

Model Checking Temporal Aspects of Inconsistent Concurrent Systems Based on Paraconsistent Logic

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Abstract

Classical logic cannot be used to effectively reason about concurrent systems with inconsistencies (inconsistencies often occur, especially in the early stage of the development, when large and complex concurrent systems are developed). In this paper, we propose the use of a paraconsistent temporal logic (QCTL) for supporting the verification of temporal properties of such systems even where the consistent model is not available. We introduce a novel notion of paraKripke models, which grasps the paraconsistent character of the entailment relation of QCTL. Furthermore, we explore the methodology of model checking over QCTL, and describe the detailed algorithm of implementing QCTL model checker. In the sequel, a simple example is presented, showing how to exploit the proposed model checking technique to verify the temporal properties of inconsistent concurrent systems.

Key words: inconsistency, concurrent systems, paraconsistent temporal logic, model checking

1 Introduction

In recent years, model checking [1] has become an established technique for automatically verifying the correctness of finite-state concurrent systems. The technique has been effectively applied to reasoning about correctness of hardware, communication protocols, and software engineering, etc.

For the purpose of research and practice, a number of model checkers have been developed, including SPIN [2] and VIS [3]. Despite their variety, the existing model checkers are typically based on classical logic, and cannot

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be therefore used to reason about the specifications of concurrent systems containing uncertain or inconsistent information.

To the best of our knowledge, classical logic is very appealing for formal representation of specifications of concurrent systems and reasoning due to its expressivity and reasoning power. Unfortunately, inconsistency causes problems in reasoning with classical logic. In classical logic, anything can follow from an inconsistent set of assumptions, that is, inconsistency leads to trivial and meaningless reasoning. However, it has been figured out that inconsistency is an unavoidable phenomena in the development of large and complex concurrent systems [4]. In requirements engineering, models are frequently inconsistent because they combine conflicting points of view. During design and implementation, inconsistency arises when integrating components developed by different members. A significant proportion of the specification analysis process is then devoted to detecting and eliminating such inconsistencies because inconsistencies are traditionally regarded as undesirable. But from beginning to end, especially at the early stage, maintaining absolute consistency is not always possible. Often this is not even desirable since this can unnecessarily constrain the development process, can lead to the loss of important information [5]. Thus, there has been a considerable amount of research on the development of technique and tools providing practical support for how to manage inconsistencies in a more general fashion and possibly reason in the presence of inconsistencies [6,7,8].

Paraconsistent logics and multi-valued logics [9,10] provide us with new logical foundations suited for reasoning under inconsistency. Paraconsistent logics [11,12], which are weaker than classical logics and permit some contradictions to be true, achieve nontrivial reasoning under inconsistency by non-standard behavior of logical connectives, by restricting proof systems, and all that. To take full advantage of paraconsistent logics, developers do not have to roughly reject system specifications with any inconsistent information anymore, but analyze them in a more rational fashion. However, there have been relatively few attempts to develop automated reasoning tools for inconsistent models at present, and a majority of work is limited to paraconsistent logics themselves. Some notable exceptions are Hunter, Nuseibeh, and Riarka [7,13], who use a paraconsistent logic QCL to reason about evolving specifications. Additionally, following the idea of the paraconsistent logic QCL [7], presented by Hunter, et al., in this paper we present paraconsistent logic termed QCTL by extending QCL with the ability to specify the temporal aspects of concurrent systems. Further, we study the problem of model checking over the paraconsistent temporal logic QCTL.

The rest of this paper is organized as follow: Section 2 simply introduces the language of QCTL. Section 3 detailedly discusses the problem of model checking over QCTL. To motivate our work, Section 4 presents an example, showing the proposed model checking technique the power of model checking the expected temporal properties of an inconsistent concurrent system. Sec-

tion 5 summarizes the paper. For lack of space, all involved proofs have been omitted.

2 Paraconsistent temporal logic QCTL

2.1 Syntax

The syntax of QCTL is that of CTL, but they are very different in essence. QCTL is based on the paraconsistent logic methodology, whereas CTL is based on classical propositional logic. This fact leads to great difference in proof systems and semantics.

Temporary operators are introduced as follows: \bigcirc – at the next state, \Diamond – eventually, \Box – always, and U – until. Moreover, the two path quantifiers E and A have the intuitive meaning “there is a path” and “for all paths”, respectively.

Let \mathcal{P} denote a set of atomic propositions. Formulas of QCTL have the following abstract syntax, where p ranges over \mathcal{P} :

$$\alpha := p \mid \neg\alpha \mid \alpha_1 \wedge \alpha_2 \mid \alpha_1 \vee \alpha_2 \mid \text{E}(\text{A}) \bigcirc \alpha \mid \text{E}(\text{A}) \Diamond \alpha \mid \text{E}(\text{A}) \Box \alpha \mid \text{E}(\text{A})(\alpha_1 \text{U} \alpha_2)$$

Let \mathcal{L} denote the set of formulas by the above abstract syntax. Moreover, $\alpha \rightarrow \beta$ is the abbreviation for $\neg\alpha \vee \beta$ as usual. Conventionally for each $p \in \mathcal{P}$, p or $\neg p$ is called a literal. A formula of the form $l_1 \vee \dots \vee l_n$ for $n \geq 1$ is called a clause, where l_1, \dots, l_n are literals. Furthermore, we provide some basic definitions preparing for the following work.

Definition 2.1.1 Such formula in the form of $\sigma(\alpha \text{U} \beta)$, $\neg\sigma(\alpha \text{U} \beta)$, $\sigma\mathbf{x}\alpha$ or $\neg\sigma\mathbf{x}\alpha$ for $\alpha, \beta \in \mathcal{L}$ is called a quasi-literal, where σ represents the path quantifier E or A and \mathbf{x} represents one of the temporal operators \bigcirc, \Box, \Diamond . $l_1 \vee \dots \vee l_n \vee ql_1 \vee \dots \vee ql_m \in \mathcal{L}$ is called a quasi-clause, where $\forall i. 1 \leq i \leq n$, l_i is a literal and $\forall i. 1 \leq i \leq m$, ql_i is a quasi-literal. Moreover, a clause or quasi-literal is a special quasi-clause.

