

ARMA models

- Extending auto-regressive models with smoother noise.

In AR model for each t , we associate an independent noise w_t

Rice production in Maharashtra
AR(1)

MA terms.

$$x_t = \eta + \phi_1 x_{t-1} + w_t + \theta_1 w_{t-1}$$
$$x_t = \eta + \phi_1 x_{t-1} + \dots + \phi_p x_{t-p} + \underbrace{\theta_1 w_{t-1} + \theta_2 w_{t-2} + \dots + \theta_p w_{t-p}}_{+ w_t}$$

Need smoother handling of noise.

A moving average (MA) model provides that.

- ARMA models: AR models + MA models

Moving average models (MA models)

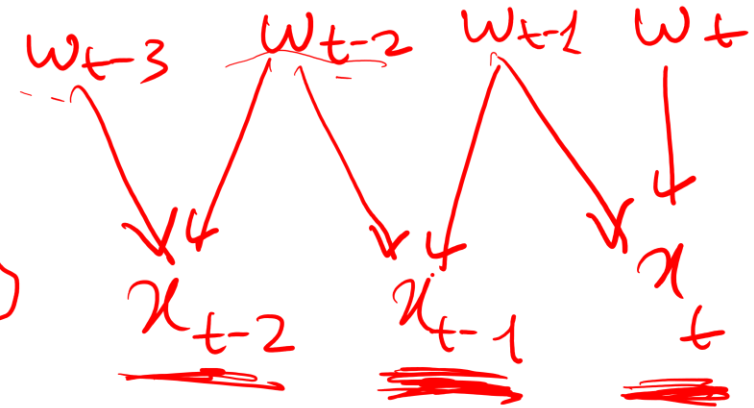
- A value x_t in a time-series sometimes cannot be explained just in terms of its past values.
- External (unknown) variables might be influencing the values
 - Example: Total wheat export of India in 2023 can be determined by wheat export in 2022, but also other external factors like weather patterns, war, exchange rates, etc.
- External variables are also time-varying → errors at each position cannot be independent.
- Moving average models capture dependency on such external unknowns.

