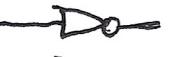


Intro. to Digital Design

- **Analog** - Time varying signals that have a continuous range of voltages/currents. (Reality, variable V/I, ↓ stability, ↓ accuracy)
- **Digital** - Discrete signal of 0/1, Low/High, True/False
(Hides pitfalls of analog by using discrete signals of 0/1, called bits)
 - 0-1 is algebraically low/high voltages.

Logic Circuits/Gates

- **Buffer**:  , $X \Rightarrow Y$
- **NOT Gate**:  , $X \Rightarrow \bar{Y}$
- **AND Gate**:  , $A, B \Rightarrow Y$
- **OR Gate**:  , $A, B \Rightarrow Y$
- **NAND Gate**:  ,
- **NOR Gate**:  ,
- **XOR Gate**:  , $A, B \Rightarrow Y$ * Multi-input XOR is odd # of 1s are inputted
- **XNOR Gate**:  ,

CMOS

- ↑ V, CMOS runs faster + noise immunity is better, but consume more power.
- $P \propto C(V^2 f)$, C = elec. C of signals, V = ps Voltage, f = signal switching freq.

Programmable Devices

- **ROMs** (Read-only memory) - stores 2D array of 2^n rows x b columns, 8b bits
 - ex. $n=6+b=8 \Rightarrow 64$ kbytes.
 - Used for complex + non-time critical functions
- **PLAs / PALs** (Programmable logic arrays) - can connect data with logic gates
 - Generally called PLDs (Programmable logic devices)
 - CPLDs are multi. PLDs connected,
- **FPGA** (Field-programmable gate array)
 - Lots of small configurable logic blocks (CLBs)

More common nowadays
Than CPLDs *

Binary, Decimal, Hexadecimal

- Groups of 8-bits = bytes, 4-bits = nibbles
- Hexadecimal is used to shorten long binary w/ 2 hexadecimal digits
= 1 byte. 0x can be used as a hex prefix.
- Binary \leftrightarrow hex

010010110110010_2
 ↓ ↓ ↓ ↓
 2 5 B 2₁₆ $\Rightarrow 25B2_{16}$

Negative Nums

- Signed-Magnitude Rep: Has sign bit @ MSB to det. sign.
- Range of $-(2^n-1)$ to 2^n-1 w/ two rep. for 0.
- Complement Representation: All bits are swapped + 1 is added to get negative value of orig. #.

ASCII

Uses 7 bits for characters, giving 128 characters.

BCD

Each digit gets 4 bits, to represent 0-9 (Any other 4-bit val is invalid)

Boolean Algebra

- On Switching Algebra
- Axioms: $X = 0$ iff $X \neq 1$, $X = 1$ iff $X \neq 0$,
- NOT Gate: X' , AND Gate: $X \cdot Y$, OR Gate: $X + Y$.
- Single Var. Theorems:

- Identities: $X + 0 = X$, $X \cdot 1 = X$

- Null Ele. : $X + 1 = 1$, $X \cdot 0 = 0$

- Idempot.: $X + X = X \cdot X = X$

- Involution: $(X')' = X$

- Complements: $X + X' = 1$, $X \cdot X' = 0$

- Two + Three Var. Theorems

- Commutativity: $X + Y = Y + X$, $X \cdot Y = Y \cdot X$

- Associativity: $(X + Y) + Z = X + (Y + Z)$, $(X \cdot Y) \cdot Z = X \cdot (Y \cdot Z)$

- Distributivity: $X \cdot Y + X \cdot Z = X \cdot (Y + Z)$, $(X + Y) \cdot (X + Z) = X + YZ$