In the sequel, σ and \mathbf{x} have the above meaning in the context, when they are not explicitly interpreted.

Definition 2.1.2 Let F be the smallest set of formulas generated by finitely applying the following rules:

1. For $p \in \mathcal{P}$, $p, \neg p \in F$.
2. Let $\alpha, \beta \in F$, and α, β be two quasi-clauses, then $\alpha \vee \beta \in F$.
3. For $\alpha, \beta \in F$, $\alpha \wedge \beta \in F$.
4. For $\alpha, \beta \in F$, $\sigma\mathbf{x}\alpha, \sigma(\alpha \text{U} \beta) \in F$.

any $\alpha = \alpha_1 \wedge \dots \wedge \alpha_n \in F$ for $n \geq 1$ is called a complete-CNF, and for $1 \leq i \leq n$, α_i is called a complete-clause.

The purpose of defining the set of formulas F is that it helps us to compute a important set $Fact_s(\alpha)$ for $\alpha \in \mathcal{L}$ used in implementing the algorithm of model checking over QCTL, and to establish a concise proof of the completeness of the proof system for QCTL.

QCTL has the same syntax with the classical temporal logic CTL. It differs from CTL at the semantic level. This is exactly the point making QCTL a paraconsistent logic.

2.2 Semantics

QCTL is motivated by the need to reason about concurrent systems with inconsistent specifications. The notion of truth or falsity is thus discarded. We here view each formula as a belief, following the idea in [7]. QCTL achieves the paraconsistent methodology by decoupling the relationship between a formula and its negation at the level of semantics. To reach this aim, a set of positive and negative objects is first constructed from the set \mathcal{P} of atomic propositions. For each $p \in \mathcal{P}$, $+p$ is called a positive object and $-p$ a negative object.

Definition 2.2.1 The set of positive and negative objects in QCTL is defined as $\mathcal{O} = \{+p \mid p \in \mathcal{P}\} \cup \{-p \mid p \in \mathcal{P}\}$.

Kripke structures are widely used as semantic models of temporal logics such as CTL [14]. We here provide QCTL with a novel semantics by extending Kripke structures to paraKripke structures.

Definition 2.2.2 A tuple $M = (S, R, L)$ is called a paraKripke structure, where

- S is a non-empty state set.
- $R \subseteq S \times S$ is a total relation, which implies for each $s \in S$ there exists $t \in S$ satisfying $(s, t) \in R$.
- $L : S \mapsto 2^{\mathcal{O}}$ is a label function, which labels each state with a set of the positive or negative objects.

ParaKripke structures are similar to the general Kripke structures except for the label functions. But it is the label function that grasps the essential idea behind the structures. In a paraKripke structure, the states are labeled by positive or negative objects included in \mathcal{O} . ParaKripke structures will be used as the semantic model of QCTL.

Definition 2.2.3 Let $M = (S, R, L)$ be a paraKripke structure. A computing path x of M is defined as $x = (s_1, \dots, s_i, \dots)$, where for all $i \geq 1$, $s_i \in S$ and $(s_i, s_{i+1}) \in R$. s_1 is called the initial state of x , and (s_1, \dots, s_k) for $k \geq 1$ an initial prefix of x .

Before defining the satisfiability relation in QCTL, we first present the satisfiability notion of a literal belief in a state. For a paraKripke structure $M = (S, R, L)$, let $s \in S$, $E_s = L(s)$ and $p \in \mathcal{P}$. Then (1) p is satisfiable in s iff $+p \in E_s$, and (2) $\neg p$ is satisfiable in s iff $-p \in E_s$.

From the above discussion, we see that paraKripke structures incorporate the notion of belief, in which it is possible that both an atomic proposition and its negation are satisfiable in a same state, that is, a state can be labeled by $+p$ and $-p$ for $p \in \mathcal{P}$. Therefore, QCTL decouples the link between a formula and its negation at the level of semantics. This makes it a paraconsistent logic.

For achieving the non-trivial inference under inconsistencies, a proof procedure in QCTL is a two-stage affair: decompositional steps followed by compositional steps, by which the trivial reasoning is avoided under inconsistency. The details can be found in the full vision of the paper. To capture this idea, we need to establish two satisfiability relations for both stages called the strong satisfiability relation and the weak satisfiability relation. The notion of strong satisfaction corresponds to the decompositional phase and the notion of weak satisfaction corresponds to the compositional phase, respectively.

Definition 2.2.4 Let $M = (S, R, L)$ be a paraKripke structure. The strong satisfiability relation \models_{ts} is defined as follows:

1. For atomic formula p , $(M, s) \models_{ts} p$ iff $+p \in L(s)$.
2. For atomic formula p , $(M, s) \models_{ts} \neg p$ iff $-p \in L(s)$.
3. $(M, s) \models_{ts} \alpha \wedge \beta$ iff $(M, s) \models_{ts} \alpha$ and $(M, s) \models_{ts} \beta$.
4. For a clause $\alpha = l_1 \vee \dots \vee l_n$, where l_1, \dots, l_n are literals, $(M, s) \models_{ts} \alpha$ iff $\exists i. 1 \leq i \leq n$, $(M, s) \models_{ts} l_i$ and $\forall i. 1 \leq i \leq n$, $(M, s) \models_{ts} \neg l_i$ implies $(M, s) \models_{ts} Disj(\alpha, l_i)$, where $Disj(\alpha, l_i)$ is the original formula $l_1 \vee \dots \vee l_n$ without the disjunct l_i .
5. For a quasi-clause $\alpha = l_1 \vee \dots \vee l_n \vee ql_1 \vee \dots \vee ql_m$, $(M, s) \models_{ts} \alpha$ iff $(M, s) \models_{ts} l_1 \vee \dots \vee l_n$ or $\exists i. 1 \leq i \leq m$, $(M, s) \models_{ts} ql_i$, where l_1, \dots, l_n are literals, and ql_1, \dots, ql_m are quasi-literals.
6. $(M, s) \models_{ts} E\bigcirc \alpha$ iff there is $t \in S$ satisfying $(s, t) \in R$ and $(M, t) \models_{ts} \alpha$.
7. $(M, s) \models_{ts} A\bigcirc \alpha$ iff for all $t \in S$ with $(s, t) \in R$, $(M, t) \models_{ts} \alpha$.
8. $(M, s) \models_{ts} E\Diamond \alpha$ iff there is a computing path $x = (s_0, \dots, s_n, \dots)$ with $s_0 = s$ and $\exists i. i \geq 1$, $(M, s_i) \models_{ts} \alpha$.
9. $(M, s) \models_{ts} A\Diamond \alpha$ iff for all computing paths with initial state s , $(M, s) \models_{ts} E\Diamond \alpha$.
10. $(M, s) \models_{ts} E(\alpha \cup \beta)$ iff there is an initial prefix (s_0, \dots, s_k) of a computing path x with the initial state $s_0 = s$, satisfying that $(M, s_k) \models_{ts} \beta$ and $(M, s_i) \models_{ts} \alpha$ for all $i < k$.
11. $(M, s) \models_{ts} A(\alpha \cup \beta)$ iff for all computing paths with initial state s , $(M, s) \models_{ts} E(\alpha \cup \beta)$.
12. $(M, s) \models_{ts} E\Box \alpha$ iff there is a computing path $x = (s_0, \dots, s_n, \dots)$ with $s_0 = s$ and $\forall i. i \geq 0$, $(M, s_i) \models_{ts} \alpha$.

13. $(M, s) \models_{ts} \mathbf{A}\Box\alpha$ iff for each computing path $x = (s_0, \dots, s_n, \dots)$ with the initial state $s_0 = s$, $(M, s_i) \models_{ts} \alpha$, where $i \geq 0$.

Definition 2.2.5 The weak satisfiability relation \models_{tw} is defined as follows:

- In all the items except for the fourth in Definition 2.2.4, \models_{ts} is replaced by \models_{tw} .
- For a clause $\alpha = l_1 \vee \dots \vee l_n$, $(M, s) \models_{tw} \alpha$ iff $\exists i. 1 \leq i \leq n, (M, s) \models_{tw} l_i$.

The strong satisfiability is much more restricted than the weak satisfiability relation with regard to disjunction, as shown in the fourth and fifth items of Definition 2.2.4. The reason we need such motivation is that we have decoupled the link between a formula and its negation. By putting the link between each disjunct in a quasi-clause and its negation into the definition for disjunction, we, on the one hand, to some degree provide the meaning of negation operator \neg , on the other hand, provide a semantics account for paraconsistent reasoning using resolution.

Clearly, the strong and weak satisfiability relations do not cover all formulae in \mathcal{L} . For instance, $\alpha \wedge (\beta \vee \gamma)$ and $\neg \mathbf{E}\Diamond\alpha$, where $\alpha, \beta, \gamma \in \mathcal{L}$, therefore we need to extend Definition 2.2.4 and 2.2.5. Before accomplishing this work, we define a binary relation \approx_t on \mathcal{L} .

Definition 2.2.6 Let $\alpha, \beta \in \mathcal{L}$. $\alpha \approx_t \beta$ iff for every paraKripke structure $M = (S, R, L)$ and every $s \in S$, $(M, s) \models_{ts} \alpha$ ($(M, s) \models_{tw} \alpha$) implies $(M, s) \models_{ts} \beta$ (respectively, $(M, s) \models_{tw} \beta$), and vice versa.

Proposition 2.2.1 \approx_t is an equivalence relation on \mathcal{L} .

For defining full semantics of QCTL, we make the strong and weak satisfiability relations cover all formulae in \mathcal{L} by extending Definition 2.2.4 and 2.2.5. The strong and weak satisfiability models of formulae of the form $\neg\sigma\mathbf{x}\alpha$ and $\neg\sigma(\alpha \mathbf{U} \beta)$ can be indirectly defined as E'1-E'6 by \approx_t . In a similar way, we further define the full behavior of \neg, \vee , and \rightarrow as E1-E7 in order that the strong and weak satisfiability relations cover all formulas in \mathcal{L}_t .

- | | |
|---|--|
| E1. $\neg\neg\alpha \vee \beta \approx_t \alpha \vee \beta$ | E'1. $\neg\mathbf{E} \bigcirc \alpha \approx_t \mathbf{A} \bigcirc (\neg\alpha)$ |
| E2. $\neg(\alpha \wedge \beta) \vee \gamma \approx_t \neg\alpha \vee \neg\beta \vee \gamma$ | E'2. $\neg\mathbf{A} \bigcirc \alpha \approx_t \mathbf{E} \bigcirc (\neg\alpha)$ |
| E3. $\neg(\alpha \vee \beta) \vee \gamma \approx_t (\neg\alpha \wedge \neg\beta) \vee \gamma$ | E'3. $\neg\mathbf{E}\Diamond\alpha \approx_t \mathbf{A}\Box(\neg\alpha)$ |
| E4. $\alpha \vee (\beta \wedge \gamma) \approx_t (\alpha \vee \beta) \wedge (\alpha \vee \gamma)$ | E'4. $\neg\mathbf{A}\Diamond\alpha \approx_t \mathbf{E}\Box(\neg\alpha)$ |
| E5. $\alpha \wedge (\beta \vee \gamma) \approx_t (\alpha \wedge \beta) \vee (\alpha \wedge \gamma)$ | E'5. $\neg\mathbf{E}(\alpha \mathbf{U} \beta) \approx_t \mathbf{A}\Box(\neg\beta) \vee \mathbf{A}((\alpha \wedge \neg\beta) \mathbf{U} (\neg\alpha \wedge \neg\beta))$ |
| E6. $(\alpha \rightarrow \beta) \vee \gamma \approx_t \neg\alpha \vee \beta \vee \gamma$ | E'6. $\neg\mathbf{A}(\alpha \mathbf{U} \beta) \approx_t \mathbf{E}\Box(\neg\beta) \vee \mathbf{E}((\alpha \wedge \neg\beta) \mathbf{U} (\neg\alpha \wedge \neg\beta))$ |
| E7. $\neg(\alpha \rightarrow \beta) \vee \gamma \approx_t (\alpha \wedge \neg\beta) \vee \gamma$ | |

