## Representer Theorem

He He

CDS, NYU

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## SVM solution is in the "span of the data"

• We found the SVM dual problem can be written as:

$$\sup_{\alpha \in \mathbb{R}^n} \qquad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i$$
s.t. 
$$\sum_{i=1}^n \alpha_i y_i = 0$$

$$\alpha_i \in \left[0, \frac{c}{n}\right] \ i = 1, \dots, n.$$

- Given dual solution  $\alpha^*$ , primal solution is  $w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$ .
- Notice:  $w^*$  is a linear combination of training inputs  $x_1, \ldots, x_n$ .
- We refer to this phenomenon by saying " $w^*$  is in the span of the data."
  - Or in math,  $w^* \in \text{span}(x_1, \dots, x_n)$ .

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Ridge regression solution is in the "span of the data"

• The ridge regression solution for regularization parameter  $\lambda > 0$  is

$$w^* = \arg\min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n \left\{ w^T x_i - y_i \right\}^2 + \lambda ||w||_2^2.$$

• This has a closed form solution (Homework #3):

$$w^* = \left(X^T X + \lambda I\right)^{-1} X^T y,$$

where X is the design matrix, with  $x_1, \ldots, x_n$  as rows.

Ridge regression solution is in the "span of the data"

• Rearranging  $w^* = (X^T X + \lambda I)^{-1} X^T y$ , we can show that (also Homework #3):

$$w^* = X^T \underbrace{\left(\frac{1}{\lambda}y - \frac{1}{\lambda}Xw^*\right)}_{\alpha^*}$$
$$= X^T \alpha^* = \sum_{i=1}^n \alpha_i^* x_i.$$

- So  $w^*$  is in the span of the data.
  - i.e.  $w^* \in \operatorname{span}(x_1, \ldots, x_n)$

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ullet The ridge regression solution for regularization parameter  $\lambda>0$  is

$$w^* = \arg\min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n \left\{ w^T x_i - y_i \right\}^2 + \lambda ||w||_2^2.$$

- We now know that  $w^* \in \operatorname{span}(x_1, \dots, x_n) \subset \mathbb{R}^d$ .
- So rather than minimizing over all of  $\mathbb{R}^d$ , we can minimize over span  $(x_1, \dots, x_n)$ .

$$w^* = \underset{w \in \text{span}(x_1, ..., x_n)}{\arg \min} \frac{1}{n} \sum_{i=1}^n \{ w^T x_i - y_i \}^2 + \lambda ||w||_2^2.$$

• Let's reparameterize the objective by replacing w as a linear combination of the inputs.

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If solution is in the span of the data, we can reparameterize

- Note that for any  $w \in \text{span}(x_1, \dots, x_n)$ , we have  $w = X^T \alpha$ , for some  $\alpha \in \mathbb{R}^n$ .
- So let's replace w with  $X^T \alpha$  in our optimization problem:

- To get  $w^*$  from the reparameterized optimization problem, we just take  $w^* = X^T \alpha^*$ .
- We changed the dimension of our optimization variable from d to n. Is this useful?

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## Consider very large feature spaces

- Suppose we have a 300-million dimension feature space [very large]
  - (e.g. using high order monomial interaction terms as features, as described last lecture)
- Suppose we have a training set of 300,000 examples [fairly large]
- In the original formulation, we solve a 300-million dimension optimization problem.
- In the reparameterized formulation, we solve a 300,000-dimension optimization problem.
- This is why we care about when the solution is in the span of the data.
- This reparameterization is interesting when we have more features than data  $(d \gg n)$ .

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What's next?

- For SVM and ridge regression, we found that the solution is in the span of the data.
  - derived in two rather ad-hoc ways
- Up next: The Representer Theorem, which shows that this "span of the data" result occurs far more generally, and we prove it using basic linear algebra.

