

SC 639 (Autumn 2020) - Mathematical Structures for Control

Ravi N. Banavar ¹
Harsh Oza ¹

¹Systems and Control Engineering,
IIT Bombay, India

June 28, 2021

Isomorphism
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Rank and Nullity
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Inner Product and Norm
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Approximation
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Outline

① Isomorphism

② Rank and Nullity

③ Inner Product and Norm

④ Approximation

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Isomorphism

Isomorphism

A bijective linear transformation between two finite dimensional subspaces is called an **isomorphism**.

- Let $A : V \rightarrow W$ be a linear mapping between two subspaces.
- Subspaces V and W are called isomorphic to each other if the A is surjective and injective.
- If A is an isomorphism, then $\dim(V) = \dim(W)$.

Isomorphism
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Rank and Nullity
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Inner Product and Norm
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Approximation
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① Isomorphism

② Rank and Nullity

③ Inner Product and Norm

④ Approximation

Range space and Null space

Range Space

Let $A : V \rightarrow W$ be a linear transformation. The **range space** ($\mathbf{R(A)}$) is given by following.

$$R(A) = \{w \in W | w = Av, \forall v \in V\} \quad (1)$$

Null space

Let $A : V \rightarrow W$ be a linear transformation. The **null space** ($\mathbf{N(A)}$) is given by following.

$$N(A) = \{v \in V | Av = 0, \forall v \in V\} \quad (2)$$

- $R(A)$ is a subspace of W .
- $N(A)$ is a subspace of V .
- A is one-one if $N(A) = \{0\}$

Rank and Nullity

- The dimension of Range space of A is called **Rank of A** ($\rho(A)$).
- The dimension of Null space of A is called **Nullity of A** ($\nu(A)$).

Rank-Nullity Theorem

Let $A : V \rightarrow W$ be linear with $\dim(V) = k$. Then,

$$\rho(A) + \nu(A) = k \quad (3)$$

Proof

- Let $\nu(A) = m$ and basis for null space of A be $\{u_1, u_2, \dots, u_m\}$.
- Extend the set as $\{u_1, u_2, \dots, u_n, w_1, w_2, \dots, w_n\}$ to be a basis of the vector space V . Thus $\dim(V) = m + n$
- We need to prove that $R(A)$ is finite and $\dim(R(A)) = n$
- Let $v \in V$

$$v = a_1u_1 + a_2u_2 + \dots + a_nu_n + b_1w_1 + b_2w_2 + \dots + b_nw_n$$

applying transformation A on both sides,

$$Av = b_1Aw_1 + b_2Aw_2 + \dots + b_nAw_n$$

Here, Au_i disappears because $u_i \in N(A)$

- This implies $\{Aw_1, Aw_2, \dots, Aw_n\}$ spans the entire range of A .

Proof

- Now, we show $\{Aw_1, Aw_2, \dots, Aw_n\}$ is linearly independent.

$$c_1Aw_1 + c_2Aw_2 + \dots + c_nAw_n = 0$$

Then,

$$A(c_1w_1 + c_2w_2 + \dots + c_nw_n) = 0$$

hence, $(c_1w_1 + c_2w_2 + \dots + c_nw_n) \in N(A)$

$$(c_1w_1 + c_2w_2 + \dots + c_nw_n) = (d_1u_1 + d_2u_2 + \dots + d_nu_n)$$

- This implies all c and d are zero because $\{u_1, u_2, \dots, u_n, w_1, w_2, \dots, w_n\}$ is linearly independent.
- Thus, $\{Aw_1, Aw_2, \dots, Aw_n\}$ is linearly independent and spans the range of A .

Isomorphism
○○

Rank and Nullity
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Inner Product and Norm
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Approximation
○○○○○○○○○

Outline

① Isomorphism

② Rank and Nullity

③ Inner Product and Norm

④ Approximation

Norm

Norm

Given a vector space V over a field \mathcal{F} , a norm on V is a non-negative valued function $\|\cdot\| : V \rightarrow$ with following properties.

