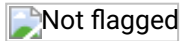


## Question 1

Complete

Mark 1 out of 1



Flag question

### Question text

Which one of the following is a real time operating system?

Select one:

- ☐ A. RTLinux
- ☐ B. VxWorks
- ☐ C. Windows CE
- ☒ D. All of the mentioned

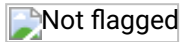
### Feedback

The correct answer is: All of the mentioned

## Question 2

Complete

Mark 0 out of 1



Flag question

### Question text

Preemptive, priority based scheduling guarantees

Select one:

- ☒ A. Hard real time functionality
- ☐ B. Soft real time functionality

- ☐ C. Protection of memory
- ☐ D. None of the above

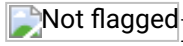
### Feedback

The correct answer is: Soft real time functionality

### Question 3

Complete

Mark 1 out of 1



Flag question

### Question text

In a \_\_\_\_\_ real time system, it is guaranteed that critical real time tasks will be completed within their deadlines.

Select one:

- ☐ A. Soft
- ☒ B. Hard
- ☐ C. Critical
- ☐ D. None of the above

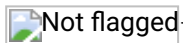
### Feedback

The correct answer is: Hard

### Question 4

Complete

Mark 1 out of 1



Flag question

### Question text

Some of the properties of real time systems include :

Select one:

- ☐ A. Single purpose
- ☐ B. Inexpensively mass produced
- ☐ C. Small size
- ☒ D. All of the above

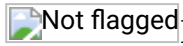
### Feedback

The correct answer is: All of the above

## Question 5

Complete

Mark 0 out of 1



Flag question

### Question text

If a set of processes cannot be scheduled by rate monotonic scheduling algorithm, then :  
Select one:

- ☒ A. They can be scheduled by EDF algorithm
- ☐ B. They cannot be scheduled by EDF algorithm
- ☐ C. They cannot be scheduled by any other algorithm
- ☐ D. None of the above

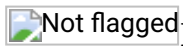
### Feedback

The correct answer is: They cannot be scheduled by any other algorithm

## Question 6

Complete

Mark 1 out of 1



Flag question

### Question text

The method mlock() does \_\_\_\_\_ .

Select one:

- ☐ A. Lock Complete process address space.
- ☒ B. Lock specified region of process address space.
- ☐ C. Lock the whole process.
- ☐ D. None of the Above.

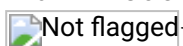
### Feedback

The correct answer is: Lock specified region of process address space.

## Question 7

Complete

Mark 1 out of 1



Flag question

### Question text

Priority inversion can be happen if \_\_\_\_\_.

Select one:

- ☒ A. Low priority process locks a semaphore needed by high priority process.
- ☐ B. High priority process locks a semaphore needed by low priority process.
- ☐ C. Both A and B are possible
- ☐ D. None of the above

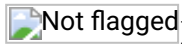
### Feedback

The correct answer is: Low priority process locks a semaphore needed by high priority process.

## Question 8

Complete

Mark 0 out of 1



Flag question

### Question text

In typical RTOS, tasks runs in \_\_\_\_\_.

Select one:

- ☐ A. User Mode
- ☐ B. Abort Mode
- ☐ C. Privileged mode
- ☒ D. None of the above

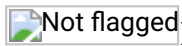
### Feedback

The correct answer is: Privileged mode

## Question 9

Complete

Mark 1 out of 1



Flag question

### Question text

Which RTOS scheduling algorithm cannot use CPU upto 100% ?

Select one:

- ☐ A. Propotional share
- ☐ B. Earliest deadline frist
- ☒ C. Rate Monotonic Scheduling
- ☐ D. None of the above

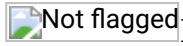
### Feedback

The correct answer is: Rate Monotonic Scheduling

## Question 10

Complete

Mark 1 out of 1



Flag question

### Question text

RTAI supports \_\_\_\_\_ architectures.

