Cloud Computing CPU Allocation and Scheduling Algorithms Using CloudSim Simulator

FCFS

- Algorithm is based on the arrival time of the resource request.
- AwT = $(\sum Tn) / NT$
- Where AwT Average Waiting Time, Tn: Tasks Waiting time for execution, NT: Number of tasks

SJF

- Choose the task with the shortest execution time in order to take the lead of the queue and then FCFS way.
- AwT = $(\sum Tn) / NT$
- Where AwT Average Waiting Time, Tn: Tasks Waiting time for execution, NT: Number of tasks

RR (static time quantum)

- Tasks submitted to VM sorted in ascending order based on burst time (execution time for each task)
- Computing time quantum
 - \circ TQ = (NP * MIPS) / 1000
 - TQ (Time Quantum), NP (Number of Processors), MIPS (Millions Instruction per second)
- For each task in the queue list
 - o CPU allocates the time quantum for task execution
 - o If task executed, sent to finished list
 - o If task not executed, sent to waiting list.

RR (dynamic time quantum)

- Tasks submitted to VM sorted in ascending order based on burst time (execution time for each task).
- Computing time quantum
 - $TQ = \sum Tn / NT$
 - TQ (Time Quantum), Tn (task burst time), NT(Number of tasks)
- For each task on the queue list
 - If task burst time < time quantum
 - Time quantum = task burst time
 - CPU allocates time quantum for task execution
 - Task executed, sent to finish list
 - If task burst time > time quantum
 - CPU allocates time quantum for task execution
 - Task sent to the waiting list
 - If waiting list not empty
 - Send tasks from waiting list to queue list.

Analysis of Job Scheduling Algorithms in Cloud Computing

FCFS

- Initialize tasks
- First task assigned to the queue and add task up to n numbers
- Add next tan in the main queue

- for i = 0 to i < main queue-size
 - o if task i+1 length < task i length
 - add task i+1 in front of task i in the queue

Improved Max-Min Algorithm in Cloud Computing

Max-Min

- 1. for all submitted tasks in meta-task; Ti
- for all resources; R_i
- 3. Cij = Eij + rj
- 4. While meta-task is not empty
- find task T_kconsumes <u>maximum completion time</u>.
- assignT_k to the resource R_j which gives <u>minimum</u> execution time.
- remove T_k from meta-tasks set
- 8. update rj for selected Rj
- 9. update Cij for all j

Improved Max-Min

- 1. for all submitted tasks in meta-task; T_i
- for all resources; R_i
- 3. Cij = Eij + rj
- While meta-task is not empty
- find task T_kcosts maximum execution time.
- 6. $assignT_k$ to the resource R_j which gives $\underline{\textit{minimum}}$ $\underline{\textit{completiontime}}$.
- 7. remove T_k from meta-tasks set
- update r_i for selected R_i
- update Cij for all j

COMPARATIVE STUDY OF SCHEDULING AL-GORITHMS IN CLOUD COMPUTING ENVIRONMENT

Random Algorithm

```
1 Nocl ← cloudletlist.size();
2 NoVM ← VML.size();
3 index \leftarrow 0;
4 for j ← 0 to Nocl do
5 cl \leftarrow cloudletlist.get(j);
6 index ← random() × (NoVM - 1);
7 v \leftarrow VML.get(index);
8 stagein \leftarrow TransferTime(cl, v, in);
9 stageout ← TransferTime(cl, v, out);
10 exec ← ExecuteTime(cl, v);
11 if (cl.AT + stagein + exec + stageout + v.RT \le cl.DL) then
12 sendjob(cl, v);
13 update(v);
14 else
15 Drop(cl);
16 FailedJobs;
17 endif
```

Round Robin algorithm

```
1 Nocl ← cloudletlist.size();
2 NoVM ← VML.size();
3 index \leftarrow 0;
4 for j \leftarrow 0 to Nocl do
5 cl ← cloudletlist.get(j);
6 index ← (index+1) mod NoVM;
7 v \leftarrow VML.get(index);
8 stagein ← TransferTime(cl, v, in);
9 stageout \leftarrow TransferTime(cl, v, out);
10 exec \leftarrow ExecuteTime(cl, v);
11 if (cl.AT + stagein + exec + stageout + v.RT \le cl.DL) then
12 sendjob(cl, v);
13 update(v);
14 else
15 Drop(cl);
16 FailedJobs:
17 end
```