Let, $v, w \in V$ and if a is a scalar then,

- 1 $\|av\| = |a| \cdot \|v\|,$
- 2 $\|v\| \geq 0$, with equality if and only if $v = 0_V$,
- 3 $\|v + w\| \leq \|v\| + \|w\|,$

Examples of Norm

- ❶ Let $v \in \mathbb{R}^n$. The p-norm is given by,

$$\|v\|_p = \sqrt[p]{\sum_{i=1}^n |v_i|^p}$$

- ❷ Let $A \in \mathbb{R}^{m \times n}$. The Frobenius norm is given by, $\|A\| = \sqrt{\text{Tr}(A^T A)}$
- ❸ Let V be the vector space consisting of all continuous functions on $[a, b]$ and $f \in V$. Then, $\|f\|_1 = \int_a^b |f(x)| dx$
- ❹ The 2-norm of a signal $f(t)$ is $\|f\|_2 = \left(\int_{-\infty}^{\infty} f(t)^2 dt \right)^{1/2}$

Inner Product

Inner Product

An inner product in a vector space is a numerically valued function of ordered pair of vectors v and w , such that

- ❶ $\langle \alpha_1 v_1 + \alpha_2 v_2, w \rangle = \alpha_1 \langle v_1, w \rangle + \alpha_2 \langle v_2, w \rangle$
- ❷ $\langle v, w \rangle = \overline{\langle w, v \rangle}$;
- ❸ $\langle v, v \rangle \geq 0$; $\langle v, v \rangle = 0$ if and only if $v = 0$

Examples:

- ❶ Let $u, v \in V = \mathbb{R}^n$. Then, $\langle u, v \rangle = u^T v$ is an inner product.
- ❷ Let V be the vector space consisting of all continuous functions and $f, g \in V$. Then, $\langle f, g \rangle = \int_0^1 f(t)g(t) dt$ is an inner product.
- ❸ Let $u, v \in \mathbb{R}^2$. Then $\langle u, v \rangle = u_1 v_1 + 10 u_2 v_2$ is an inner product.

Norm induced by inner product

Norm (induced by inner product)

Let V be an inner product space. The norm of a vector $v \in V$ is defined to be a scalar $\|v\| = \sqrt{\langle v, v \rangle}$.

Let V be an inner product space. If $v, w \in V$ and if a is a scalar then, it satisfies following additional properties.

- 1 $\|v + w\|^2 + \|v - w\|^2 = 2(\|v\|^2 + \|w\|^2)$
- 2 $\|v - w\| \geq |||v| - |w|||$

Bessel's Inequality

Theorem

Let V be an inner product space and $u = \{u_1, u_2, \dots, u_n\}$ be an orthonormal set in V . Let $x \in V$ be arbitrary. Define $u \in V$ by $u = \sum_{k=1}^n \langle x, u_k \rangle u_k$. Then,

$$\|u\|^2 = \sum_{k=1}^n |\langle x, u_k \rangle|^2 \leq \|x\|^2 \quad (4)$$

Proof.

Let $g = \sum_{k=1}^n \langle x, u_k \rangle u_k$

$$\|g\|^2 = \langle g, g \rangle = \sum_{k=1}^n \langle x, u_k \rangle^2 \|u_k\|^2 = \sum_{k=1}^n \langle x, u_k \rangle^2 \quad (5)$$

For each $x \in V$ we have that,

$$\begin{aligned} 0 &\leq \|x - g\|^2 = \langle x - g, x - g \rangle \\ &= \|x\|^2 - 2\langle x, g \rangle + \|g\|^2 \\ &= \|x\|^2 - 2\langle x, \sum_{k=1}^n \langle x, u_k \rangle u_k \rangle + \|g\|^2 \\ &= \|x\|^2 - 2 \sum_{k=1}^n |\langle x, u_k \rangle|^2 + \|g\|^2 \\ &= \|x\|^2 - \|g\|^2 \end{aligned} \quad (6)$$

Therefore, $\|g\|^2 \leq \|x\|^2$, which implies that, $\|g\| \leq \|x\|$.

$$\sum_{k=1}^n |\langle x, u_k \rangle|^2 \leq \|x\|^2 \quad (7)$$

Cauchy-Schwarz Inequality

Recall: We may write a vector u as a scalar multiple of a nonzero vector v , plus a vector orthogonal to the vector v .

$$u = \frac{\langle u, v \rangle}{\|v\|^2} v + \left(u - \frac{\langle u, v \rangle}{\|v\|^2} v \right) \quad (8)$$

Theorem

Let V be an inner product space and $u, v \in V$. Then,

$$|\langle u, v \rangle| \leq \|u\| \|v\| \quad (9)$$

Proof.

