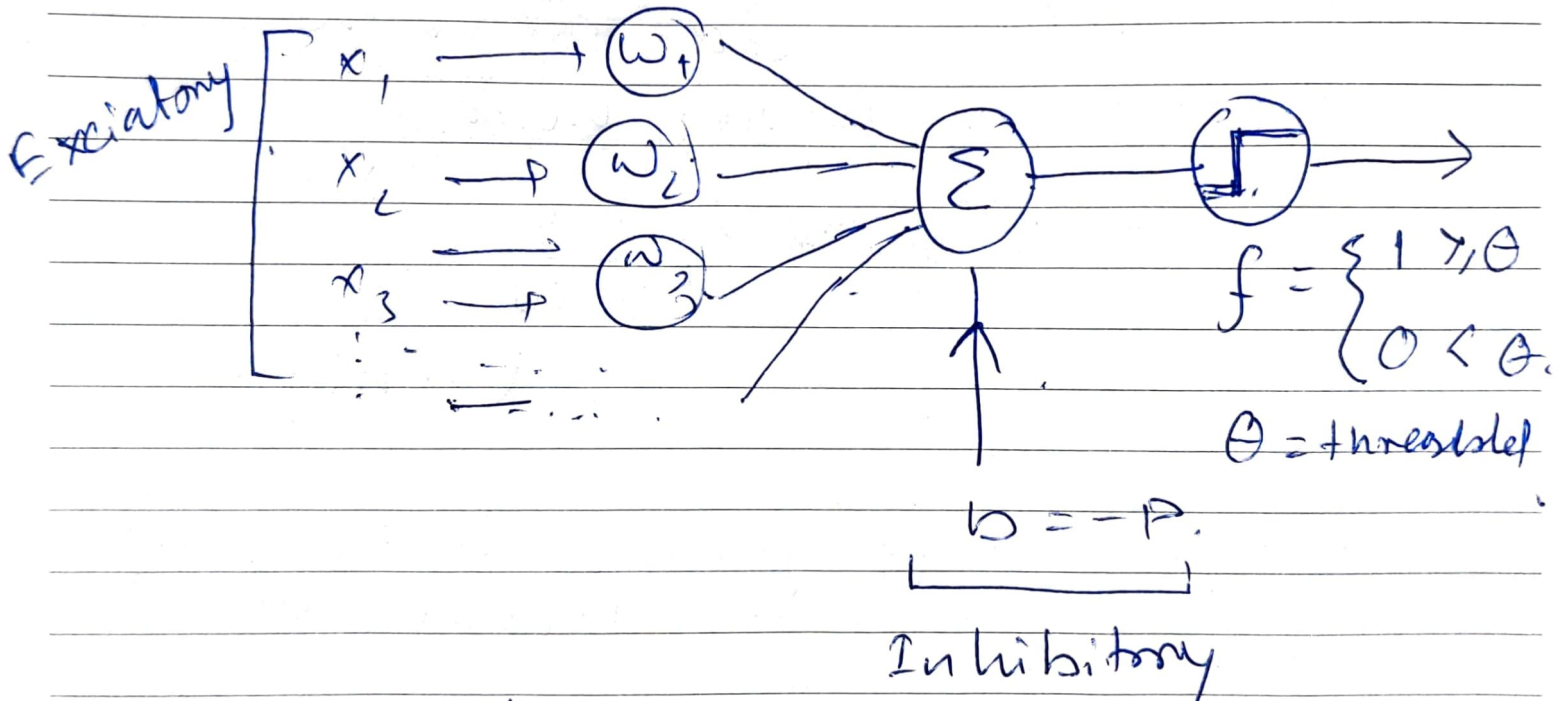


# Deep Learning:

## ① McCulloch - Pitts Neuron [1943]



\* No particular training algorithm.

