Abhishek Kulkarni

Curriculum Vitae

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Research Interests

- Formal Methods for Robotics.
- Automated Reasoning.
- Reactive Synthesis.
- Game and Hypergame Theory.
- Mission/Task Planning.
- Algorithmically Complete Motion Planning.

Education

- Aug'16 M.S./Ph.D. in Robotics Engineering,
- Present Worcester Polytechnic Institute (WPI), Worcester, MA, USA, CGPA 3.67/4.0.
- Aug'12 Bachelor of Technology in Electronics and Telecommunication Engineering,
- May'16 Vishwakarma Institute of Technology (VIT), Pune, India, CGPA 8.72/10.0.

Industry Experience

- Aug'17 Robotics Research Intern, NodeIn Inc..
 - **Dec'17** Developed provably-correct motion planning algorithm for quadcopter traveling in urban environment using formal methods approach.
- May'17 Hardware-Software Intern, Mathworks.
 - Aug'17 Extended MATLAB's hardware support for Arduino with additional sensors.

Conference Publications

- **2019** Abhishek N. Kulkarni and Jie Fu, Opportunistic Synthesis in Reactive Games under Information Asymmetry, Conference on Decision and Control (CDC), 2019. (accepted)
- **2018 Abhishek N. Kulkarni** and Jie Fu, A Compositional Approach to Reactive Games under Temporal Logic Specifications, Annual American Control Conference (ACC), 2018.
- 2015 Siddharth Nitin Patki, Madhura Joshi and Abhishek N. Kulkarni, Dot Matrix Text Recognition for Industrial Carton Classification, International Conference on Industrial Instrumentation and Control (ICIC), 2015.
- **2014** Abhishek N. Kulkarni, Anita S. Joshi and Satish R. Inamdar, *Big Data Management of a Cyber-Physical Multi-location Chemical Factory*, International Journal of Industrial Electronics and Electrical Engineering (IJIEEE), vol. 2, issue 8, pp. 9-14, Aug. 2014.

Teaching and Leadership Roles

- Fall'19 Guest lecturer for RBE595: Formal Method in Robotics course for Prof. Jie Fu.
- Spring'18 TA for *ECE2799: Electrical and Computer Engineering Design* in Term-B for Prof. Shamsur Mazumder.
- Spring'18 TA for ECE2019: Sensors, Circuits and Systems in Term-A for Prof. Shamsur Mazumder.
- Spring'17 Talk on An Informal Introduction to Formal Methods for the robotics honor society, Rho-Beta-Epsilon.
- Summer'15 Designed and taught *Embedded Systems Programming with Arduino* at Cognitive Robotics and Intelligent SysTems Lab (CRISTL) group at VIT.
 - Fall'15 Organized a 6-day workshop on *Image Processing using OpenCV* by Anand Muglikar as part of CRISTL.
- Summer'14 Founded and led CRISTL group at VIT with focus on theoretical aspects of robotics.

Skills

Languages Python, C/C++, Embedded C, VB.NET, Shell Script.

Tools Robot Operating System (ROS), Gazebo, OpenCV, MATLAB, Visual Studio, Unity3D, LATEX, GitHub.

Embedded AVR, BeagleBone Black, Raspberry Pi, Arduino, NVidia Jetson TX2. **Platforms**

Selected Honors/Awards

2014-2016 Research Grant from Board of College and University Development (BCUD) for developing a Low-cost Educational Robotics Platform: Curio.