Properties of a series following MA(1) model $p=0, q=1$

$$x_t = \eta + \theta_1 \omega_{t-1} + \omega_t$$

$$x_{t-1} = \eta + \theta_1 \omega_{t-2} + \omega_{t-1}$$

$$x_{t-2} = \eta + \theta_1 \omega_{t-3} + \omega_{t-2}$$



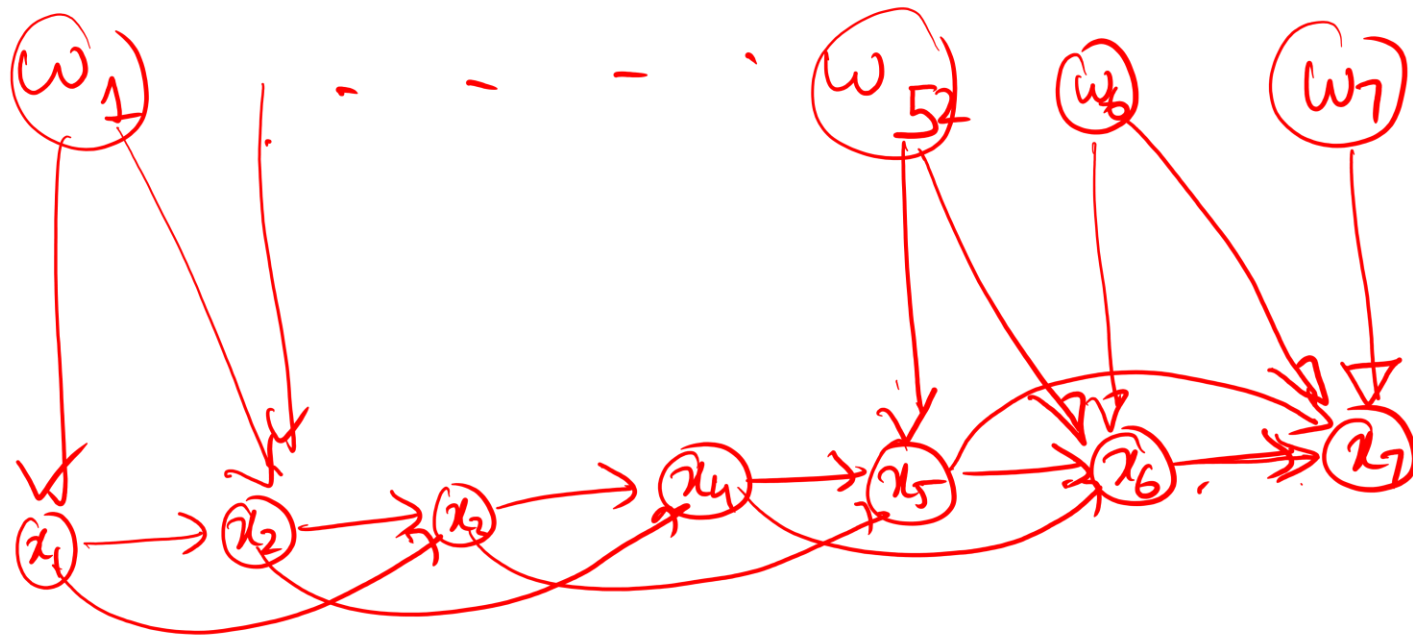
- Mean is $E(x_t) = \mu$
- Variance is $Var(x_t) = \sigma_w^2(1 + \theta_1^2)$
- Autocorrelation function (ACF) is:

$$E(x_t x_{t-1})$$

$$\underline{\rho_1} = \frac{\theta_1}{1 + \theta_1^2}, \text{ and } \rho_h = 0 \text{ for } h \geq 2$$

Pictorial representation of dependency.

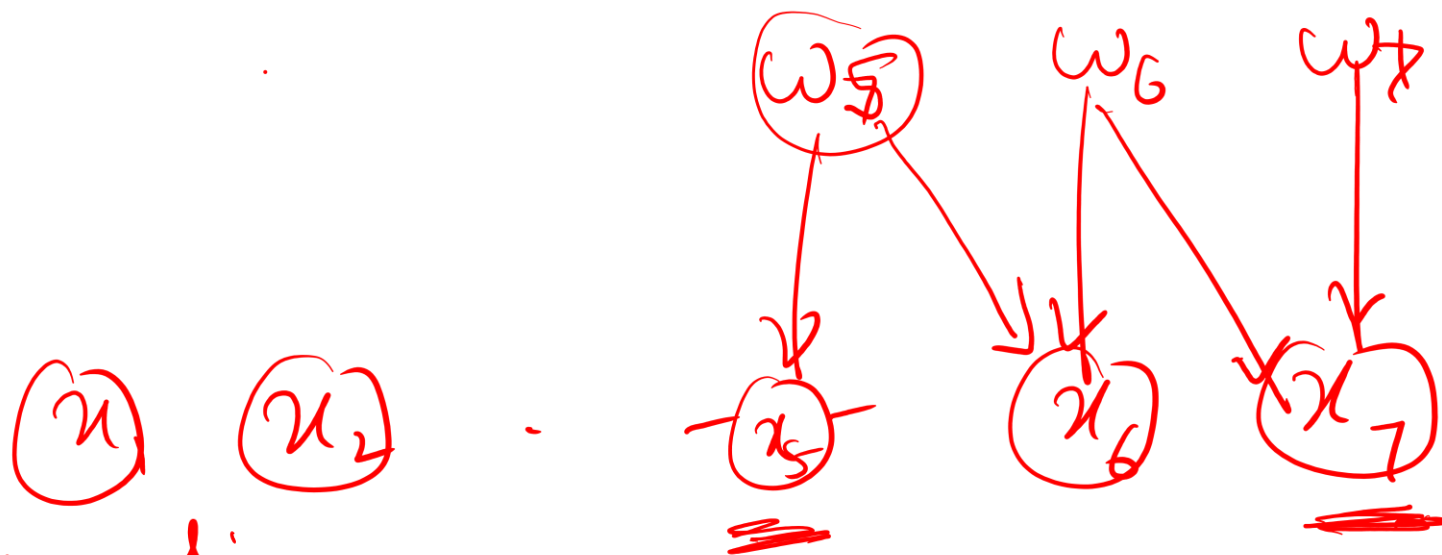
$$\begin{aligned} E(x_t x_{t-1}) &= E((n + \theta_1 \omega_{t-1} + \omega_t) x_{t-1}) \\ &= n E(x_{t-1}) + \theta_1 E(\omega_{t-1} \cdot x_{t-1}) + E(\omega_t x_{t-1}) \\ &= \end{aligned}$$