- Combining - ~~$X + X \cdot Y = X$, $X \cdot (X + Y) = X$~~

- Covering - $X + X \cdot Y = X$, $X \cdot (X + Y) = X$

- Combining - $X \cdot Y + X \cdot Y' = X$, $(X + Y) \cdot (X + Y') = X$

- Consensus - $XY + X'Z + YZ = XY + X'Z$

$$(X + Y)(X' + Z)(Y + Z) = (X + Y)(X + Z')$$

- N-var Theorems

- DeMorgan's Law: $(X_1 \cdot X_2 \cdot \dots \cdot X_n)' = (X_1' + X_2' + \dots + X_n')$

$$(X_1 + X_2 + \dots + X_n)' = (X_1' \cdot X_2' \cdot \dots \cdot X_n')$$

- Shannon's Exp. Theorems:

$$\begin{aligned} F(X_1, X_2, \dots, X_N) &= X_1 F(1, X_2, \dots, X_N) + X_1' F(0, X_2, \dots, X_N) \\ &= (X_1 + F(0, X_2, \dots, X_N))(X_1' + F(1, X_2, \dots, X_N)) \end{aligned}$$

- Duality

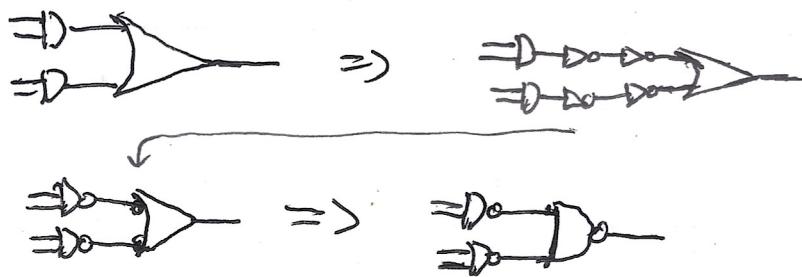
- Swap All 0/1 and +/·, Eg. is true

• Complement: $F(X) \Rightarrow \overline{F(X)}$

Combinational - Circuit
Synthesis

- We can simplify circuits by having inputs that will be calculated from more complex circuits (~~other~~ (clock/lock signal)). We can also use bools w/ them.
- NAND + NOR gates are usually faster in CMOS.
- To utilize them insert two ^{theoretical} not gates between gates and update circuits, w/o pushing inputs through etc.

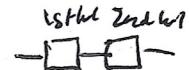
Ex.



- Any splits should happen before the not gate to each input.

- Minimization

- Minimize # of levels/gates
- Minimize # inputs on each 1st lvl gate
- Minimize # inputs on the 2nd lvl gate.



- Karnaugh Maps - Used like truth tables to minimize.

00	01	11	10
0			
0			
1			

Will expand on later

- Timing Hazards - When a false output is triggered b/c prop. delay, or when multiple changes happen that also cause this.

- Static 1 Hazard - Should be 1 but flips to 0 for a sec (Usually SOP)
- Static 0 Hazard - Should be 0 but flips to 1 for a sec (Usually POS)
- Dynamic Hazard - Changes multiple times in the output.

Representations of Logic Functions

• Representations:

- Literal & Var/Complement of var (x/x')
- Product Term: Single Literal or Product of multiple literals ($x/x'y/x'y'$)
- Sum-of-products expression (SOP): Logical sum of product terms ($xy+yz$)
- Sum Term: Single Literal or Sum of multiple literals ($x/x+y$)
- Normal Term: Prod/Sum Term which each variable only appears once. (xyz)
- n-var minterm: Product Term with n literals ($xyz - 3\text{-var min.}$)
- n-var maxterm: Sum Term with n literals ($x+y+z - 3\text{-var max.}$)

• Minterm/Maxterm Table ($\text{Max} = \text{Opp of literal value}, \text{Min} = \text{Same as literal value}$)

	X	Y	Z	Min.	Max.
0	0	0	0	$x'y'z'$	$x+y+z$
1	0	0	1	$x'y'z$	$x+y+z'$
2	0	1	0	$x'yz'$	$x+y+z$
3	0	1	1	$x'yz$	$x+y+z'$
4	1	0	0	$xy'z'$	$x+y'z$
5	1	0	1	$xy'z$	$x'+y+z'$
6	1	1	0	xyz'	$x'+y+z$
7	1	1	1	xyz	$x'+y'+z'$

