#### **Import Libraries**

```
In [26]: import pandas as pd
import numpy as np
import seaborn as sns
import matplotlib.pyplot as plt
from geopy.distance import geodesic
from IPython.display import Image
In [27]: from google.colab import drive
drive.mount('/content/drive')
```

Drive already mounted at /content/drive; to attempt to forcibly remount, cal l drive.mount("/content/drive", force remount=True).

## **Parsing Location Coordinates**

```
In [28]:
    ride = pd.read_csv("/content/drive/MyDrive/Colab Notebooks/rideshare_kaggle.cs
# ride = pd.read_csv('rideshare_kaggle.csv')
x = ride[["latitude","longitude"]]
```

```
In [29]: | coords = {
              'Haymarket Square': [42.364,-71.060],
              'Back Bay' : [42.3503, -71.0810],
              'North End': [42.3647, -71.0542],
              'North Station': [42.3661,-71.0631],
              'Beacon Hill': [42.3588,-71.0707],
              'Boston University': [42.3505, -71.1054],
              'Fenway': [42.3505,-71.1054],
              'South Station': [42.3519,-71.0551],
              'Theatre District': [42.352, -71.065],
              'West End': [42.3661,-71.0631],
              'Financial District' : [42.3559,-71.0550],
              'Northeastern University': [42.3398, -71.0892]
         }
         def parse_lat(document):
           ret = [0,0]
           if document:
             lat = coords[document][0]
           return lat
         def parse long(document):
           ret = [0,0]
           if document:
             lon = coords[document][1]
           return lon
In [30]: | s_coords1 = ride["source"].apply(parse_lat)
         s_coords2 = ride["source"].apply(parse_long)
         d_coords1 = ride["destination"].apply(parse_lat)
         d_coords2 = ride["destination"].apply(parse_long)
         11 = s_coords1.append(d_coords1, ignore_index = True)
         12 = s_coords2.append(d_coords2, ignore_index = True)
         <ipython-input-30-a8d0bef7471d>:6: FutureWarning: The series.append method i
         s deprecated and will be removed from pandas in a future version. Use panda
         s.concat instead.
           11 = s_coords1.append(d_coords1, ignore_index = True)
         <ipython-input-30-a8d0bef7471d>:7: FutureWarning: The series.append method i
         s deprecated and will be removed from pandas in a future version. Use panda
         s.concat instead.
           12 = s_coords2.append(d_coords2, ignore_index = True)
```

```
In [31]: x = pd.concat([11,12],axis=1)
         print(x)
                                 1
                  42.3640 -71.0600
                  42.3640 -71.0600
         1
         2
                  42.3640 -71.0600
         3
                  42.3640 -71.0600
         4
                  42.3640 -71.0600
                      . . .
         1386137 42.3647 -71.0542
         1386138 42.3647 -71.0542
         1386139 42.3647 -71.0542
         1386140 42.3647 -71.0542
         1386141 42.3647 -71.0542
         [1386142 rows x 2 columns]
In [32]: pip install -U googlemaps
         Looking in indexes: https://pypi.org/simple, (https://pypi.org/simple,) http
         s://us-python.pkg.dev/colab-wheels/public/simple/ (https://us-python.pkg.de
         v/colab-wheels/public/simple/)
         Requirement already satisfied: googlemaps in /usr/local/lib/python3.9/dist-p
         ackages (4.10.0)
         Requirement already satisfied: requests<3.0,>=2.20.0 in /usr/local/lib/pytho
         n3.9/dist-packages (from googlemaps) (2.27.1)
         Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.9/dist
         -packages (from requests<3.0,>=2.20.0->googlemaps) (3.4)
         Requirement already satisfied: charset-normalizer~=2.0.0 in /usr/local/lib/p
         ython3.9/dist-packages (from requests<3.0,>=2.20.0->googlemaps) (2.0.12)
         Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.
         9/dist-packages (from requests<3.0,>=2.20.0->googlemaps) (2022.12.7)
         Requirement already satisfied: urllib3<1.27,>=1.21.1 in /usr/local/lib/pytho
         n3.9/dist-packages (from requests<3.0,>=2.20.0->googlemaps) (1.26.15)
In [33]: import googlemaps
         gmaps = googlemaps.Client(key='AIzaSyB-Dvs504EXQNMt1L-S79Yi12I58dCejLQ')
```

#### **Plotting Hubs using Heatmap**

<ipython-input-34-5e371f4aa757>:1: FutureWarning: The series.append method i
s deprecated and will be removed from pandas in a future version. Use panda
s.concat instead.

