

Assignment 3

Problem – To make a growing neural network

Approach – I went for a different approach, then told in class. A decision tree is also a kind of neural network, it grows by partitioning data on best feature on each level (entropy and information theory properties are used).

Similarly, I transformed my image to 16*16 and RGB to greyscale, then each of the of the image pixel acts as feature, I selected best feature at each level. How? I selected the feature which classifies the most images and then that feature is not considered again for making next choices.

Code – Link to Kaggle - <https://www.kaggle.com/code/abgo24/notebook33ed841c96>

```
import numpy as np

import cv2

from sklearn.metrics import accuracy_score

from sklearn.model_selection import train_test_split

import matplotlib.pyplot as plt

import random

import os

import cv2

import networkx as nx

G = nx.DiGraph()

faces=[]

image_target_size=[218,178]

image_dir_map={"faces":["/kaggle/input/celeba-dataset/img_align_celeba/img_align_celeba"],

               "nfaces":["/kaggle/input/natural-images/natural_images/airplane",

                        '/kaggle/input/natural-images/natural_images/car',

                        '/kaggle/input/natural-images/natural_images/cat',

                        '/kaggle/input/natural-images/natural_images/dog',

                        '/kaggle/input/natural-images/natural_images/flower',

                        '/kaggle/input/natural-images/natural_images/fruit',
```

```
    '/kaggle/input/natural-images/natural_images/motorbike']}]}
```

```
for key,val in image_dir_map.items():
```

```
    for image_directory in val:
```

```
        for root, _, filenames in os.walk(image_directory):
```

```
            if key ==str('faces'):
```

```
                img_len=1200
```

```
                face=1
```

```
            else :
```

```
                img_len=200
```

```
                face=0
```

```
            i=0
```

```
            while i<img_len:
```

```
                i+=1
```

```
                image_path = os.path.join(root, filenames[i])
```

```
                image = cv2.imread(image_path)
```

```
                image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
```

```
                current_size = image.shape[:2]
```

```
                if current_size[0] != image_target_size[0] or current_size[1] != image_target_size[1]:
```

```
                    image = cv2.resize(image, (image_target_size[1], image_target_size[0]),interpolation =  
cv2.INTER_AREA)
```

```
                    if image.shape[:2][0]==image_target_size[0] and image.shape[:2][1]==image_target_size[1]:
```

```
                        image_array = np.array(image)
```

```
                        faces.append([image_array , face])
```

```
                    else:
```

```
                        print(f'Not correct size {image_path}')
```

```
class SingleLayerNN:
```

```
    def __init__(self):
```

```

self.W = np.random.randn()

self.b = 0

def sigmoid(self, z):
    return 1 / (1 + np.exp(-z))

def fit(self, X, y, learning_rate=0.01, epochs=25):
    m, n = X.shape

    self.W = np.zeros(n)

    self.b = 0

    for _ in range(epochs):
        z = np.dot(X, self.W) + self.b

        y_pred = self.sigmoid(z)

        dw = (1 / m) * np.dot(X.T, (y_pred - y))

        db = (1 / m) * np.sum(y_pred - y)

        self.W -= learning_rate * dw

        self.b -= learning_rate * db

def predict(self, X):
    z = np.dot(X, self.W) + self.b

    y_pred = self.sigmoid(z)

    binary_predictions = (y_pred > 0.5).astype(int)

    return binary_predictions

def find_best_feature(X, y, used_features):
    best_feature = None

    best_accuracy = 0.0

    best_predictions = None

    for feature_index in range(X.shape[0]):

```

```

if(feature_index in used_features):
    continue

feature_mask = np.zeros(X.shape)
feature_mask[feature_index] = 1
masked_X = X * feature_mask
train_size = int(0.8 * len(y))
X_train, X_test = masked_X[:train_size], masked_X[train_size:]
y_train, y_test = y[:train_size], y[train_size:]
classifier = SingleLayerNN()
classifier.fit(X_train, y_train)
predictions = classifier.predict(X_test)
accuracy = accuracy_score(y_test, predictions)
if accuracy > best_accuracy:
    best_feature = feature_index
    best_accuracy = accuracy
    best_predictions = predictions

return best_feature, best_accuracy, best_predictions

```

```

class TreeNode:

    def __init__(self, feature_index=None, depth=0):
        self.feature_index = feature_index
        self.left = None
        self.right = None
        self.depth = depth

def build_neural_tree(X, y, max_depth=0, used_features=set()):
    if len(set(y)) == 1 or max_depth==0:

```

```

    return None

best_feature, best_accuracy, best_predictions = find_best_feature(X, y, used_features)
used_features.add(best_feature)

node = TreeNode(feature_index=best_feature, depth=max_depth)

left_indices = np.where(best_predictions == 0)[0]
right_indices = np.where(best_predictions == 1)[0]

node.left = build_neural_tree(X[left_indices], y[left_indices], max_depth-1, used_features)
node.right = build_neural_tree(X[right_indices], y[right_indices], max_depth-1, used_features)

return node

```

```

X = np.array([(((img[0].reshape(-1))/255)*2-1 for img in faces)])
y = np.array([img[1] for img in faces])

max_depth=5

root_node = build_neural_tree(X, y, max_depth)

```

```

def add_nodes_and_edges(node, parent=None):
    if node is None:
        return
    else :
        node_identifier = generate_unique_identifier()
        G.add_node(node_identifier, feature_index=node.feature_index, depth=node.depth)

        if parent is not None:
            edge_identifier = generate_edge_identifier()
            G.add_edge(node_identifier, edge_identifier)

        if node.left:
            add_nodes_and_edges(node.left, parent=node)

        if node.right:
            add_nodes_and_edges(node.right, parent=node)

```

```
def generate_unique_identifier():  
    global node_counter  
    node_counter += 1  
    return node_counter  
  
def generate_edge_identifier():  
    global edge_counter  
    edge_counter += 1  
    return edge_counter  
  
node_counter = 0  
edge_counter = 0  
add_nodes_and_edges(root_node)  
nx.draw(G)  
plt.title("Neural Tree")  
plt.axis('off')  
plt.show()
```

Graph of neural tree

Neural Tree