$$F = \sum_{(x,y,z)} (0,1,2) = \text{SOP of minterms}$$

↑
on-set

F is 1 for 0,1,2
only

$$F = \prod_{(x,y,z)} (0,1,2) = \text{POS of maxterms}$$

↑
off-set

F is 0 for 0,1,2
only

$$F = \sum_{x,y,z} () = \prod_{(x,y,z)} (\bar{}) \quad \text{where}$$

$(\bar{})$ is the
opposite set
of maxterms

Karnaugh Maps

(Minterms listed)

wx \ yz	00	01	11	10
00	0	4	12	8
01	1	5	13	9
11	3	7	15	11
10	2	6	14	10

- To Simplify, Circle all adjacent 1's/0's after doing SOP/POS respectively in powers of 2 groups.
 - The variables that don't change in the group will be represented in the term in the sum product expression.
 - Repeat for all groups

• Can be used to prevent errors

- Adjacent groupings w/ no overlap cause static errors.
- Add a group overlapping the adjacency to solve.

Verilog

- Verilog is a HDL (Hardware Description Lang.) where you can design, simulate, and synthesize almost any digital circuit.

- Modules build verilog (functions)
 - Usually 1 file w/ .v prefix
 - Ex. module Example (x, y, z);


```
input x, y;
output z;
assign z = x & ~y;
endmodule
```

- Module Structure:

- module module-name (port-name, port-name, ..., port-name);
 - input decl.
 - Output decl.
 - inout decl.
 - Net decl.
 - Var decl.
 - Param decl.
 - Func. decl.
 - task decl.

Concurr. statements
endmodule

- input [^{msb}:_{lsb}] ident, ident, ..., ident;
 Output [_{lsb}:^{msb}] ident, ...; (only read by other mod.)
 inout ... (can be used for in/out)
- [msb : lsb] is optional, but indicates index of most sig bit / least sig bit.

- All vars have to be 0, 1, x, z ($x = \text{unknown}$, $z = \text{high imp.}$) used in 3-state logic
- Bitwise op: &, |, ^, (~, !), ~
 \oplus \otimes \boxtimes \boxdot $\boxtimes\text{NOR}$

- Nets - enable connectivity, default is write!
- reg - store bits for use in module
- integer - stored 32-bit # (used for loops)
- Literals: $L^B N ..$ where L is length of the literal in bits, B is the base
 - of the literals and N is the literal numbers to translate.

- Parameters: Constants/Used to store literals.

- [v1:v2] ... = vector, B ... [v1:v2] = array & can be combined as vector is like bits.
- Vector uses {} , N{} produces N len vector of 1s.

- Struct mod, busser is bus \Rightarrow M (out, int, int, ..., b)

~~can go more in depth.~~

Logical op. + Expressions

- If any bit is 1, the value is true.
- Expressions return 1'b1 or 1'b0 (T/F) with 0-left padding if assigned to larger bitsize
- Operators: &&, ||, !!, ==, !=, >, >=, <, <=
- Conditional operator: $x ? y : z$ - evaluates as y or z depending on x.
 - same as if x:
 - ref y
 - else
 - ref z

Compiler Directives

- `include filename, `define identifier text
- `L₁ike (

Verilog Structural Models

- Structural Model - Uses inbuilt gates + nets/wires for functions.
 - use instatiators that are unique, aka: `not U1(A,B);`
- Dataflow Model - Uses bitwise operators + assign for functions.
- Behavioral Model - Uses traditional C code logic and always for functions
 - always @ (sig1 or sig2...), always @ (sig1, sig2...), always @ (*),
 always @ (posedge sig1), always @ (posedge sig1), always @ (posedge sig1),
 - ~~* #1 #2~~ trigger when those signals change, #3 ~~trigger when~~ when any signal mentioned changes in body, #4/#5 = Rising + Edge
 - begin can be named + tracked (`begin: name`)
 - if (cond) ~~value;~~ ^{exp.} else if (cond) ~~value;~~ ^{exp.} else exp.
 - Case (C)


```
case1, case2: exp1;
            case3: exp3;
            default: exp;
          endcase
```

 - for loops work the same, instead of brackets.
 - ~~functions/tasks~~ are procedures that don't use () function, ~~task~~

