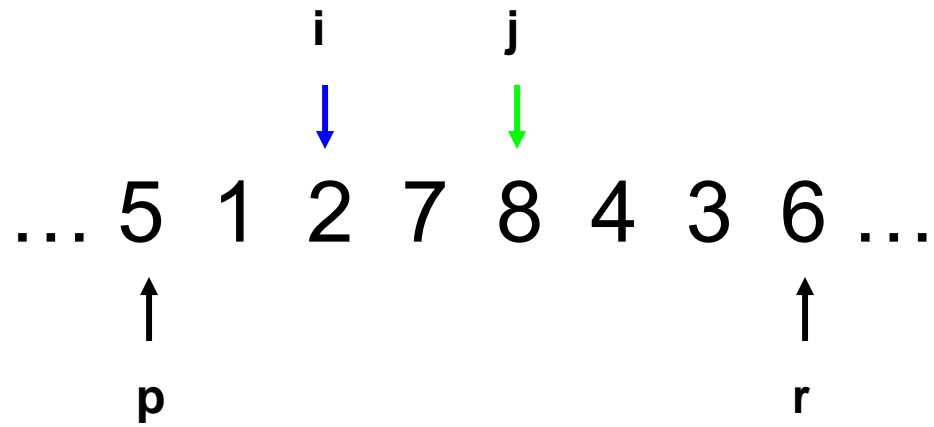
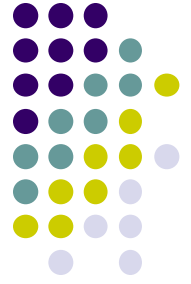
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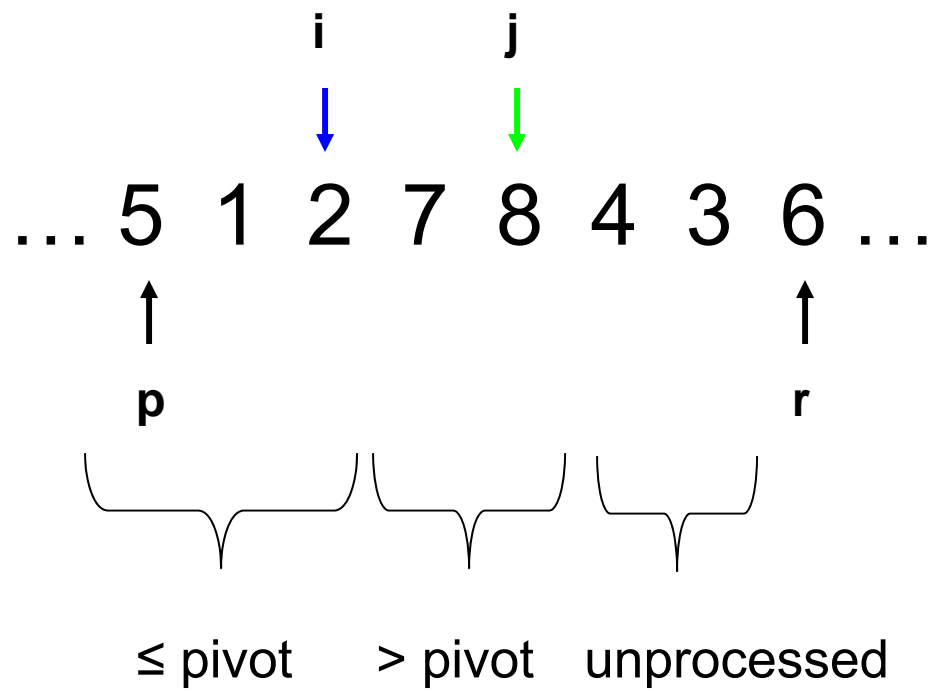
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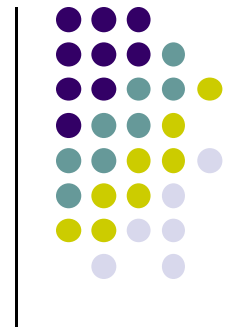
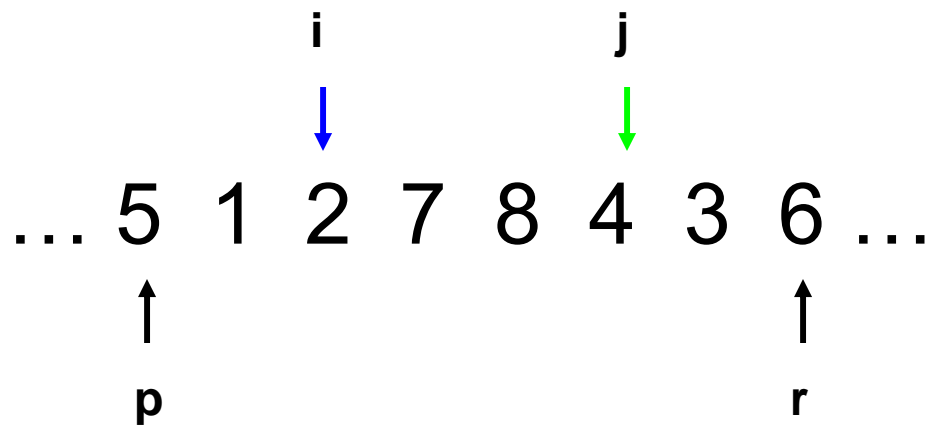
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What's happening?