MA(1)

AR(2)

$$p = 0, \quad q = 1$$



Original:

$$\rightarrow x_t = \theta_1 \underline{w_{t-1}} + w_t + \eta \quad : \quad \text{To determine } \text{PACF}(x_t, x_{t-2}) = \theta_2$$

$$\rightarrow x_t = \underline{\phi_1 x_{t-1}} + \underline{\phi_2 x_{t-2}} + \tilde{\eta}$$

ARMA (p,q) model

Each x_t depends on p previous x -values, and q -previous error values

$$x_t = \eta + \phi_1 x_{t-1} + \cdots + \phi_p x_{t-p} + w_t + \theta_1 w_{t-1} + \cdots + \theta_q w_{t-q}$$

Estimating all the parameters of this model is not as straightforward as least-square regression since the w_t values are not observed (Not covered)

Comparing AR(1) and MA(1) on ACF and PACF

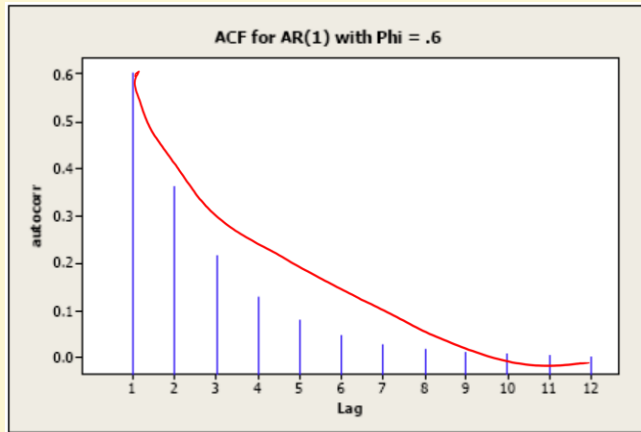
- ACF=plain correlation
- PACF(x_t , x_{t-2})=conditional correlation or what extra contribution you get from x_{t-2} after you x_{t-1}

Shape of ACF and PACF of a series following AR(1) model

Following is the ACF of an AR(1) with $\phi_1 = 0.6$, for the first 12 lags.

Note!

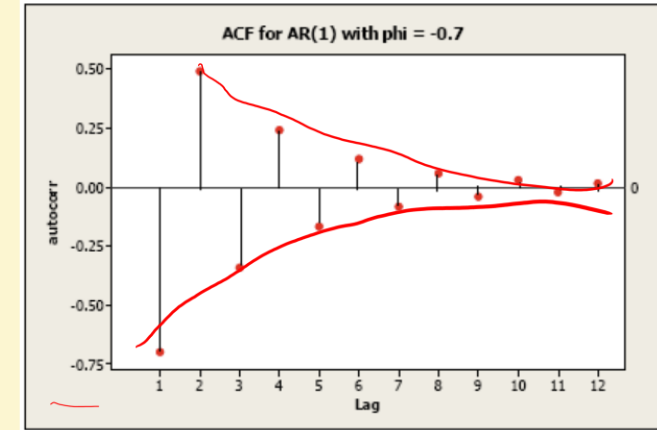
The tapering pattern:



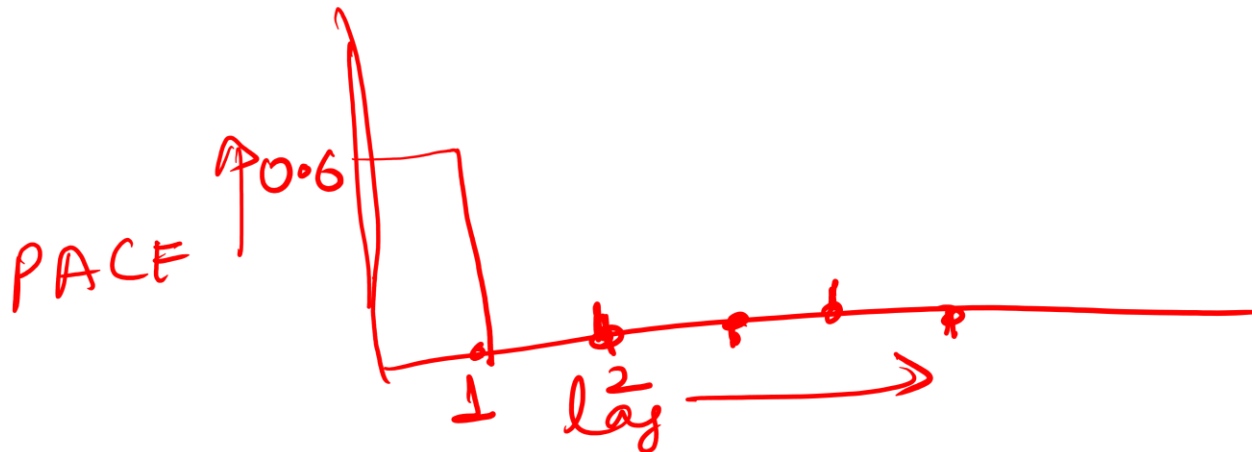
The ACF of an AR(1) with $\phi_1 = -0.7$ follows.

Note!