Math Review: Inner Product Spaces and Hilbert Spaces

## Hypothesis spaces we've seen so far

Finite-dimensional vector space (linear functions):

$$\mathcal{H} = \{ f : \mathcal{X} \to \mathsf{R} \mid f(x) = w^T x, \quad w, x \in \mathsf{R}^d \} .$$

To consider more complex input spaces (e.g. text, images), we use a feature map  $\phi: \mathcal{X} \to \mathcal{F}$ :

$$\mathcal{H} = \left\{ f \colon \mathcal{X} \to \mathsf{R} \mid f(x) = w^{\mathsf{T}} \varphi(x) \right\} .$$

- Φ does not have to be linear.
- ullet The feature space  ${\mathcal F}$  can be  ${\mathsf R}^d$  (Euclidean space) or an infinite-dimensional vector space.
- We would like more structure on  $\mathcal{F}$ .

## Inner Product Space (or "Pre-Hilbert" Spaces)

An inner product space (over reals) is a vector space V with an inner product, which is a mapping

$$\langle \cdot, \cdot \rangle : \mathcal{V} \times \mathcal{V} \to \mathsf{R}$$

that has the following properties:  $\forall x, y, z \in \mathcal{V}$  and  $a, b \in \mathbb{R}$ :

- Symmetry:  $\langle x, y \rangle = \langle y, x \rangle$
- Linearity:  $\langle ax + by, z \rangle = a \langle x, z \rangle + b \langle y, z \rangle$
- Positive-definiteness:  $\langle x, x \rangle \ge 0$  and  $\langle x, x \rangle = 0 \iff x = 0_{\mathcal{V}}$ .

To show a function  $\langle \cdot, \cdot \rangle$  is an inner product, we need to check the above conditions.

Exercise: show that  $\langle x, y \rangle \stackrel{\text{def}}{=} x^T y$  is an inner product on  $\mathbb{R}^d$ .

#### Norm from Inner Product

Inner product is nice because it gives us notions of "size", "distance", "angle" in the vector space.

For an inner product space, we can ddefine a norm as

$$||x|| \stackrel{\text{def}}{=} \sqrt{\langle x, x \rangle}.$$

#### Example

 $R^d$  with standard Euclidean inner product is an inner product space:

$$\langle x, y \rangle := x^T y \qquad \forall x, y \in \mathbb{R}^d.$$

Norm is

$$||x|| = \sqrt{x^T x}$$
.

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# Orthogonality (Definitions)

#### Definition

Two vectors are **orthogonal** if  $\langle x, x' \rangle = 0$ . We denote this by  $x \perp x'$ .

#### Definition

x is orthogonal to a set S, i.e.  $x \perp S$ , if  $x \perp s$  for all  $x \in S$ .

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# Pythagorean Theorem

#### Theorem (Pythagorean Theorem)

If 
$$x \perp x'$$
, then  $||x + x'||^2 = ||x||^2 + ||x'||^2$ .

#### Proof.

We have

$$||x+x'||^2 = \langle x+x', x+x' \rangle$$

$$= \langle x, x \rangle + \langle x, x' \rangle + \langle x', x \rangle + \langle x', x' \rangle$$

$$= ||x||^2 + ||x'||^2.$$



#### Hilbert Space

- A pre-Hilbert space is a vector space equipped with an inner product.
- We need an additional technical condition for Hilbert space: completeness.
- A space is **complete** if all Cauchy sequences in the space converge to a point in the space.

#### Definition

A Hilbert space is a complete inner product space.

#### Example

Any finite dimensional inner produce space is a Hilbert space.

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The Representer Theorem

# Generalize from SVM Objective

• SVM objective:

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} ||w||^2 + \frac{c}{n} \sum_{i=1}^n \max(0, 1 - y_i [\langle w, x_i \rangle]).$$

• Generalized objective:

$$\min_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle),$$

where

- $w, x_1, \dots, x_n \in \mathcal{H}$  for some Hilbert space  $\mathcal{H}$ . (We typically have  $\mathcal{H} = \mathbb{R}^d$ .)
- $\|\cdot\|$  is the norm corresponding to the inner product of  $\mathcal{H}$ . (i.e.  $\|w\| = \sqrt{\langle w, w \rangle}$ )
- $R:[0,\infty)\to R$  is nondecreasing (Regularization term), and
- $L: \mathbb{R}^n \to \mathbb{R}$  is arbitrary (Loss term).

