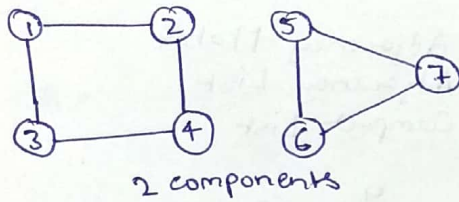


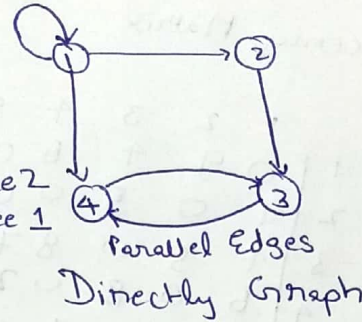
Graphs

Non-Connected

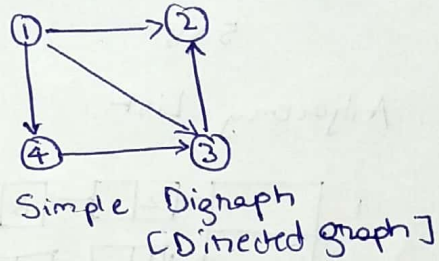
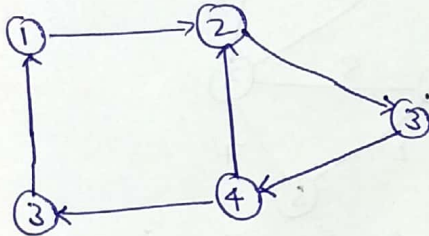


Self Loop

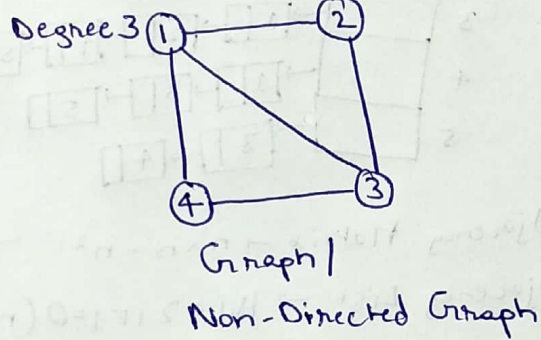
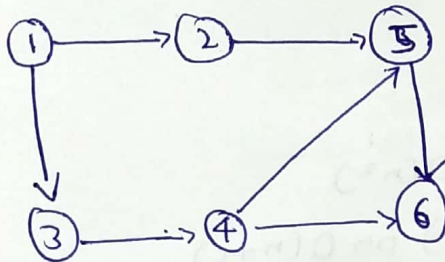
Indegree 2
outdegree 1



Strongly-Connected



Directed Acyclic Graph
(DAG)

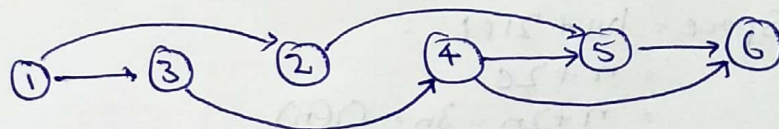


Articulation Point \rightarrow Removing that vertex from the graph, the graph will become non-connected graph.

Strongly Connected Graph \rightarrow If you can reach any vertex from any other vertex.
A path exists b/w any two pair of vertices

Path \rightarrow Set of all the vertices in between a pair of vertex.

Cyclic Path \rightarrow Starts from one vertex and ends at the same vertex.
on "Cycle"



Topological ordering
DAG can be arranged linearly such that
edges going in forward direction

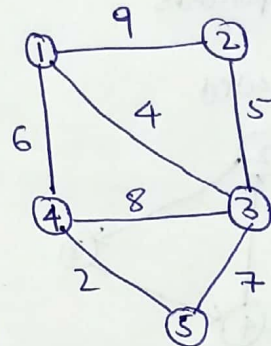
Representation of Undirected Graph

Adjacency Matrix

$$A = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{bmatrix} 0 & 9 & 4 & 6 & 0 \\ 9 & 0 & 5 & 0 & 0 \\ 4 & 5 & 0 & 8 & 7 \\ 6 & 0 & 8 & 0 & 2 \\ 0 & 0 & 7 & 2 & 0 \end{bmatrix} \end{matrix}$$