Let $u, v \in V$. If $v = 0$, then both sides of (9) equal 0 and the desired inequality holds. Thus we assume that $v \neq 0$. Consider orthogonal decomposition,

$$u = \frac{\langle u, v \rangle}{\|v\|^2} v + w$$

By Pythagorean theorem,

$$\begin{aligned} \|u\|^2 &= \left\| \frac{\langle u, v \rangle}{\|v\|^2} v \right\|^2 + \|w\|^2 \\ &= \frac{|\langle u, v \rangle|^2}{\|v\|^2} + \|w\|^2 \\ &\geq \frac{|\langle u, v \rangle|^2}{\|v\|^2} \end{aligned}$$

Multiplying both sides of this inequality by $\|v\|^2$ and taking square root gives the Cauchy-Schwarz inequality. □

Adjoint Transformation

- Let V be any vector space and V' be its dual space. A is a linear transformation V .
- For each fixed $y \in V'$, the function y' defined by $y'(x) = [Ax, y]$ is a linear functional on V .
- The adjoint $A' : V' \rightarrow V$ is defined by the following property.

$$[Ax, y] = [x, A'y] \quad (10)$$

Adjoint Transformation (based on inner product)

Let V and W be inner product spaces and $A : V \rightarrow W$ be a linear transformation. A linear transformation $A' : W \rightarrow V$ satisfying the condition $\langle A(v), w \rangle = \langle v, A'(w) \rangle$ for all $V \in V$ and $W \in W$ is called an adjoint transformation of A .

Let V, W and Y be inner product spaces. Let $A : v \rightarrow W$, $B : v \rightarrow W$ and $C : W \rightarrow Y$ be linear transformations having adjoints and k be a scalar. Then,

- ① $(A + B)' = A' + B'$
- ② $(kA)' = \bar{k}A'$
- ③ $(CA)' = A'C'$
- ④ $(A')' = A$

Riesz Representation Theorem

Riesz Representation Theorem

Let V be an inner product space. If $\delta \in V'$ then there exists a unique vector $y \in V$ satisfying $\delta(v) = \langle v, y \rangle$ for all $v \in V$.

Example: Let $n > 1$ be an integer and let V be the subspace of \mathcal{P}_n consisting of all polynomial functions of degree at most n , on which we have an inner product defined by $\langle f, g \rangle = \int_{-1}^1 f(t)g(t) dt$. Let $\delta \in V'$ be a linear functional defined by $\delta : f \mapsto f(0)$. Then there exists a polynomial function $p \in V$ satisfying the condition $\delta(f) = \int_{-1}^1 f(t)p(t) dt$ for all $f \in V$.

Projection

Projection

If V is the direct sum of \mathcal{M} and \mathcal{N} , so that every $z \in V$ may be written, uniquely, in form of $z = x + y$, with $x \in \mathcal{M}$ and $y \in \mathcal{N}$, the projection on \mathcal{M} along \mathcal{N} is the transformation E defined by, $Ez = x$.

- A linear transformation E is a projection on some subspace if and only if it is idempotent, that is, $E^2 = E$.

Proof: If E is the projection on \mathcal{M} along \mathcal{N} , and if $z = x + y$, then

$$E^2z = EEz = Ex = x = Ez \quad (11)$$

Conversely, suppose $E^2 = E$. Let \mathcal{N} be a set of all vectors $z \in V$ such that $Ez = 0$. Let \mathcal{M} be a set of all vectors $z \in V$ such that $Ez = z$.

For an arbitrary z we have,

$$z = Ez + (1 - E)z$$

If we write $Ez = x$ and $(1 - E)z = y$, then $Ex = E^2z = Ez = x$ and $Ey = E(1 - E)z = Ez - E^2z = 0$, so that $x \in \mathcal{M}$ and $y \in \mathcal{N}$. This proves $V = \mathcal{M} \oplus \mathcal{N}$ and that the projection on \mathcal{M} along \mathcal{N} is E .

Properties of Projections

- If E is a projection on \mathcal{M} along \mathcal{N} , then \mathcal{M} and \mathcal{N} are, respectively, the sets of all solutions of equations $Ez = z$ and $Ez = 0$.
- A linear transformation E is a projection if and only if $1 - E$ is a projection. If E is a projection on \mathcal{M} along \mathcal{N} then $1 - E$ is the projection on \mathcal{N} along \mathcal{M} .
- $E_1 + E_2$ is a projection $\iff E_1E_2 = E_2E_1 = 0$; then $E = E_1 + E_2$ is a projection on \mathcal{M} along \mathcal{N} , where $\mathcal{M} = \mathcal{M}_1 \oplus \mathcal{M}_2$ and $\mathcal{N} = \mathcal{N}_1 \cap \mathcal{N}_2$
- $E_1 - E_2$ is a projection $\iff E_1E_2 = E_2E_1 = E_2$; then $E = E_1 - E_2$ is a projection on \mathcal{M} along \mathcal{N} , where $\mathcal{M} = \mathcal{M}_1 \cap \mathcal{N}_2$ and $\mathcal{N} = \mathcal{N}_1 \oplus \mathcal{M}_2$
- If $E_1E_2 = E_2E_1 = E$, then E is a projection on \mathcal{M} along \mathcal{N} , where $\mathcal{M} = \mathcal{M}_1 \cap \mathcal{M}_2$ and $\mathcal{N} = \mathcal{N}_1 + \mathcal{N}_2$
- If \mathcal{M} is a subspace invariant under linear transformation A , then $EAE = AE$ for every projection E on \mathcal{M} . Conversely, if $EAE = AE$ for some projection E on \mathcal{M} , then \mathcal{M} is invariant under linear transformation A .

