SVM Dual Problem

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SVM as a Quadratic Program

The SVM optimization problem is equivalent to

minimize
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
subject to
$$-\xi_i \leqslant 0 \quad \text{for } i = 1, \dots, n$$

$$\left(1 - y_i \left[w^T x_i + b\right]\right) - \xi_i \leqslant 0 \quad \text{for } i = 1, \dots, n$$

- Differentiable objective function
- n+d+1 unknowns and 2n affine constraints.
- A quadratic program that can be solved by any off-the-shelf QP solver.
- Let's learn more by examining the dual.

Why Do We Care About the Dual?

The Lagrangian

The general [inequality-constrained] optimization problem is:

minimize
$$f_0(x)$$

subject to $f_i(x) \le 0, i = 1,..., m$

Definition

The Lagrangian for this optimization problem is

$$L(x,\lambda) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x).$$

- λ_i 's are called Lagrange multipliers (also called the dual variables).
- Weighted sum of the objective and constraint functions
- Hard constraints → soft constraints

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Definition

The Lagrange dual function is

$$g(\lambda) = \inf_{x} L(x, \lambda) = \inf_{x} \left(f_0(x) + \sum_{i=1}^{m} \lambda_i f_i(x) \right)$$

- $g(\lambda)$ is concave (why?)
- Lower bound property: if $\lambda \succeq 0$, $g(\lambda) \leqslant p^*$ where p^* is the optimal value of the optimization problem.
- $g(\lambda)$ can be $-\infty$ (uninformative lower bound)

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The Primal and the Dual

• For any primal form optimization problem,

minimize
$$f_0(x)$$

subject to $f_i(x) \leq 0$, $i = 1, ..., m$,

there is a recipe for constructing a corresponding Lagrangian dual problem:

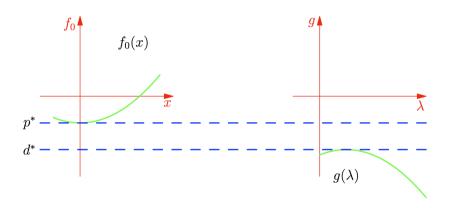
maximize
$$g(\lambda)$$

subject to $\lambda_i \ge 0, i = 1, ..., m$,

- The dual problem is always a convex optimization problem.
- The dual variables often have interesting and relevant interpretations.
- The dual variables provide certificate for optimality.

Weak Duality

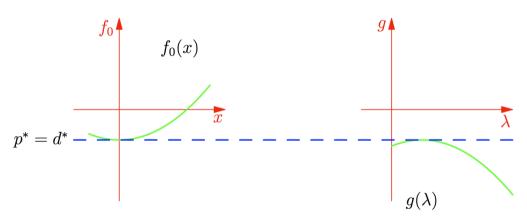
We always have **weak duality**: $p^* \geqslant d^*$.



Plot courtesy of Brett Bernstein.

Strong Duality

For some problems, we have strong duality: $p^* = d^*$.



For convex problems, strong duality is fairly typical.

Plot courtesy of Brett Bernstein. He He (CDS, NYU)

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• Assume strong duality. Let x^* be primal optimal and λ^* be dual optimal. Then:

$$\begin{array}{lll} f_0(x^*) & = & g(\lambda^*) = \inf_x L(x,\lambda^*) & \text{(strong duality and definition)} \\ & \leqslant & L(x^*,\lambda^*) \\ & = & f_0(x^*) + \sum_{i=1}^m \lambda_i^* f_i(x^*) \\ & \leqslant & f_0(x^*). \end{array}$$

Each term in sum $\sum_{i=1}^{\infty} \lambda_i^* f_i(x^*)$ must actually be 0. That is

$$\lambda_i > 0 \implies f_i(x^*) = 0$$
 and $f_i(x^*) < 0 \implies \lambda_i = 0 \quad \forall i$

This condition is known as complementary slackness.

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The SVM Dual Problem

SVM Lagrange Multipliers

minimize
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
subject to
$$-\xi_i \leqslant 0 \quad \text{for } i = 1, \dots, n$$
$$\left(1 - y_i \left[w^T x_i + b\right]\right) - \xi_i \leqslant 0 \quad \text{for } i = 1, \dots, n$$

Lagrange Multiplier	Constraint
λ_i	$-\xi_i \leqslant 0$
α_i	$\left(1-y_i\left[w^Tx_i+b\right]\right)-\xi_i\leqslant 0$

$$L(w, b, \xi, \alpha, \lambda) = \frac{1}{2} ||w||^2 + \frac{c}{n} \sum_{i=1}^{n} \xi_i + \sum_{i=1}^{n} \alpha_i \left(1 - y_i \left[w^T x_i + b \right] - \xi_i \right) + \sum_{i=1}^{n} \lambda_i \left(-\xi_i \right)$$

Dual optimum value: $d^* = \sup_{\alpha, \lambda \succ 0} \inf_{w, b, \xi} L(w, b, \xi, \alpha, \lambda)$

Strong Duality by Slater's Constraint Qualification

The SVM optimization problem:

minimize
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
subject to
$$-\xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$
$$\left(1 - y_i \left[w^T x_i + b\right]\right) - \xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$

Slater's constraint qualification:

- Convex problem + affine constraints ⇒ strong duality iff problem is feasible
- Do we have a feasible point?
- For SVM, we have strong duality.