So far, we have made all preparations for defining the entailment relation

\models_t of QCTL. Let $2^{\mathcal{L}}$ denote the power set of \mathcal{L} :

Definition 2.2.7 The entailment relation \models_t of QCTL is defined as follows:

- $\models_t \subseteq (2^{\mathcal{L}} - \emptyset) \times \mathcal{L}$, where \emptyset is the empty set.
- For $\Gamma \in 2^{\mathcal{L}} - \emptyset$ and $\beta \in \mathcal{L}$, $\Gamma \models_t \beta$ iff for all paraKripke structure $M = (S, R, L)$ and $s \in S$, $(M, s) \models_{ts} \alpha$ for all $\alpha \in \Gamma$ implies $(M, s) \models_{tw} \beta$.

The entailment relation is paraconsistent. In the next section, we will build the novel notion of model based on the entailment relation \models_t , such that we can employ automatically model checking technique to analyze the temporal properties of concurrent systems in the presence of inconsistency.

3 QCTL model checking

3.1 Methodology

As mentioned above, we can model concurrent systems containing inconsistent information using paraKripke structures. Because the entailment relation \models_t of QCTL is defined in a mode, very different from that of classical logic, it is unapt for paraKripke structures to model specifications of inconsistent concurrent systems, just as standard Kripke structures do in [1,15].

In what follows, we build the notion of models based on paraKripke structures, which differs from that based on standard Kripke structures.

Definition 3.1.1 Let $\alpha \in \mathcal{L}$, and a tuple $M = (S, R, L, S_0)$ be a paraKripke structure, where $S_0 \subseteq S$ is a non-empty set of initial states. $(M, s_0) \models_t \alpha$ for $s_0 \in S_0$ iff there exists a finite set of formulas $\Gamma \subseteq \mathcal{L}$, which satisfies that $\forall \gamma. \gamma \in \Gamma$, $(M, s_0) \models_{ts} \gamma$ and $\Gamma \models_t \alpha$. M is a paraKripke model of α iff $\forall s. s \in S_0$, $(M, s) \models_t \alpha$.

We argue that it is unacceptable to directly transform a model checking problem to an inference problem according to Definition 3.1.1. Hence, the following work focuses our efforts on studying the method of performing model checking over QCTL.

Many assertions, which naturally hold in classical model checking method, are not evident, even completely improper in the case of model checking over QCTL, i.e., typically, for a temporal formula α in CTL, a model of α implies that it is not a model of $\neg\alpha$.

Given a paraKripke structure $M = (S, R, L, S_0)$, we first provide some basic propositions.

Proposition 3.1.1 Let l_1, \dots, l_n for $n \geq 1$ be literals, and ql_1, \dots, ql_m for $m \geq 1$ quasi-literals. For $s \in S$,

1. $(M, s) \models_t l_1 \vee \dots \vee l_n$ iff $(M, s) \models_t l_1$ or \dots or $(M, s) \models_t l_n$.

2. $(M, s) \models_t l_1 \vee \dots \vee l_n \vee ql_1 \vee \dots \vee ql_m$ iff $(M, s) \models_t l_1 \vee \dots \vee l_n$, $(M, s) \models_t ql_1$ or \dots or $(M, s) \models_t ql_m$.

Proposition 3.1.2 Let $\alpha, \beta \in \mathcal{L}$. For $s \in S$,

1. $(M, s) \models_t \alpha \vee \beta$ iff $(M, s) \models_t \alpha$ or $(M, s) \models_t \beta$.
2. $(M, s) \models_t \alpha \wedge \beta$ iff $(M, s) \models_t \alpha$ and $(M, s) \models_t \beta$.
3. Let $\alpha_1 \wedge \dots \wedge \alpha_n$ for $n \geq 1$ be a complete-CNF of α . $(M, s) \models_t \alpha$ iff $(M, s) \models_t \alpha_1$ and \dots and $(M, s) \models_t \alpha_n$.

Proposition 3.1.2 does not mean that $\Gamma \models_t \alpha \vee \beta$ must result in $\Gamma \models_t \alpha$ or $\Gamma \models_t \beta$. Consider $\Gamma = \{p \vee q\}$ for $p, q \in \mathcal{P}$. Obviously, $\Gamma \models_t p \vee q$, but $\Gamma \not\models_t p$ and $\Gamma \not\models_t q$.

For a formula α , Let $Fact_s(\alpha) = \{\alpha' \mid (M, s) \models_{ts} \alpha' \text{ implies } (M, s) \models_{tw} \alpha\}$, intuitively called a set of strong factors of α . The detailed definition of $Fact_s(\alpha)$ will be postponed until the next subsection.

Proposition 3.1.3 Let $\alpha \in \mathcal{L}$, and $s \in S$. The followings hold:

1. $(M, s) \models_t \mathbf{E} \bigcirc \alpha$ iff $\exists t. t \in S, (s, t) \in R$ and $(M, t) \models_t \alpha$.
2. $(M, s) \models_t \mathbf{E} \Diamond \alpha$ iff there is a computing path (s_0, s_1, \dots) with the initial state $s_0 = s$, satisfying that $\exists i. i \geq 1, (M, s_i) \models_t \alpha$.

We have derived some basic conclusions on paraKripke models, which are the base of implementing the detailed algorithms. But so far, we do not involve the method of model checking these formulas, such as $\mathbf{E}(\alpha \mathbf{U} \beta)$, $\mathbf{A} \Box \alpha$ and $\mathbf{A} \bigcirc \alpha$ for $\alpha, \beta \in \mathcal{L}$. The paraconsistent character of the entailment relation of QCTL makes model checking these formulas more complex and more intractable than $\mathbf{E} \bigcirc \alpha$ and $\mathbf{E} \Diamond \alpha$.