Read-only Memories (ROMs)

- A ROM is a memory with 2^n data entries of size b .
 - To access, there are n address pins and b output pins
- FPGAs use small ROMs and Lookup Tables (LUTs)

Decoding + Selecting

- Uses n inputs + 2^n outputs + enable signal (turn on enable) $\xrightarrow{\text{to use}}$
- Translates the binary input and activates the corresponding output pin ($0 - 2^n - 1$)
- Any pin can be active low/high
- Seven Segment Displays use Decoders:

$\begin{matrix} & 1 & 2 & 3 \\ & \downarrow & & \downarrow \\ 4 & 5 & 6 & 7 \\ & \downarrow & & \downarrow \\ 8 & 9 & 10 & 11 \\ & \downarrow & & \downarrow \\ 0 & 1 & 2 & 3 \end{matrix}$
 7-bit number w/ MSB being 9.
- Binary Encoders do the opposite, 2^n inputs $\rightarrow n$ outputs decimal \rightarrow binary. (pins $0 - 2^n - 1$)

Multiplexing

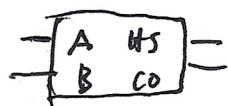
- Uses a decoder + Data lines
- n inputs + 2^n datalines + 1 output + enable signal
- Links the correct dataline to output depending on the n -bit address.
- Demultiplexers do the opposite n inputs + 1 data line + 2^n output lines.
 - Directs data to specific wire.

Priority Encoders

- Fixes issues of basic encoder which needs only one input high
- Encodes the highest significant bit that is active and encodes it into binary
 $001 \rightarrow 001$

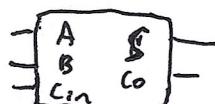
Adders + Subtractors

- Half adder



$$\begin{aligned} HS &= A \oplus B && \leftarrow \text{Half Sum} \\ CO &= AB && \leftarrow \text{Carry Out} \end{aligned}$$

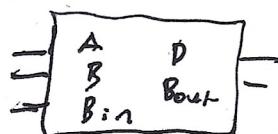
- Full adder



$$\begin{aligned} S &= A \oplus B \oplus Cin && \leftarrow \text{Sum} \\ CO &= AB + A'Cin + BCin && \leftarrow \text{Carry Out} \end{aligned}$$

- We can chain full adders to add more bits and make a ripple adder. (But ineff.)

- Full subtractor



$$\begin{aligned} D &= A \oplus B \oplus Bin && \leftarrow \text{Difference} \\ Bout &= A'B + A'Bin + BBin && \leftarrow \text{Borrow out.} \end{aligned}$$

- Carry Look ahead adder

- $S_i = a_i \oplus b_i \oplus c_i$

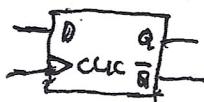
- Uses next-level logic to generate the carries for each bit.

Binary Codes for Decimals

- Regular Binary
- Gray Code

State Machine

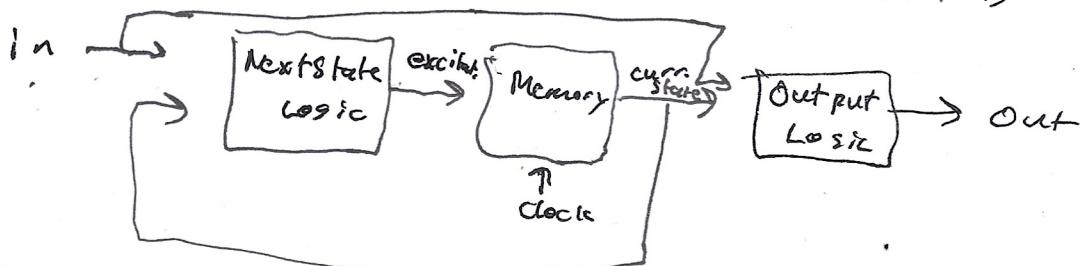
- Clock Signals are used for State Machines/ Sequential Circuits
 - Active high = triggered on rising edge
 - Active low = triggered on falling edge.
- D Slipslops commonly used to store data in state machines



D is data line, Q is data, \bar{Q} is data complement
 CLK is clock, D is stored to S ~~at~~ clock rising edge.

