DS-GA 1003 Machine Learning Lecture 2

February 9, 2021

1 Gradient Descent

- Gradient is the steepest ascent direction.
 - Derivative tells us how much the function value f(x) changes if we move x a tiny bit.
 - For multivariable functions, we need directional derivatives to know how fast f(x) changes along u.
 - The fastest ascent direction is given by

$$\mathop{\arg\max}_{\|u\|_2=1} \nabla f(x) \cdot u = \frac{\nabla f(x)}{\|\nabla f(x)\|_2}$$

- * Show by Cauchy-Schwarz.
- * (draw) Geometric explanation: $a \cdot b = ||a||_2 ||b||_2 \cos \theta$.
- Where does gradient descent converge?
 - Stationary/Critical points: x where $\nabla f(x) = 0$.
 - (draw) Local/global minimum/maximum, flat region of critical points
 - (draw) Are all critical points local minima/maxima? [no, saddle points.]
 - In general, GD converges to stationary points. With certain conditions (e.g. f is convex, gradient cannot change arbitrarily fast, small step size), we can reach global minimum.
- What is the true "step size"?
 - $-\eta \|\nabla f(x)\|_2$. Step is smaller as we move towards the extremum.
- Line search methods
 - Exact line search: find the optimize step size along a descent direction

$$\underset{\eta \ge 0}{\arg\min} f(x - \eta \nabla f(x))$$

Ususally we cannot minimize it exactly.

- Back-tracking line search: find the step size so that we get the expected amount of decrease in f(x)

* Start with $\eta = 1$, repeat $\eta \leftarrow \beta \eta$ until

$$f(x^k - \eta \nabla f(x^k)) \le f(x^k) - \alpha \eta \nabla^T f(x^k) \nabla f(x^k) = f(x^k) - \alpha \eta \|\nabla f(x^k)\|_2^2$$

- * (draw function of the step size)
- * Can prevent step sizes that are too large

2 Case study: Least Square Regression

• Closed form solution:

$$(X^T X)w = Xy$$

- $-X^TX: O(nd^2)$
- -Xy: O(nd)
- Solving $d \times d$ linear system: $O(d^3)$
- Gradient descent:

$$f(w) = \frac{1}{2} ||Xw - y||_2^2 \tag{1}$$

$$\nabla_w f(w) = X^T (Xw - y) \tag{2}$$

$$w^{t+1} = w^t - \eta^t X^T (Xw - y) \tag{3}$$

- Compute the gradient: O(nd)
- Gradient descent: O(ndt)