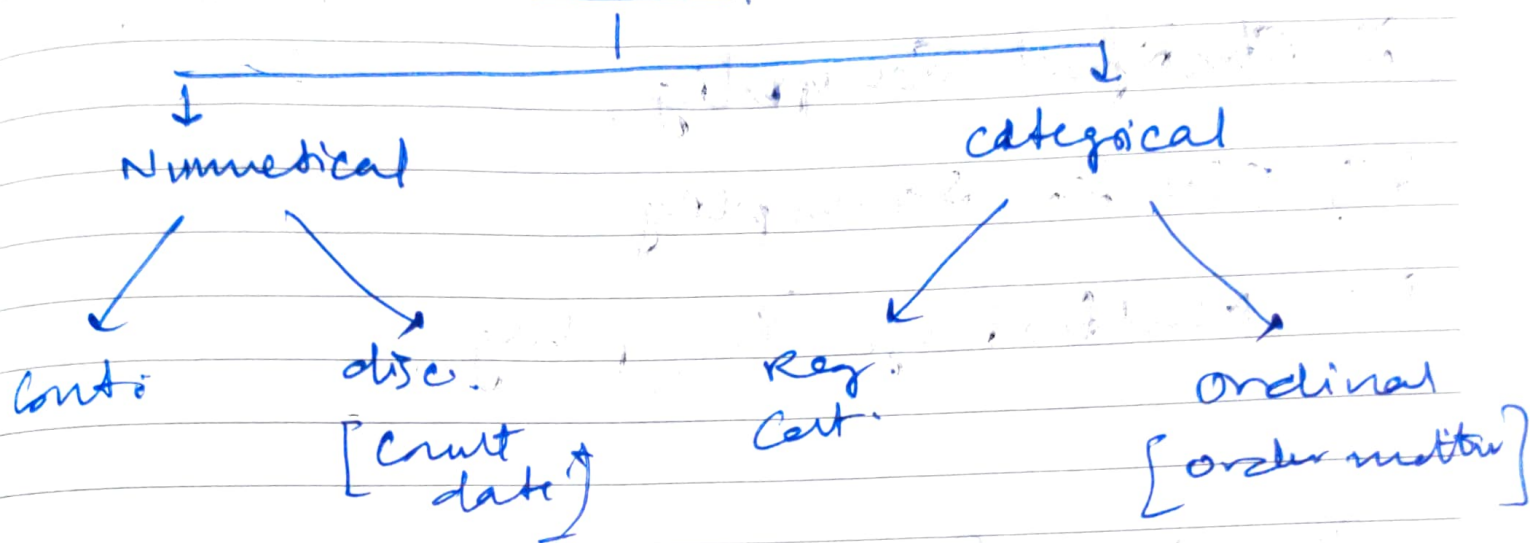
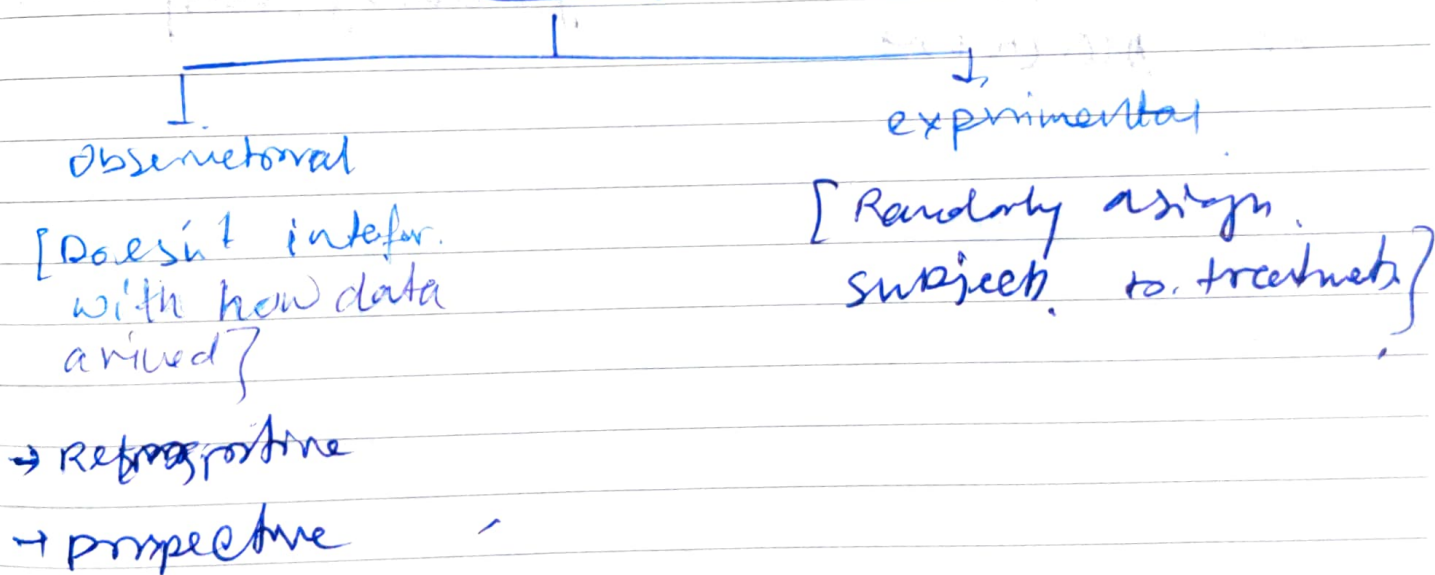