State Machine Structure

- Mealy state-machine - Output depends on state + inputs



- Moore state - machine output depends on state only
 - Removes connection from in to output logic.

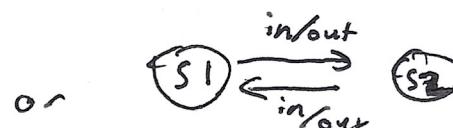
State Machine Design

1. Make a state table (state/output)
2. Use state minimization
3. Choose state variables and assign combos to the named states
4. Sub state-var combos to create transition/out table that shows the next state.
5. Choose a flip flop to store the state (usually D)
6. Construct excitation table (what vals needed for next state)
7. Derive excitation equations
8. Derive output eqs.
9. Draw logic diagram showing state-var storage, reg. Excitation, and output eqs.

- State Diagram ex:



Moore



Mealy

State Machine cont'd

Derry

- Excitation Logic = Next State Logic
- Transition Table
- State Table
- State Out-table

Q_1	Q_0	IN	Q_1^*	Q_0^*
0 0	0 0	0 1		
0 1	0 1	b 0		
1 0	1 0	1 1		
1 1	1 1	0 0		

S	0	1
A	A	B
B	B	C
C	C	D
D	D	A

- Mealy:

S	0	1
A	$A_{1,0}$	$B_{1,0}$
B	$B_{1,0}$	$C_{1,0}$
C	$C_{1,0}$	$D_{1,0}$
D	$D_{1,0}$	$A_{1,1}$

- Moore:

S	0	1	IN	out
A	A	B		0
B	B	C		0
C	C	D		0
D	D	A		1

State Minimization

1. Partition States based on output
2. Keep Partitioning based on nextstate partition locations differences when $\text{in} = 0$ or $\text{in} = 1$.

ex. $AB \text{ or } CD \Rightarrow AB \xrightarrow{\text{in}} \begin{matrix} AB \\ CA \\ CB \\ BA \end{matrix} \xrightarrow{\text{out}} \begin{matrix} AB \\ CA \\ CB \\ BA \end{matrix}$

• # FF = $\lceil \log_2(\text{#S}) \rceil$

Verilog

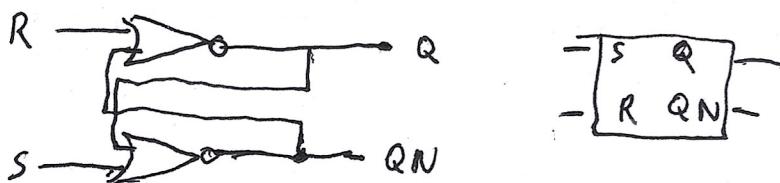
- Next state Logic: always_ff + cases (use =)
- State Mem + Output Logic: ~~always_comb~~ always-comb (use <=)

Bistable Elements

- Bistable - Two stable states
- Metastable - A third stable point in between logic levels (not truly stable).

Latches + Flip Flops

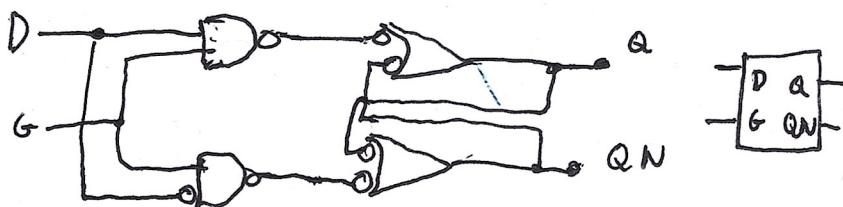
- S-R Latch



S	R	Q	Q _N
0	0	0	Q _N
0	1	0	1
1	0	1	0
1	1	0	0

Latches onto the set/reset.