Now take a look at $\mathbf{E}(\alpha \mathbf{U} \beta)$. According to Definition 3.1.1, for $s \in S$, $(M, s) \models_t \mathbf{E}(\alpha \mathbf{U} \beta)$ means that $\exists \Gamma. \Gamma \subseteq \mathcal{L}, \forall \gamma. \gamma \in \Gamma, (M, s) \models_{ts} \gamma$ and $\Gamma \models_t \mathbf{E}(\alpha \mathbf{U} \beta)$. The proof system for QCTL determines there must exist $\mathbf{E}(\alpha' \mathbf{U} \beta')$, satisfying that $\mathbf{E}(\alpha' \mathbf{U} \beta') \in \Gamma$, or that $\mathbf{E}(\alpha' \mathbf{U} \beta')$ is derived from Γ by applying the decomposition rules, where $\alpha' \in Fact_s(\alpha)$ and $\beta' \in Fact_s(\beta)$. In other words, $(M, s) \models_t \mathbf{E}(\alpha \mathbf{U} \beta)$ iff $(M, s) \models_{ts} \mathbf{E}(\alpha' \mathbf{U} \beta')$. According to the traditional viewpoint, $(M, s) \models_t \mathbf{E}(\alpha \mathbf{U} \beta)$ iff there exists some initial prefix (s_0, \dots, s_k) of a computing path with the initial state $s_0 = s$, satisfying that $(M, s_k) \models_t \beta$ and $(M, s_i) \models_t \alpha$ for $0 \leq i < k$. However, this verdict is not correct in the notion of paraKripke models.

Let us illustrate this point by an example. Fig.1 show a paraKripke structure M with the initial state s_0 , where $L(s_0) = \{+p, -q, -r, -p'\}, L(s_1) = \{-p, +q, -r, -p'\}, L(s_2) = \{-p, -q, +r, -r, -p'\}$ and $L(s_3) = \{-p, -q, +r, +p'\}$ for $p, q, r, p' \in \mathcal{P}$.

Consider the temporal property $\mathbf{E}(p \vee q \vee r \mathbf{U} p')$. Clearly, for $0 \leq i \leq 2$, $(M, s_i) \models_t p \vee q \vee r$, and $(M, s_3) \models_t p'$. But it cannot deduce $(M, s_0) \models_t$

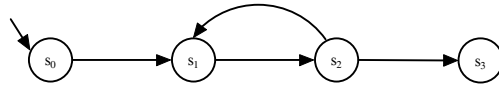


Fig. 1. An example of paraKripke model

$E(p \vee q \vee r \cup p')$. In fact, $Fact_s(p \vee q \vee r) = \{p, q, r, p \vee q, p \vee r, q \vee r, p \vee q \vee r\}$. From Fig.1, we see that there is not any $f_s \in Fact_s(p \vee q \vee r)$, satisfying that for $0 \leq i \leq 2$, $(M, s_i) \models_{ts} f_s$, in other words, $(M, s_0) \not\models_t E(p \vee q \vee r \cup p')$.

Similarly, model checking such formulas beginning with the universal quantifier A and $E\Box\alpha$ faces the same challenge like model checking $E(\alpha \cup \beta)$: the paraconsistency of the entailment relation increases the complexity of model checking such formulas.

ParaKripke structures weaken the meaning of negation operator \neg in the sense that both α and $\neg\alpha$ are exclusively satisfied each other. In model checking over QCTL, $(M, s) \models_t \alpha$ does not deny $(M, s) \models_t \neg\alpha$. Hence, the problem of model checking formulas, such as $\neg\alpha$ and $\neg E\Diamond\alpha$, has to be solved in term of the behavior of the negation operator \neg in paraKripke models. Take some examples as follows: $(M, s) \models_t \neg(\alpha \vee \beta)$ iff $(M, s) \models_t \neg\alpha \wedge \neg\beta$, $(M, s) \models_t \neg E\Diamond\alpha$ iff $(M, s) \models_t A\Box(\neg\alpha)$, and $(M, s) \models_t \neg(\alpha \rightarrow \beta)$ iff $(M, s) \models_t \alpha \wedge \neg\beta$.

3.2 Implementing the algorithm

The model checking problem for QCTL is to verify for a given paraKripke structure M , a state $s \in S$, and a formula $\alpha \in \mathcal{L}$ whether $(M, s) \models_t \alpha$. Though QCTL is a paraconsistent temporal logic, we can basically implement the algorithm in spirit that is inspired by [16]. This point gets demonstrated just by what the last subsection gives.

Before deep analyzing the algorithm given in Fig.2, we now provide the more accurate interpretation of the aforementioned set $Fact_s(\alpha)$ for $\alpha \in \mathcal{L}$, which is vital for constructing the algorithm. For a clause $\alpha \in \mathcal{L}$, let $Literals(\alpha) = \{l \mid l \text{ is a disjunct of } \alpha\}$. The following definition specifies $Fact_s(\alpha)$ in the case of a complete-clause α .

Definition 3.2.1 Let α be a complete-clause. $Fact_s(\alpha)$ is inductively defined as follows:

- If $\alpha = l_1 \vee \dots \vee l_n$ for $n \geq 1$ is a clause, then $Fact_s(\alpha) = \bigcup_{i=1}^n \{l_1 \vee \dots \vee l_i \mid Literals(l_1 \vee \dots \vee l_i) \subseteq Literals(\alpha)\}$.
- If $\alpha = \sigma\mathbf{x}(\beta_1 \wedge \dots \wedge \beta_n)$, then $Fact_s(\alpha) = \{\sigma\mathbf{x}(\beta'_1 \wedge \dots \wedge \beta'_n) \mid \text{for } 1 \leq i \leq n, \beta'_i \in Fact_s(\beta_i)\}$.
- If $\alpha = \sigma((\beta_1 \wedge \dots \wedge \beta_n) \cup (\gamma_1 \wedge \dots \wedge \gamma_m))$, then $Fact_s(\alpha) = \{\sigma((\beta'_1 \wedge \dots \wedge \beta'_n) \cup (\gamma'_1 \wedge \dots \wedge \gamma'_m)) \mid \text{for } 1 \leq i \leq n \text{ and } 1 \leq j \leq m, \beta'_i \in Fact_s(\beta_i), \gamma'_j \in Fact_s(\gamma_j)\}$.
- If $\alpha = l_1 \vee \dots \vee ql_i \vee \dots \vee ql_n$, where for $i \leq j \leq n$, ql_j is a quasi-literal, and if $i > 1$,

for $1 \leq j \leq i-1$, l_j is a literal, then $Fact_s(\alpha) = \bigcup_{m=1}^n \{\gamma_1 \vee \dots \vee \gamma_m \mid \text{for } 1 \leq l \leq m, \text{ if } \gamma_l \text{ is a quasi-literal, } \gamma_l \in Fact_s(ql_i) \cup \dots \cup Fact_s(ql_n), \text{ and if } \gamma_l \text{ is a literal, } \exists k. 1 \leq k < i, \gamma_l = l_k\}$.

So for any formula $\alpha \in \mathcal{L}$, let $\alpha_1 \wedge \dots \wedge \alpha_n$ for $n \geq 1$ be the complete-CNF of α . $Fact_s(\alpha) = \{\alpha'_1 \wedge \dots \wedge \alpha'_n \mid \text{for } 1 \leq i \leq n, \alpha'_i \in Fact_s(\alpha_i)\}$.

Fig.2 and Fig.3 show the details of the naive algorithm for model checking over QCTL. In fact, the function $Check(\alpha)$ returns the set of states denoted $Sat(\alpha)$, in which the property α is satisfied, that is, for $s \in Sat(\alpha)$, $(M, s) \models_t \alpha$. $Sat(\alpha)$ is computed in a recursive way by considering the sub-formulas of α , similarly like what has been done in [15]. The recursive computation basically boils down to a bottom-up traversal of the parse tree of the formula α . Each node of the parse tree of α represents a sub-formula of α , and the only root node represents the formula α . But because paraKripke structures decouple the relationship between a formula and its negation at the level of semantics and the notion of paraKripke models is introduced, involving the strong satisfiability relation, the parse tree of a formula is constructed in a different means from the traditional method, namely, the set of sub-formulas of a formula has different underlying meaning.

Both $Check(\alpha)$ and $CheckS(\alpha)$ need to traverse the sub-formulas of α , but, in which, the traversal behaves in unlike manner, and the sets of sub-formulas of α contain the formulas generated by different means. Let $Sub(\alpha)$ and $Sub_s(\alpha)$ denote the set of sub-formulas of α in $Check(\alpha)$, and that in $CheckS(\alpha)$, respectively. For simplicity, we do not explicitly give the entire definitions of $Sub(\alpha)$ and $Sub_s(\alpha)$, and only formulate the following noteworthy points:

- For $p \in \mathcal{P}$, $Sub(\neg p) = Sub_s(\neg p) = \{\neg p\}$, and it is not the case that $Sub(\neg p) = \{\neg p, p\}$. In particular, for a clause c , $Sub_s(c) = \{c\}$. This item makes clear sub-formulas possibly represented by the leaf nodes of the parse tree.
- $Sub(\alpha \wedge \beta) = \{\alpha \wedge \beta\} \cup Sub(\alpha) \cup Sub(\beta)$, and $Sub_s(\alpha \wedge \beta) = \{\alpha \wedge \beta\} \cup Sub_s(\alpha) \cup Sub_s(\beta)$. For a complete-clause $\alpha = c \vee ql_1 \vee \dots \vee ql_n$ for $n \geq 1$, where c is a clause, and for $1 \leq i \leq n$, ql_i is a quasi-literal, $Sub_s(\alpha) = \{c, \alpha\} \cup Sub_s(ql_1) \cup \dots \cup Sub_s(ql_n)$.
- For any formula α , $Sub(\neg\alpha)$ cannot be computed by $Sub(\neg\alpha) = \{\neg\alpha\} \cup Sub(\alpha)$. We should compute $Sub(\neg\alpha)$ according to the de Morgan laws, double negation elimination. Some examples are in order: $Sub(\neg(\beta \wedge \gamma)) = Sub(\neg\beta \vee \neg\gamma)$, $Sub(\neg(\beta \vee \gamma)) = Sub(\neg\beta \wedge \neg\gamma)$, and $Sub(\neg\neg\alpha) = Sub(\alpha)$; Especially, when the negation operator directly acts on path qualifiers **E** or **A**, such as $\neg\mathbf{E} \bigcirc \alpha$ and $\neg\mathbf{A} \Diamond \alpha$, we should compute the set of sub-formulas of such formulas according to the semantics of the corresponding formulas. For instance, $Sub(\neg\mathbf{E} \bigcirc \alpha) = Sub(\mathbf{A} \bigcirc (\neg\alpha))$, and $Sub(\neg\mathbf{A} \Diamond \alpha) = Sub(\mathbf{E} \Box (\neg\alpha))$. Fig. 2 shows that $CheckS(\alpha)$ is called always when α is a complete-CNF or a complete-clause, hence, we are not concerned about the above situation as to $Sub_s(\alpha)$.

```

function CheckEU( $\alpha, \Phi$ : formula): set of states;
begin
  var satpsi, now, pre, sat: set of states
  satpsi, now, pre, sat $f_s$ , sat=Check( $\Phi$ ),  $\emptyset$ ,  $\emptyset$ ,  $\emptyset$ ,  $\emptyset$ 
  for each  $f_s \in Fact(\alpha)$ 
    sat $f_s$ =CheckS( $f_s$ )
    now=satpsi
    do
      pre=now
      now=pre  $\cup (\{s \mid R(s) \cap pre \neq \emptyset\} \cap satf_s)$ 
    until pre=now
    sat=sat  $\cup$  now
  end for
  return sat
end

function CheckEG( $\alpha$ : formula): set of states;
begin
  var satpsi, now, pre, sat: set of states
  satpsi, now, pre, sat $f_s$ , sat=Check( $\Psi$ ), S,  $\emptyset$ ,  $\emptyset$ ,  $\emptyset$ 
  for each  $f_s \in Fact(\Psi)$ 
    sat $f_s$ =CheckS( $f_s$ )
    now=S
    do
      pre=now
      now=pre  $\cap (\{s \in S \mid R(s) \cap pre \neq \emptyset\} \cap satf_s)$ 
    until now=pre
    sat=sat  $\cup$  now
  end for
  return sat
end

function Check( $\alpha$ : formula): set of states ;
begin
  switch( $\alpha$ )
    case  $\alpha = p \in \mathcal{P}$ : return  $\{s \mid s \in S, +p \in L(s)\}$ 
    case  $\alpha = \neg p$  for  $p \in \mathcal{P}$ : return  $\{s \mid s \in S, -p \in L(s)\}$ 
    case  $\alpha = \alpha_1 \wedge \alpha_2$ : return Check( $\alpha_1$ )  $\cap$  Check( $\alpha_2$ )
    case  $\alpha = \alpha_1 \vee \alpha_2$ : return Check( $\alpha_1$ )  $\cup$  Check( $\alpha_2$ )
    case  $\alpha = E \bigcirc \alpha_1$ : return  $\{s \in S \mid R(s) \cap Check(\alpha_1) \neq \emptyset\}$ 
    case  $\alpha = E(\alpha_1 \cup \alpha_2)$ : return CheckEU( $\alpha_1, \alpha_2$ )
    case  $\alpha = E\Box \alpha_1$ : return CheckEG( $\alpha_1$ )
    case  $\alpha = \neg(\alpha_1 \wedge \alpha_2)$ : return Check( $\neg\alpha_1 \vee \neg\alpha_2$ )
    case  $\alpha = \neg E\Diamond \alpha_1$ : return Check( $A\Box \alpha_1$ )
     $\vdots$ 
  end switch
end