Minimum Completion Time

```
1 initialization:
2 Nocl ← cloudletlist.size();
3 NoVM ← VML.size();
4 index \leftarrow 0:
5 for j \leftarrow 0 to Nocl do
6 cl ← cloudletlist.get(j);
7 min ← +∞:
8 for i \leftarrow 0 to NoVM do
9 v ← VML.get(i);
10 if min > (v.getready() + cl.getlength()/v.speed) then
11 min ← v.getready() + cl.getlength()/v.speed;
12 index \leftarrow i:
13 end
14 end
15 v ← VML.get(index);
16 stagein ← TransferTime(cl, v, in);
17 stageout \leftarrow TransferTime(cl, v, out);
18 exec \leftarrow ExecuteTime(cl, v);
19 if (cl.AT + stagein + exec + stageout + v.RT \le cl.DL) then
20 sendjob(cl, v);
21 update(v);
22 else
23 Drop(cl);
24 FailedJobs:
25 end
```

Opportunistic Load balancing algorithm

```
1 initialization;
2 Nocl ← cloudletlist.size();
3 NoVM ← VML.size();
4 index \leftarrow 0;
5 for j \leftarrow 0 to Nocl do
6 cl ← cloudletlist.get(j);
7 min \leftarrow +\infty;
8 for i \leftarrow 0 to NoVM do
9 v \leftarrow VML.get(i);
10 if min \ge (v.getready()) then
11 min ← v.getready();
12 index \leftarrow i;
13 end
14 end
15 v \leftarrow VML.get(index);
16 stagein ← TransferTime(cl, v, in);
17 stageout \leftarrow TransferTime(cl, v, out);
18 exec \leftarrow ExecuteTime(c, v);
19 if (cl.AT + stagein + exec + stageout + v.RT \le cl.DL) then
20 sendjob(cl, v);
21 update(v);
22 else
23 Drop(cl);
24 FailedJobs:
25 end
```

RASA: A New Task Scheduling Algorithm in Grid Environment

Min-Min

- for all tasks T_i in meta-task M_v
- for all resources R_i
- $C_{ij}=E_{ij}+r_i$
- 4. do until all tasks in M_v are mapped
- 5. for each task in M_v find the earliest

completion time and the resource that obtines it

- find the task T_k with the <u>minimum</u> earliest completion time
- 7. assigne task T_k to the resource R_l that gives the

earliest completion time

- 8. delete task T_k from M_v
- update r_I
- 10. update C_{il} for all i
- 11.end do

Max-Min

- 1. for all tasks T_i in meta-task M_v
- for all resources R_i
- 3. $C_{ij}=E_{ij}+r_j$
- 4. do until all tasks in M_v are mapped
- for each task in M_v find the earliest completion time and the resource that obtines it

6. find the task T_k with the maximu earliest

completion time

- assigne task T_k to the resource R_l that gives the earliest completion time
- 8. delete task T_k from M_v
- 9. update r_I
- 10. update C_{il} for all i
- 11.end do

Resource aware scheduling algorithm

1. for all tasks T_i in meta-task M_v	
2. for al	l resources R_j
3.	$C_{ij}=E_j+r_j$
4. do until a	Il tasks in M_{ν} are mapped
5. if the	number of resources is even then
6.	for each task in M_v find the earliest completion
	time and the resource that obtines it
7.	find the task T_k with the maximum earliest
	completion time
8.	assigne task T_k to the resource R_l that gives the
	earliest completion time
9.	delete task T_k from M_v
10.	update r_l
11.	update C_{il} for all i
12. else	
13.	for each task in M_v find the earliest completion
	time and the resource that obtines it
14.	find the task T_k with the minimum earliest
	completion time
15.	assigne task T_k to the resource R_l that gives the
	earliest completion time
16.	delete task T_k from M_v
17.	update r_l
18.	update C_{il} for all i
19. end i 1	
20. end do	

Efficient Task Scheduling Algorithms for Cloud Computing Environment

Longest Cloudlet Fastest Processing element (LCFP)

- Sort the cloudlets in descending order of length.
- Sort the PEs across all the hosts in descending order of processing power.
- Create virtual machines in the sorted list of PEs by packing as many VMs as possible in the fastest PE.
- Map the cloudlets from the sorted list to the created VM.

Shortest Cloudlet Fastest Processing element (SCFP)

- Sort the cloudlets in ascending order of length.
- Sort the PEs across all the hosts in descending order of processing power.
- Create virtual machines in the sorted list of PEs by packing as many VMs as possible in the fastest PE.
- Map the cloudlets from the sorted list to the created VM.

Task Scheduling in Cloud Computing: A Survey

A Comparison Study of Eleven Static Heuristics for Mapping a Class of Independent Tasks onto Ileterogeneous Distributed Computing Systems

A SURVEY ON ECONOMIC CLOUD SCHEDULERS FOR OPTIMIZED TASK SCHEDULING

Study and Analysis of Various Task Scheduling Algorithms in the Cloud Computing Environment

Dynamic Mapping of a Class of Independent Tasks onto Heterogeneous Computing Systems