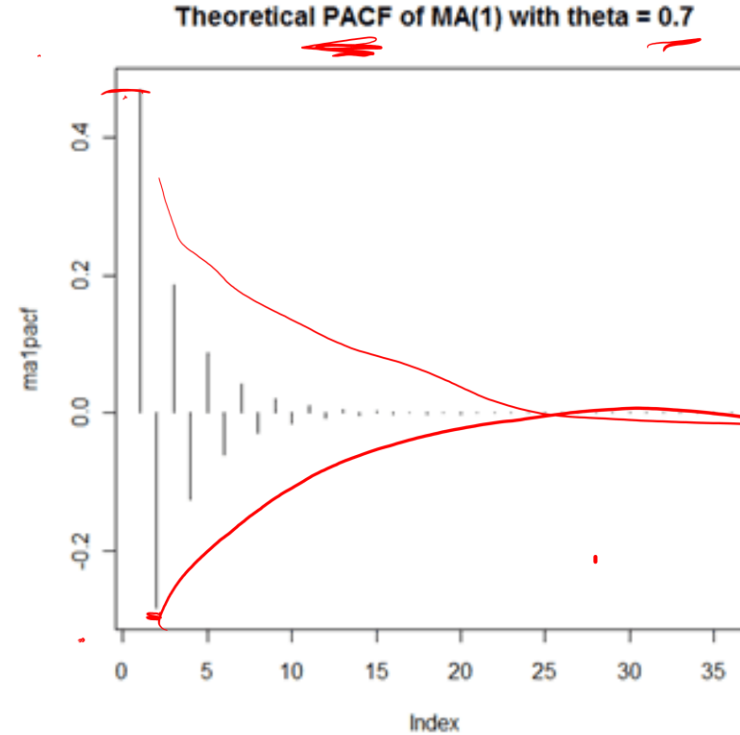
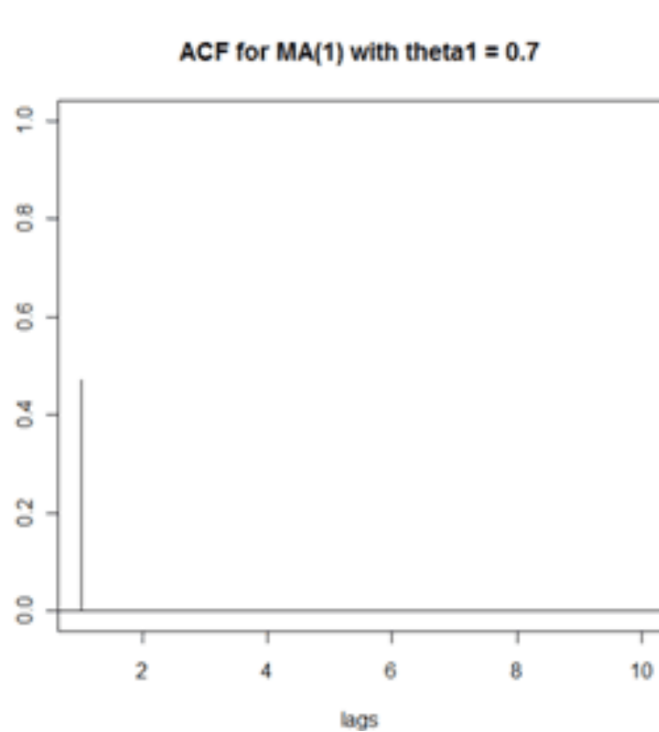
The alternating and tapering pattern.



$$PACF(x_t, x_{t-1}) = ACF(x_t, x_{t-1}) ; \underline{PACF(x_t, x_{t-2}) = 0}$$



Shape of ACF and PACF of a series following MA(1) model



$$\text{PACF}(x_t, x_{t+2}) = -\theta_1^2$$

$$\begin{aligned}
 \underline{x_t} &= \theta_1 \underline{w_{t-1}} + w_t & ; & \quad w_t = \underline{x_t - \theta_1 w_{t-1}} \\
 &= \theta_1 (\underline{x_{t-1}} - \theta_1 w_{t-2}) + w_t \\
 &= \theta_1 (\underline{x_{t-1}} - \theta_1 (\underline{x_{t-2}} - \theta_1 w_{t-3})) + w_t \\
 &= \left\{ \theta_1 \underline{x_{t-1}} - \theta_1^2 \underline{x_{t-2}} + \theta_1^3 \underline{w_{t-3}} + w_t \right\}
 \end{aligned}$$