5x5

1. Adjacency Matrix
2. Adjacency List
3. Compact List

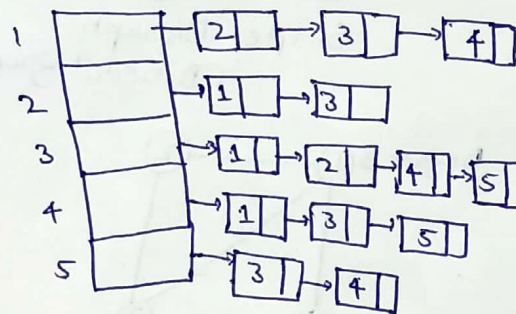


$$G = (V, E)$$

$$|V| = n = 5$$

$$|E| = e = 7$$

Adjacency List



Adjacency Matrix $\rightarrow n \times n = n^2$ TC = $O(n^2)$

Adjacency List $\rightarrow |V| + 2|E| = O(n + 2e)$ or $O(n + e)$

→ Similarly in Adjacency List, we should store weight in each node as well.

Compact List Representation

→ Single dimension Array

$$\text{Size of Array} = |V| + 2|E| + 1$$

	7	10	12	16	19	21	2	3	4	1	3	1	2	3	4	1	3	5	3	4
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
	Vertices						1			2		3			4		5			

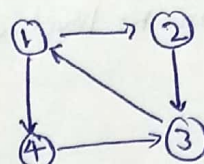
$$\begin{aligned} \text{Space} &= |V| + 2|E| \\ &= n + 2e \\ &= n + 2n = 3n = O(n) \end{aligned}$$

Representation of Directed Graphs

$$A = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

4x4

Adjacency Matrix

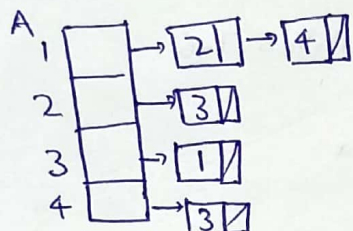


$G(V, E)$

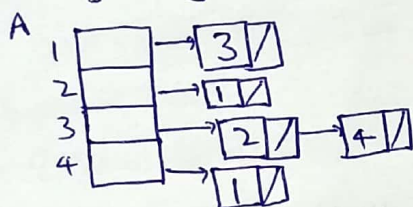
$|V| = 4 \quad |E| = 5$

Indegree \rightarrow Check Column

Outdegree \rightarrow Check Row



Adjacency List \rightarrow (Outdegree)



Inverse Adjacency List \rightarrow (Indegree)

Time taken $= O(n^2)$

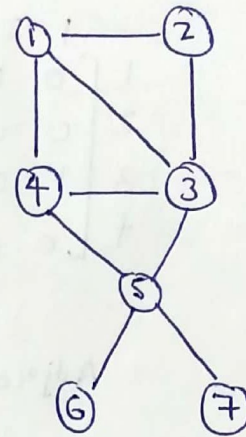
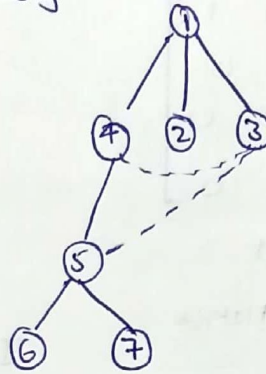
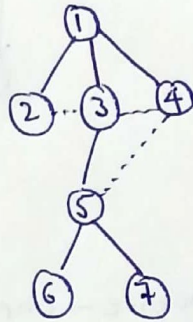
if Adjacency Matrix used

if Adjacency List used,

Time taken $= O(n)$

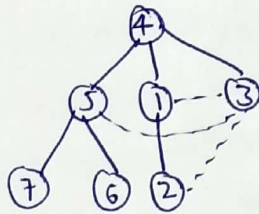
Breadth First Search (BFS)

→ Similar to level order of Binary Tree



BFS: 1, 2, 3, 4, 5, 6, 7 BFS: 1, 4, 2, 3, 5, 7, 6

→ For 1 graph, multiple BFS possible.
→ We can start in any order, with any vertex



BFS: 4, 5, 1, 3, 7, 6, 2

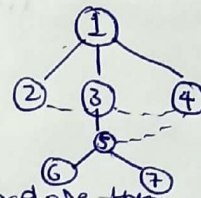
BFS: Start from any vertex you like.

→ When you visit a vertex, explore all its adjacent vertices
→ While exploring, you can visit adjacent vertex in any order

1) Visiting

BFS: 1, 2, 3, 4, 5, 6, 7

Queue: 1, 2, 3, 4, 5, 6, 7



→ select vertices from queue, one by one and explore them
→ Once you visit a vertex, add it to the queue.

BFS Spanning Tree.