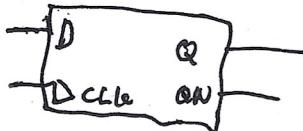
- D Latch



G	D	Q	Q _N
1	0	0	1
1	1	1	0
0	X	Q	Q _N

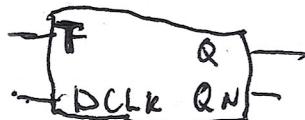
Latches Data when enabled

- D Flip Flop



Updates Data Value @ Q from D
on edge of clock signal (usually pos edge)
Sometimes has enable.

- T Flip Flop



Toggles Data Value @ Q when
T=1 on edge of clock signal (usually posedge)
Sometimes has enable.

Counters

- Ripple Counter - links bunch of TFFs so that whenever a bit updated from 1 → 0 it ripples the bit forward in QN. (Very Slow)
- Synchronous Counter - Links TFFs with one clock signal and a AND gate w/ master enable + the previous bit. (All bits update at the same time)

Shift Registers

- Data line + Clock
- Shifts all bits left/right and inserts new bit from data line.
- Can use serial i/o or parallel i/o (One data line vs multiple)

~~Points~~More Counters

- Ring Counter - Link out back to in to loop the bits making a ring of repeated numbers
- Johnson Counter - Ring Counter but QN is linked to in instead, leading to twice as many states.
- Linear Feedback Shift-Res Counter - Uses xor gates to loop through all $2^n - 1$ possible states.

Iterative vs Sequential

- Iterative - Uses no storage or clock
- Sequential - Uses FFs and requires clock pulses,

Verilog Test Benches

• Steps:

1. Declaration of the test-bench module itself.
 - No inputs or outputs
2. Instantiation of the component to be test (DUT/OUT)
3. An always block to create a free running clock.
4. Statements to init. DUT apply multiple test inputs and check output.

• Construction Methods:

- Try to visit every ^{normal} state and take all normal transitions.
- Try to test every "feature" of the DUT.

Synchronizer Failure & Metastability

- Synchronizer Failure - uses output while still in metastable state
 - can be avoided by waiting long enough before using output.
- To get out of this state, some spec into a valid state defines the published specifications.
- Or wait long enough for metastability to be resolved.
- t_r - metastability resolution time or how much time before metastability causes a sync. fail.
 - usually $t_r = t_{clock} - t_{combs} - t_{setup}$
 - $$t_r = \frac{t_{clock}}{\text{Clock period}} - t_{combs} - t_{prop\ delay} - t_{FF\ setup\ time}$$
 - Fast clocks often are used, so minimize $t_{combs} + t_{setup}$ to maximize t_r for more reliability.
- t_s - setup time, t_h - hold time bracket the decision window
 - 0 changes outside d.w. = output will settle into pd
 - else metastability is possible and can persist past t_r .
- $MTBF(t_r) = \frac{e^{-t_r/\tau}}{T_0 \cdot f_a}$
 - mean time between sync fails.
 - T_0 clock # changes per sec
 - t_r & τ are electrical characteristics
- Setup viol = misses data, Hold viol = gets wrong data
 - data arrives too late
 - data leaves too early.
- t_{skew} - time gap between ^{identical} clock signals
- Setup time constraint: $T_{-c} \geq t_{-pd} + t_{-setup} + t_{-pcg} + t_{-skew}$ \checkmark time to stable & (pd sometimes)
- Hold time constraint: $t_{-hold} \leq t_{-ccg} + t_{-cd} - t_{-skew}$
- t_s is before clock pulse, t_h is after.
 - t_{cd} of g \checkmark time to change (like t_{pd} but not stable yet just when output starts changing)

(CMOS Logic Circuits)

- V_{DD} is certain voltage + noise. Anything outside logic/Logic 0 ranges is invalid.

- Typical CMOS operates at 5V, but some circuits use ~~lower~~ lower voltage to save power.

- $0\text{--}30\%$ of V_{DD} is Logic 0, $70\text{--}100\%$ of V_{DD} is Logic 1
 - $30\text{--}70\%$ is invalid

- $R_{DS} \approx 1M\Omega$ when off, $R_{DS} \approx 1\Omega$ when on.