Select one:

- ☐ A. X86
- ☐ B. X86\_64
- ☐ C. Power PC
- ☐ D. ARM cortex M3
- ☒ E. All of the Above

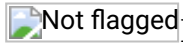
### Feedback

The correct answer is: All of the Above

## Question 11

Complete

Mark 0 out of 1



Flag question

### Question text

Which of the following function is used to create real time task in RTAI?

Select one:

- ☐ A. rt\_task\_init()
- ☐ B. rt\_init\_task()
- ☒ C. rtai\_init\_task()
- ☐ D. rtai\_task\_init()

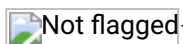
### Feedback

The correct answer is: rt\_init\_task()

## Question 12

Complete

Mark 1 out of 1



Flag question

### Question text

Real time systems must have \_\_\_\_\_ .

Select one:

- ☒ A. Preemptive kernels
- ☐ B. Non preemptive kernels
- ☐ C. Neither preemptive nor non preemptive kernels
- ☐ D. None of the above

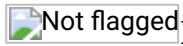
### Feedback

The correct answer is: Preemptive kernels

### Question 13

Complete

Mark 0 out of 1



Flag question

### Question text

A task existing in the ready state cannot be moved into which of the following states?

Select one:

- ☐ A. wait, ISR state
- ☐ B. Running state
- ☒ C. Dormant state
- ☐ D. Both A and B

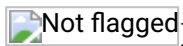
### Feedback

The correct answer is: wait, ISR state

### Question 14

Complete

Mark 1 out of 1



Flag question

### Question text

What parameter is of less significance with reference to RTOS?

Select one:

- ☐ A. Interrupt latency
- ☐ B. Interrupt recovery time
- ☐ C. Interrupt response time
- ☒ D. Throughput

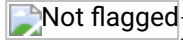
## Feedback

The correct answer is: Throughput

## Question 15

Complete

Mark 1 out of 1



Flag question

### Question text

Which of the following can be applied to periodic scheduling?

Select one:

- ☒ A. EDF
- ☐ B. LL
- ☐ C. LST
- ☐ D. EDD

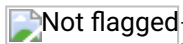
## Feedback

The correct answer is: EDF

## Question 16

Complete

Mark 0 out of 1



Flag question

### Question text

Which linux service gets called from RT task to creates a real time fifo (RT-FIFO).

Select one:

- ☐ A. rtf\_create()
- ☒ B. rtfifo\_create()
- ☐ C. rtf\_create\_task()
- ☐ D. rtfifo\_create\_task()

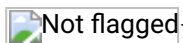
## Feedback

The correct answer is: rtf\_create()

## Question 17

Complete

Mark 1 out of 1



Flag question

### Question text

A \_\_\_\_\_ of a task is the time at which the release of a task will produce the largest response time.

Select one:

- ☐ A. soft instance
- ☐ B. hard instance
- ☒ C. critical instance
- ☐ D. both A and B

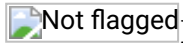
### Feedback

The correct answer is: critical instance

### Question 18

Complete

Mark 0 out of 1



Flag question

### Question text

Reentrant function is one that

Select one:

- ☐ A. should be executed by only one task at a time otherwise data corruption occurs
- ☐ B. will allow 2 tasks to use it but not more than 2
- ☐ C. will allow any number of taskd to execute it without data corruption
- ☒ D. Both A and B

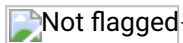
### Feedback

The correct answer is: will allow any number of taskd to execute it without data corruption

### Question 19

Complete

Mark 1 out of 1



Flag question

### Question text

RTOS handles interrupts in

Select one:

- ☒ A. Deterministic Time
- ☐ B. Non Deterministic time
- ☐ C. Constant time



☐ D. None of the Above

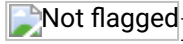
### Feedback

The correct answer is: Deterministic Time

### Question 20

Complete

Mark 1 out of 1



Flag question

#### Question text

In proportional share algorithm, CPU time = 100 shares ( $T = 100$ )  $P1 = 50$  shares  $P2 = 15$  shares  $P3 = 20$  shares What is the cpu utilization ?

