# COMS 4721: Machine Learning for Data Science Lecture 13, 3/2/2017

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## **BOOSTING**

General method for taking any binery classifier and improving it.

#### **BAGGING CLASSIFIERS**

### Algorithm: Bagging binary classifiers

Given 
$$(x_1, y_1), \ldots, (x_n, y_n), x \in \mathcal{X}, y \in \{-1, +1\}$$

For  $b = 1, \ldots, B$ 

Sample a bootstrap dataset  $\mathcal{B}_b$  of size  $n$ . For each entry in  $\mathcal{B}_b$ , select  $(x_i, y_i)$  with probability  $\frac{1}{n}$ . Some  $(x_i, y_i)$  will repeat and some won't appear in  $\mathcal{B}_b$ .

Learn a classifier  $f_b$  using data in  $\mathcal{B}_b$ .

Define the classification rule to be

(So we nowhave 13 classifiers where each one is beautiful bootstrapping dataset.)

 $f_{bag}(x_0) = \text{sign}\left(\sum_{b=1}^{B} f_b(x_0)\right)$ 

Prevaluate  $x_b$  on each classifier  $x_b$  bootstrapping dataset.)

Attensionly take a majority state.

- ▶ With bagging, we observe that a *committee* of classifiers votes on a label.
- ► Each classifier is learned on a *bootstrap sample* from the data set.
- ▶ Learning a collection of classifiers is referred to as an *ensemble method*.

BOOSTING (development of this i'dea, motivations now can we take a medio cre classifier, and boost them so the sung these classifiers gives a

How is it that a committee of blockheads can somehow arrive at highly reasoned decisions, despite the weak judgment of the individual members?

- Schapire & Freund, "Boosting: Foundations and Algorithms"

**Boosting** is another powerful method for ensemble learning. It is similar to bagging in that a set of classifiers are combined to make a better one.

It works for any classifier, but a "weak" one that is easy to learn is usually chosen. (weak = accuracy a little better than random guessing)

#### Short history

1984: Leslie Valiant and Michael Kearns ask if "boosting" is possible.

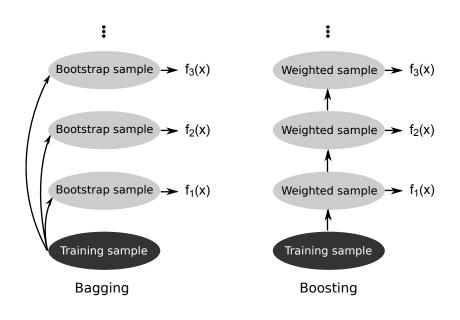
1989: Robert Schapire creates first boosting algorithm.

1990: Yoav Freund creates an optimal boosting algorithm.

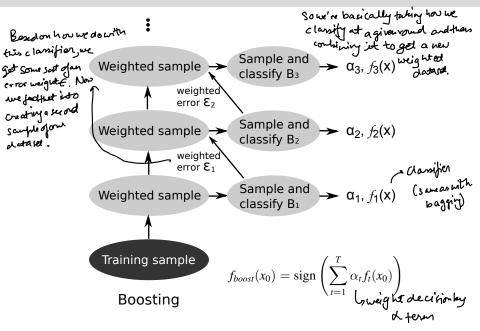
1995: Freund and Schapire create AdaBoost (Adaptive Boosting), the major boosting algorithm.

different in a ve So what boostir a weighted sam And then given So it's not pullir	e very high level is almost the same but ery crucial way. Ing does is at first creates aple of our data set to learn a classifier. This weighted sample it generates a new weighted sample. Ing from the original training sample. The weighted sample of the previous round of classification.		
To generate a new data set for which we get a new classifier.			
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## BAGGING VS BOOSTING (OVERVIEW)



## THE ADABOOST ALGORITHM (SAMPLING VERSION)



## THE ADABOOST ALGORITHM (SAMPLING VERSION)

## Algorithm: Boosting a binary classifier

data prosire.

Given 
$$(x_1, y_1), \dots, (x_n, y_n), x \in \mathcal{X}, y \in \{-1, +1\}, \text{ set } w_1(i) = \frac{1}{n} \text{ for } i = 1:n$$

▶ For t = 1, ..., T

1. Sample a bootstrap dataset  $\mathcal{B}_t$  of size *n* according to distribution  $w_t$ . Notice we pick  $(x_i, y_i)$  with probability  $w_t(i)$  and not  $\frac{1}{n}$ .

