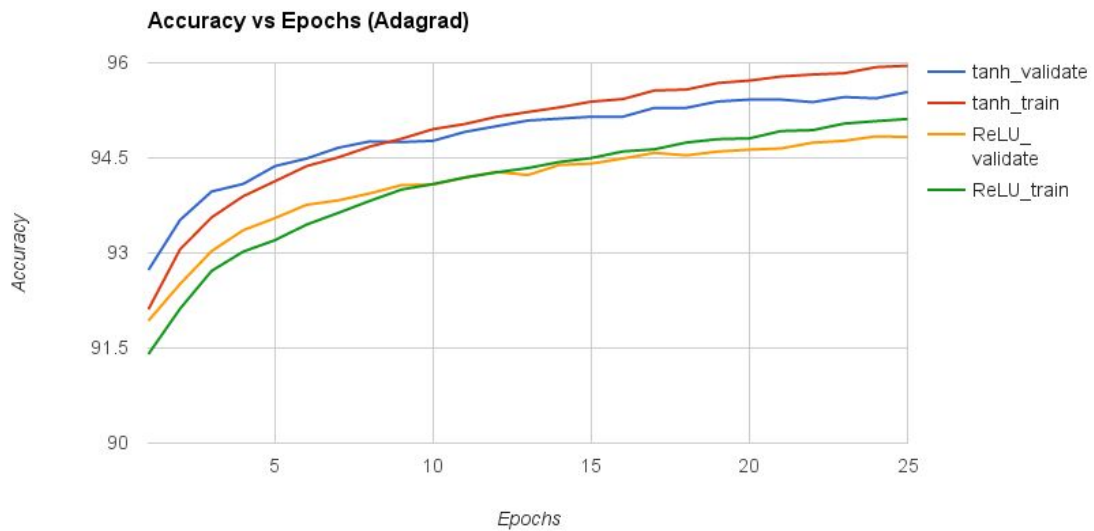
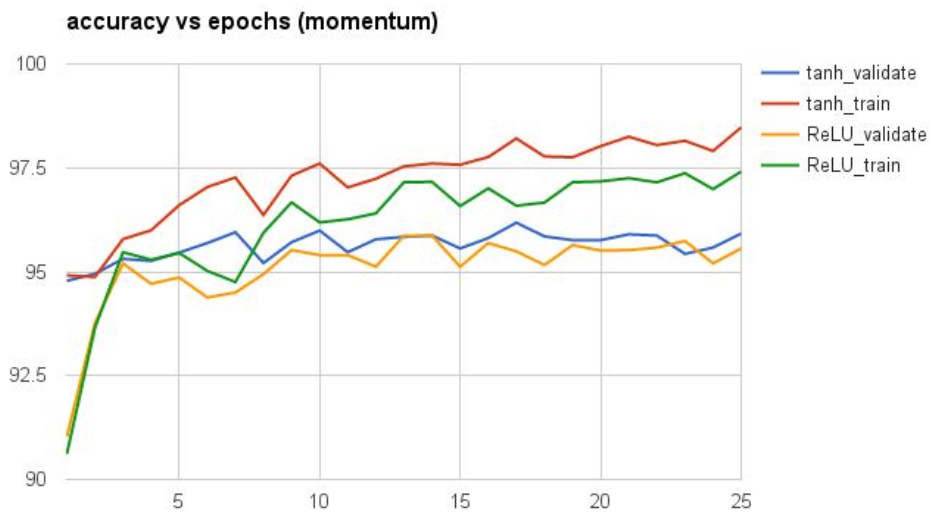