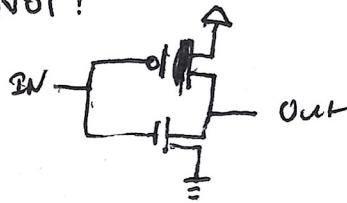
($V_{GS} = 0$)

($V_{GS} \approx 5V(N), -5V(P)$)

- NMOS & PMOS are combined in CMOS Circuits, w/
 PMOS being wired to V_{DD} / ~~at the top~~ at the top, NMOS being wired to GND,
 at the bottom and output in the middle

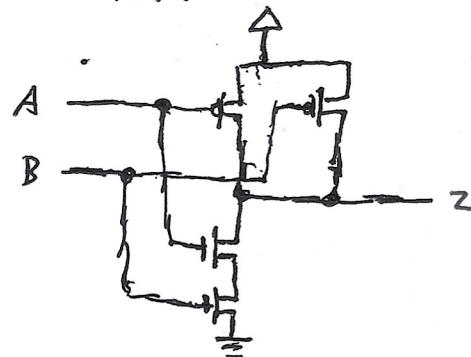
- PMOS is wired as the complement of the logic function,
 while NMOS is wired normally for inverting gates (ignoring the non-NAND)
- Non-inverting gates have the output of the complementary
 inverting gate linked to a simple CMOS NOT.

- NOT:

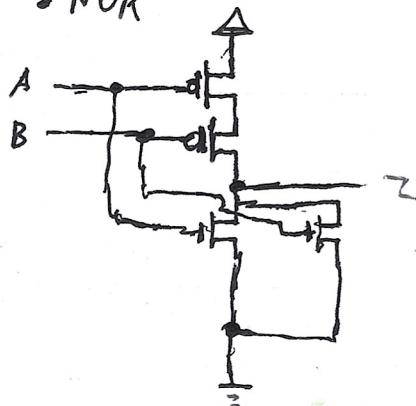


$\frac{d}{dt} = \text{PMOS}, \frac{d}{dt} = \text{NMOS}$

- NAND:



- NOR



Buzz/AND/OR can be achieved by attaching Z from one of these gates to a NOT gate.

Electrical Behavior of CMOS Circuits

Datasheet for CMOS Devices

$V_{IH}/V_{IH\min}$ = Min. Logic High Level for input (usually 70% V_{CC})

$V_{IL}/V_{IL\max}$ = Max Logic Low Level for input (usually 30% V_{CC})

$V_{OH}/V_{OH\min}$ = Min Logic High for Output (usually $V_{CC} - 0.1$)

$V_{OL}/V_{OL\max}$ = Max Logic Low for Output (usually $V_{CC} + 0.1 \approx V_{CC}$)

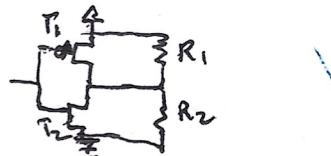
$I_{H/I_L} \approx \pm 1\text{mA}$ = ~~Max curr for input through that into acc.~~ (Cause FET tech.)

- DC Noise Margin

$$\begin{aligned} - \text{Low Noise Margin (LNM)} &= |V_{IL\max} - V_{OL\max}| \\ - \text{High Noise Margin (HNM)} &= |V_{OH\min} - V_{IL\min}| \end{aligned}$$

When attached to res. load, behaves nonideally.

Ex.



- Convert to Thevenin form (the R load) (Do not use like)

- Replace transistors w/ Resistors (1M Ω for off, 100 Ω for on)

- Calculate voltage division w/ low res/^{200 Ω for on} transistor resistance

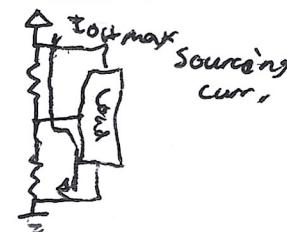
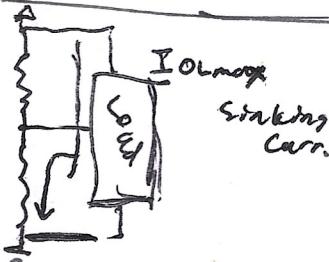
Ex.