Learn a classifier  $f_t$  using data in  $\mathcal{B}_t$ .

Calculation of the second of the control of the co

$$f_{boost}(x_0) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t f_t(x_0)\right).$$

**Comment:** Description usually simplified to "learn classifier  $f_t$  using distribution  $w_t$ ."

」:
So on the first iteration we sample a bootstrap data set of size n using a uniform distribution on our data. (こんとの しんりょうしょう)
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However, at iteration t this distribution on the data might be different.

And so whatever the distribution on our data set is at iteration t, we sample n times from that to construct a bootstrap sample bt.

Then we learn a classifier at iteration t using the data in bt.

# Difference frembagging:

So this is exactly the same thing as was done in bagging.

The only difference is that the way that we constructed this data set was different because it's not necessarily with a uniform distribution. So that's the key difference.

Another key difference is that after we construct this classifier, before we can go to the next iteration.

We need to first decide,
how do we update this weight probability distribution on our data?

\*\* We then calculate the probability of error
at iteration t according to the distribution on the data at iteration t.
So what that's saying is that the error at iteration t is going to be equal.
To the sum of all of the probability weights
on the data that are misclassified.
According to the classifier that we learned only at iteration t.

And also we have to get these alphas that I've discussed previously that are used in the classification.

we then evaluate that classifier at all n data points in our original data set And if our classifier gets it wrong then we include that probability of that observation and sum up those misclassified weights.

We re aming the weights only on the misclassified data according to

So, we learned ft from the data in bt,

bu danifier that we dearnt at iteration t.

So we do this many times, capital T times, where T is arbitrary but large.

And then we get out of this T pairs, capital T pairs of classifier and its associated weight alpha.

And then for a new data point, the boosted classifier is equal to the sign of each individual classifier's prediction.

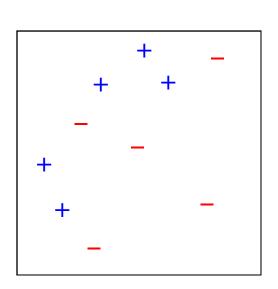
Weighted by a pha for that particular classifier.

So we sum that up.

Weighted by alpha for that particular classifier.

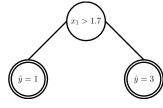
So we sum that up.

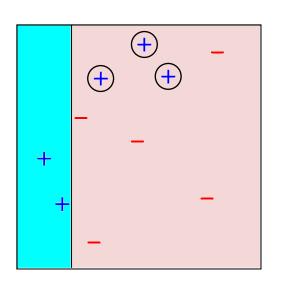
And then again it's like a majority vote except it's a majority weighted vote in this case. And then we take the sign, that's our final classification.



Take weak it was it was

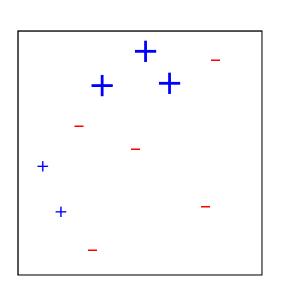
Here: Use a decision stump





#### Round 1 classifier

Weighted error:  $\epsilon_1 = 0.3$ Weight update:  $\alpha_1 = 0.42$ 



Now we weight soft Weighted data ighted uses

ter round 1

detaposite

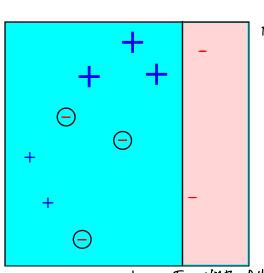
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Step 3: we take weight on 3 moints from the previous round.

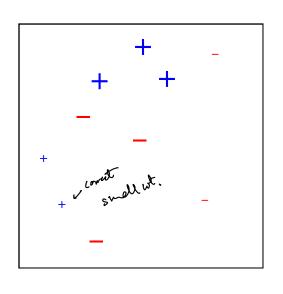
The up deted wights and sum them

Round 2 classifier

Weighted error:  $\epsilon_2 = 0.21$ Weight update:  $\alpha_2 = 0.65$ 

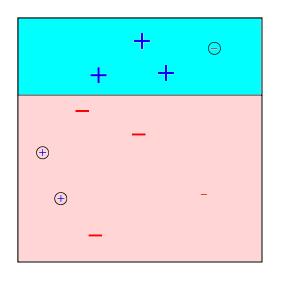
In the next bootstrop round, we have more of these miss classified points.