## ② Hebbian Learning [1949]

"Neurons fire together, wire together"

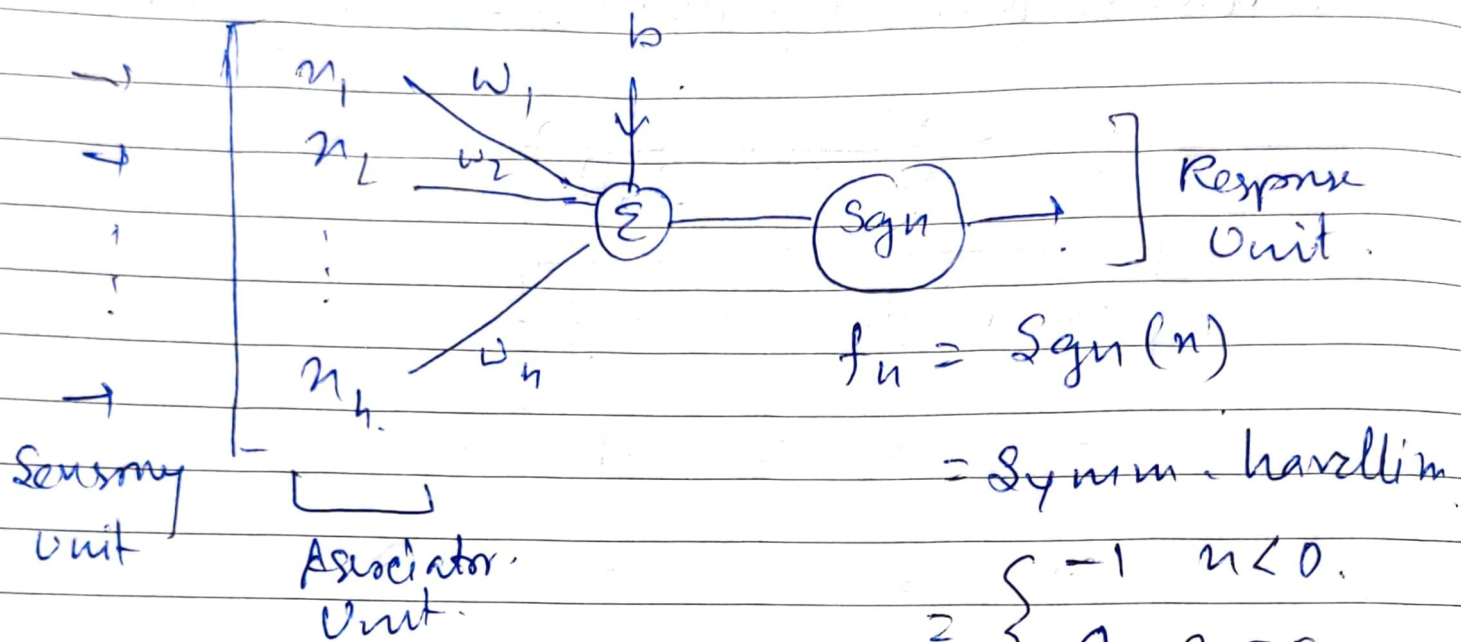
x	y	$\Delta w$
+	+	+
-	-	+
+	-	-
-	+	-

Weight & bias update:

$$w_i(\text{new}) = w_i(\text{old}) + x_i \cdot y$$

$$b_j(\text{new}) = b(\text{old}) + y$$

### ③ - Rosenblatt's Perceptron: [1958]



### Perceptron Learning Theorem

$$w_i(\text{new}) = w_i(\text{old}) + \alpha [t - y] x_i$$

$$t = \begin{cases} +1 & x \in C_1 \\ -1 & x \in C_2 \end{cases}$$

\*  $C_1$  &  $C_2$  are two class for binary classification

If soln<sup>n</sup> exist this learning will generate correct response for all training pattern within finite number of steps.



## ④ Adaptive Linear Neuron (Adeline)

- \* Consists of single linear unit.

linear unit: Unit with linear  
activation function

$$\text{ie. net} = \sum x_i w_i + b$$

- \* Can be trained by Delta/Widrow-Hoff rule / LMS Learning Algo.