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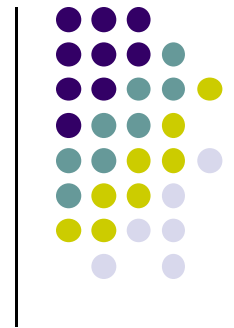
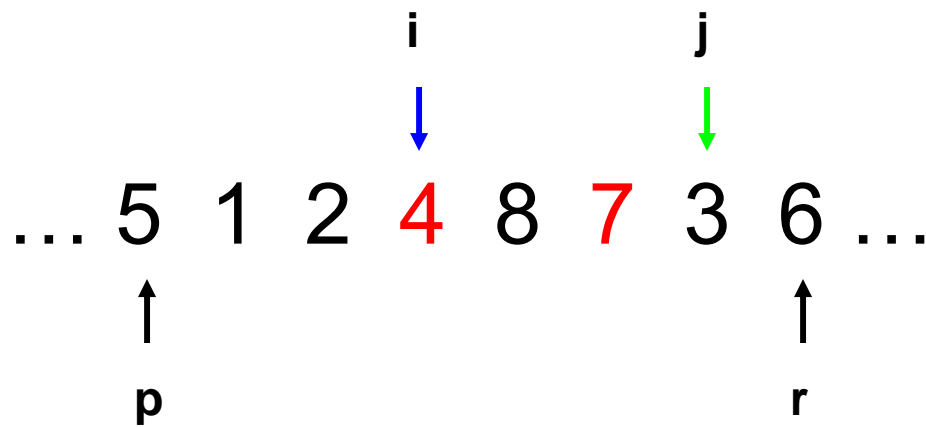
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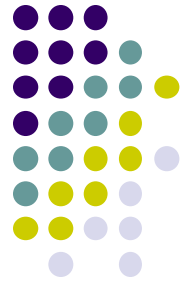
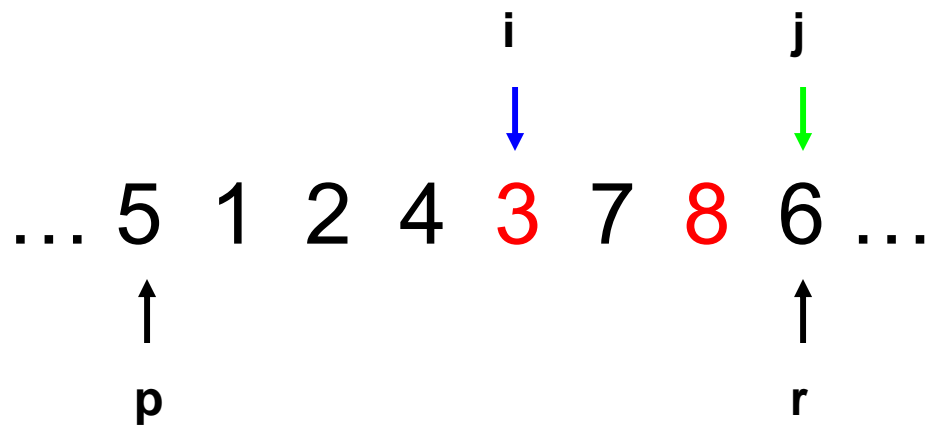
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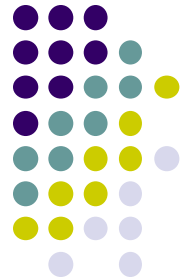
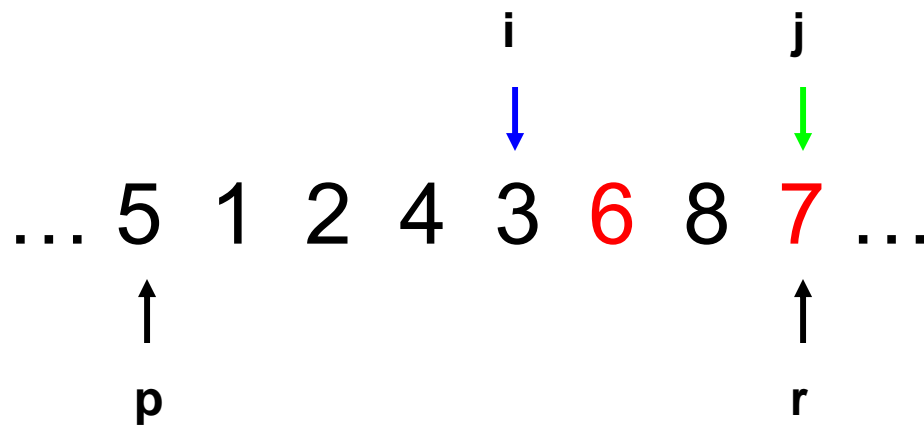
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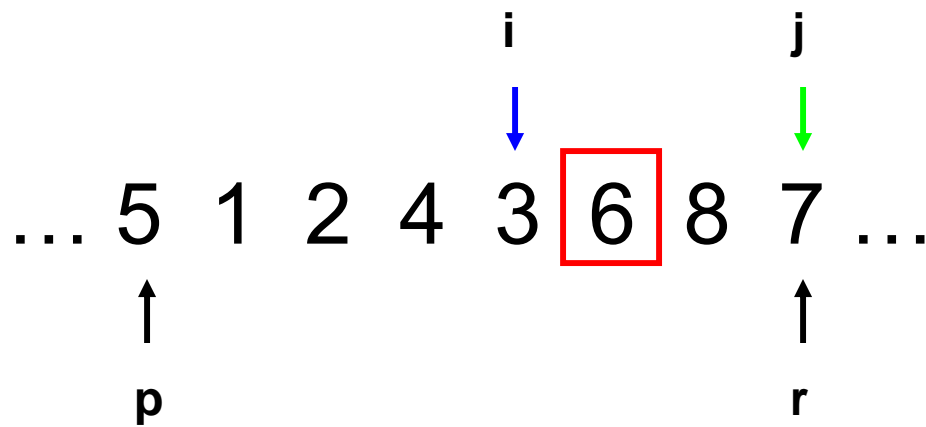
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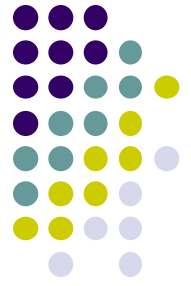
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# Trace of Quicksort