Select one:

- ☐ A. 0.079
- ☒ B. 0.85
- ☐ C. 0.085
- ☐ D. 0.79

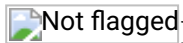
### Feedback

The correct answer is: 0.85

### Question 21

Complete

Mark 0 out of 1



Flag question

#### Question text

Interrupt jitter means,

Select one:

- ☐ A. The variation in interrupt latency
- ☒ B. The variation in interrupt arrival time
- ☐ C. The interrupt latency
- ☐ D. None of the above

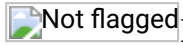
### Feedback

The correct answer is: The variation in interrupt latency

### Question 22

Complete

Mark 0 out of 1



Flag question

### Question text

Which scheduling algorithm is an optimal scheduling policy for mono-processor system?

Select one:

- ☒ A. preemptive algorithm
- ☐ B. LST (Least stack time)
- ☐ C. EDD (Earlist due date)
- ☐ D. LL (Least laxity)

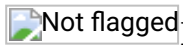
### Feedback

The correct answer is: LL (Least laxity)

## Question 23

Complete

Mark 1 out of 1



Flag question

### Question text

Identify which of these are real-time applications scenarios:

Select one:

- ☐ A. An on-line bus ticketing system
- ☐ B. Printing of annual report of a company's annual report
- ☐ C. Reconciling a day's transactions in an account book of a small company
- ☒ D. An aircrafts' yaw control system

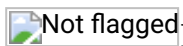
### Feedback

The correct answer is: An aircrafts' yaw control system

## Question 24

Complete

Mark 1 out of 1



Flag question

### Question text

Which algorithm is non-preemptive and can be used with a mono processor?

Select one:

- ☒ A. LDF
- ☐ B. pre-emptive
- ☐ C. aperiodic
- ☐ D. LL

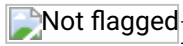
### Feedback

The correct answer is: LDF

## Question 25

Complete

Mark 0 out of 1



Flag question

### Question text

Deadline interval – execution time =

Select one:

- ☐ A. laxity
- ☐ B. execution time
- ☐ C. deadline interval
- ☒ D. period

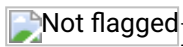
### Feedback

The correct answer is: laxity

## Question 26

Complete

Mark 0 out of 1



Flag question

### Question text

The execution of the task is known as

Select one:

- ☐ A. Process
- ☐ B. Job
- ☐ C. Task
- ☒ D. Thread

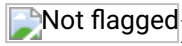
### Feedback

The correct answer is: Job

## Question 27

Complete

Mark 0 out of 1



Flag question

### Question text

Which of the following can execute quickly, if the interrupt priority is higher in the system?

Select one:

- ☐ A. EDD
- ☐ B. Sporadic event
- ☐ C. LL
- ☒ D. Aperiodic scheduling

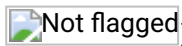
### Feedback

The correct answer is: Sporadic event

## Question 28

Complete

Mark 1 out of 1



Flag question

### Question text

The scheduler admits a process using :

Select one:

- ☐ A. two phase locking protocol
- ☐ B. admission control algorithm
- ☒ C. busy wait polling
- ☐ D. none of the above

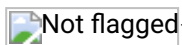
### Feedback

The correct answer is: busy wait polling

## Question 29

Complete

Mark 1 out of 1



Flag question

### Question text

If there are a total of  $T = 100$  shares to be divided among three processes, A, B and C. A is assigned 50 shares, B is assigned 15 shares and C is assigned 20 shares. C will have \_\_\_\_\_ percent of the total processor time.

Select one:

- ☒ A. 20
- ☐ B. 15
- ☐ C. 50
- ☐ D. none of the above

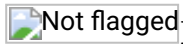
### Feedback

The correct answer is: 20

## Question 30

Complete

Mark 1 out of 1



Flag question

### Question text

Which are types of RTAI tasks?

Select one:

- ☐ A. Short, Long
- ☐ B. IO bound, CPU bound
- ☐ C. Single threaded, Multi threaded
- ☒ D. One Shot, Periodic

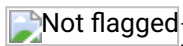
### Feedback

The correct answer is: One Shot, Periodic

## Question 31

Complete

Mark 1 out of 1



Flag question

### Question text

Which of the following is not work of the Real time executive?