Statistics

Variables



Study



Sampling Methods:

- i) SRS (Simple Random Sampling)
- ii) Stratified Sampling.
- iii) Cluster Sampling.
- iv) Multistage Sampling.

Placebo → Fake treatment.

Placebo Effect → Showing change despite no
or placebo.

Least Sq., Regrsm., and Pseudo Inv.

$$Ax = b$$

Underdetermined: $n < m$ (short-fat A)

$$\begin{matrix} A & x & = & b \\ \boxed{} & \boxed{} & = & \boxed{} \end{matrix}$$

∞ many soln.
 $\min \| \tilde{x} \|_2 \text{ s.t. } A\tilde{x} = b$
 (min norm soln)

Overdetermined: $n > m$ (tall skinny A)

$$\begin{matrix} A & x & = & b \\ \boxed{} & \boxed{} & = & \boxed{} \end{matrix}$$

0 soln.
 $\min \| A\tilde{x} - b \|_2$ (least sq soln)

$$A = U \Sigma V^T \Rightarrow A^+ = \underbrace{V \Sigma^+ U^T}_{\text{M.P. Pseudo Inv.}}$$

$$Ax = b$$

(left)

$$\Rightarrow U \Sigma V^T x = b$$

$$\Rightarrow V \Sigma^+ U^T U \Sigma V^T x = V \Sigma^+ U^T b$$

$\{V, U, \Sigma\}$
 are orthonormal
 i.e. $U^T U = I$

$$\Rightarrow \tilde{x} = V \Sigma^+ U^T b \quad A^+ := A^+ b$$

$$\hat{A}\hat{x} = \hat{U}\hat{\Sigma}\hat{V}^T\hat{V}\hat{\Sigma}^T\hat{U}^T b$$

$$= \hat{U}\hat{U}^T b$$

project of b into $\text{span}(\hat{U})$
 $= \text{span}(A)$

Solⁿ of $Ax = b$ only exist if b is in column space of A .

* $\text{Col}(A)$ Column space of A
 $= \text{Col}(\hat{U})$ — range.

* ~~Kernel~~

* $\text{Ker}(A^T)$ orthogonal complement of $\text{Col}(A)$
 kernel of A^T .

* $\text{row}(A)$ row space of A
 $= \text{row}_{\text{Col}}(V) = \text{row}(V^T)$