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# General Objective Function for Linear Hypothesis Space (Details)

Generalized objective:

$$\min_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle)$$

- We can map  $x_i$  to a feature space.
- The prediction/score function  $x \mapsto \langle w, x \rangle$  is linear in w.

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# General Objective Function for Linear Hypothesis Space (Details)

• Generalized objective:

$$\min_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle)$$

- Ridge regression and SVM are of this form. (Verify this!)
- What if we penalize with  $\lambda ||w||_2$  instead of  $\lambda ||w||_2^2$ ? Yes!
- ullet What if we use lasso regression? No!  $\ell_1$  norm does not correspond to an inner product.

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## The Representer Theorem: Quick Summary

• Generalized objective:

$$w^* = \arg\min_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle)$$

• Representer theorem tells us we can look for  $w^*$  in the span of the data:

$$w^* = \underset{w \in \operatorname{span}(x_1, \dots, x_n)}{\operatorname{arg\,min}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle).$$

• So we can reparameterize as before:

$$\alpha^* = \operatorname*{arg\,min}_{\alpha \in \mathbb{R}^n} R\left( \left\| \sum_{i=1}^n \alpha_i x_i \right\| \right) + L\left( \left\langle \sum_{i=1}^n \alpha_i x_i, x_1 \right\rangle, \dots, \left\langle \sum_{i=1}^n \alpha_i x_i, x_n \right\rangle \right).$$

Our reparameterization trick applies much more broadly than SVM and ridge.

#### Theorem (Representer Theorem)

Let

$$J(w) = R(||w||) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle),$$

where

- $w, x_1, ..., x_n \in \mathcal{H}$  for some Hilbert space  $\mathcal{H}$ . (We typically have  $\mathcal{H} = \mathbb{R}^d$ .)
- $\|\cdot\|$  is the norm corresponding to the inner product of  $\mathfrak{R}$ . (i.e.  $\|w\| = \sqrt{\langle w, w \rangle}$ )
- $R:[0,\infty)\to R$  is nondecreasing (Regularization term), and
- $L: \mathbb{R}^n \to \mathbb{R}$  is arbitrary (Loss term).

Then it has a minimizer of the form  $w^* = \sum_{i=1}^n \alpha_i x_i$ .

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The Representer Theorem (Proof sketch)

Reparameterizing our Generalized Objective Function

### Rewriting the Objective Function

• Define the training score function  $s: \mathbb{R}^d \to \mathbb{R}^n$  by

$$s(w) = \begin{pmatrix} \langle w, x_1 \rangle \\ \vdots \\ \langle w, x_n \rangle \end{pmatrix},$$

which gives the **training score vector** for any w.

• We can then rewrite the objective function as

$$J(w) = R(||w||) + L(s(w)),$$

where now  $L: \mathbb{R}^{n \times 1} \to \mathbb{R}$  takes a column vector as input.

• This will allow us to have a slick reparameterized version...

## Reparameterize the Generalized Objective

- By the Representer Theorem, it's sufficient to minimize J(w) for w of the form  $\sum_{i=1}^{n} \alpha_i x_i$ .
- Plugging this form into J(w), we see we can just minimize

$$J_0(\alpha) = R\left(\left\|\sum_{i=1}^n \alpha_i x_i\right\|\right) + L\left(s\left(\sum_{i=1}^n \alpha_i x_i\right)\right)$$

over 
$$\alpha = (\alpha_1, \dots, \alpha_n)^T \in \mathbb{R}^{n \times 1}$$
.