And update weights. All cornects downweight



Weighted data

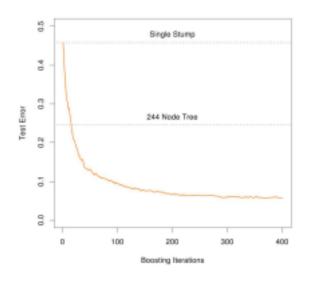
After round 2



#### Round 2 classifier

Weighted error:  $\epsilon_3 = 0.14$ Weight update:  $\alpha_3 = 0.92$ 





#### Example problem

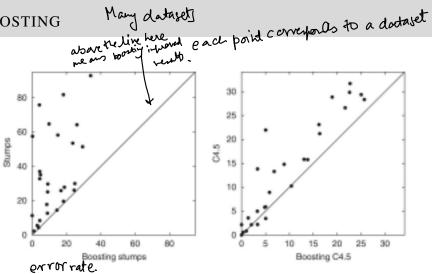
Random guessing 50% error

**Decision stump** 45.8% error

Full decision tree 24.7% error

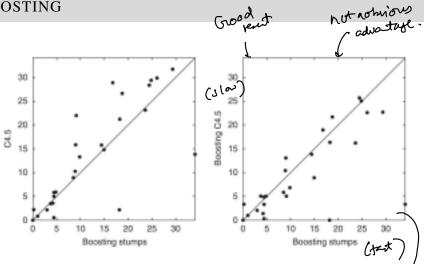
Boosted stump 5.8% error

**BOOSTING** 



Point = one dataset. Location = error rate w/ and w/o boosting. The boosted version of the same classifier almost always produces better results.

BOOSTING



(left) Boosting a bad classifier is often better than not boosting a good one. (right) Boosting a good classifier is often better, but can take more time.

Overell not clear that boosting a devision struppes in general wase then boosting a very good devision tree.

#### **BOOSTING AND FEATURE MAPS**

**Q**: What makes boosting work so well?

A: This is a well-studied question. We will present one analysis later, but we can also give intuition by tying it in with what we've already learned.

The classification for a new 
$$x_0$$
 from boosting is 
$$+ \text{lor-1}$$
 decision 
$$\begin{cases} \text{decision of } \\ \text{each } \end{cases} \text{ decision of } \\ \text{each } \end{cases} \text{ decision of } \\ \text{lor of } \\ \text{decision of } \\ \text{lor of } \end{cases}$$
 Define  $\phi(x) = [f_1(x), \dots, f_T(x)]^{\top}$ , where each  $f_t(x) \in \{-1, +1\}$ .

- We can think of  $\phi(x)$  as a high dimensional feature map of x.
- ▶ The vector  $\boldsymbol{\alpha} = [\alpha_1, \dots, \alpha_T]^{\top}$  corresponds to a hyperplane.
- So the classifier can be written  $f_{boost}(x_0) = \text{sign}(\phi(x_0)^\top \alpha)$ .
- Boosting learns the feature mapping and hyperplane simultaneously. Boosting is trying to learn in anonitine way (adaptive a ordine method) learna high diversional feature mapping along with the decision. The linear decision bondary defined by a such that I we can clearly all of the data in our training set.

Something prove: That's going to learn a linear danifier that perfectly classifies on training set.

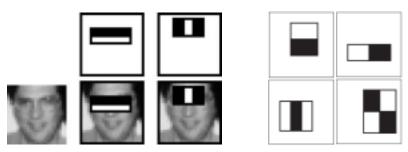
**APPLICATION: FACE DETECTION** 

FACE DETECTION (VIOLA & JONES, 2001) Clarifier that does ok and then bross it softest we get

Problem: Locate the faces in an image or video. excellent performance.

**Processing**: Divide image into patches of different scales, e.g.,  $24 \times 24$ ,  $48 \times 48$ , etc. Extract *features* from each patch.

**Classify** each patch as face or no face using a *boosted decision stump*. This can be done in real-time, for example by your digital camera (at 15 fps).



- One patch from a larger image. Mask it with many "feature extractors."
- ► Each pattern gives one number, which is the sum of all pixels in black region minus sum of pixels in white region (total of 45,000+ features).

## FACE DETECTION (EXAMPLE RESULTS)













ANALYSIS OF BOOSTING

#### ANALYSIS OF BOOSTING

#### Training error theorem

We can use *analysis* to make a statement about the accuracy of boosting on the training data.