# Quicksort



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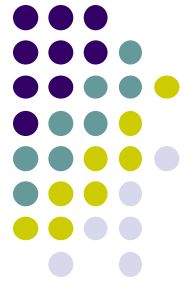
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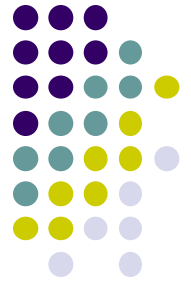
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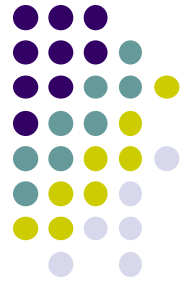
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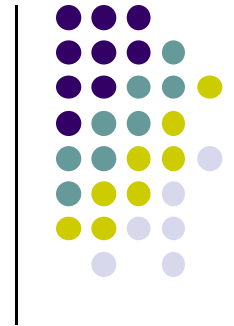
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1 2 3 4 6 8 7 5

QUICKSORT( $A, p, r$ )

1 **if**  $p < r$

2  $q \leftarrow \text{PARTITION}(A, p, r)$

3 QUICKSORT( $A, p, q - 1$ )

4 QUICKSORT( $A, q + 1, r$ )



1 2 3 4 5 8 7 6

What happens here?

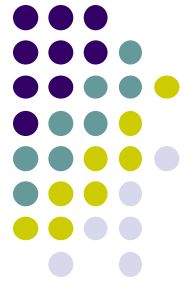
QUICKSORT( $A, p, r$ )

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4 QUICKSORT( $A, q + 1, r$ )



1 2 3 4 5 8 7 6

QUICKSORT( $A, p, r$ )

1   **if**  $p < r$

2                    $q \leftarrow \text{PARTITION}(A, p, r)$

3                   QUICKSORT( $A, p, q - 1$ )

4                   QUICKSORT( $A, q + 1, r$ )



1 2 3 4 5 8 7 6

QUICKSORT( $A, p, r$ )

1 if  $p < r$

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4 QUICKSORT( $A, q + 1, r$ )



1 2 3 4 5 **6** 7 8

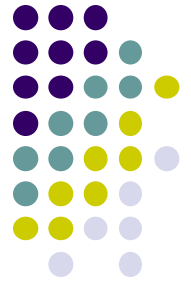
QUICKSORT( $A, p, r$ )

1 **if**  $p < r$

2  $q \leftarrow \text{PARTITION}(A, p, r)$

3 QUICKSORT( $A, p, q - 1$ )

4 QUICKSORT( $A, q + 1, r$ )



1 2 3 4 5 6 7 8

QUICKSORT( $A, p, r$ )

1   **if**  $p < r$

2            $q \leftarrow \text{PARTITION}(A, p, r)$

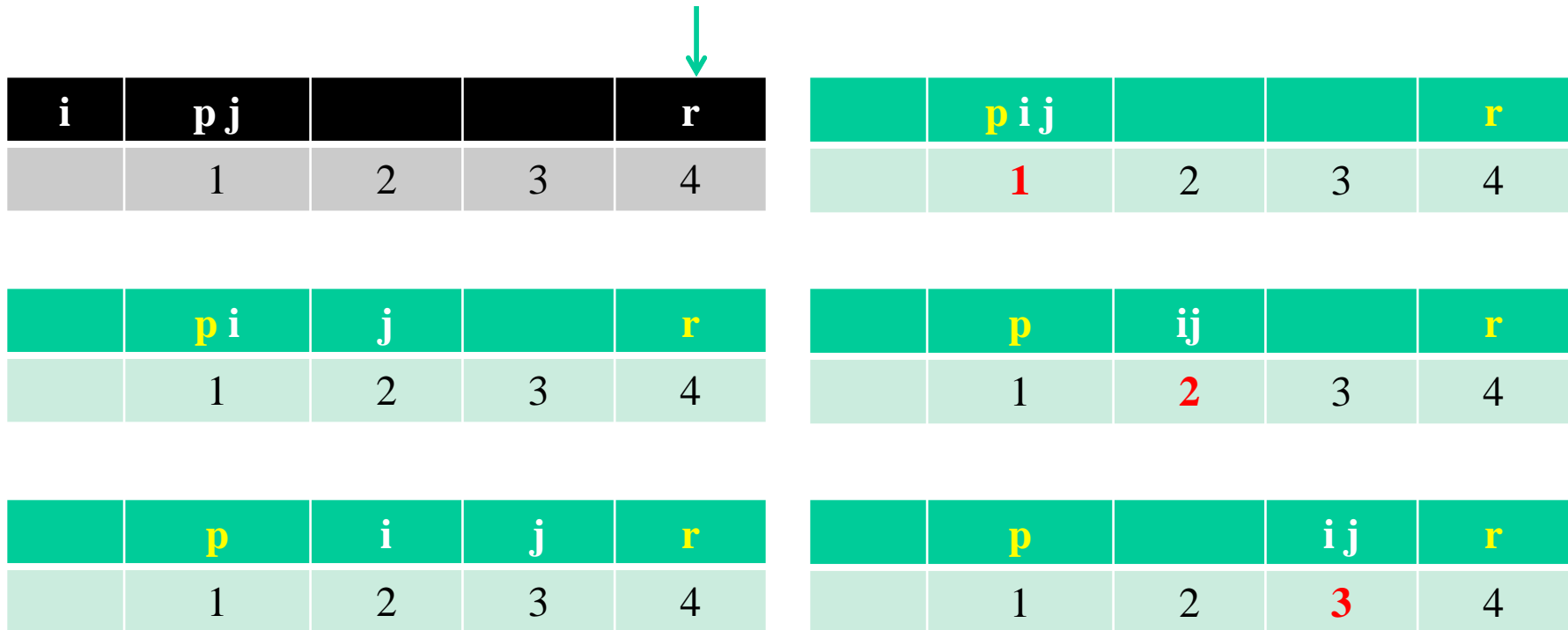
3           QUICKSORT( $A, p, q - 1$ )