* $\text{Ker}(A)$ null space

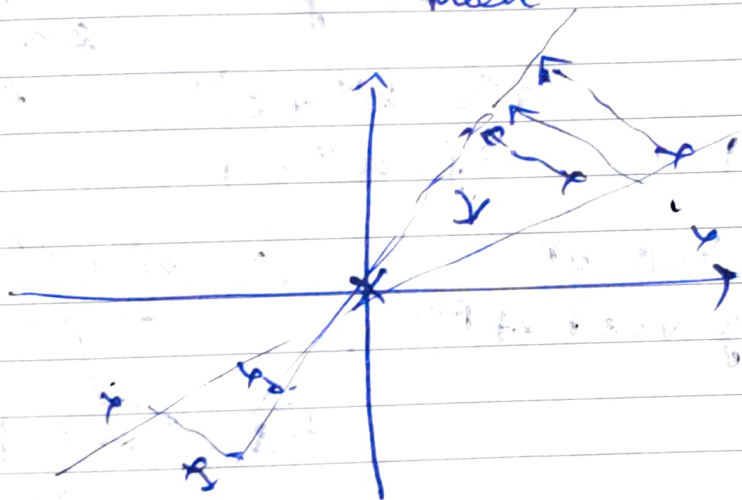
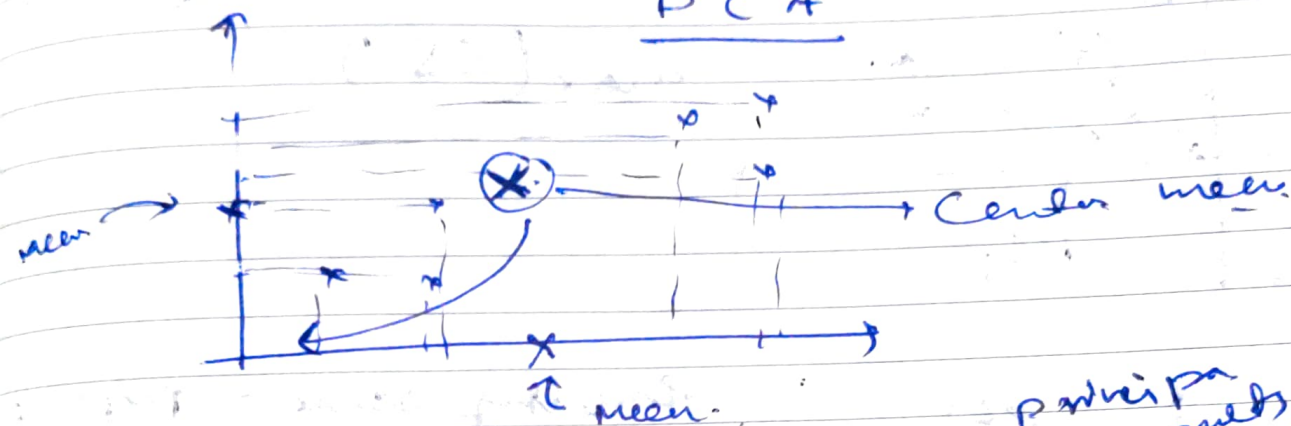
↳ set of all vec^s x s.t. $Ax = 0$

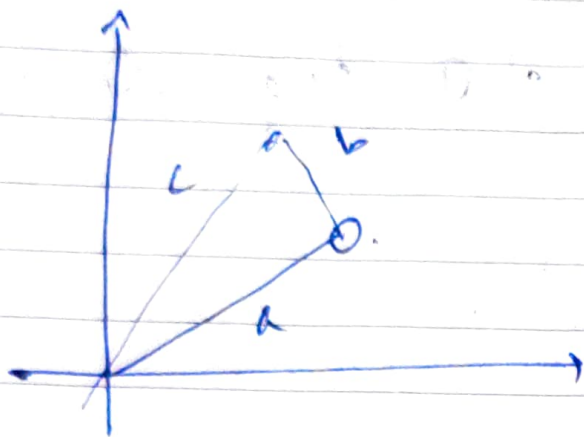
if $\dim(\ker(A)) \neq 0$, then ∞ solns.

$$A(x + x_{null}) = b.$$

also soln.

$$P \subset A$$



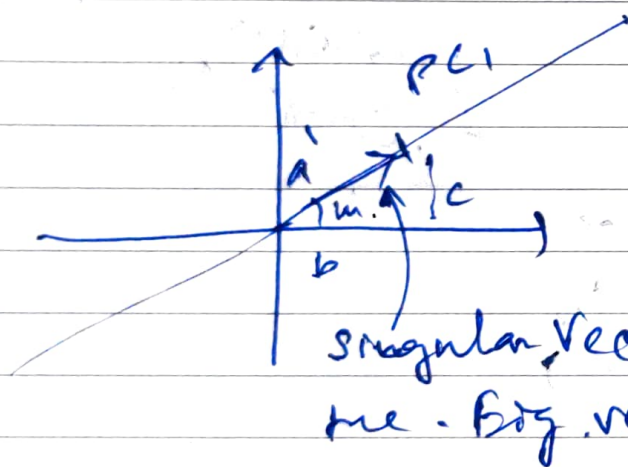
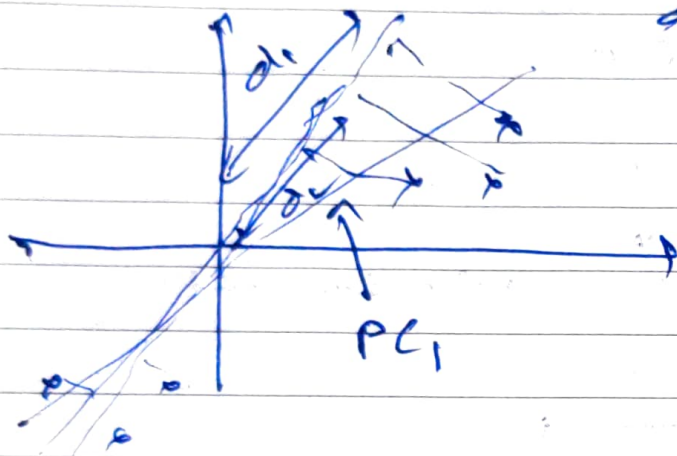