```

Fig. 2. The recursive algorithm for model checking over QCTL

- For such formulas beginning with the universal quantifier A , $E\Box\alpha$, and $E(\alpha \cup \beta)$, the computation of the set of sub-formulas strangely behaves due to the notion of paraKripke models. Typically, consider $E(\alpha \cup \Psi)$ as an example. Fig. 2 shows that $Check(E(\alpha \cup \Psi))$ essentially involves the traversal to the formulas in $Fact_s(\alpha) \cup Sub(\Psi)$, moreover, for $f_s \in Fact(\alpha)$, the traversal to f_s is executed by $CheckS(f_s)$. Therefore, $Sub(E(\alpha \cup \Psi)) = \{E(\alpha \cup \Psi)\} \cup \bigcup_{f_s \in Fact_s(\alpha)} Sub_s(f_s) \cup Sub(\Psi)$, as such, $Sub(E\Box\alpha) = \{E\Box\alpha\} \cup \bigcup_{f_s \in Fact_s(\alpha)} Sub_s(f_s)$.

The while parse tree of a formula α , traversed by the recursive algorithm for model checking over QCTL, can be therefore constructed by applying the rules of computing $Sub(\cdot)$ and $Sub_s(\cdot)$ in a similar way in [15], where \cdot represents

```

function TestClause(s: state, c: clause): True or False;
  (*  $c = c_1 \vee \dots \vee c_n$  for  $n \geq 1$  *)
begin
  if  $n = 1$  return ( $+c_1 \in L(s)$  ? True : False)
  else
    if  $+c_1 \notin L(s) \dots$  and  $+c_n \notin L(s)$  return False
    for  $1 \leq i \leq n$ 
      if  $+c_i \in L(s)$ 
        if TestClause(s, Disj(c, ci)) = False return False
    end for
    return True
  end

function CheckS( $\alpha$ : complete-CNF formula): set of states;
  (*  $\alpha = \alpha_1 \wedge \dots \wedge \alpha_n$  for  $n \geq 1$  *)
begin
  if  $n > 1$  return  $\bigcap_{i=1}^n \text{CheckS}(\alpha_i)$ 
  else
    switch( $\alpha$ )
      case  $\alpha = l_1 \vee \dots \vee l_m$ : return  $\{s \mid \text{TestClause}(s, \alpha) = \text{True}\}$ 
      (*  $m \geq 1$  and for  $1 \leq i \leq m$ ,  $l_i$  is a literal. *)
      case  $\alpha = c \vee ql_1 \vee \dots \vee ql_m$ : return  $\text{CheckS}(c) \cup \text{CheckS}(ql_1) \cup \dots \cup \text{CheckS}(ql_m)$ 
      (*  $m \geq 1$ , and for  $1 \leq i \leq m$ ,  $ql_i$  is a quasi-literal, and c is a clause. *)
      case  $\alpha = E \bigcirc \Psi$ : return  $\{s \in S \mid R(s) \cap \text{CheckS}(\Psi) \neq \emptyset\}$ 
      case  $\alpha = E(\beta \cup \Psi)$ : return  $\text{CheckSEU}(\beta, \Psi)$ 
      case  $\alpha = E \square \Psi$ : return  $\text{CheckSEG}(\Psi)$ 
      case  $\alpha = \neg(\beta \wedge \Psi)$ : return  $\text{CheckS}(\neg\beta \vee \neg\Psi)$ 
      case  $\alpha = \neg E \Diamond \beta$ : return  $\text{CheckS}(A \square \beta)$ 
       $\vdots$ 
    end switch
  end

```

Fig. 3. The algorithm for checking strong satisfiability

some formula. The root node of this parse tree represents α , and the leaf nodes represent atomic formulas, their negations, or some clauses.