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SVM Dual Function: First Order Conditions

Lagrange dual function is the inf over primal variables of *L*:

$$g(\alpha, \lambda) = \inf_{w, b, \xi} L(w, b, \xi, \alpha, \lambda)$$

$$= \inf_{w, b, \xi} \left[\frac{1}{2} w^{T} w + \sum_{i=1}^{n} \xi_{i} \left(\frac{c}{n} - \alpha_{i} - \lambda_{i} \right) + \sum_{i=1}^{n} \alpha_{i} \left(1 - y_{i} \left[w^{T} x_{i} + b \right] \right) \right]$$

$$\partial_{w} L = 0 \iff w - \sum_{i=1}^{n} \alpha_{i} y_{i} x_{i} = 0 \iff w = \sum_{i=1}^{n} \alpha_{i} y_{i} x_{i}$$

$$\partial_{b} L = 0 \iff -\sum_{i=1}^{n} \alpha_{i} y_{i} = 0 \iff \sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

$$\partial_{\xi_{i}} L = 0 \iff \frac{c}{n} - \alpha_{i} - \lambda_{i} = 0 \iff \alpha_{i} + \lambda_{i} = \frac{c}{n}$$

SVM Dual Function

- Substituting these conditions back into L, the second term disappears.
- First and third terms become

$$\frac{1}{2}w^Tw = \frac{1}{2}\sum_{i,j=1}^n \alpha_i\alpha_jy_iy_jx_i^Tx_j$$

$$\sum_{i=1}^n \alpha_i(1-y_i[w^Tx_i+b]) = \sum_{i=1}^n \alpha_i - \sum_{i,j=1}^n \alpha_i\alpha_jy_iy_jx_j^Tx_i - b\sum_{i=1}^n \alpha_iy_i.$$

Putting it together, the dual function is

$$g(\alpha, \lambda) = \begin{cases} \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_i \alpha_j y_i y_j x_j^T x_i & \sum_{i=1}^{n} \alpha_i y_i = 0 \\ -\infty & \text{otherwise.} \end{cases}$$

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The dual function is

$$g(\alpha, \lambda) = \begin{cases} \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_i \alpha_j y_i y_j x_j^T x_i & \sum_{i=1}^{n} \alpha_i y_i = 0 \\ -\infty & \text{otherwise.} \end{cases}$$

• The dual problem is $\sup_{\alpha,\lambda \succeq 0} g(\alpha,\lambda)$:

$$\sup_{\alpha,\lambda} \qquad \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{j}^{T} x_{i}$$
s.t.
$$\sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

$$\alpha_{i} + \lambda_{i} = \frac{c}{n} \quad \alpha_{i}, \lambda_{i} \geqslant 0, \ i = 1, \dots, n$$

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Insights from the Dual Problem

KKT Conditions

For convex problems, if Slater's condition is satisfied, then KKT conditions provide necessary and sufficient conditions for the optimal solution.

- Primal feasibility: $f_i(x) \leq 0 \quad \forall i$
- Dual feasibility: $\lambda \succeq 0$
- Complementary slackness: $\lambda_i f_i(x) = 0$
- First-order condition:

$$\frac{\partial}{\partial x}L(x,\lambda)=0$$

The SVM Dual Solution

• We found the SVM dual problem can be written as:

$$\sup_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{j}^{T} x_{i}$$
s.t.
$$\sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

$$\alpha_{i} \in \left[0, \frac{c}{n}\right] \ i = 1, \dots, n.$$

- Given solution α^* to dual, primal solution is $w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$.
- The solution is in the space spanned by the inputs.
- Note $\alpha_i^* \in [0, \frac{c}{n}]$. So c controls max weight on each example. (Robustness!)
 - What's the relation between c and regularization?