Select one:

- ☐ A. RT task management
- ☐ B. RT IPC
- ☒ C. Memory Management and file IO
- ☐ D. Scheduling

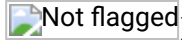
## Feedback

The correct answer is: Memory Management and file IO

## Question 32

Complete

Mark 1 out of 1



Flag question

### Question text

In FreeRTOS, if multiple tasks are same priority and are always in running or ready state then kernel create \_\_\_\_\_ where each gets a full ticks before switching to next.

Select one:

- ☐ A. least laxity frist
- ☒ B. round Robin model
- ☐ C. earilest deadline frist
- ☐ D. rate monotonic

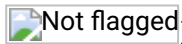
## Feedback

The correct answer is: round Robin model

## Question 33

Complete

Mark 1 out of 1



Flag question

### Question text

The Cortex-M3 port includes which of the following standard FreeRTOS features

Select one:

- ☐ A. Pre-emptive or co-operative operation
- ☐ B. Very flexible task priority
- ☐ C. Queues
- ☐ D. Mutex
- ☒ E. All of the above

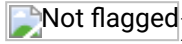
## Feedback

The correct answer is: All of the above

## Question 34

Complete

Mark 1 out of 1



Flag question

### Question text

For real time operating systems, interrupt latency should be \_\_\_\_\_ .

Select one:

- ☐ A. Maximum
- ☒ B. Minimal
- ☐ C. Zero
- ☐ D. Dependent on the scheduling

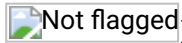
### Feedback

The correct answer is: Minimal

## Question 35

Complete

Mark 0 out of 1



Flag question

### Question text

A task can use the \_\_\_\_\_ API function to delete itself or other task

Select one:

- ☐ A. vDeleteTask()
- ☐ B. vDelete()
- ☐ C. vTaskDelete()
- ☒ D. TaskDelete()

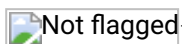
### Feedback

The correct answer is: vTaskDelete()

## Question 36

Complete

Mark 0 out of 1



Flag question

### Question text

Type of processor in which single task of a particular application is process is termed as \_\_\_\_\_ .

Select one:

- ☒ A. Real time processor
- ☐ B. Dedicated processor
- ☐ C. Applicant processor
- ☐ D. One task processor

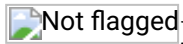
### Feedback

The correct answer is: Dedicated processor

## Question 37

Complete

Mark 0 out of 1



Flag question

### Question text

If the period of a process is 'p', then the rate of the task is \_\_\_\_\_ .

Select one:

- ☒ A.  $p^2$
- ☐ B.  $2 \cdot p$
- ☐ C.  $1/p$
- ☐ D.  $p$

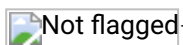
### Feedback

The correct answer is:  $1/p$

## Question 38

Complete

Mark 0 out of 1



Flag question

### Question text

In rate monotonic scheduling, a process with a shorter period is assigned :

Select one:

- ☐ A. A higher priority
- ☐ B. A lower priority
- ☐ C. Higher & lower priority
- ☒ D. None of the above

### Feedback

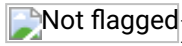
The correct answer is: A higher priority



## Question 39

Complete

Mark 1 out of 1



Flag question

### Question text

Real time systems need to \_\_\_\_\_ the interrupt latency.

Select one:

- ☒ A. Minimize
- ☐ B. Maximize
- ☐ C. Not bother about
- ☐ D. None of the above

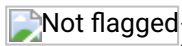
### Feedback

The correct answer is: Minimize

## Question 40

Complete

Mark 1 out of 1



Flag question

### Question text

The amount of time required for the scheduling dispatcher to stop one process and start another is known as \_\_\_\_\_ .

Select one:

- ☐ A. Event latency
- ☐ B. Interrupt latency
- ☒ C. Dispatch latency
- ☐ D. Context switch

### Feedback

The correct answer is: Dispatch latency

Finish review

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