11 = s\_coords1.append(d\_coords1, ignore\_index = True)

<ipython-input-34-5e371f4aa757>:2: FutureWarning: The series.append method i
s deprecated and will be removed from pandas in a future version. Use panda
s.concat instead.

12 = s\_coords2.append(d\_coords2, ignore\_index = True)



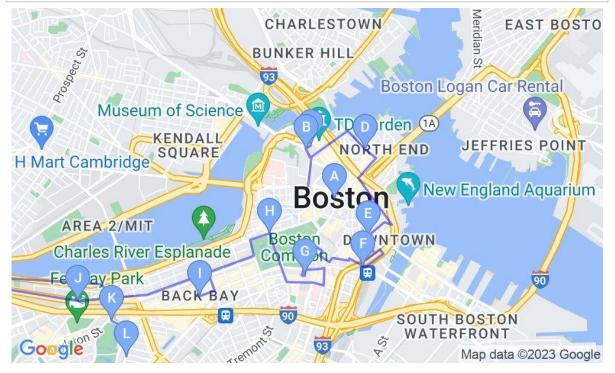


### **Example Route Through all Hubs**

```
In [35]: | waypoints = [
              'Back Bay, Boston',
              'North End, Boston',
              'North Station, Boston',
              'Beacon Hill, Boston',
              'Boston University, Boston',
              'Fenway, Boston',
              'South Station, Boston',
              'Theatre District, Boston',
              'West End, Boston',
              'Financial District, Boston',
         results = gmaps.directions(origin = 'Haymarket Square, Boston',
                                                    destination = 'Northeastern Universit
                                                    waypoints = waypoints,
                                                    optimize waypoints = True)
         for i, leg in enumerate(results[0]["legs"]):
             print("Stop:" + str(i),
                  leg["start_address"],
                  "==> ",
                  leg["end address"],
                  "distance: ",
                  leg["distance"]["value"],
                  "traveling Time: ",
                  leg["duration"]["value"]
             )
```

```
Stop: 0 Boston, MA, USA ==> West End, Boston, MA, USA distance: 843 traveli
ng Time: 286
Stop:1 West End, Boston, MA, USA ==> North Station, 135 Causeway St, Bosto
n, MA 02114, USA distance: 88 traveling Time: 33
Stop:2 North Station, 135 Causeway St, Boston, MA 02114, USA ==> North End,
Boston, MA, USA distance: 1091 traveling Time: 522
Stop: 3 North End, Boston, MA, USA ==> Financial District, Boston, MA, USA d
istance: 1565 traveling Time: 494
Stop:4 Financial District, Boston, MA, USA ==> South Station, 700 Atlantic
Ave, Boston, MA 02110, USA distance: 543 traveling Time: 157
Stop:5 South Station, 700 Atlantic Ave, Boston, MA 02110, USA ==> Boston Th
eater District, Boston, MA, USA distance: 1948 traveling Time: 636
Stop:6 Boston Theater District, Boston, MA, USA ==> Beacon Hill, Boston, M
A, USA distance: 1564 traveling Time: 535
Stop:7 Beacon Hill, Boston, MA, USA ==> Back Bay, Boston, MA, USA distance:
1453 traveling Time: 346
Stop:8 Back Bay, Boston, MA, USA ==> Boston, MA 02215, USA distance: 2044
traveling Time: 443
Stop:9 Boston, MA 02215, USA ==> Fenway-Kenmore, Boston, MA, USA distance:
2970 traveling Time: 326
Stop:10 Fenway-Kenmore, Boston, MA, USA ==> 360 Huntington Ave, Boston, MA
02115, USA distance: 542 traveling Time: 97
```

```
In [36]: | marker_points = []
         waypoints = []
         #extract the location points from the previous directions function
         for leg in results[0]["legs"]:
             leg_start_loc = leg["start_location"]
             marker_points.append(f'{leg_start_loc["lat"]},{leg_start_loc["lng"]}')
             for step in leg["steps"]:
                 end_loc = step["end_location"]
                 waypoints.append(f'{end_loc["lat"]},{end_loc["lng"]}')
         last_stop = results[0]["legs"][-1]["end_location"]
         marker points.append(f'{last_stop["lat"]},{last_stop["lng"]}')
         markers = [ "color:blue|size:mid|label:" + chr(65+i) + "|"
                    + r for i, r in enumerate(marker_points)]
         result_map = gmaps.static_map(
                          center = waypoints[0],
                          scale=2,
                          zoom=13,
                          size=[500, 300],
                          format="jpg",
                          maptype="roadmap",
                          markers=markers,
                          path="color:0x0000ff|weight:2|" + "|".join(waypoints))
```