$$a^v = b^v + c^v$$

If a is const, b & c are
inv. prop.

$$d_1^2 + d_2^2 + \dots + d_k^2 = SS$$

max(SS)



loading score = prop of
each component
in PC_1

$$a^v = b^v + c^v$$

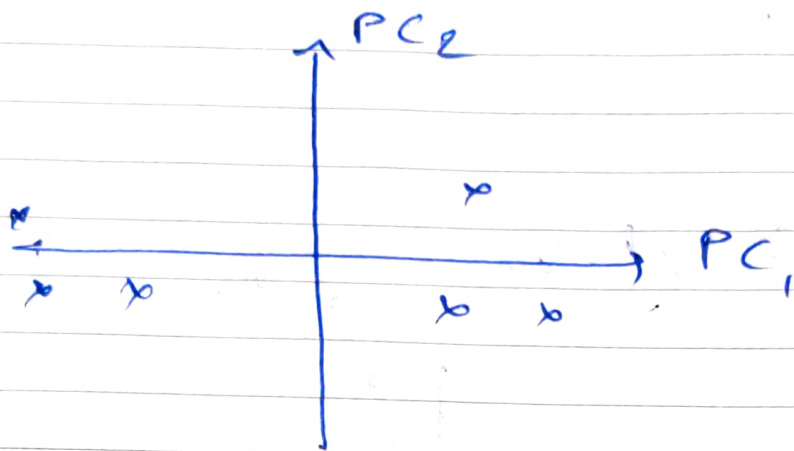
if $a^v = 1$,

$$\therefore b^v + c^v = 1$$

b^v & c^v are loading
score

singular vec or
the eig. vec of PC_1

PC_2 will be \perp to PC_1 and give
largest output.



$$X = \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \quad \begin{matrix} n \\ \text{sample} \end{matrix}$$

$m = \text{measurement}$
 $n \times m \quad n \times m \quad m \times m$

eigen decomposition of

$$(X^T X) \rightarrow W$$

$m \times m \quad \nearrow$

$$T = XW$$

\nearrow $\text{Col}(W) = \text{loadings}$

"score"

each col. of W is a PC.
 \rightarrow ordered col. by value of λ .

$$W_p = \begin{bmatrix} 1 & & & 1 \\ W_1 & \dots & W_p \\ 1 & & & 1 \end{bmatrix}$$

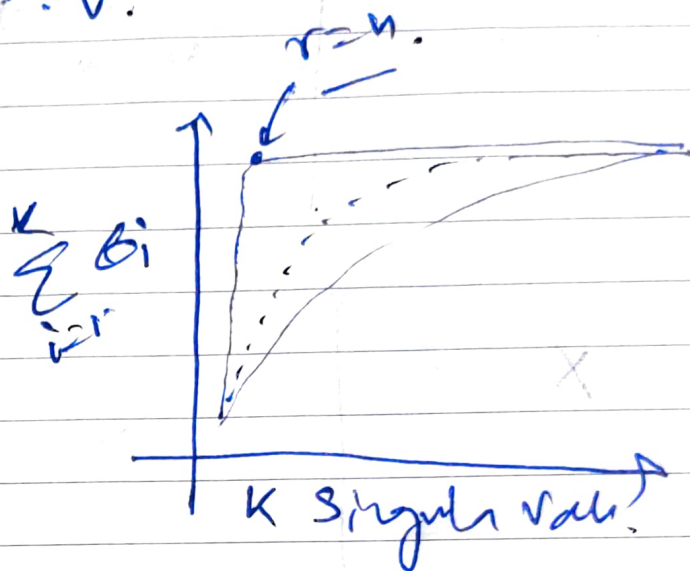
$$T_r = X W_r$$

$n \times r$ $n \times m$ $m \times r$

$$T = XW$$

$$XV = U \Sigma V^T \cdot V$$

$$T = U \Sigma$$



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System of linear Eq.

i) inconsistent \rightarrow No Soluⁿ.

ii) Consistent \rightarrow One or many Soluⁿ.