**Theorem**: Under the AdaBoost framework, if  $\epsilon_t$  is the weighted error of

classifier 
$$f_t$$
, then for the classifier  $f_{boost}(x_0) = \operatorname{sign}(\sum_{t=1}^T \alpha_t f_t(x_0))$ , where  $f_t$  is the weighted through the classifier  $f_{boost}(x_0) = \operatorname{sign}(\sum_{t=1}^T \alpha_t f_t(x_0))$ , where  $f_t$  is the weighted through the classifier  $f_{boost}(x_0) = \operatorname{sign}(\sum_{t=1}^T \alpha_t f_t(x_0))$ , where  $f_t$  is the weighted through the control of the classifier  $f_t$  is the weighted through the control of the classifier  $f_t$  is the weighted through the classifier  $f_t$  in the classifier  $f_t$  is the weighted through the classifier  $f_t$  in the classifier  $f_t$  and  $f_t$  is the weighted through the classifier  $f_t$  is the weight  $f_t$  and  $f_t$  is the wei

Even if each  $\epsilon_t$  is only a little better than random guessing, the sum over T classifiers can lead to a large negative value in the exponent when T is large.

For example, if we set:

$$\epsilon_t=0.45,\ T=1000 
ightarrow {
m training error} \leq 0.0067.$$
 So this theorem shows that a bunch of these weak densities that don't do very well on their own when combined spushes the training error down to a a the not of classifiers we seem own when combined spushes the training error down to a a the not of classifiers we seem

#### PROOF OF THEOREM

#### Setup

We break the proof into three steps. It is an application of the fact that

if 
$$\underbrace{a < b}_{\text{Step 2}}$$
 and  $\underbrace{b < c}_{\text{Step 3}}$  then  $\underbrace{a < c}_{\text{conclusion}}$ 

- ▶ Step 1 calculates the value of *b*.
- ▶ Steps 2 and 3 prove the two inequalities.

Also recall the following step from AdaBoost:

- ▶ Update  $\hat{w}_{t+1}(i) = w_t(i)e^{-\alpha_t y_i f_t(x_i)}$ .
- ► Normalize  $w_{t+1}(i) = \frac{\hat{w}_{t+1}(i)}{\sum_{j} \hat{w}_{t+1}(j)}$   $\longrightarrow$  Define  $Z_t = \sum_{j} \hat{w}_{t+1}(j)$ .

## PROOF OF THEOREM $(a \le b \le c)$

#### Step 1

We first want to expand the equation of the weights to show that

$$w_{T+1}(i) = \frac{1}{n} \frac{e^{-y_i \sum_{t=1}^{T} \alpha_t f_t(x_i)}}{\prod_{t=1}^{T} Z_t} = \frac{1}{n} \frac{e^{-y_i f_{boost}^{(T)}(x_i)}}{\prod_{t=1}^{T} Z_t} \quad (f_{boost}^{(T)} \text{ is up to step } T)$$

#### **Derivation of Step 1**:

Notice the update rule:  $w_{t+1}(i) = \frac{1}{Z_t} w_t(i) e^{-\alpha_t y_i f_t(x_i)}$ 

Do the same expansion for  $w_t(i)$  and continue until reaching  $w_1(i) = \frac{1}{n}$ ,

$$w_{T+1}(i) = w_1(i) \frac{e^{-\alpha_1 y_i f_1(x_i)}}{Z_1} \times \cdots \times \frac{e^{-\alpha_T y_i f_T(x_i)}}{Z_T}$$

**The product**  $\prod_{t=1}^{T} Z_t$  is "b" above. We use this form of  $w_{T+1}(i)$  in Step 2.

#### Step 2

Next show that the training error of  $f_{boost}^{(T)}$  after T steps is  $\leq \prod_{t=1}^{T} Z_t$ .