Choosing p, q

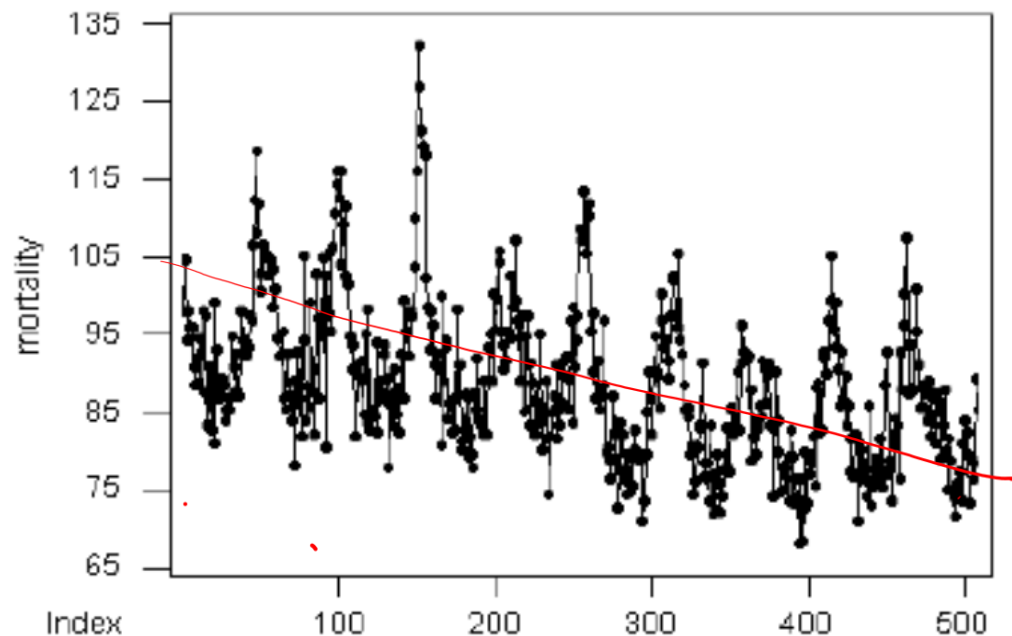
- Data may follow an $ARIMA(p, d, 0)$ model if the ACF and PACF plots of the differenced data show the following patterns:
 - the ACF is exponentially decaying or sinusoidal;
 - there is a significant spike at lag p in the PACF, but none beyond lag p .
- The data may follow an $ARIMA(0, d, q)$ model if the ACF and PACF plots of the differenced data show the following patterns:
 - The PACF is exponentially decaying or sinusoidal;
 - There is a significant spike at lag q in the ACF, but none beyond lag q .

Handling trend in time-series.

$$\underline{x}_t = \underline{\alpha}t + \phi_1 x_{t-1} + \theta_1 \omega_{t-1} + \omega_t$$

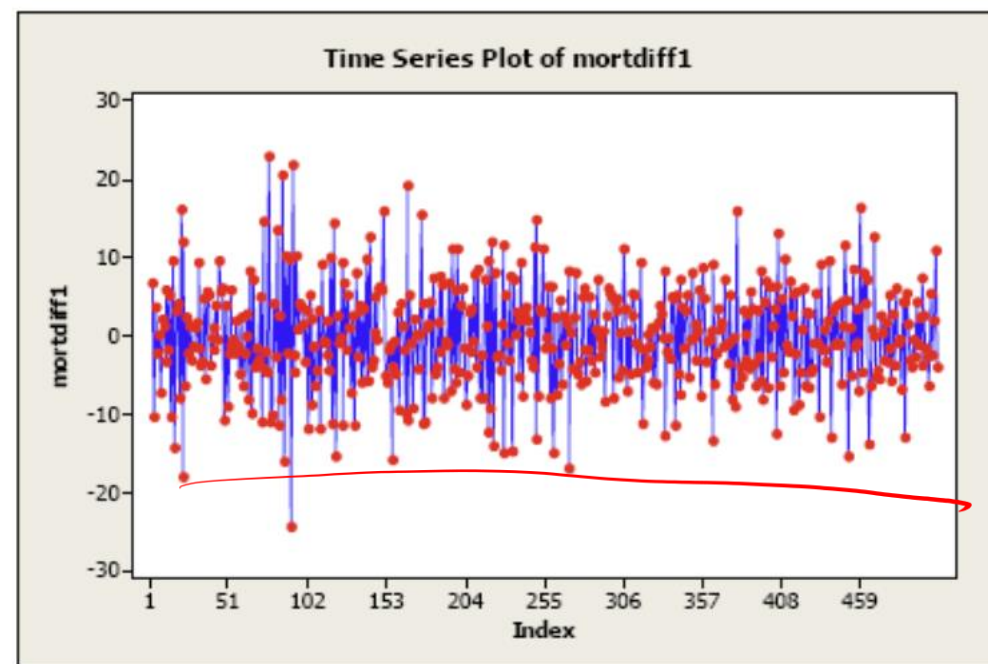
- If a time-series has a linear trend, then replace each value x_t with difference of consecutive x-values

