

Task 1 :

```
✓ ▶ %!prun -f res_cvimage res_cvimage(imgs)
```

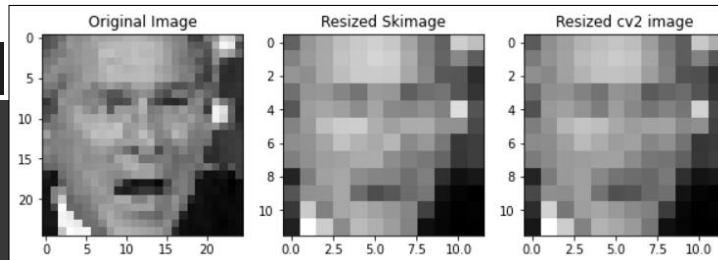
Timer unit: 1e-09 s

Total time: 0.00209092 s

File: <ipython-input-9-93f758906d52>

Function: res_cvimage at line 5

Line #	Hits	Time	Per Hit	% Time	Line Contents
=====					
5					def res_cvimage(imgs):
6	1	13325.0	13325.0	0.6	new_size = (imgs[0].shape[0]//2, imgs[1].shape[1]//2)
7	1	347.0	347.0	0.0	res_im = []
8	200	101751.0	508.8	4.9	for im in imgs:
9	200	1731026.0	8655.1	82.8	image_resized = cv2.resize(im, new_size, interpolation =
cv2.INTER_AREA)					
10	200	89674.0	448.4	4.3	res_im.append(image_resized)
11	1	154794.0	154794.0	7.4	return np.asarray(res_im)



In **task 1**, I have used the function `cv2.resize()` which increases the speed of the code and takes less time that is 82.8%.

As `cv2.resize` is a function from OpenCV library written in C++, which is much faster than Python.

Also OpenCV utilize multiple CPU cores to process images which improves the performance of `cv2.resize()` function.

Task 2 :

MULTI PROCESSING

```
%%timeit
def approximate_pi_multiprocessing(nums):
    def worker_process(queue, n):
        pi_2 = 1
        nom, den = 2.0, 1.0
        for i in range(n):
            pi_2 *= nom / den
            if i % 2: nom += 2
            else: den += 2
        queue.put(2*pi_2)
    queue = multiprocessing.Queue()
    processes = []
    for n in nums:
        process = multiprocessing.Process(target=worker_process,
                                         args=(queue, n))
        processes.append(process)
        process.start()

    for process in processes:
        process.join()

    pi_values = []
    while not queue.empty():
        pi_values.append(queue.get())
    return pi_values

63.1 ns ± 9.28 ns per loop (mean ± std. dev. of 7 runs, 1000000 loops each)
```

In **task 2**, the Multi Processing is faster than Multi Threading because it is a CPU bound task which is running in parallel for calculating the approximate pi. Here, multiprocessing has multiple CPU cores when compared to multithreading which is having a single core.

MULTI THREADING

```
%%timeit
def approximate_pi_multithread(nums):
    def worker_thread(queue, n):
        pi_2 = 1
        nom, den = 2.0, 1.0
        for i in range(n):
            pi_2 *= nom / den
            if i % 2:
                nom += 2
            else:
                den += 2
        queue.put(2*pi_2)

    queue = queue.Queue()
    threads = []
    for n in nums:
        thread = threading.Thread(target=worker_thread, args=(queue, n))
        threads.append(thread)
        thread.start()

    for thread in threads:
        thread.join()

    pi_values = []
    while not queue.empty():
        pi_values.append(queue.get())

    return pi_values

72.5 ns ± 1.12 ns per loop (mean ± std. dev. of 7 runs, 1000000 loops each)
```

Task 3 :

MULTI THREADING

```
%%timeit
def load_array_threading(filenamees):
    def worker_thread(filename, data):
        data.append((filename, np.load(filename)))

    data = []
    threads = []

    for filename in filenamees:
        thread = threading.Thread(target=worker_thread, args=(filename, data))
        threads.append(thread)
        thread.start()

    for thread in threads:
        thread.join()

    return data

74.8 ns ± 1.39 ns per loop (mean ± std. dev. of 7 runs, 1000000 loops each)
```

MULTI PROCESSING

```
%%timeit
def load_array(filenamees):
    with concurrent.futures.ProcessPoolExecutor() as executor:
        futures = {executor.submit(np.load, filename):filename for filename in filenamees}
        result = {}

    for future in concurrent.futures.as_completed(futures):
        filename = futures[future]
        if future.exception() is None:
            result[filename] = future.result()
        else:
            print(f'{filename} generated an exception: {future.exception()}')
    return result

70.5 ns ± 0.599 ns per loop (mean ± std. dev. of 7 runs, 1000000 loops each)
```

In **task 3**, the Multi Processing is faster than Multi threading because `concurrent.futures` library provides a higher level interface for creating and managing threads which simplifies the code.

But, generally, for I/O bound tasks, using multiple threads is faster.

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