

MSI exercise 3

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1 Task 1

1.

$$\nabla f(x) = 2Qx + c, \nabla^2 f(x) = 2Q \quad (1)$$

2. Q should be invertible and Positive Semi-Definite

3.

$$\begin{aligned} 2Qx^* + c &= 0 \\ x^* &= -\frac{1}{2}Q^{-1}C \end{aligned} \quad (2)$$

$$\begin{aligned} f(x^*) &= \frac{1}{4}c^T Q^{-1} Q Q^{-1} c - \frac{1}{2}c^T Q^{-1} c \\ f(x^*) &= -\frac{1}{4}c^T Q^{-1} c \end{aligned} \quad (3)$$

2 Task 2

$$\nabla f(x) = 2 \begin{bmatrix} 4 & 1 \\ 1 & 2 \end{bmatrix} x + \begin{bmatrix} 3 \\ 4 \end{bmatrix} = 0 \quad (4)$$

$$x = -\frac{1}{2} \begin{bmatrix} 4 & 1 \\ 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} -0.1429 \\ -0.9286 \end{bmatrix} \quad (5)$$

There exists a single value for x that satisfies the First order Necessary Condition. This is the Global Minimizer as well because the objective function is convex.

3 Task 3

$$\begin{aligned}
E[S^2] &= E \left[\frac{1}{N-1} \sum_{n=1}^N (Y(n) - M(Y_N))^2 \right] \\
&= \frac{1}{N-1} \sum_{n=1}^N E [Y(n)^2 - 2 * Y(n) * M(Y_N) + M(Y_N)^2] \\
&= \frac{N}{N-1} (E[Y(n)^2] - 2E[Y(n) * M(Y_N)] + E[M(Y_N)^2]) \\
&= \frac{N}{N-1} \left(E[Y(n)^2] - 2E \left[Y(n) * \frac{(Y(1) + \dots + Y(n) + \dots + Y(N))}{N} \right] + E[M(Y_N)^2] \right) \\
&= \frac{N}{N-1} \left(\sigma_Y^2 + \mu_y^2 - 2 \left(\frac{\sigma_Y^2}{N} + \mu_y^2 \right) + \frac{\sigma_Y^2}{N} + \mu_y^2 \right) \\
&= \frac{N}{N-1} \left(\sigma_Y^2 - \frac{\sigma_Y^2}{N} \right) = \sigma_Y^2
\end{aligned} \tag{6}$$

If we use the factor (N - 1) for the variance, we end up with an unbiased estimator, as shown.

4 Task 4

- **Part b**

$$\Phi = \begin{bmatrix} 1 & i(1) \\ 1 & i(2) \\ \cdot & \cdot \\ \cdot & \cdot \\ 1 & i(N) \end{bmatrix}, y = \begin{bmatrix} u(1) \\ u(2) \\ \cdot \\ \cdot \\ u(N) \end{bmatrix}, \theta = \begin{bmatrix} E \\ R \end{bmatrix} \tag{7}$$

$$m = \Phi\theta \tag{8}$$

- **Part e** The second dataset is noisier. The first dataset assumes Gaussian Noise. The second dataset assumes Uniform Noise.