#### **Simple Route Between 2 Hubs**

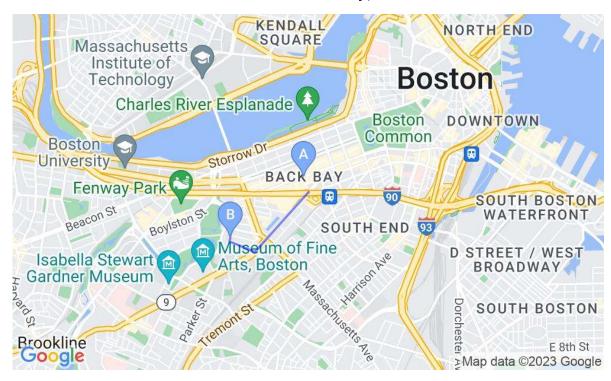
```
In [38]: |locations = [
              'Haymarket Square, Boston',
              'Back Bay, Boston',
              'North End, Boston',
              'North Station, Boston',
              'Beacon Hill, Boston',
              'Boston University, Boston',
              'Fenway, Boston',
              'South Station, Boston',
              'Theatre District, Boston',
              'West End, Boston',
              'Financial District, Boston',
              'Northeastern University, Boston']
         location_geocodes = {}
         for loc in locations:
           location_geocodes[loc] = gmaps.geocode(loc)
```

```
In [39]: print('1. Haymarket Square')
         print('2. Back Bay')
         print('3. North End')
         print('4. North Station')
         print('5. Beacon Hill')
         print('6. Boston University')
         print('7. Fenway')
         print('8. South Station')
         print('9. Theatre District')
         print('10. West End')
         print('11. Financial District')
         print('12. Northeastern University')
         print("-----")
         s = input("Select Source Option: ")
         d = input("Select Destination Option: ")
         source = locations[int(s)-1]
         destination = locations[int(d)-1]
         print("----")
         print('Selected Source: ',source)
         print('Selected Destination: ',destination)
         results = gmaps.directions(origin = source,
                                                destination = destination,
                                                optimize_waypoints = True)
         marker_points = []
         waypoints = []
         #extract the location points from the previous directions function
         for leg in results[0]["legs"]:
             leg start loc = leg["start location"]
            marker_points.append(f'{leg_start_loc["lat"]},{leg_start_loc["lng"]}')
            for step in leg["steps"]:
                end loc = step["end location"]
                waypoints.append(f'{end loc["lat"]},{end loc["lng"]}')
         last stop = results[0]["legs"][-1]["end location"]
         marker_points.append(f'{last_stop["lat"]},{last_stop["lng"]}')
         markers = [ "color:blue|size:mid|label:" + chr(65+i) + "|"
                   + r for i, r in enumerate(marker_points)]
         result map2 = gmaps.static map(
                         center = waypoints[0],
                         scale=2,
                         zoom=13,
                         size=[500, 300],
                         format="jpg",
                         maptype="roadmap",
                         markers=markers,
                         path="color:0x0000ff|weight:2|" + "|".join(waypoints))
         with open('driving_route_map2.jpg', 'wb') as img:
             for chunk in result_map2:
                 img.write(chunk)
```

```
i = Image('driving_route_map2.jpg')
display(i)
1. Haymarket Square
2. Back Bay
3. North End
4. North Station
5. Beacon Hill
6. Boston University
7. Fenway
8. South Station
9. Theatre District
10. West End
11. Financial District
12. Northeastern University
Select Source Option: 2
Select Destination Option: 12
```