$$V_{out} = V_{thev} \left(\frac{100}{(200 + R_{thev})} \right) \quad (\text{For } V_{in} \text{ High})$$

$$V_{out} = V_{thev} + (V_{CC} - V_{thev}) \left(\frac{R_{thev}}{(200 + R_{thev})} \right) \quad (\text{For } V_{in} \text{ Low})$$

Hard to calc (not given parameters)

- $I_{OL\max}$ = Max sink current when Out Low
- $I_{OL\max}$ = Max source current when Out High



TTL load
↓ Precise
V + more curr
vs CMOS load

$$R_P(\text{on}) \approx \frac{V_{CC} - V_{OH\max}}{|I_{OL\max}|}$$

$$R_A(\text{on}) \approx \frac{V_{OL\max}}{|I_{OL\max}|}$$

Electrical Behavior of CMOS Circuits

• Non-ideal inputs,

- When inputs to logic gates aren't ideal, this causes unideal output voltages which worsen with loads, due to the transistors both not having high resistances.

- This also causes current wastage + power wastage

• Loading beyond rated fanout (max inputs gate can drive) causes

- V_{OMAX} to be exceeded

- V_{OLMIN} to not be met

- Prop delay ↑, Rise/Fall times ↑, Op temp ↑ \Rightarrow reliability & faster failure.

• Don't leave floating inputs, tie them to other outputs or logic V_0 , according to switching logic rules.CMOS Dynamic Behavior

• Transition time

- Rise time : t_r - time for signal to rise from 10% to 90%.

- Fall time : t_f - time for signal to fall from 90% to 10%

• Propagation Delay

- Time for Output to Change from Input

- t_{PLH} : time from input change to output change $H \rightarrow L$
(measured @ 50%) \downarrow
for in & out

- t_{PHL} : time from input change to output change $L \rightarrow H$

• Power Dissipation

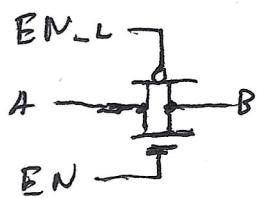
$$P_T = C_{PD} \cdot V_{CC}^2 \cdot f$$

$\times C_{PD}$ - Power Diss. Capacitance, resp. current flow changes

$\times f$ - freq. of transitions / output changes

Other CMOS Input Structures

• Transmission Gate



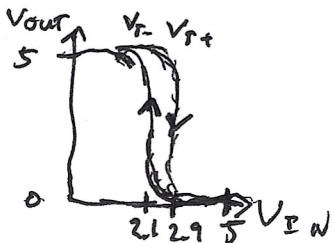
$EN_L \rightarrow EN$ always opposite

$EN_H = 1 - EN_{op-imp}$

$EN_L = A \rightarrow B$ is dc.

- $A \rightarrow B$ prop delay is so used in large scale CMOS devices
 - * (Multiplexers / Flip Flops)

• Schmitt Trigger Inputs



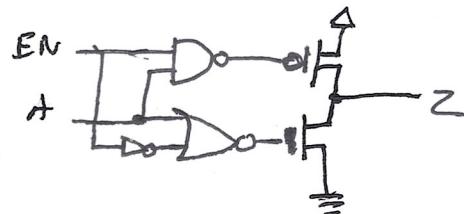
Low \rightarrow High EN threshold is ~~V_T+~~ V_T+

High \rightarrow Low EN threshold is V_T-

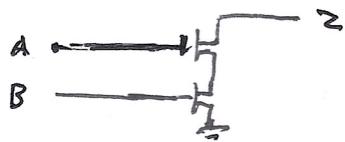
(Regular Input has one threshold)

• Three State Output

- Hi, Lo, Hi-Z (High Impedance)
- Hi-Z \approx Not connected.
- Add enable pin as such \Rightarrow



- Open Drain - No connection to Vcc, Only low out is outputted, otherwise it's open. Used w/ a external pull up resistor to achieve higher V.



High \rightarrow Low is fast
Low \rightarrow High is slow.