4           QUICKSORT( $A, q + 1, r$ )

# Quicksort Analysis

- (1) “Bad” split on sorted lists
- (2) “Bad” split vs Uneven split
- (3) Average case analysis

Sorted List : **Partition** (Beginning and ending of each iteration)



	p		i j	r
	1	2	3	4

**Red:**  $O(n)$  comparisons and  $O(n)$  (trivial) swaps for each call of **Partition**;  
 $T(n) = T(n-1) + O(n)$ ;  
 $O(n^2)$  swaps for quicksort



### Reverse Sorted List : Partition (Beginning and ending of each iteration)

<b>i</b>	<b>p j</b>			<b>r</b>
	4	3	2	1

	<b>p i j</b>			<b>r</b>
	4	3	2	1

	<b>p i</b>	<b>j</b>		<b>r</b>
	4	3	2	1

	<b>p i</b>	<b>j</b>		<b>r</b>
	4	3	2	1

	<b>p i</b>		<b>j</b>	<b>r</b>
	4	3	2	1

	<b>p i</b>		<b>j</b>	<b>r</b>
	4	3	<b>2</b>	1

	<b>p</b> i		<b>j</b>	<b>r</b>
	<b>1</b>	3	2	<b>4</b>

↑

**Red:**  $O(n)$  comparisons and one swap for each call of Partition;

$$T(n) = T(n-1) + O(n)$$

## O(n) swaps for quicksort

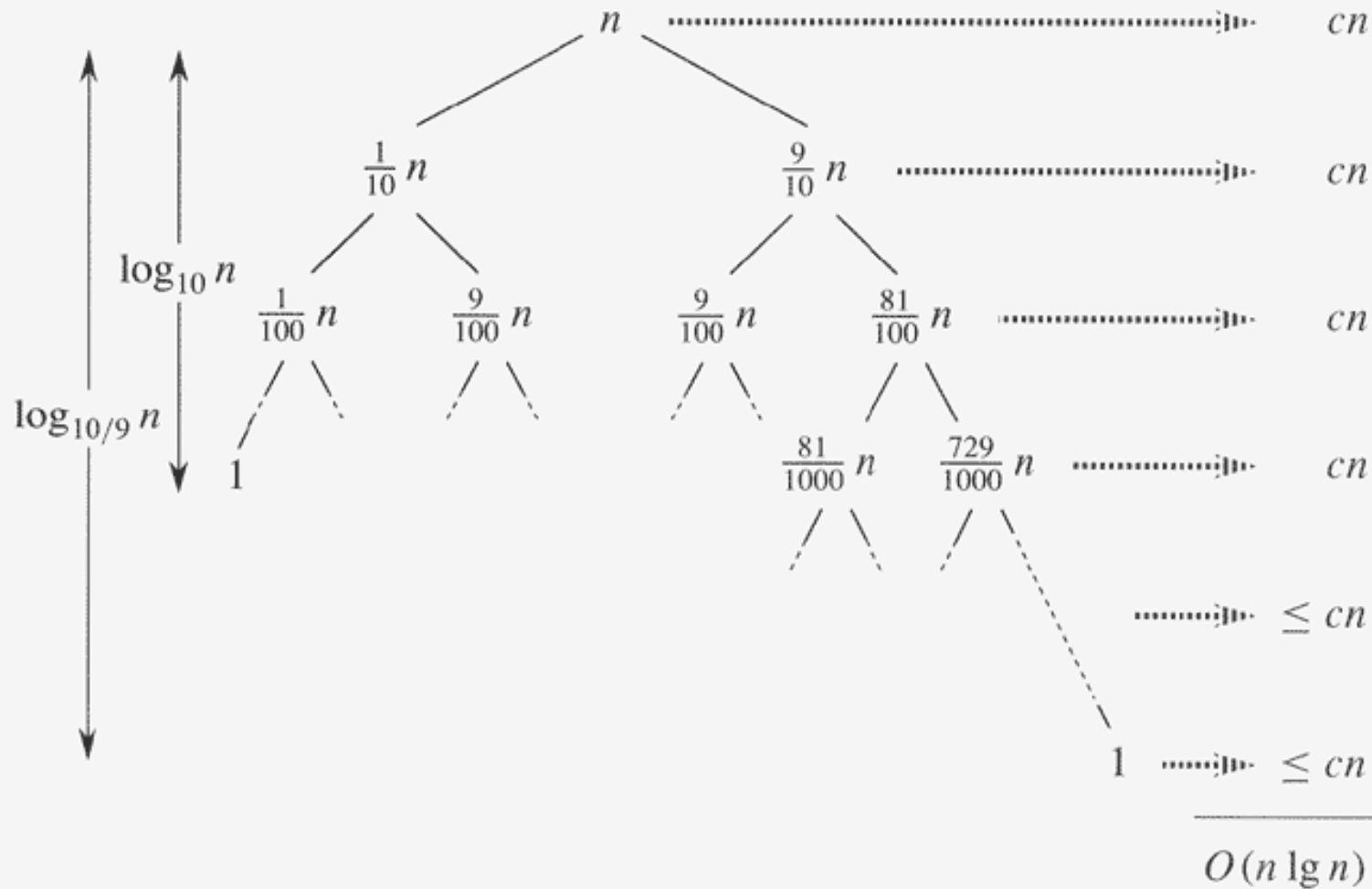
## O(n<sup>2</sup>) comparisons for quicksort

# Quicksort Average case?

- How close to “even” split do we need to maintain an  $O(n \log n)$  running time?
  - Say the Partition procedure always splits the array into some constant ratio  $b$ -to- $a$ , e.g., 9-to-1
  - What is the recurrence?