Selected Source: Back Bay, Boston

Selected Destination: Northeastern University, Boston



# Routing Any Possible Rideshare Routes Through Hubs

```
In [40]:
         def route():
           print("-----")
           s = input("Select Source Address: ")
           d = input("Select Destination Address: ")
           print("-----")
           # s = "Nickerson Field"
           # d = "John F. Kennedy Presidential Library and Museum"
           source = gmaps.geocode(s)
           destination = gmaps.geocode(d)
           print(source[0]["formatted_address"])
           print(source[0]["geometry"]["location"]["lat"])
           print(source[0]["geometry"]["location"]["lng"])
           print()
           print(destination[0]["formatted_address"])
           print(destination[0]["geometry"]["location"]["lat"])
           print(destination[0]["geometry"]["location"]["lng"])
           print()
           max s dist = float('inf')
           max_d_dist = float('inf')
           closest_source_hub = locations[0]
           closest_dest_hub = locations[0]
           for loc,loc_geo in location_geocodes.items():
             curr_dist1 = gmaps.distance_matrix(origins=source[0]['formatted_address']]
                                destinations=loc_geo[0]["formatted_address"])['rows'][
             curr_dist2 = gmaps.distance_matrix(origins=loc_geo[0]['formatted_address']
                                destinations=destination[0]["formatted_address"])['row
             if curr_dist1 < max_s_dist:</pre>
               closest source hub = loc
               max_s_dist = curr_dist1
             if curr_dist2 < max_d_dist:</pre>
               closest dest hub = loc
               max_d_dist = curr_dist2
           print("Closest hub to source = ",closest_source_hub)
           print("Closest hub to destination = ",closest_dest_hub)
           waypoints = [source[0]['formatted_address'],closest_source_hub,closest_dest_
           results = gmaps.directions(origin = source[0]['formatted_address'],
                                                  destination = destination[0]['format
                                                  waypoints = waypoints,
                                                  optimize_waypoints = True)
           w =waypoints
           marker_points = []
           waypoints = []
```

```
#extract the location points from the previous directions function
for leg in results[0]["legs"]:
    leg_start_loc = leg["start_location"]
    marker points.append(f'{leg_start_loc["lat"]},{leg_start_loc["lng"]}')
    for step in leg["steps"]:
        end_loc = step["end_location"]
        waypoints.append(f'{end_loc["lat"]},{end_loc["lng"]}')
last_stop = results[0]["legs"][-1]["end_location"]
marker_points.append(f'{last_stop["lat"]},{last_stop["lng"]}')
markers = [ "color:blue|size:mid|label:" + chr(65+i) + "|"
          + r for i, r in enumerate(w)]
result map = gmaps.static map(
                scale=2,
                zoom=12,
                size=[500, 300],
                format="jpg",
                maptype="roadmap",
                markers=markers,
                path="color:0x0000ff|weight:2|" + "|".join(waypoints))
with open('driving_route_map2.jpg', 'wb') as img:
    for chunk in result_map:
        img.write(chunk)
i = Image('driving_route_map2.jpg')
display(i)
```

Select Source Address: boston latin academy Select Destination Address: museum of science

205 Townsend St, Boston, MA 02121, USA

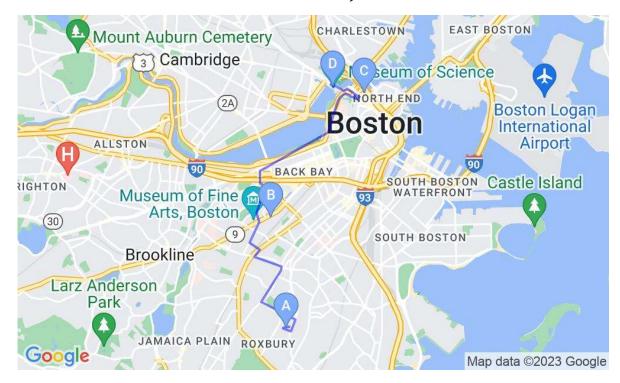
42.316119

-71.0845953

Museum Of Science Driveway, Boston, MA 02114, USA 42.367714

-71.0709771

Closest hub to source = Northeastern University, Boston Closest hub to destination = North Station, Boston



-----

Select Source Address: MIT

Select Destination Address: boston university

77 Massachusetts Ave, Cambridge, MA 02139, USA

42.360091

-71.09416

Boston, MA 02215, USA

42.3504997

-71.1053991

Closest hub to source = Fenway, Boston
Closest hub to destination = Boston University, Boston



-----

Select Source Address: MIT

Select Destination Address: BU medical campus

77 Massachusetts Ave, Cambridge, MA 02139, USA

42.360091

-71.09416

715 Albany St #437, Boston, MA 02118, USA

42.3355579

-71.0711474

Closest hub to source = Fenway, Boston
Closest hub to destination = Northeastern University, Boston



In [ ]: