

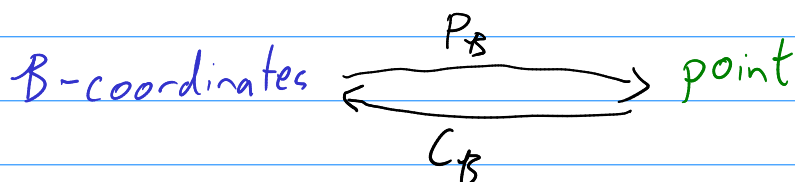
Linear transformations in terms of coordinates.

Let $B = \{X_1, \dots, X_n\}$ be an ordered basis for \mathbb{R}^n .

If $Y = a_1 X_1 + \dots + a_n X_n$, then we say Y has coordinates $[a_1, \dots, a_n]^T$ with respect to B .

We have the point matrix $P_B = \begin{bmatrix} | & & | \\ X_1 & \dots & X_n \\ | & & | \end{bmatrix}$

and the coordinate matrix $C_B = P_B^{-1}$.



ex. Say $B = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \right\}$.

$$\text{Then } P_B = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}.$$

So, the point with B -coordinates $\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$ is

$$\begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 + 1 - 2 \\ 1 - 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$$

Another example: $\begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ = the 2nd basis vector of B .

$$C_B = P_B^{-1} = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}^{-1}$$

$$\left[\begin{array}{ccc|ccc} 1 & 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{-R_2+R_1 \\ -R_3+R_1}} \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & -1 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{-R_3+R_2 \\ -R_1+R_3}} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -1 & -1 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right]$$

$$\text{So } C_B = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

So the coordinates of $\begin{bmatrix} 0 \\ 2 \\ 3 \end{bmatrix}$ in terms of B are:

$$\begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 & -2 & -3 \\ 2 & -3 \\ 3 \end{bmatrix} = \begin{bmatrix} -5 \\ -1 \\ 3 \end{bmatrix}$$

Say we have a linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$.
Write M_T for the matrix of T (with respect to the standard basis)

Say B is an ordered basis for \mathbb{R}^n .

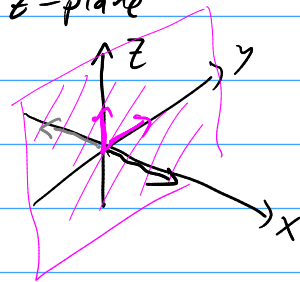
There's a matrix $M_{T,B}$ such that, if $Q = [a_1, \dots, a_n]^T$ is the B -coordinates of a point $P \in \mathbb{R}^n$, then $M_{T,B} Q$ is the B -coordinates of the point $T(P)$.

How do we find the matrix $M_{T,B}$?

$$\begin{array}{ccccccc} Q & \longrightarrow & P = P_B Q & \longrightarrow & M_T P_B Q & \longrightarrow & C_B M_T P_B Q \\ \text{(B-coords)} & & \text{(point in } \mathbb{R}^n) & & \text{(point in } \mathbb{R}^n) & & \text{(B-coords)} \end{array}$$

$$\text{So: } M_{T,B} = C_B M_T P_B = P_B^{-1} M_T P_B.$$

ex. In standard coords, reflection across the yz -plane has the matrix $M_T = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$



How about in the basis $B = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \right\}$?

The formula: $M_{T,B} = C_B M_T P_B$

$$= \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & -1 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & -2 & -4 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

So, for example, if we take the point with B -coordinates $[1, 1, 1]^T$, its reflection across the yz -plane has B -coords

$$M_{T,B} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -7 \\ 1 \\ 1 \end{bmatrix}$$