Soluⁿ Techniques:

(i) Gauss Elem. \rightarrow augmented matrix

$(A|B) \rightarrow$ row reduction for \rightarrow back substitution.

(ii) Gauss Jordan $\rightarrow (A|B) \rightarrow$ make $(A|B)$
reduced row echelon. or. (make $A \rightarrow I$)

over determined Sys.

no. of Eq. $>$ no. of unknowns

[usually inconsistent]

under defined Sys.

no. of Eq. $<$ no. of unknowns ($n > m$)
[usually consistent]

Homogeneous $\rightarrow AX = 0$. (always consistent)
if $n > m \rightarrow$ exist a non trivial solⁿ.

Non homogeneous $\rightarrow AX = B$ ($B \neq 0$)

Elementary Matrices:

Obtained from I by using row operator.

Type - I \rightarrow row exchange

Type - II \rightarrow ~~row~~ scalar multiple of a row.

Type - III \rightarrow multiples and addn. of row

$$X \cdot W^T = \begin{pmatrix} | & | \\ | & | \\ | & | \\ | & | \\ | & | \\ | & | \end{pmatrix}_{4 \times 6} \times \begin{pmatrix} | & | \\ | & | \\ | & | \\ | & | \end{pmatrix}_{6 \times 2}$$

$$W^T \rightarrow W = \underline{2 \times 6}$$

$$\underline{X^T W} = \begin{pmatrix} | & | & | & | & | & | \end{pmatrix}_{6 \times 1}$$

$$(n \times m)$$

$$N(A) = \{x \in \mathbb{R}^n \mid Ax = 0\}$$

$$N(A) \subseteq \mathbb{R}^n$$

$$A(\alpha x) = \alpha Ax = \alpha \cdot 0 = 0$$

$$\alpha x \in N(A)$$

$$\begin{aligned} A(x+y) &= Ax + Ay \quad x, y \in N(A) \\ &= 0 + 0 = 0 \end{aligned}$$

Null Subspaces:

A

$N(A)$ is the Null Subspace of A .

$$\text{If } A=0, N(A) = \{x \in \mathbb{R}^n \mid Ax = 0\}$$

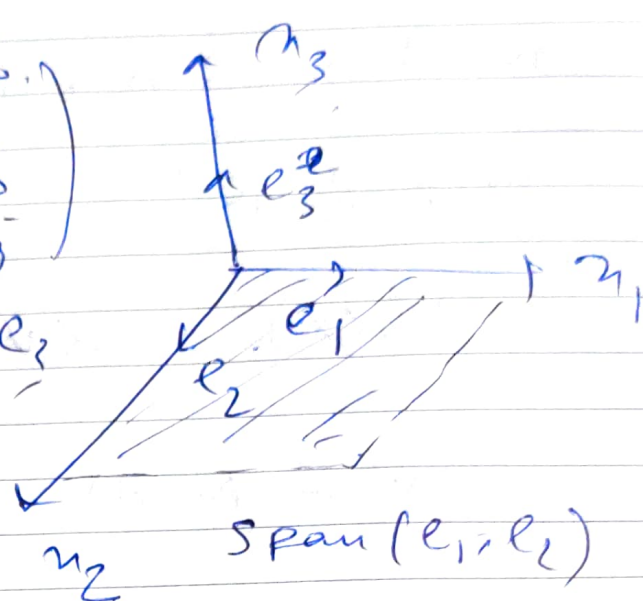
Span: Set of all linear combinations of vectors in the vector space is the span of the vectors.

