

include/ROSModule.hpp



```
graph TD; A[include/ROSModule.hpp] --> B[iostream]; A --> C[vector]; A --> D[ros/ros.h];
```

The diagram illustrates the dependencies of the file `include/ROSModule.hpp`. It is represented by a grey rectangular box at the top. Three blue arrows originate from the bottom of this box and point to three separate white rectangular boxes below it. The boxes are labeled `iostream`, `vector`, and `ros/ros.h` from left to right, indicating that `include/ROSModule.hpp` includes these three components.

iostream

vector

ros/ros.h