- With some new notation, we can substantially simplify
  - the norm piece  $||w|| = ||\sum_{i=1}^{n} \alpha_i x_i||$ , and
  - the score piece  $s(w) = s(\sum_{i=1}^{n} \alpha_i x_i)$ .

## Simplifying the Reparameterized Norm

• For the norm piece  $||w|| = ||\sum_{i=1}^{n} \alpha_i x_i||$ , we have

$$||w||^{2} = \langle w, w \rangle$$

$$= \left\langle \sum_{i=1}^{n} \alpha_{i} x_{i}, \sum_{j=1}^{n} \alpha_{j} x_{j} \right\rangle$$

$$= \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} \langle x_{i}, x_{j} \rangle.$$

- This expression involves the  $n^2$  inner products between all pairs of input vectors.
- We often put those values together into a matrix (Gram/Kernel matrix).

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### Example: Gram Matrix for the Dot Product

- Consider  $x_1, \ldots, x_n \in \mathbb{R}^{d \times 1}$  with the standard inner product  $\langle x, x' \rangle = x^T x'$ .
- Let  $X \in \mathbb{R}^{n \times d}$  be the **design matrix**, which has each input vector as a row:

$$X = \begin{pmatrix} -x_1^T - \\ \vdots \\ -x_n^T - \end{pmatrix}.$$

• Then the Gram matrix is

$$K = \begin{pmatrix} x_1^T x_1 & \cdots & x_1^T x_n \\ \vdots & \ddots & \cdots \\ x_n^T x_1 & \cdots & x_n^T x_n \end{pmatrix} = \begin{pmatrix} -x_1^T - \\ \vdots \\ -x_n^T - \end{pmatrix} \begin{pmatrix} | & \cdots & | \\ x_1 & \cdots & x_n \\ | & \cdots & | \end{pmatrix}$$
$$= XX^T$$

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## Simplifying the Reparametrized Norm

• With  $w = \sum_{i=1}^{n} \alpha_i x_i$ , we have

$$||w||^{2} = \langle w, w \rangle$$

$$= \left\langle \sum_{i=1}^{n} \alpha_{i} x_{i}, \sum_{j=1}^{n} \alpha_{j} x_{j} \right\rangle$$

$$= \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} \langle x_{i}, x_{j} \rangle$$

$$= \alpha^{T} K \alpha.$$

### Simplifying the Training Score Vector

• The score for  $x_j$  for  $w = \sum_{i=1}^n \alpha_i x_i$  is

$$\langle w, x_j \rangle = \left\langle \sum_{i=1}^n \alpha_i x_i, x_j \right\rangle = \sum_{i=1}^n \alpha_i \left\langle x_i, x_j \right\rangle$$

• The training score vector is

$$s\left(\sum_{i=1}^{n}\alpha_{i}x_{i}\right) = \begin{pmatrix} \sum_{i=1}^{n}\alpha_{i}\langle x_{i}, x_{1}\rangle \\ \vdots \\ \sum_{i=1}^{n}\alpha_{i}\langle x_{i}, x_{n}\rangle \end{pmatrix} = \begin{pmatrix} \alpha_{1}\langle x_{1}, x_{1}\rangle + \dots + \alpha_{n}\langle x_{n}, x_{1}\rangle \\ \vdots \\ \alpha_{1}\langle x_{1}, x_{n}\rangle + \dots + \alpha_{n}\langle x_{n}, x_{n}\rangle \end{pmatrix}$$
$$= \begin{pmatrix} \langle x_{1}, x_{1}\rangle & \dots & \langle x_{1}, x_{n}\rangle \\ \vdots & \ddots & \dots \\ \langle x_{n}, x_{1}\rangle & \dots & \langle x_{n}, x_{n}\rangle \end{pmatrix} \begin{pmatrix} \alpha_{1} \\ \vdots \\ \alpha_{n} \end{pmatrix}$$
$$= K\alpha$$

• Putting it all together, our reparameterized objective function can be written as

$$J_0(\alpha) = R\left(\left\|\sum_{i=1}^n \alpha_i x_i\right\|\right) + L\left(s\left(\sum_{i=1}^n \alpha_i x_i\right)\right)$$
$$= R\left(\sqrt{\alpha^T K \alpha}\right) + L(K \alpha),$$

which we minimize over  $\alpha \in \mathbb{R}^n$ .