Span of a Vector Space:
 $\alpha e_1 + \beta e_2 = \begin{pmatrix} \alpha \\ \beta \\ 0 \end{pmatrix}$

Span of \mathbb{R}^3 is e_1, e_2, e_3

$$+ \alpha_1 e_1 + \alpha_2 e_2 + \alpha_3 e_3$$

$$= \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}$$



Span(e_1, e_2)

e_1, e_2, \dots, e_n

\rightarrow ~~an~~ unit basis vector.

$$v_1 + v_2 + \dots + v_n \in V.$$

$$\text{Span}(v_1 + v_2 + \dots + v_n) \in V \subseteq \text{proj.}$$

ex (3)

$$\rightarrow \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = v.$$

we have to prove closure prop in addition and multiplication.

$$\beta v = (\beta \alpha_1) v_1 + (\beta \alpha_2) v_2 + \dots + (\beta \alpha_n) v_n \\ \in \text{Span of } (v_1, v_2, \dots, v_n)$$

$$v = \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n$$

$$w = \beta_1 v_1 + \beta_2 v_2 + \dots + \beta_n v_n$$

$$v+w = (\alpha_1 + \beta_1)v_1 + (\alpha_2 + \beta_2)v_2 + \dots + (\alpha_n + \beta_n)v_n$$

$$\in \text{Span}(v_1, v_2, \dots, v_n)$$

Spanning Set:

$\{v_1, v_2, \dots, v_n\}$ spanning set of V .

i.e. $\text{Span}(v_1, v_2, \dots, v_n) = V$.

→ a) $\{(n_1, n_2)^T \mid n_1 + n_2 = 0\} \in \mathbb{R}^2$.

$$n_1 = -n_2$$

$$\therefore x = (a, -a)^T \in S$$

then, $\alpha x = (\alpha a, -\alpha a)^T \in S$

$$x+y = (a, -a) + (b, -b) = \{a+b, -(a+b)\} \in S$$

Linear Envelopes

span $(V_1, V_2, \dots, V_n) \in W$

$$\text{if } c_1 V_1 + c_2 V_2 + \dots + c_n V_n = 0.$$

$$\Rightarrow c_1 = c_2 = \dots = c_n = 0$$

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$$c_1 x_{11} + c_2 x_{12} + \dots + c_n x_{1n} = 0$$

$$c_1 x_{21} + c_2 x_{22} + \dots + c_n x_{2n} = 0$$

$$c_1 x_{n1} + c_2 x_{n2} + \dots + c_n x_{nn} = 0$$

Vector Space $C^{(n-1)}[a, b]$:

let, $f_1, f_2, \dots, f_n \in C^{(n-1)}[a, b]$

$\exists c_1, c_2, \dots, c_n \neq 0$ such that,

$$c_1 f_1^{(n)} + c_2 f_2^{(n)} + c_3 f_3^{(n)} + \dots + c_n f_n^{(n)} = 0.$$

$\forall n \in [a, b]$,

$$c_1 f_1'(n) + c_2 f_2'(n) + \dots + c_n f_n'(n)$$

if f is continuous differentiable, $= 0$

$$c_1 f_1(n) + c_2 f_2(n) + \dots + c_n f_n(n) = 0$$

$$c_1 f_1'(n) + c_2 f_2'(n) + \dots + c_n f_n'(n) = 0,$$

$$c_1 f_1^{(n-1)}(n) + c_2 f_2^{(n-1)}(n) + \dots + c_n f_n^{(n-1)}(n) = 0.$$

for all fixed $n \in [a, b]$ the eq.

becomes,

$$\begin{pmatrix} f_1(n) & f_2(n) & \dots & f_n(n) \\ f_1'(n) & f_2'(n) & \dots & f_n'(n) \\ \vdots & \vdots & & \vdots \\ f_1^{(n-1)}(n) & f_2^{(n-1)}(n) & \dots & f_n^{(n-1)}(n) \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

will have the same non-trivial soln.
 if $\{f_1, f_2, \dots, f_n\}$ is
 linearly dependent in $C^{(n-1)}[a, b]$

Wronskian:

$$W[f_1, f_2, \dots, f_n](n) = \begin{vmatrix} f_1(n) & \dots & f_n(n) \\ f_1'(n) & \dots & f_n'(n) \\ \vdots & & \vdots \\ f_1^{(n-1)}(n) & \dots & f_n^{(n-1)}(n) \end{vmatrix}$$

If $W \neq 0 \rightarrow f_1, \dots, f_n$ linearly independent
 but $W = 0$ doesn't mean f_1, f_2, \dots, f_n
 linearly dependent.