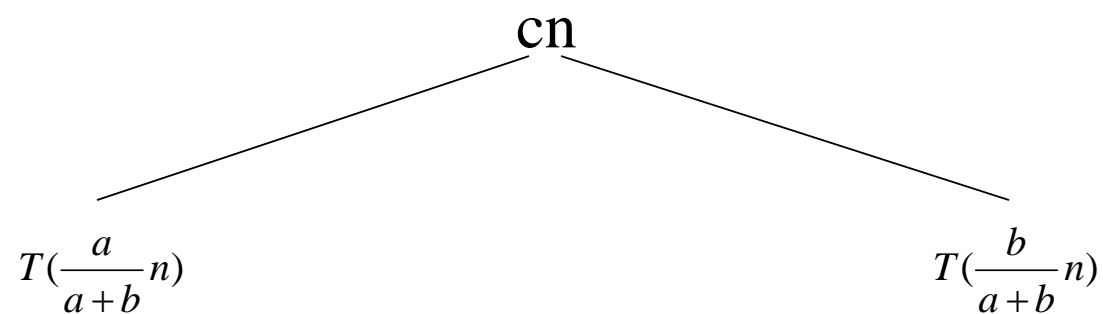
$$T(n) \leq T\left(\frac{a}{a+b}n\right) + T\left(\frac{b}{a+b}n\right) + cn$$

$$E.g., T(n) \leq T\left(\frac{9}{10}n\right) + T\left(\frac{1}{10}n\right) + cn$$

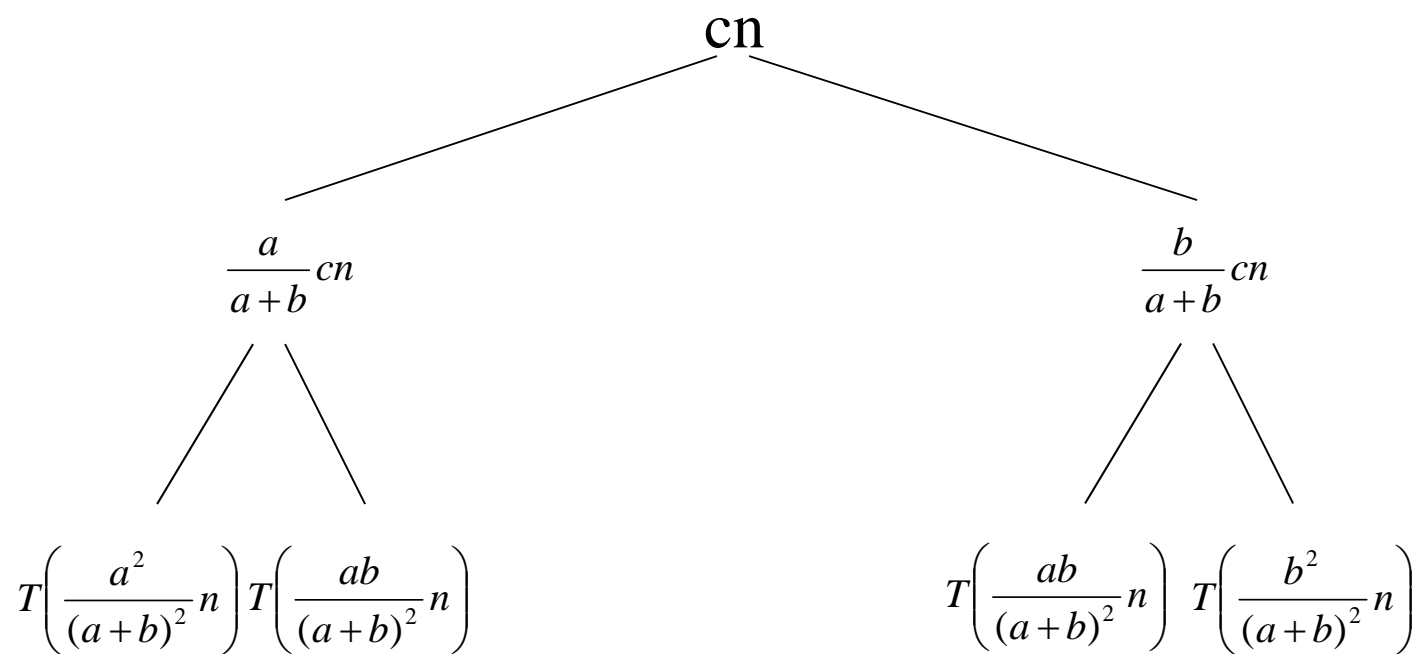


**Figure 7.4** A recursion tree for QUICKSORT in which PARTITION always produces a 9-to-1 split, yielding a running time of  $O(n \lg n)$ . Nodes show subproblem sizes, with per-level costs on the right. The per-level costs include the constant  $c$  implicit in the  $\Theta(n)$  term.