ABHINAV AGRWAL

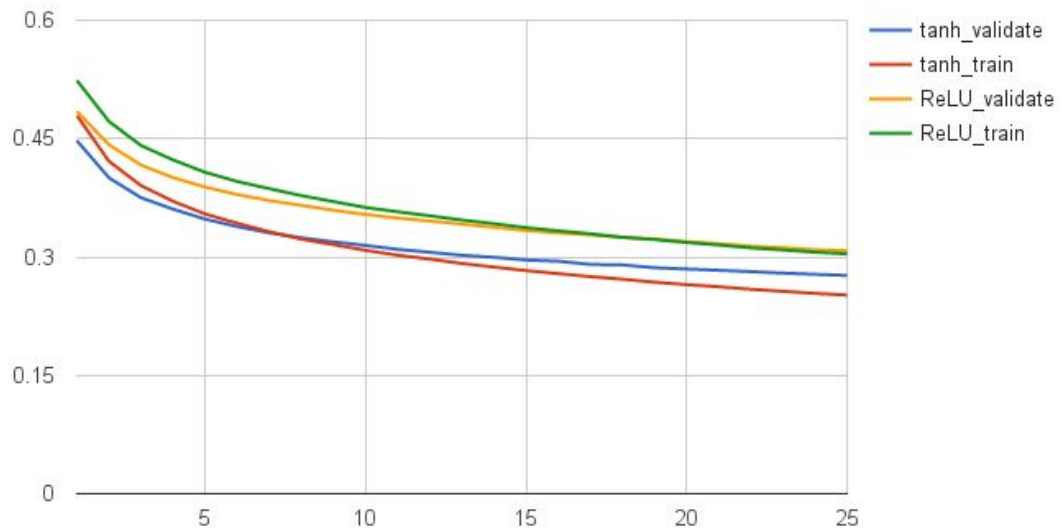
ROLL NO. : 14011

CS698A - ASSIGNMENT 1

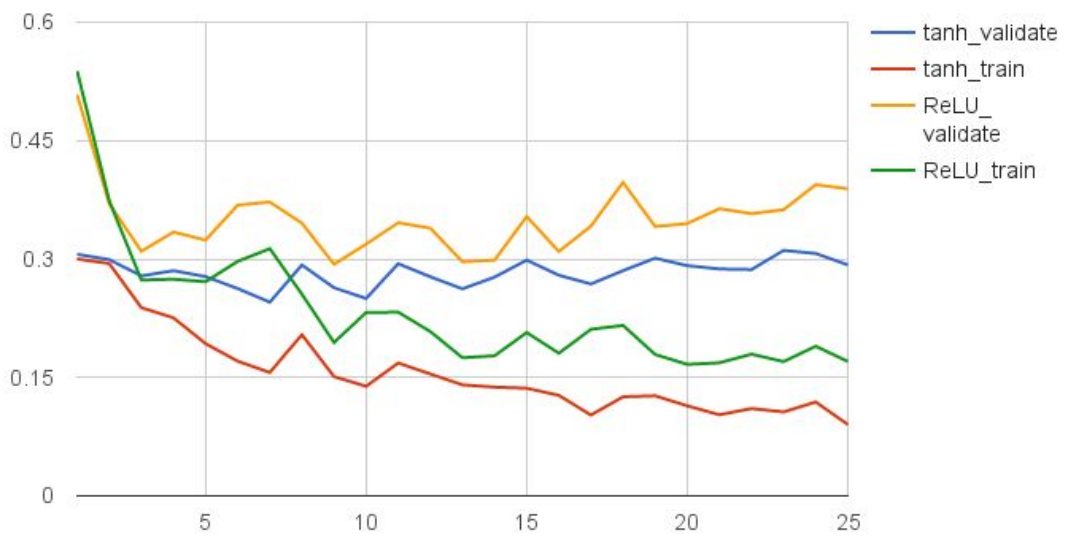
**PLOTS:**

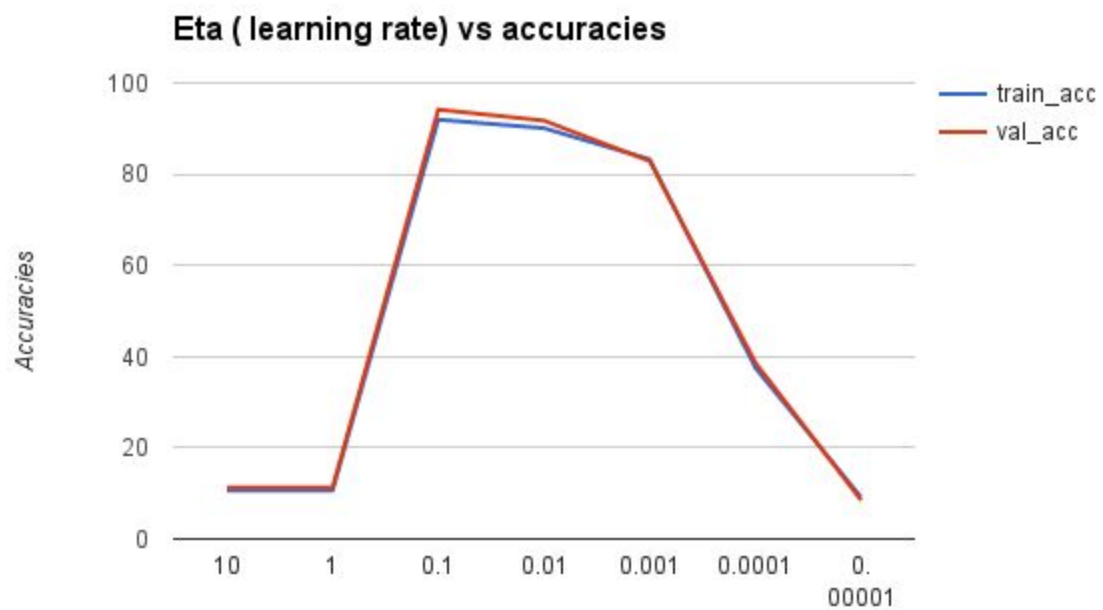
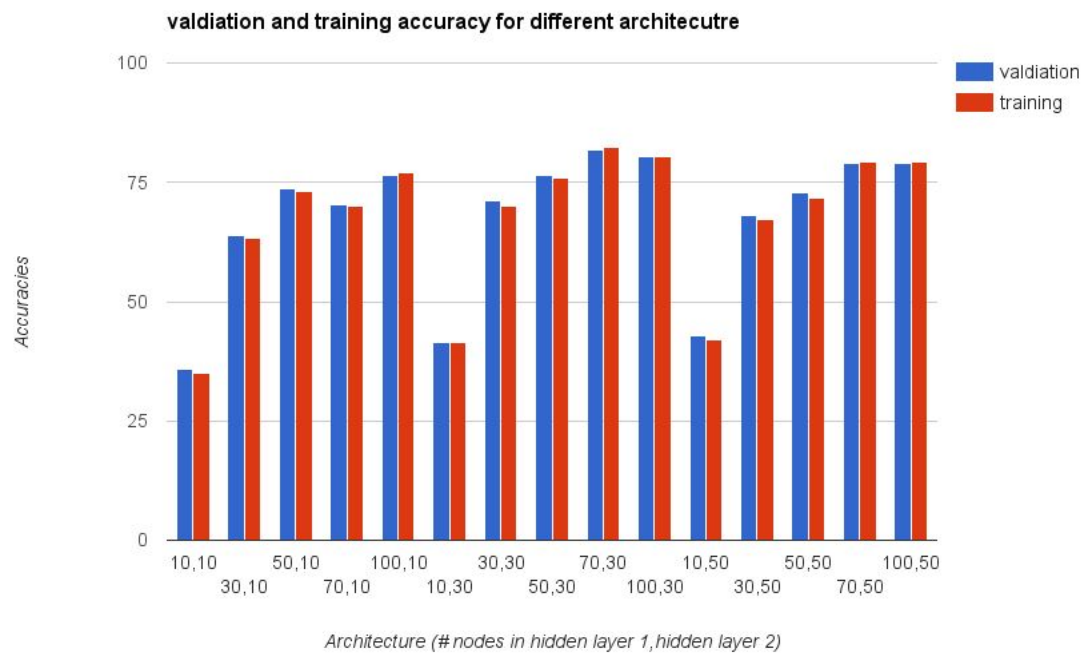


**Cost vs Epochs (Adagrad)**



**cost vs epochs (momentum)**





## **FINDINGS:**

The plots reveal that :

- Best choice for activation function is tanh (out of ReLU and itself ) and the best way to update your gradients is momentum (out of momentum and adagrad), as it achieves higher accuracies with less number of epochs.
- The eta(learning rate) when varied over the a range represents a typical gaussian curve and the corresponding accuracy reaches maximum when eta is of the order of 0.1  
The eta=0.1 and the activation function=ReLU and the gradient = momentum for these findings. The network was trained with 10,000 examples and maximum accuracy out three epochs was used to come with data that is sufficient for intuitive results
- The study of different architecture validates the intuitive findings that the simple architecture (#no. of hidden nodes (10,10),(10,30) and so on) have limited abilities while the the architecture with sufficient number of parameters can learn with less number of epochs.  
The eta=0.1 and the activation function=tanh and the gradient = momentum for these findings. The network was trained with 10,000 examples and maximum accuracy out two epochs was used to come with data that is sufficient for intuitive results

## **CODE:**

The code files are attached with the submission and a jupyter notebook is also attached to show how the play with the code.

## **GRADIENT CHECK:**

The following graph shows the numerical and back-propagated gradients for a particular weight matrix and randomly chosen example. This was done after training for two epochs, using 10000 examples.

The function grad\_check() was used for this and the details of implementation are in the jupyter notebook.

