

Andrew's Ng

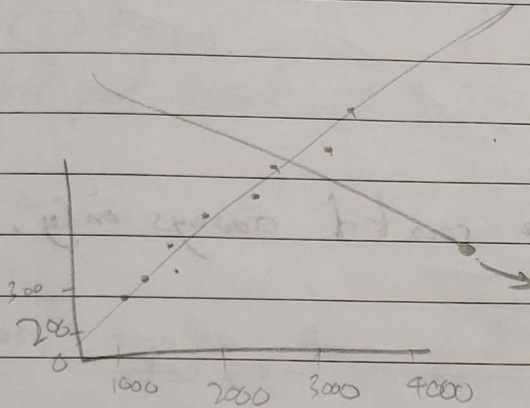
y's \rightarrow output variable / target value

Scanned by CamScanner

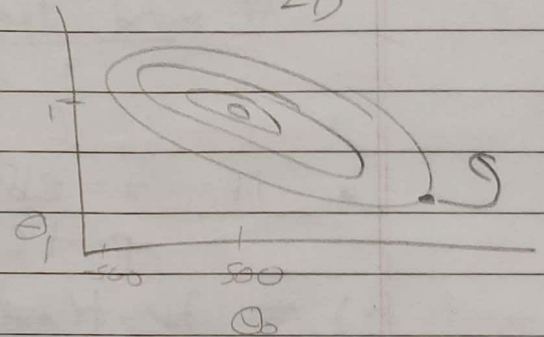
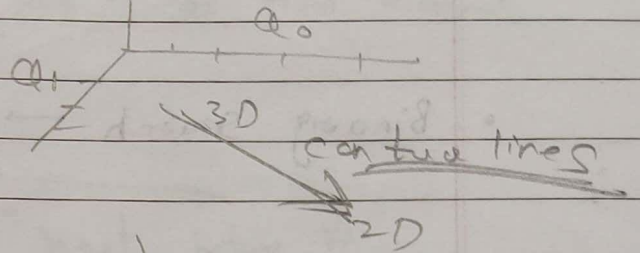
nothing is fixed here

$$h_0(x)$$

$$J(\theta_0, \theta_1)$$



$$J(\theta_0, \theta_1)$$

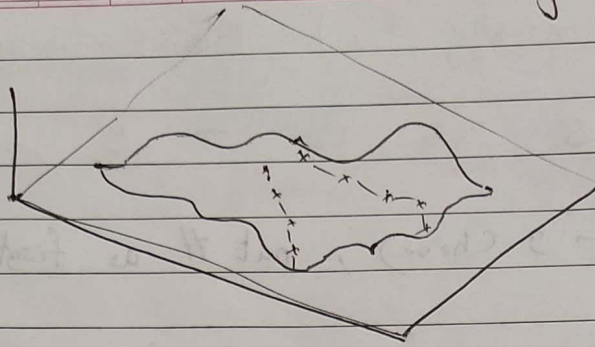


Gradient Descent

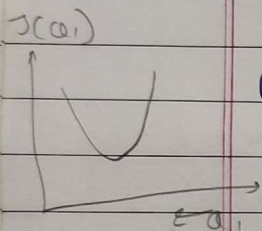
Page No: 3

Date: / /

Gradient Descent Algo.



Depending on starting point, the local minima changes.



$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \quad (\text{for } j=0 \text{ \& } j=1)$$

learning rate

derivative

First calculate RHS & update θ_0, θ_1 simultaneously.

Correct: simultaneous update | Incorrect:

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) \quad \text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1) \quad \theta_0 := \text{temp0}$$

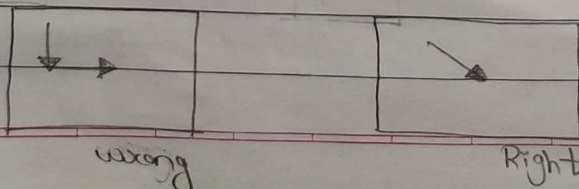
$$\theta_0 := \text{temp0}$$

$$\text{temp1} := \text{temp} \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

$$\theta_1 := \text{temp1}$$

$$\theta_1 := \text{temp1}$$

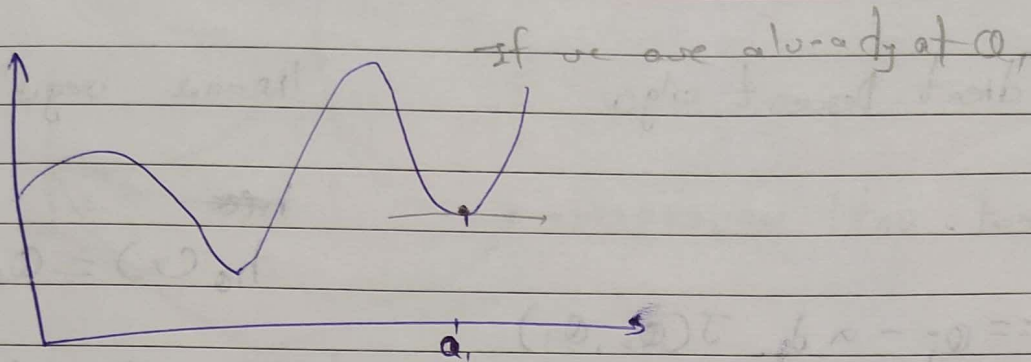
We want to move in steepest direction in each step, that's why we want simultaneous update.