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Complementary Slackness Conditions

• Recall our primal constraints and Lagrange multipliers:

Lagrange Multiplier	Constraint
λ_i	$-\xi_i \leqslant 0$
α_i	$(1-y_if(x_i))-\xi_i\leqslant 0$

- Recall first order condition $\nabla_{\xi_i} L = 0$ gave us $\lambda_i^* = \frac{c}{n} \alpha_i^*$.
- By strong duality, we must have **complementary slackness**:

$$\alpha_i^* \left(1 - y_i f^*(x_i) - \xi_i^* \right) = 0$$
$$\lambda_i^* \xi_i^* = \left(\frac{c}{n} - \alpha_i^* \right) \xi_i^* = 0$$

Consequences of Complementary Slackness

By strong duality, we must have complementary slackness.

$$\alpha_i^* \left(1 - y_i f^*(x_i) - \xi_i^*\right) = 0$$
$$\left(\frac{c}{n} - \alpha_i^*\right) \xi_i^* = 0$$

Recall "slack variable" $\xi_i^* = \max(0, 1 - y_i f^*(x_i))$ is the hinge loss on (x_i, y_i) .

- If $y_i f^*(x_i) > 1$ then the margin loss is $\xi_i^* = 0$, and we get $\alpha_i^* = 0$.
- If $y_i f^*(x_i) < 1$ then the margin loss is $\xi_i^* > 0$, so $\alpha_i^* = \frac{c}{n}$.
- If $\alpha_i^* = 0$, then $\xi_i^* = 0$, which implies no loss, so $y_i f^*(x) \ge 1$.
- If $\alpha_i^* \in (0, \frac{c}{n})$, then $\xi_i^* = 0$, which implies $1 y_i f^*(x_i) = 0$.

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Complementary Slackness Results: Summary

If α^* is a solution to the dual problem, then primal solution is

$$w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$$
 where $\alpha_i^* \in [0, \frac{c}{n}]$.

Relation between margin and example weights (α_i 's):

$$lpha_i^* = 0 \implies y_i f^*(x_i) \ge 1$$
 $lpha_i^* \in \left(0, \frac{c}{n}\right) \implies y_i f^*(x_i) = 1$
 $lpha_i^* = \frac{c}{n} \implies y_i f^*(x_i) \le 1$
 $y_i f^*(x_i) < 1 \implies lpha_i^* = \frac{c}{n}$
 $y_i f^*(x_i) > 1 \implies lpha_i^* \in \left[0, \frac{c}{n}\right]$
 $y_i f^*(x_i) > 1 \implies lpha_i^* = 0$

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Support Vectors

• If α^* is a solution to the dual problem, then primal solution is

$$w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$$

with $\alpha_i^* \in [0, \frac{c}{n}]$.

- The x_i 's corresponding to $\alpha_i^* > 0$ are called **support vectors**.
- Few margin errors or "on the margin" examples \implies sparsity in input examples.

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The Bias Term: b

• For our SVM primal, the complementary slackness conditions are:

$$\alpha_i^* \left(1 - y_i \left[x_i^T w^* + b \right] - \xi_i^* \right) = 0$$
 (1)

$$\lambda_i^* \xi_i^* = \left(\frac{c}{n} - \alpha_i^*\right) \xi_i^* = 0 \tag{2}$$

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- Suppose there's an i such that $\alpha_i^* \in (0, \frac{c}{n})$.
- (2) implies $\xi_i^* = 0$.
- (1) implies

$$y_{i} \left[x_{i}^{T} w^{*} + b^{*} \right] = 1$$

$$\iff x_{i}^{T} w^{*} + b^{*} = y_{i} \text{ (use } y_{i} \in \{-1, 1\})$$

$$\iff b^{*} = y_{i} - x_{i}^{T} w^{*}$$

The Bias Term: b

• We get the same b^* for any choice of i with $\alpha_i^* \in (0, \frac{c}{n})$

$$b^* = y_i - x_i^T w^*$$

• With numerical error, more robust to average over all eligible i's:

$$b^* = \operatorname{mean}\left\{y_i - x_i^T w^* \mid \alpha_i^* \in \left(0, \frac{c}{n}\right)\right\}.$$

- If there are no $\alpha_i^* \in (0, \frac{c}{n})$?
 - Then we have a degenerate SVM training problem¹ ($w^* = 0$).

¹See Rifkin et al.'s "A Note on Support Vector Machine Degeneracy", an MIT AI Lab Technical Report.

Teaser for Kernelization

Dual Problem: Dependence on x through inner products

SVM Dual Problem:

$$\sup_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{j}^{T} x_{i}$$
s.t.
$$\sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

$$\alpha_{i} \in \left[0, \frac{c}{n}\right] \ i = 1, \dots, n.$$

- Note that all dependence on inputs x_i and x_j is through their inner product: $\langle x_j, x_i \rangle = x_j^T x_i$.
- We can replace $x_i^T x_i$ by other products...
- This is a "kernelized" objective function.

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