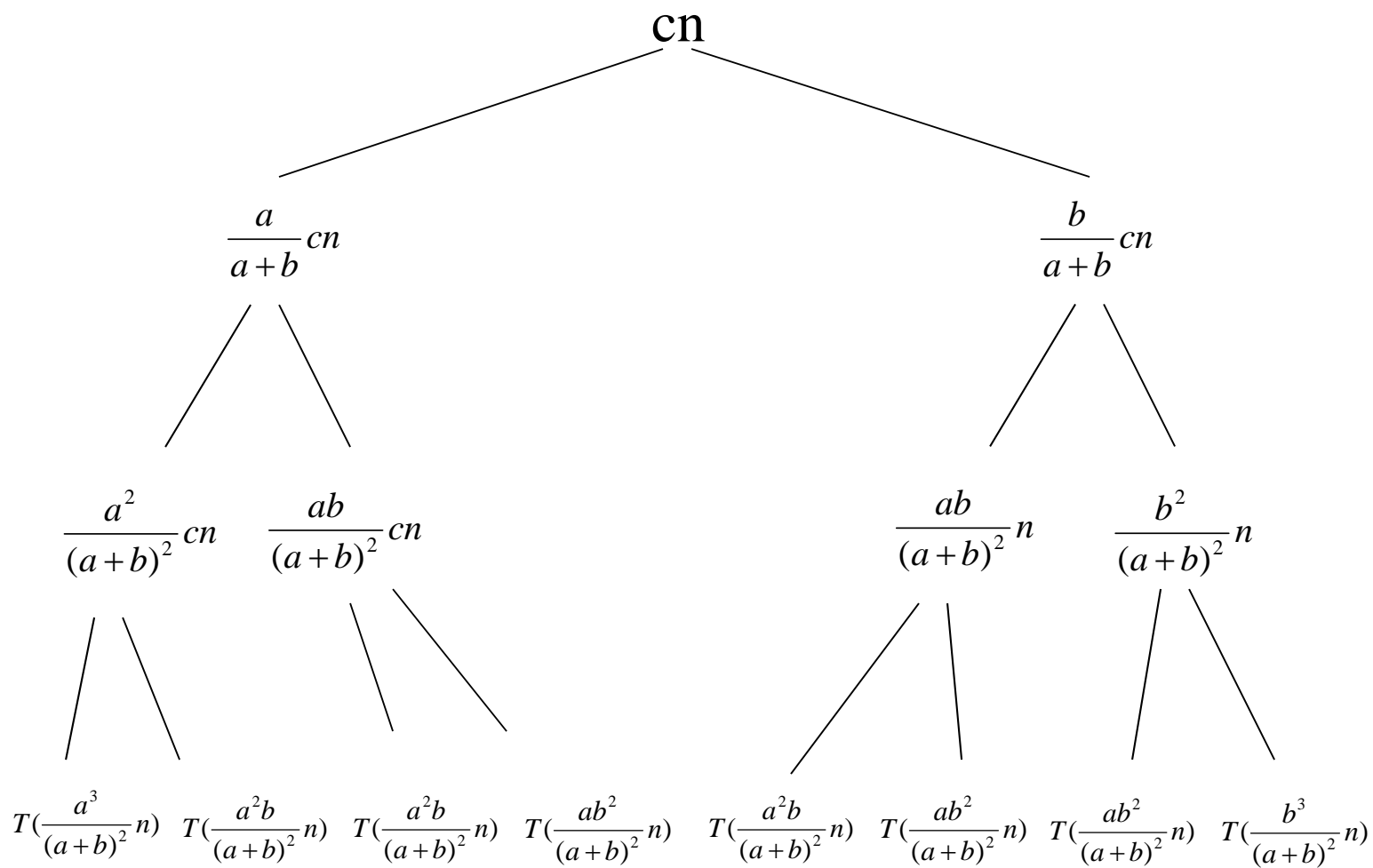
$$T(n) \leq T\left(\frac{a}{a+b}n\right) + T\left(\frac{b}{a+b}n\right) + cn$$



$$T(n) \leq T\left(\frac{a}{a+b}n\right) + T\left(\frac{b}{a+b}n\right) + cn$$



$$T(n) \leq T\left(\frac{a}{a+b}n\right) + T\left(\frac{b}{a+b}n\right) + cn$$



$$T(n) \leq T\left(\frac{a}{a+b}n\right) + T\left(\frac{b}{a+b}n\right) + cn$$

Level 0:

cn

$$\text{Level 1: } = cn\left(\frac{a}{a+b}\right) + cn\left(\frac{b}{a+b}\right) = cn$$

$$\text{Level 2: } = cn\left(\frac{a^2}{(a+b)^2}\right) + cn\left(\frac{ab}{(a+b)^2}\right) + cn\left(\frac{ab}{(a+b)^2}\right) + cn\left(\frac{b^2}{(a+b)^2}\right)$$

$$= cn\left(\frac{a^2 + 2ab + b^2}{(a+b)^2}\right) = cn\left(\frac{(a+b)^2}{(a+b)^2}\right) = cn$$

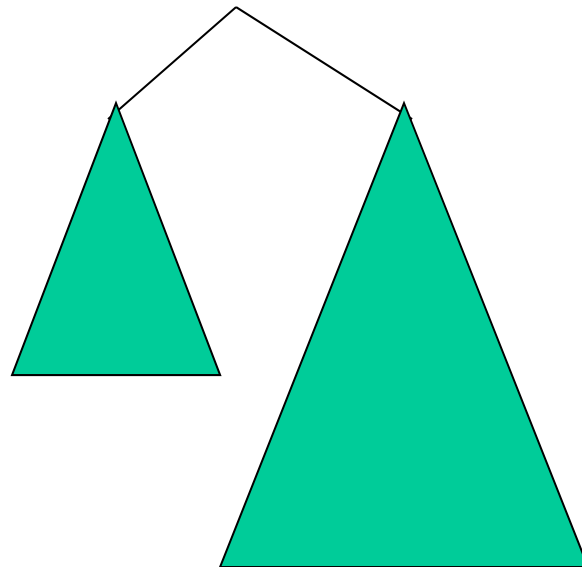
$$\text{Level 3: } = cn\left(\frac{(a+b)^2 a + (a+b)^2 b}{(a+b)^3}\right)$$

$$= cn\left(\frac{(a+b)(a+b)^2}{(a+b)^3}\right) = cn$$

$$\text{Level d: } = cn\left(\frac{(a+b)^d}{(a+b)^d}\right) = cn$$

# What is the depth of the tree?

- Leaves will have different heights
- Want to pick the deepest leaf
- Assume  $a < b$