From Step 1: 
$$w_{T+1}(i) = \frac{1}{n} \frac{e^{-y_i f_{boost}^{(T)}(x_i)}}{\prod_{t=1}^{T} Z_t} \implies w_{T+1}(i) \prod_{t=1}^{T} Z_t = \frac{1}{n} e^{-y_i f_{boost}^{(T)}(x_i)}$$

#### **Derivation of Step 2**:

(Observe that  $0 < e^{z_1}$  and  $1 < e^{z_2}$  for any  $z_1 < 0 < z_2$ .)

$$\frac{1}{n} \sum_{i=1}^{n} \mathbb{1} \{ y_i \neq f_{boost}^{(T)}(x_i) \} \leq \frac{1}{n} \sum_{i=1}^{n} e^{-y_i f_{boost}^{(T)}(x_i)}$$

$$= \sum_{i=1}^{n} w_{T+1}(i) \prod_{t=1}^{T} Z_t$$

$$= \prod_{t=1}^{T} Z_t$$

"a" is the training error - the quantity we care about.

#### Step 3

The final step is to calculate an upper bound on  $Z_t$ , and by extension  $\prod_{t=1}^T Z_t$ .

#### **Derivation of Step 3**:

This step is slightly more involved. It also shows why  $\alpha_t := \frac{1}{2} \ln \left( \frac{1 - \epsilon_t}{\epsilon_t} \right)$ .

$$Z_t = \sum_{i=1}^n w_t(i)e^{-\alpha_t y_i f_t(x_i)}$$

$$= \sum_{i: y_i = f_t(x_i)} e^{-\alpha_t} w_t(i) + \sum_{i: y_i \neq f_t(x_i)} e^{\alpha_t} w_t(i)$$

$$= e^{-\alpha_t} (1 - \epsilon_t) + e^{\alpha_t} \epsilon_t$$

Remember we <u>defined</u>  $\epsilon_t = \sum_{i: y_i \neq f_t(x_i)} w_t(i)$ , the probability of error for  $w_t$ .

#### **Derivation of Step 3** (continued):

Remember from Step 2 that

training error 
$$=\frac{1}{n}\sum_{i=1}^{n}\mathbb{1}\{y_i\neq f_{boost}(x_i)\} \leq \prod_{t=1}^{T}Z_t$$
.

and we just showed that  $Z_t = e^{-\alpha_t}(1 - \epsilon_t) + e^{\alpha_t}\epsilon_t$ .

We want the training error to be small, so we pick  $\alpha_t$  to *minimize*  $Z_t$ . Minimizing, we get the value of  $\alpha_t$  used by AdaBoost:

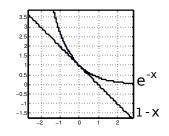
$$\alpha_t = \frac{1}{2} \ln \left( \frac{1 - \epsilon_t}{\epsilon_t} \right).$$

Plugging this value back in gives  $Z_t = 2\sqrt{\epsilon_t(1-\epsilon_t)}$ .

#### **Derivation of Step 3** (continued):

Next, re-write  $Z_t$  as

$$Z_t = 2\sqrt{\epsilon_t(1-\epsilon_t)}$$
$$= \sqrt{1-4(\frac{1}{2}-\epsilon_t)^2}$$



Then, use the inequality  $1 - x \le e^{-x}$  to conclude that

$$Z_t = \left(1 - 4(\frac{1}{2} - \epsilon_t)^2\right)^{\frac{1}{2}} \le \left(e^{-4(\frac{1}{2} - \epsilon_t)^2}\right)^{\frac{1}{2}} = e^{-2(\frac{1}{2} - \epsilon_t)^2}.$$

#### PROOF OF THEOREM

### Concluding the right inequality $(a \le b \le c)$

Because both sides of  $Z_t \le e^{-2(\frac{1}{2} - \epsilon_t)^2}$  are positive, we can say that

$$\prod_{t=1}^{T} Z_t \leq \prod_{t=1}^{T} e^{-2(\frac{1}{2} - \epsilon_t)^2} = e^{-2\sum_{t=1}^{T} (\frac{1}{2} - \epsilon_t)^2}.$$

This concludes the " $b \le c$ " portion of the proof.

#### Combining everything

training error 
$$=$$
  $\underbrace{\frac{1}{n}\sum_{i=1}^{n}\mathbb{1}\{y_i\neq f_{boost}(x_i)\}}_{d} \leq \underbrace{\prod_{t=1}^{b}Z_t}_{d} \leq \underbrace{e^{-2\sum_{t=1}^{T}(\frac{1}{2}-\epsilon_t)^2}}_{c}.$ 

We set out to prove "a < c" and we did so by using "b" as a stepping-stone.

#### TRAINING VS TESTING ERROR

**Q**: Driving the training error to zero leads one to ask, does boosting overfit?

**A**: Sometimes, but very often it doesn't!

