

# A Well-Balanced Stochastic Galerkin Method for PDEs with Random Forcing

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## Contents

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# 1 Introduction

[Jin2015]

## 2 Preliminaries

## 3 Methods

As we described in the introduction, the scheme we will be working with combines parts of a well-balanced scheme and stochastic galerkin method. As we are working a system of the form

$$u_t + f(u)_x = -b'(x)u \quad (1)$$

At the steady state we have that  $u_t = 0$ , and so (??) becomes the steady state condition

$$f(u)_x + b'(x)u = 0 \quad (2)$$

We will assume that our flux function  $f$  is such that  $\frac{f'(\xi)}{\xi}$  is a well-defined number for all  $\xi$ . We can now define an operator  $D : \mathbb{R} \rightarrow \mathbb{R}$  by

$$D(u) = \int_0^u \frac{f'(\xi)}{\xi} d\xi$$

Now if  $u(x)$  is a strong solution to ?? and  $u > 0$ , then by Liebniz rule

$$D(u(x))_x + b'(x) = \frac{f'(u(x))u_x}{u(x)} + b'(x) = \frac{f(u(x))_x}{u(x)} + b'(x) = 0$$

This shows that if  $u$  is a strong solution to (??) and  $u > 0$ , then  $D(u(x)) + q(x)$  is equal to some constant. If we assume that  $D$  is monotone so that  $D'(x) \neq 0$ , then we can see that

$$u(x) = \frac{f(u)_x}{D'(x)}$$

If we adopt the finite volume framework, then we shall have  $N_x$  cells with uniform mesh size of  $\Delta x$ . For  $j = 1, \dots, N_x$ , we let  $x_j$  represent the point at the center of the cell and let  $x_{j+1/2}$  represent the point at the cell interface. Since we will have a uniform mesh, then  $\Delta x = x_{j+1/2} - x_{j-1/2}$ . We also have a uniform discretization in time and let  $t^n$  represent the discretization at then  $n^{th}$  level and  $\Delta t = t^n - t^{n-1}$ . The cell average at  $t^n$  over  $[x_{j-1/2}, x_{j+1/2}]$  is given by

$$u_j^n = \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^n) dx$$

At the cell interfaces we will have

$$D_{j+1/2} = D(u_{j+1/2})$$

$$\begin{aligned} f_{j+1/2} &= f(u_{j+1/2}) \\ b_{j+1/2} &= b(x_{j+1/2}) \end{aligned}$$

Then discrete analog to (??) will be

$$\begin{aligned} \frac{f_{j+1/2} - f_{j-1/2}}{\Delta x} &= -\frac{(b_{j+1/2} - b_{j-1/2})}{\Delta x} \left( \frac{f_{j+1/2} - f_{j-1/2}}{D_{j+1/2} - D_{j-1/2}} \right) \\ D_{j+1/2} - D_{j-1/2} &= -(b_{j+1/2} - b_{j-1/2}) \\ D_{j+1/2} + b_{j+1/2} &= D_{j-1/2} + b_{j-1/2} = \text{constant} \end{aligned}$$

In particular for the Burgers' equation we have that  $f(u) = \frac{u^2}{2}$ , so  $D(u) = u$  and so

$$\frac{f_{j+1/2} - f_{j-1/2}}{D_{j+1/2} - D_{j-1/2}} = \frac{u_{j+1/2}^2 - u_{j-1/2}^2}{2(u_{j+1/2} - u_{j-1/2})} = \frac{u_{j+1/2} + u_{j-1/2}}{2}$$

It follows that the following semi-discrete method for the Burgers' equation is well-balanced.

$$\partial_t u_j + \left( \frac{u_{j+1/2}^2 - u_{j-1/2}^2}{\Delta x} \right) = - \left( \frac{b_{j+1/2} - b_{j-1/2}}{\Delta x} \right) \left( \frac{u_{j+1/2} + u_{j-1/2}}{2} \right) \quad (3)$$

It is described in [Jin2001] that for a general  $f$  that the scheme is well balanced.

$$\partial_t u_j + \left( \frac{f_{j+1/2} - f_{j-1/2}}{\Delta x} \right) = - \left( \frac{b_{j+1/2} - b_{j-1/2}}{\Delta x} \right) \left( \frac{u_{j+1/2} + u_{j-1/2}}{2} \right) \quad (4)$$

In particular, (??) is a special case of this general formulation. This gives us the formulation for the deterministic well-balancing.