Dotted edges → Cross Edges

Time = $O(n)$

eg. 1) 2, 3, 1, 5, 4, 7, 6
2) 5, 7, 3, 6, 4, 2, 1
3) 1, 4, 3, 2, 5, 7, 6

all correct

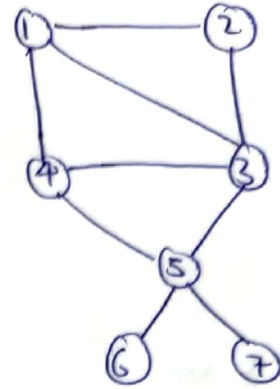
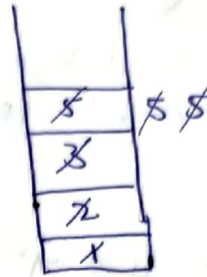
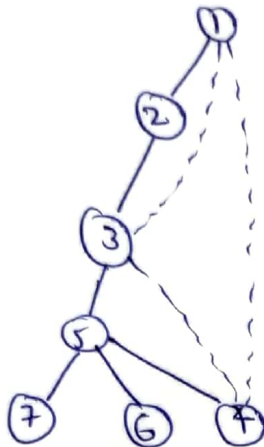
For program: Mainkin

- i) Queue → Enqueue & Dequeue → Insert & Delete
- ii) Adjacency Matrix
- iii) Visited Array [Flag for visited vertex]

Depth First Search (DFS)

→ Similar to pre-order traversal

1. Visited 2. Exploring



Uses a Stack

→ When you get a new vertex, suspend previous vertex

→ Explore the new vertex.

→ You can start from any vertex.

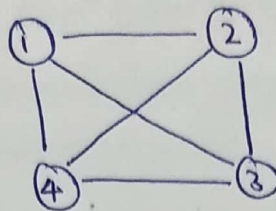
→ DFS Spanning Tree

Back Edge → Connecting to previous level Node

Time = $O(V)$ [Analytical Time]

eg. 1) 1, 3, 5, 4, 7, 6, 2
2) 1, 2, 3, 4, 5, 6, 7
3) 1, 4, 5, 7, 3, 2, 6] all correct

Spanning Tree



$$G = (V, E)$$

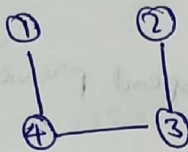
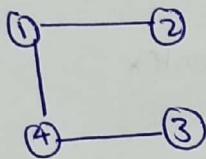
$$|V| = n \quad |E| = e$$

1. Spanning Tree
2. Prim's MST
3. Kruskal's MST

$$S \subseteq G$$

We can find S only if graph is connected.

$$S = (V', E') \quad |V'| = |V| \quad |E'| = |V| - 1$$



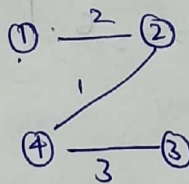
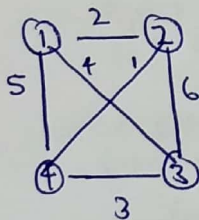
→ More than one spanning Tree for same graph.

→ S Conditions: i - Connected ii - No Cycle

$$|E| \begin{cases} |V| - 1 \\ 6 \\ 3 \end{cases} \rightarrow \begin{cases} \text{Total possible} \\ \text{the reject with Cycles} \end{cases}$$

$$6C_3 - 4 = 20 - 4 = 16 \text{ Spanning Trees}$$

Minimum Cost Spanning Tree



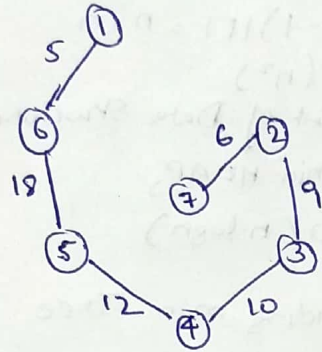
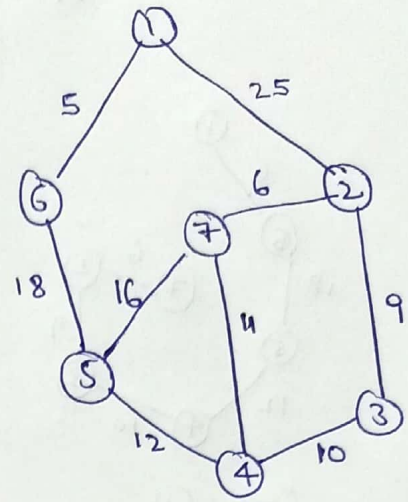
Try all, select best with minimum cost.

Prim's Algorithm

→ Select minimum cost edge from graph.