- \* Activation (generally):
    - Bipolar Step fun.
    - Sigmoid
    - Hyperbolic Tan.
- Delta/Widrow-Hoff Rule:

$$\Delta w = \alpha (t - y_{in}) x_i$$

Weight & Bias Update:

$$w_i(\text{new}) = w_i(\text{old}) + \alpha (t - y_{in}) x_i$$

$$b(\text{new}) = b(\text{old}) + \alpha (t - y_{in})$$

for non linear activation function,

$$\Delta w_{ji} = \alpha (t_j - y_j) g'(n_j) x_i \quad n_j = \text{net}$$

### ③ Least Mean Square:

Loss (L) = Mean Sq Err.

$$\text{ie } L(w, b) = E [t(k) - y(k)]^2$$

$$= E e(k)^2 = E [e(k)^T e(k)]$$

$$\nabla \hat{L}(w, b) = \nabla e(k)^2$$

\* Approx LMS without expectation of  $e$ .

$$\frac{\partial \hat{L}(w, b)}{\partial w} = \frac{\partial e(k)^2}{\partial w}$$

$$= 2e(k) \cdot \frac{\partial e(k)}{\partial w}$$

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$$\frac{\partial \hat{L}(w, b)}{\partial b} = \frac{\partial e(k)}{\partial b} = 2e(k) \cdot \frac{\partial e(k)}{\partial b}$$

$$\frac{\partial e(k)}{\partial w} = \frac{\partial}{\partial w} [t(k) - y(k)]$$

$$y(k) = \sigma \left[ \underbrace{w^T x(k)}_z + b \right]$$

$$\frac{\partial}{\partial w} [t(k) - \sigma [w^T x(k) + b]]$$

$$= - \frac{\partial}{\partial w} \sigma [w^T x(k) + b]$$

$$= - \frac{\partial \sigma(z)}{\partial z} \cdot \frac{\partial}{\partial w} [w^T x(k) + b]$$

$$= - \frac{\partial \sigma(z)}{\partial z} x(k) = - \sigma'(z) x(k)$$

$$\frac{\partial \ell(k)}{\partial b} = \frac{\partial}{\partial b} [t(k) - \sigma(w^T x(k) + b)]$$

$$= - \frac{\partial \sigma(z)}{\partial z} \cdot \frac{\partial}{\partial b} [w^T x(k) + b]$$

$$= - \frac{\partial \sigma(z)}{\partial z} = - \sigma'(z)$$



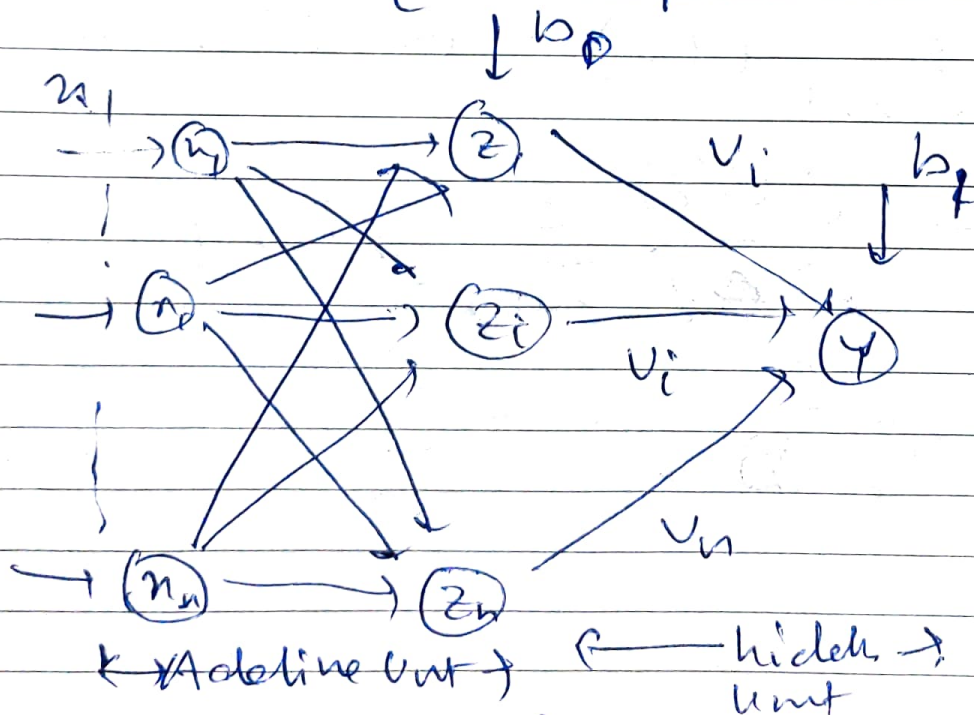
A/c Steepest Descent,

$$x_{k+1} = x_k - \alpha \nabla L(\omega, b)$$

$$\begin{aligned} \omega(k+1) &= \omega(k) + 2\alpha e(k) \cdot \sigma'(z) \cdot x(k) \\ &= \omega(k) + \eta e(k) \cdot \sigma'(z) \cdot x(k) \end{aligned}$$