Isomorphism
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Rank and Nullity
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Inner Product and Norm
○○○○○○○○○○○○○○○

Approximation
●○○○○○○○○○

Outline

① Isomorphism

② Rank and Nullity

③ Inner Product and Norm

④ Approximation

Least Squares Method

- Let a linear system be given by $Ax = b$, where $A \in^{m \times n}$, $x \in^m$ and $b \in^n$ then, the aim is to find best approximation of b which is in the range space of A .
- The problem is converted to minimizing the error $e = \|Ax - b\|^2$.
- The solution \hat{x} is which minimizes e is the same as locating the point $p = A\hat{x}$ that is closer to b than any other point in the column space of A .
- The error vector e must be perpendicular to the column space.
- All vectors perpendicular to the column space lie in the left nullspace. Thus the error vector e must be in the nullspace of A^T :

$$\begin{aligned}A^T(b - A\hat{x}) &= 0 \\ \hat{x} &= (A^T A)^{-1} A^T b \\ p = A\hat{x} &= A \left((A^T A)^{-1} A^T b \right)\end{aligned}\tag{12}$$

Example

Let a linear system be $Ax = b$ where,

$$A = \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{pmatrix} \quad b = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}$$

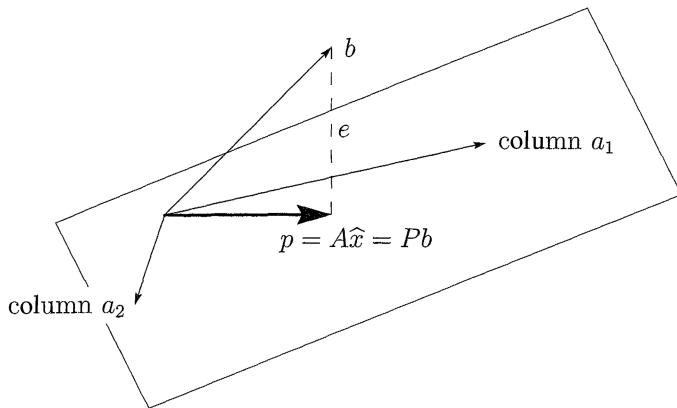
Here, b does not lie in the column space of A . So we have to find a best approximation which lies in column span of A .

By (12) we get,

$$p = \begin{pmatrix} 5 \\ 2 \\ -1 \end{pmatrix}$$

Geometrically, p is an orthogonal projection of b on column space of A .

Geometric representation of least squares approximation



Example

Problem: Sheldon wants to buy an apartment. But he wants to make sure that he pays the right market value for the apartment. So he decides to do a survey and tabulates them as under.

Area (in hundred Sq. ft)	12	10	15	6
No. of Bedrooms	2	3	4	1
Price(in Lacs)	70	75	85	50

Now, Sheldon has finalized a 750 Sq. ft. and 3 bedroom apartment. What do you think he should pay? (For 0 Sq. ft. and 0 bedroom apartment the price should be zero.)

Example

$$12x + 2y = 70$$

$$10x + 3y = 75$$

$$15x + 4y = 85$$

$$60x + 1y = 50$$

We write it as

$$AX = b$$

where,

$$A = \begin{pmatrix} 12 & 2 \\ 10 & 3 \\ 15 & 4 \\ 6 & 1 \end{pmatrix} \quad X = \begin{pmatrix} x \\ y \end{pmatrix} \quad b = \begin{pmatrix} 70 \\ 75 \\ 85 \\ 50 \end{pmatrix}$$

$$\begin{aligned} X &= (A^T A)^{-1} A^T b \\ &= \begin{pmatrix} 5.800 \\ 1.967 \end{pmatrix} \end{aligned}$$

Example

Now we have to find the value of a 750 sq. ft. and 3 bedroom apartment.

$$\begin{aligned} \text{Price} &= 7.5x + 3y \\ &= 49.4 \end{aligned}$$

Hence, Sheldon should pay 49.4 Lacs for the apartment.

References

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Isomorphism
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Rank and Nullity
○○○○○

Inner Product and Norm
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Approximation
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