For the stochastic case, we incorporate some uncertainty into our bottom topography via a random variable  $Z : \Omega \rightarrow \mathbb{R}$  with law  $P$ . For every instance of our random variable  $Z$ , let  $u(x, t; Z)$  be the function  $(x, t) \rightarrow u(x, t; Z)$  which solves

$$u_t(x, t; Z) + f(u(x, t; Z))_x = -b(x; Z)u(x, t; Z)$$

If we suppose that we have appropriate integrability conditions so that  $u(x, t; Z), Z \in L^2(P)$  holds for all  $(x, t)$ , then we can use that  $u(x, t; Z)$  will be  $Z$ -measurable. Consider

$$\mathcal{P}_Z = \{\phi(Z) : \phi \text{ is a polynomial of any order}\}$$

Then  $\mathcal{P}_Z$  is a dense vector subspace in the space of all  $Z$ -measurable functions. Since  $\mathcal{P}_Z \subset L^2(P)$  by our integrability assumption on  $Z$  and that  $L^2(P)$  is a Hilbert space, then we can find an orthonormal basis  $\{\Phi_m(Z)\}_{m \in \mathbb{N}}$  of  $\mathcal{P}_Z$ . Thus  $\{\Phi_m(Z)\}_{m \in \mathbb{N}}$  is dense in the space  $Z$ -measurable functions. Then since  $u(x, t; Z)$  is  $Z$ -measurable, then we can find coefficients  $\hat{u}_m(x, t)$  such that  $P$ -almost everywhere we have that

$$u(x, t; Z) = \sum_{m \in \mathbb{N}} \hat{u}_m(x, t) \Phi_m(Z) \quad \hat{u}_m(x, t) = \mathbb{E}[u(x, t; Z) \Phi_m(Z)]$$

$$b(x; Z) = \sum_{m \in \mathbb{N}} \hat{b}_m(x) \Phi_m(Z) \quad \hat{b}_m(x) = \mathbb{E}[b(x; Z) \Phi_m(Z)]$$

We want our scheme to respect our stochastic PDE almost everywhere, this is equivalent to enforcing the condition

$$\mathbb{E}[(\partial_t u(x, t; Z) + f(u(x, t; Z))_x) \Phi_m(Z)] = \mathbb{E}[-b'(x, Z) u(x, t; Z) \Phi_m(Z)] \quad (5)$$

holds for all  $m$ . In the discrete setting, we can only take a finite number of basis elements, so let  $N$  represent the number of nodes that we are considering. Then the galerkin approximation of  $u$  and  $b$  in terms of  $Z$  is given by

$$u_N(x, t; Z) = \sum_{m=1}^{N+1} \hat{u}_m(x, t) \Phi_m(Z)$$

$$b_N(x; Z) = \sum_{m=1}^{N+1} \hat{b}_m(x) \Phi_m(Z)$$

If we fix  $t$ , then let  $u_{N,j} = u_N(x_j, t; Z)$  where the right hand side is the cell average over  $[x_{j-1/2}, x_{j+1/2}]$ . We take  $u_{j+1/2} \approx u_j$  and similarly for the other components to get that with (??) we have that scheme

$$\partial_t u_{N,j} + \left( \frac{f(u_{N,j}) - f(u_{N,j-1})}{\Delta x} \right) = - \left( \frac{b_{N,j} - b_{N,j-1}}{\Delta x} \right) \left( \frac{u_{N,j} + u_{N,j-1}}{2} \right)$$

If we then enforce the condition (??), we derive the following condition on the scheme we construct

$$\mathbb{E} \left[ \left( \partial_t u_{N,j} + \left( \frac{f(u_{N,j}) - f(u_{N,j-1})}{\Delta x} \right) \right) \Phi_m(Z) \right] = - \mathbb{E} \left[ \left( \frac{b_{N,j} - b_{N,j-1}}{\Delta x} \right) \left( \frac{u_{N,j} + u_{N,j-1}}{2} \right) \Phi_m(Z) \right] \quad (6)$$

If we set  $\mathbf{u}_j = (\hat{u}_{1,j}, \dots, \hat{u}_{N+1,j})^T$ , define  $E$  to be the tensor with components  $e_{klm} = \mathbb{E}[\Phi_k \Phi_l \Phi_m]$  and  $D$  to be the tensor with components  $d_{klmnp} = \mathbb{E}[\Phi_k \Phi_l \Phi_m \Phi_n \Phi_p]$  and where  $1 \leq k, l, m, n, p \leq N+1$ . We then define matrices  $A_j, S, B$  to satisfy

$$A_{kl,j} = \sum_{m=1}^{N+1} e_{klm} \hat{u}_{m,j}$$

$$B_{kl,j} = \sum_{m=1}^{N+1} e_{klm} \hat{b}_{m,j}$$

$$S_{kl,j} = \sum_{m,n,p=1}^{N+1} d_{klmnp} \hat{u}_{m,j} \hat{u}_{n,j} \hat{u}_{p,j}$$

If  $f(u) = \frac{u^2}{2}$ , then a scheme which satisfies (??) and (??) is

$$\partial_t \mathbf{u}_j + \frac{A_j \mathbf{u}_j - A_{j-1} \mathbf{u}_{j-1}}{2\Delta x} = - \frac{(B_j - B_{j-1})(\mathbf{u}_j + \mathbf{u}_{j-1})}{2\Delta x}$$

If  $f(u) = \frac{u^4}{4}$ , then a scheme which satisfies the stochastic condition and the well-balancing condition is

$$\partial_t \mathbf{u}_j + \frac{s_j \mathbf{u}_j - S_{j-1} \mathbf{u}_{j-1}}{4\Delta x} = -\frac{(B_j - B_{j-1})(\mathbf{u}_j + \mathbf{u}_{j-1})}{2\Delta x}$$

## 4 Results

## 5 Conclusion