# What is the depth of the tree?

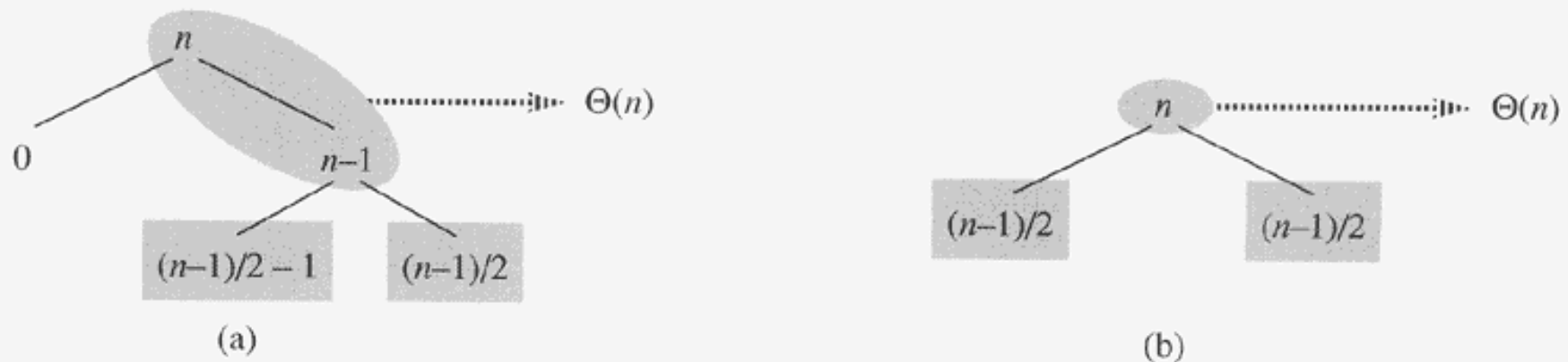
- Assume  $a < b$

$$\left(\frac{b}{a+b}\right)^d n = 1$$

...

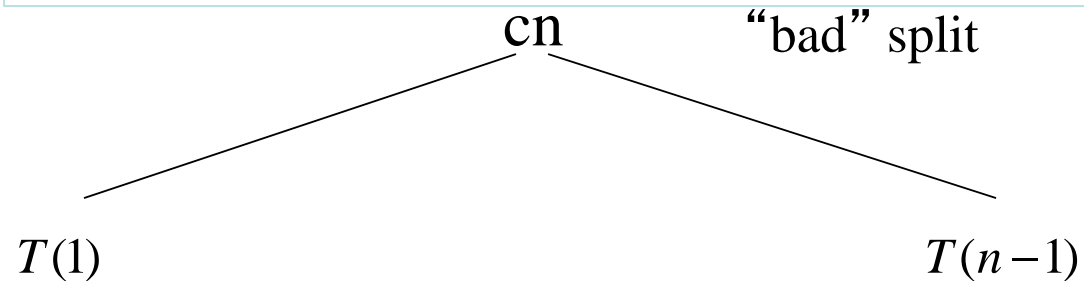
$$d = \log_{\frac{a+b}{b}} n$$

## Mixing “Good” and “Bad” Splits



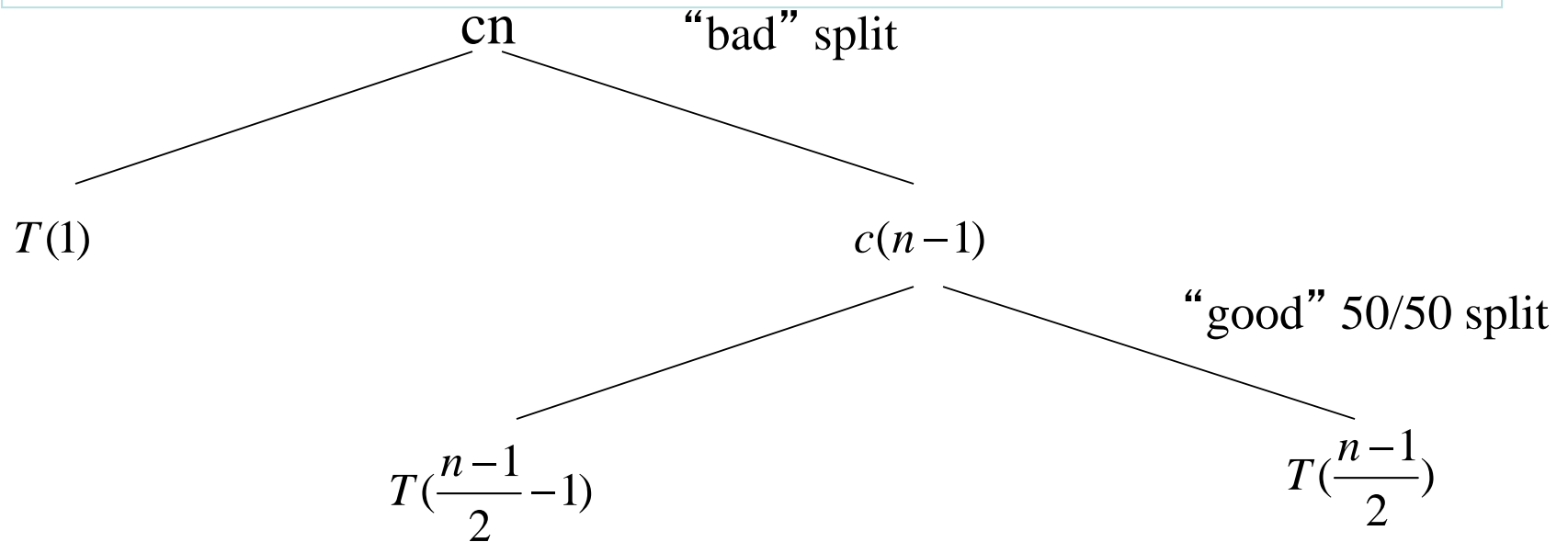
**Figure 7.5** (a) Two levels of a recursion tree for quicksort. The partitioning at the root costs  $n$  and produces a “bad” split: two subarrays of sizes  $0$  and  $n - 1$ . The partitioning of the subarray of size  $n - 1$  costs  $n - 1$  and produces a “good” split: subarrays of size  $(n - 1)/2 - 1$  and  $(n - 1)/2$ . (b) A single level of a recursion tree that is very well balanced. In both parts, the partitioning cost for the subproblems shown with elliptical shading is  $\Theta(n)$ . Yet the subproblems remaining to be solved in (a), shown with square shading, are no larger than the corresponding subproblems remaining to be solved in (b).