- $y_t = x_t - x_{t-1}$



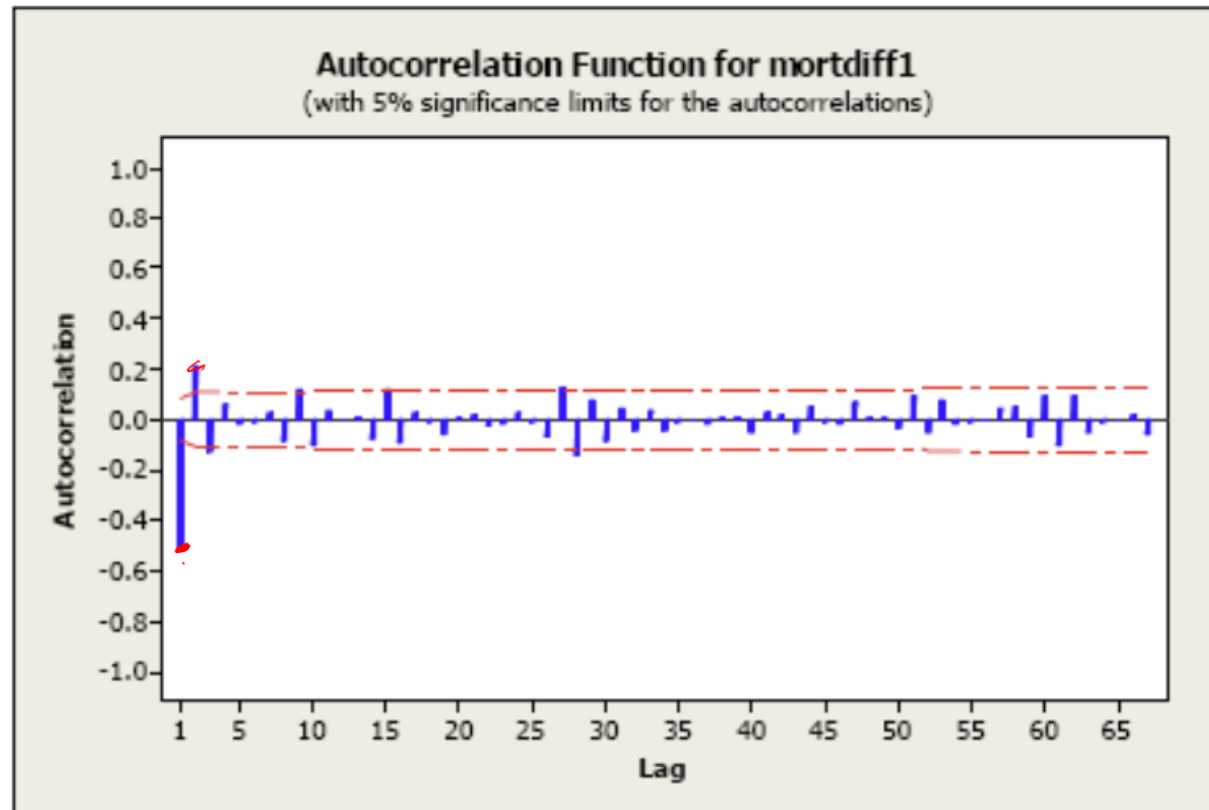
Daily cardiovascular mortality rate in Los Angeles County, 1970-1979.

Clear downward trend.