- All information needed about  $x_1, \ldots, x_n$  is summarized in the Gram matrix K.
- We're now minimizing over  $R^n$  rather than  $R^d$ .
- If  $d \gg n$ , this can be a big win computationally (at least once K is computed).

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## Reparameterizing Predictions

Suppose we've found

$$\alpha^* \in \operatorname*{arg\,min}_{\alpha \in \mathsf{R}^n} R\left(\sqrt{\alpha^T K \alpha}\right) + L\left(K\alpha\right).$$

• Then we know  $w^* = \sum_{i=1}^n \alpha^* x_i$  is a solution to

$$\underset{w \in \mathcal{H}}{\operatorname{arg\,min}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle).$$

• The prediction on a new point  $x \in \mathcal{H}$  is

$$\hat{f}(x) = \langle w^*, x \rangle = \sum_{i=1}^n \alpha_i^* \langle x_i, x \rangle.$$

• To make a new prediction, we may need to touch all the training inputs  $x_1, \ldots, x_n$ .

#### More Notation

• It will be convenient to define the following column vector for any  $x \in \mathcal{H}$ :

$$k_{\mathsf{x}} = \begin{pmatrix} \langle \mathsf{x}_1, \mathsf{x} \rangle \\ \vdots \\ \langle \mathsf{x}_n, \mathsf{x} \rangle \end{pmatrix}$$

• Then we can write our predictions on a new point x as

$$\hat{f}(x) = k_x^T \alpha^*$$

# Summary So Far

- Original plan:
  - Find  $w^* \in \operatorname{arg\,min}_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle)$
  - Predict with  $\hat{f}(x) = \langle w^*, x \rangle$ .
- We showed that the following is equivalent:
  - Find  $\alpha^* \in \operatorname{arg\,min}_{\alpha \in \mathbb{R}^n} R\left(\sqrt{\alpha^T K \alpha}\right) + L(K \alpha)$
  - Predict with  $\hat{f}(x) = k_x^T \alpha^*$ , where

$$K = \begin{pmatrix} \langle x_1, x_1 \rangle & \cdots & \langle x_1, x_n \rangle \\ \vdots & \ddots & \cdots \\ \langle x_n, x_1 \rangle & \cdots & \langle x_n, x_n \rangle \end{pmatrix} \quad \text{and} \quad k_x = \begin{pmatrix} \langle x_1, x \rangle \\ \vdots \\ \langle x_n, x \rangle \end{pmatrix}$$

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• Every element  $x \in \mathcal{H}$  occurs inside an inner products with a training input  $x_i \in \mathcal{H}$ .

#### Kernelization

#### **Definition**

A method is **kernelized** if every feature vector  $\psi(x)$  only appears inside an inner product with another feature vector  $\psi(x')$ . This applies to both the optimization problem and the prediction function.

• Here we are using  $\psi(x) = x$ . Thus finding

$$\alpha^* \in \operatorname*{arg\,min}_{\alpha \in \mathsf{R}^n} R\left(\sqrt{\alpha^T K \alpha}\right) + L(K \alpha)$$

and making predictions with  $\hat{f}(x) = k_x^T \alpha^*$  is a kernelization of finding

$$w^* \in \arg\min_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, x_1 \rangle, \dots, \langle w, x_n \rangle)$$

and making predictions with  $\hat{f}(x) = \langle w^*, x \rangle$ .

#### Summary

- We used duality for SVM and bare hands for ridge regression to find their kernelized version.
- Our principle tool for kernelization is reparameterization by the representer theorem.
- Once kernelized, we can apply the kernel trick: doesn't need to represent  $\phi(x)$  explicitly.