# Quicksort average case



Limited number of “bad splits” followed  
by a “good split” is a slower “good split”!!

Quicksort average case :  
 “bad split” + “good split”  $\Rightarrow$  “good split”



$$T(n) = \underbrace{T(1) + T(\frac{n-1}{2}-1) + T(\frac{n-1}{2})}_{\text{recursion cost}} + \underbrace{\Theta(n) + \Theta(n-1)}_{\text{partition cost}}$$

Average Case Behavior: Probabilistic Analysis  
vs. Average Case Design: Randomized Algorithms

- Probabilistic analysis of a deterministic algorithm:
  - assume probability distribution on the inputs
- Randomized algorithm design:
  - use random choices in the algorithm
    - E.g., generate random permutation of the input
    - E.g., pick a pivot randomly at each step

# Randomized Algorithms

- Randomized algorithms make use of a randomizer (such as a random number generator).
- Some of the decisions of the algorithm depend on the output of the randomizer.
  - The output may vary from run to run.
  - The execution time may vary from run to run.

# Why Randomness?

Making good decisions could be expensive.

A randomized algorithm is **faster**.

- ❖ Minimum spanning trees

A linear time randomized algorithm,  
but no known linear time deterministic algorithm.

- ❖ Primality testing

A randomized polynomial time algorithm,  
but it takes thirty years to find a deterministic one.

- ❖ Volume estimation of a convex body

A randomized polynomial time **approximation** algorithm,  
but no known deterministic polynomial time approximation algorithm.

# Why Randomness?

In many practical problems,  
we need to deal with HUGE input,  
and don't even have time to read it once.  
But can we still do something useful?

**Sublinear algorithm:** randomness is essential.

- ❖ **Fingerprinting:** verifying equality of strings, pattern matching.
- ❖ **The power of two choices:** load balancing, hashing.
- ❖ **Random walk:** check connectivity in log-space.



# Two Major Classes of Randomized Algorithms

- Las Vegas algorithms:
  - Always produce the same (correct) output for the same input.
  - Execution time depends on the randomizer.
  - Goal is to minimize the odds of encountering worst case performance.
  - *Example:* Randomized quick sort

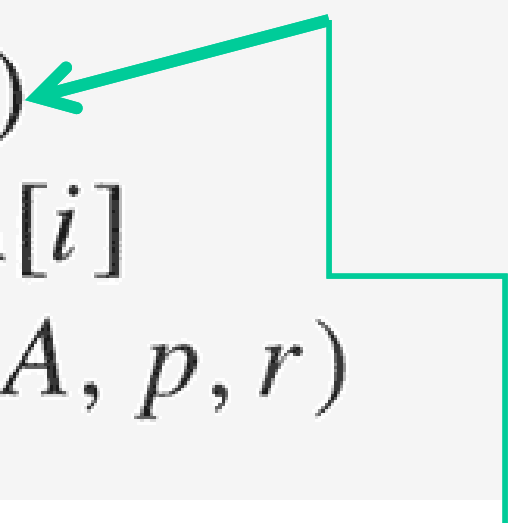
# Two Major Classes of Randomized Algorithms

- Monte Carlo algorithms:
  - Give an incorrect answer with very low probability.
  - Typically does not display variation in execution time for a particular input.
  - Goal is to provide an answer that has a high likelihood of being correct in a reasonable time.
  - *Example:* Determining primality of an integer with several hundred decimal digits.

# Analysis of Probabilistic/Randomized Algorithms

- Analysis is often complex and typically requires concepts from
  - Probability
  - Statistics
  - Number theory
- Uses (pseudo-random generator) *Random(a,b)* which returns an integer between *a* and *b*, inclusive with each integer being equally likely.
- Assume cost of producing a single random value is constant.

```
RANDOMIZED-PARTITION( $A, p, r$ )  
1   $i \leftarrow \text{RANDOM}(p, r)$   
2  exchange  $A[r] \leftrightarrow A[i]$   
3  return PARTITION( $A, p, r$ )
```



Pick pivot randomly

RANDOMIZED-QUICKSORT( $A, p, r$ )

```
1  if  $p < r$   
2      then  $q \leftarrow \text{RANDOMIZED-PARTITION}(A, p, r)$   
3          RANDOMIZED-QUICKSORT( $A, p, q - 1$ )  
4          RANDOMIZED-QUICKSORT( $A, q + 1, r$ )
```

## HOARE-PARTITION( $A, p, r$ )

```
1   $x \leftarrow A[p]$ 
2   $i \leftarrow p - 1$ 
3   $j \leftarrow r + 1$ 
4  while TRUE
5      do repeat  $j \leftarrow j - 1$ 
6          until  $A[j] \leq x$ 
7      repeat  $i \leftarrow i + 1$ 
8          until  $A[i] \geq x$ 
9      if  $i < j$ 
10         then exchange  $A[i] \leftrightarrow A[j]$ 
11         else return  $j$ 
```

QUICKSORT'(A,  $p$ ,  $r$ )

1   **while**  $p < r$

2       **do**  $\triangleright$  Partition and sort left subarray.

3        $q \leftarrow \text{PARTITION}(A, p, r)$

4       QUICKSORT'(A,  $p$ ,  $q - 1$ )

5        $p \leftarrow q + 1$