Now, select next minimum cost edge but it should be connected to the previous edge.

Repeat.



$$\text{Total Cost} = 5 + 18 + 12 + 10 + 9 + 6 = 60$$

$$\text{Time} = (|V| - 1)|E|$$

$$= n \times n \times n \approx O(n^2)$$

$$\text{If we use heap we can reduce time: } (|V| - 1) \log |E|$$

$$= O(n \log n)$$

For writing program:

i) Identify the type of Data Structure required.

Graph represented by Adjacency Matrix.

ii) Take 2-D array to store the Spanning Tree.

iii) 'near' Array → (size = $(|V| + 1)$) Used to check adjacent.

Check either lower Triangular / Upper Triangular & find min. weight.
Write down in the 2-D array.

→ In 'near' array write down which vertex is close to which of the adjacent vertex previously selected in Spanning Tree.

→ Now, Repeating steps:

From 'near' find out minimum.

Write that edge in Spanning Tree Result Array.

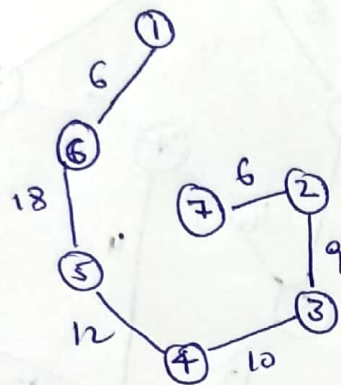
Update 'near' array.

Mark the included vertex as '0'.

Repeat.

Kruskal's Algorithm

Spanning Tree



Cost = 60

- 1) Always select the min. weight from the graph
- 2) Make sure that vertex is not forming a cycle.

$$\text{Time} = (|V| - 1)|E| = n \times n \\ = O(n^2)$$

(independent of Data Structure)

If we use min HEAP,
 $O(n \log n)$

In Kruskal's → more focus on finding min. Tree

Prim's → more focus on finding Tree

Kruskal's Algorithm - If 2 non-connected graphs,

Finds spanning tree for each graph individually.

Prim's Algorithm - Find spanning tree for only one of the individual graphs.

Steps:

- 1) Find out min. cost edge
 - 2) Find out if it is forming a cycle or not
 - 3) Perform weighted union upon them.
- Repeat

→ If diff. parents we can join new vertices, as it implies it's not forming a cycle.

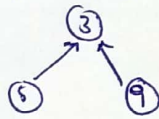
Disjoint Sets

$$U = \{1, 2, 3, 4, 5, 6, 7, 8, 9, 10\}$$

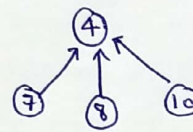
S

-1	-1	-1	-1	-1	-1	-1	-1	-1	-1	-1
0	1	2	3	4	5	6	7	8	9	10

$$A = \{3, 5, 9\}$$



$$B = \{4, 7, 8, 10\}$$



$$A \cap B = \emptyset$$

-1	-1	-1	-3	-4	3	-1	4	4	3	4
0	1	2	3	4	5	6	7	8	9	10

Disjoint sets \rightarrow If we take intersection, no common elements

-ve no. shows it's a set.

So in A, 5 and 9 are children of 3.

At 3, we write -ve \rightarrow to show it's a Head.

'magnitude' shows the total no. of nodes.

1) Union or Weighted Union

$$\text{Perform } A \cup B = \{3, 4, 5, 7, 8, 9, 10\}$$

\rightarrow Whichever has more elements

Select that one as parent.

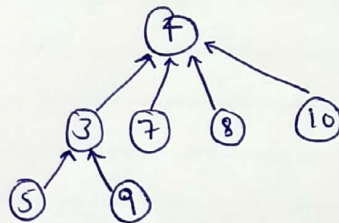
So, in this case $\rightarrow 4$

2) Find or Collapsing Find

\rightarrow To find the parent

\rightarrow Check for negative numbers in the array.

\rightarrow We just have to follow hierarchy and reach the root.



S

	-1	-1	4	-7	3	-1	4	4	3	4
0	1	2	3	4	5	6	7	8	9	10

If 2 vertices from different set connect then.

If " " " " same set don't connect then else they will form a cycle.

Kruskal's Program:

1) Take Array of Edges (No. of Columns = No. of Edges)

Now Rows, 2 \rightarrow vertices, 1 \rightarrow weight, Total = 3 Rows

2) Set List \rightarrow For detecting a cycle, Size = No. of Vertices + 1

3) Included List \rightarrow To flag if edge is included or not

4) Final Solution 2-D Array \rightarrow Data structure