Plot of first differences

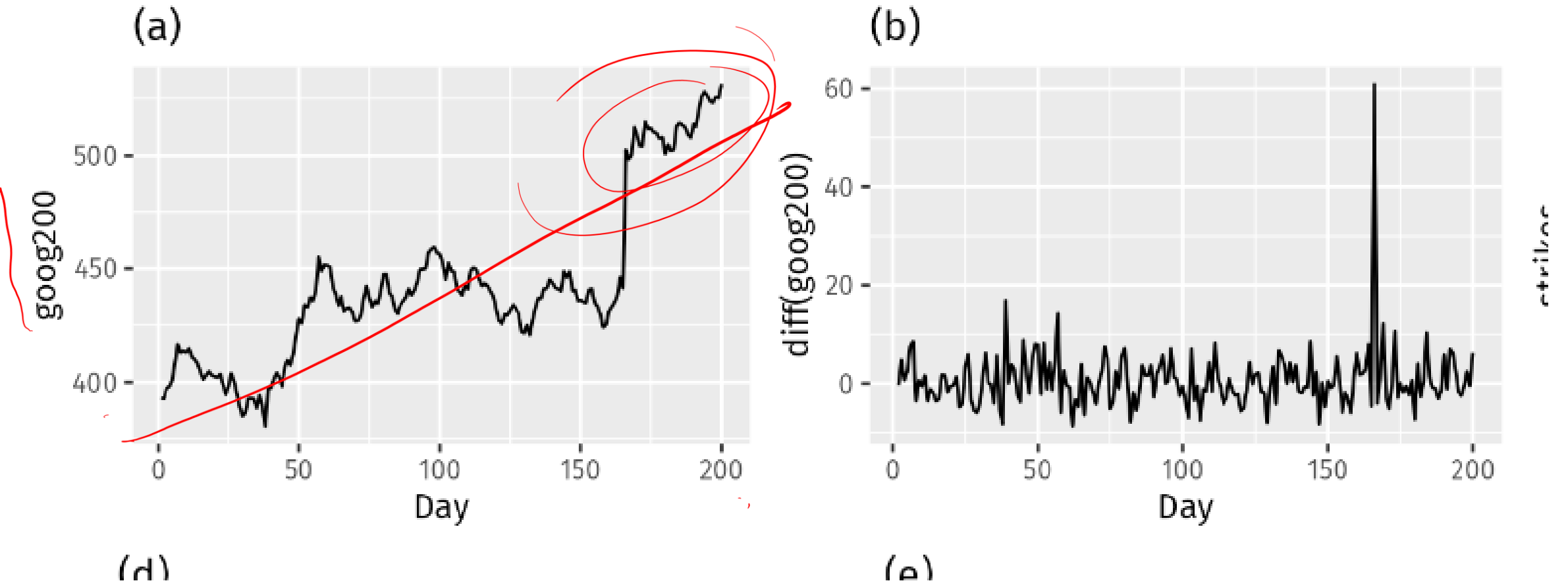
ACF of first differences.



Lag.	ACF
1.	-0.506029
2.	0.205100
3.	-0.126110
4.	0.062476
5.	-0.015190

$$\hat{y}_t = -0.04627 - 0.50636y_{t-1}$$

Another example



ARIMA(p,d,q) models

- p is the order of the autoregressive part,
- d is the degree of first difference involved,
- q is the order of the moving average part.

Example: ARIMA(2,1,1) model

Incorporating seasonality.

- Seasonality in a time series is a regular pattern that repeats over S time periods.
 - Example: monthly seasonality repeats over $S=12$ (months of the year)
 - Example: quarter seasonality repeats over $S=4$ period
- Extending ARIMA to handle seasonality. One or more of the above might work
 - Introduce a AR term x_{t-S} in the model for every period S .
 - Introduce MA term w_{t-S} in the model for every period S .
 - Create seasonal differences $y_t = x_t - x_{t-S}$

Demo

- https://colab.research.google.com/drive/1Z4zNI_bVXoFQBsCHUtxBDCBno6yhXceB?usp=sharing#scrollTo=deWKK_D1mNlr