wrong

Right

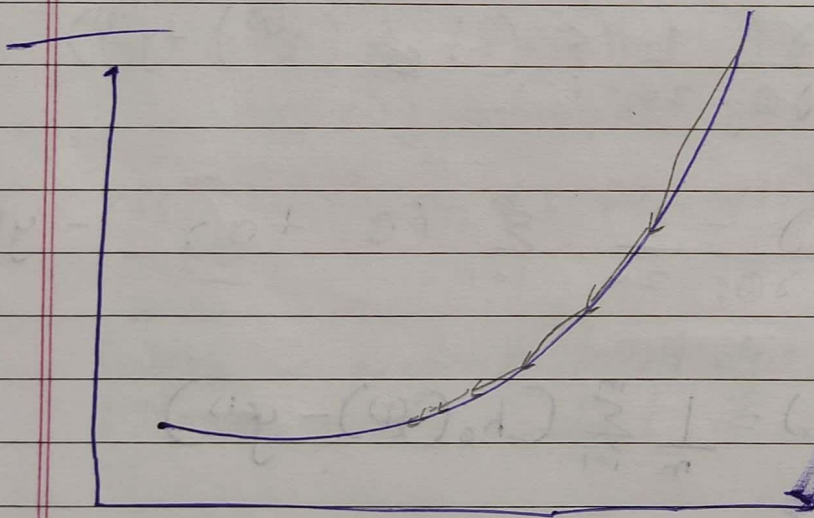
Gradient Descent Intuition



$$\alpha_1 := \alpha_0 - \alpha \frac{d}{d\alpha} J(\alpha_0)$$

\searrow
 $\rightarrow 0$

no change in α .



derivation from ϕ 's,
that's why step
 ϕ 's

so, don't have to
change α over time.

-- @ Gradient Descent for Linear Regression --

Gradient Descent algo

linear regⁿ model.

repeat until convergence

~~here~~

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

(for $j=1$ & $j=0$) $\rightarrow \theta_0, \theta_1$

$$\frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) = \frac{\partial}{\partial \theta_j} \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

$$= \frac{\partial}{\partial \theta_j} \frac{1}{2m} \sum_{i=1}^m (\theta_0 + \theta_1 x^{(i)} - y^{(i)})^2$$

$$\text{Q. } j=0: \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$$

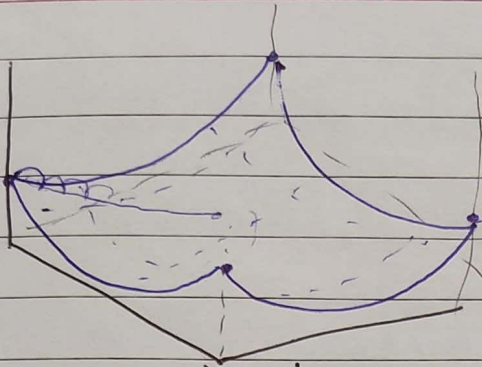
$$\text{Q. } j=1: \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1) = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x^{(i)}$$

Gradient descent for simple linear regⁿ

$$\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$$

$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x^{(i)}$$

update θ_0 & θ_1 simultaneously



convex function \rightarrow for linear regⁿ
only one global minimum
no local minimum

"Batch" Gradient Descent

"Batch": Each step of gradient descent uses $\left[\begin{matrix} \text{all } x \\ \text{all } y \end{matrix} \right]$ training examples.

$$\rightarrow \sum_{i=1}^m (h(x^{(i)}) - y^{(i)})$$

There are gradient descent algos which are not batch, looks in specific subset of training set.

★ Normal equation methods:-

Directly solves for θ_0, θ_1 .

Gradient Descent scales better to larger data sets than a normal equation method.

--- @ Matrices and Vectors ---
linear algebra

Sadguru

Page No: 7

Date: / /

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \\ 7 & 8 \end{bmatrix}$$

$$A_{11} = 1$$

$$A_{12} = 2$$

4x2 matrix

$$\mathbb{R}^{4 \times 2}$$

Vector matrix : $n \times 1$ matrix

$$y = \begin{bmatrix} 960 \\ 232 \\ 315 \\ 178 \end{bmatrix}$$

\mathbb{R}^4