The procedure of constructing the parse tree of a formula manifests the skeleton of the recursive algorithm in Fig. 2 and Fig. 3. The computation of $Sat(p)$ or $Sat(\neg p)$ for $p \in \mathcal{P}$ is straightforward. For simplicity, we only illustrate the computation of $Sat(\alpha)$ when $\alpha = E(\beta \cup \Psi)$. Then, the specific function CheckEU, see Fig. 2, is invoked that performs the computation of $Sat(\alpha)$. Intuitively, CheckEU works as follows. Obviously, for $s \in \text{Check}(\Psi)$, $s \in Sat(\alpha)$, that is, $(M, s) \models_t \alpha$. Thus, all states in $Sat(\alpha)$ are initially considered to belong to $\text{Check}(\Psi)$. For every $f_s \in \text{Fact}_s(\beta)$, an iterative procedure runs, which computes the state space, in which, for every state s , there exists a sequence of states (s_0, s_1, \dots, s_n) for $n \geq 1$, satisfying that $s_0 = s$, $s_n \in \text{Check}(\Psi)$, and for $0 \leq i \leq n-1$, $s_{i+1} \in R(s_i)$ (the set $R(s_i)$ denotes the set of direct successor states of s_i , i.e., $R(s_i) = \{s' \in S \mid (s_i, s') \in R\}$) and $s_i \in \text{CheckS}(f_s)$. The computation of $Sat(\cdot)$, where \cdot denotes such formulas with the universal quantifier, can be performed approximately like that of $Sat(E(\beta \cup \Psi))$.

CheckS(α) returns the set of states denoted $Sat_s(\alpha)$, where α is strongly satisfied, as shown in Fig 3. Consider that the routines of computing $Sat_s(\alpha)$

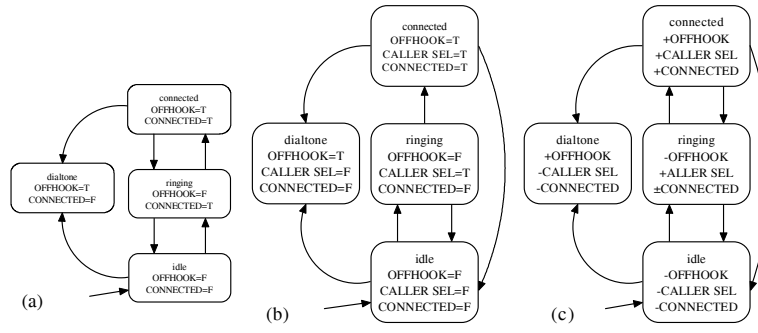


Fig. 4. (a) Viewpoint of Callee1; (b) Viewpoint of Callee2; (c) Merger of Two Viewpoints

are close to that of computing $Sat(\alpha)$ on the whole, thus we do not make a explicit interpretation of the algorithm for checking strong satisfiability.

4 Example

In this section, an example of a simplified phone system is presented, showing our motivation of proposing the model checking technique based on paraconsistent logic.

A phone system can be taken into account from different angles of view. Fig.4(a) and (b) show two different visions of viewpoints of callee1 and callee2 on the phone system. The two models are specified using standard Kripke structures based on two-valued logic. The meaning expressed by the state names and the propositions in states can be literally understood. We can easily find that the disagreement arises between callee1 and callee2. Callee1 considers that a phone allows one to replace the receiver during an incoming call without getting disconnected, and yet callee2 considers that replacing the receiver always leads to disconnect the call.

Having specified the models of the targeted system, even though partial and inconsistent, we wish to deeply analyze these models. Naturally, we can separately reason about these models, but more interestingly, we can integrate the two models (even if they are inconsistent) to perform reasoning about the merged model containing more comprehensive information on the phone system. Integrating multiple models is complicated when inconsistent information exists among models. We here do this as follows:

- Choose the underlying logic QCTL for the merged model.
- Choose signature maps, which stipulate the relationships of items between the merged model and the corresponding source models, such as states' names and propositional variables in states. We adopt the similar principle in [17].
- Choose the measure of handling the inconsistencies existing among models. Optimistically, we argue that some conflicting viewpoints on the system do not exclude each other, for instance, each model does not deny the

existence of transitions that it does not describe. This argument, we think, is appropriate for evolving specifications, especially in the early stage of the development.

Fig.4(c) shows the resulting paraKripke model.

Despite conflicting viewpoints on the system, we can verify some temporal properties of the phone system. The representational examples include:

1. $A\Box(\text{CONNECTED} \rightarrow E \bigcirc (\neg\text{OFFHOOK}))$ “if you are connected, you can hang up.”
2. $A\Box(\neg\text{CALLER_SEL} \rightarrow \neg\text{CONNECTED})$ “if none is selected, you cannot be connected.”
3. $A\Box(\neg\text{OFFHOOK} \rightarrow \neg\text{CONNECTED})$ “if you hang up, you are disconnected”.

According to Definition 3.1.1, we can easily ensure that the first property is satisfiable in the merged model, that is, Fig.4(c) is a paraKripke model of the first property. The rest of the three properties is more interesting. The second property is not expressible in callee1, but callee1 can have this property as long as it accepts the definitions in callee2 for CALLER_SEL, which callee1 does not describe. Consider the third, from Fig.4(c), we know the merged model satisfies the property. Just on this property are callee1 and callee2 conflicting. Note that the listed properties are simple, therefore, we do not explicitly explain the details of deriving the three properties from Fig.4(c). Though this example mentioned above is small and rather artificial, it suffices for illustrating the type of reasoning under inconsistency.

5 Concluding remarks

In this paper we presented a novel notion of paraKripke model based on QCTL, which grasps the essential idea behind QCTL. The methodology of checking whether a paraKripke structure is a paraKripke model of a formula in QCTL, is deep investigated. Further, we described the implementation of the algorithm for model checking over QCTL.

However, it is inadequate job. We need to continue our work in the following directions. First, We intend to conduct a series of nontrivial case studies, showing the proposed framework makes developers more efficient and more innovative in the continually evolving development process, such as requirements engineering. Further, our aim is not to replace the established approach of handling inconsistencies existing in the life cycle of software development. We plan to integrate the automated tools based on paraconsistent logics with the early work by Hunter, Finkelstein, et al.

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