$$\begin{aligned} b(k+1) &= b(k) + 2\alpha e(k) \cdot \sigma'(z) \\ &= b(k) + \eta e(k) \cdot \sigma'(z) \end{aligned}$$

⑤ Madeline [Multiple Adeline]



Learning: if  $t \neq y$ ;  $t = +1$

$$b_j(\text{new}) = b_j(\text{old}) + \alpha(1 - z_{ij})$$

$$w_{ij}(\text{new}) = w_{ij}(\text{old}) + \alpha(1 - z_{ij})z_i$$

if  $t \neq y$ ;  $t = -1$

$$w_{ij}(\text{new}) = w_{ij}(\text{old}) + \alpha(-1 - z_{ij})z_i$$

$$b_j(\text{new}) = b_j(\text{old}) + \alpha(-1 - z_{ij})$$

if  $t = y$  no update req.

## ⑦ Back propagation:

Feed Forward:

$$a^{m+1} = f^{m+1}(w^{m+1} a^m + b^{m+1})$$

A/c to LMS,  $m$

$$w_{ij}(k+1) = w_{ij}(k) - \alpha \frac{\partial \hat{E}}{\partial w_{ij}^m}$$



$$b_i^m(k+1) = b_i^m(k) - \alpha \frac{\partial \hat{L}}{\partial b_i^m}$$

$$\frac{\partial \hat{L}}{\partial w_{ij}^m} = \frac{\partial \hat{L}}{\partial z_i^m} \cdot \frac{\partial z_i^m}{\partial w_{ij}^m}$$

$$\frac{\partial \hat{L}}{\partial b_i^m} = \frac{\partial \hat{L}}{\partial z_i^m} \cdot \frac{\partial z_i^m}{\partial b_i^m}$$

Where,  $z_i^m = \sum_{j=1}^k w_{ij}^m a_j^{m-1} + b_i^m$

$k = \text{number of neuron in layer } m$

$$\frac{\partial z_i^m}{\partial w_{ij}^m} = a_j^{m-1} ; \quad \frac{\partial z_i^m}{\partial b_i^m} = 1$$

$$\delta_i^m = \frac{\partial \hat{L}}{\partial z_i^m}$$

$$\begin{aligned} w_{ij}^m(k+1) &= w_{ij}^m(k) - \alpha \delta_i^m a_j^{m-1} \\ b_i^m(k+1) &= b_i^m(k) - \alpha \delta_i^m \end{aligned}$$

$$\delta^m = \frac{\partial \hat{L}}{\partial z^m} = \begin{bmatrix} \frac{\partial \hat{L}}{\partial z_1^m} \\ \vdots \\ \frac{\partial \hat{L}}{\partial z_k^m} \end{bmatrix}$$

$$\delta^m = \frac{\partial \hat{L}}{\partial z^m} = \frac{\partial \hat{L}}{\partial z^{m+1}} \frac{\partial z^{m+1}}{\partial z^m} \rightarrow \text{back propagate}$$

$$\frac{\partial z^{m+1}}{\partial z^m} = \begin{bmatrix} \frac{\partial z_1^{m+1}}{\partial z_1^m} & \dots & \frac{\partial z_1^{m+1}}{\partial z_k^m} \\ \vdots & & \vdots \\ \frac{\partial z_l^{m+1}}{\partial z_1^m} & \dots & \frac{\partial z_l^{m+1}}{\partial z_k^m} \end{bmatrix}$$

$$\frac{\partial z_i^{m+1}}{\partial z_j^m} = \frac{\partial}{\partial z_j^m} \left[ \sum_{l=i}^k N_{lj}^{m+1} a_l^m + b_l^{m+1} \right]$$

$$= w_{l,j}^{m+1} a_l^m \quad \left[ \text{for } l=j; \text{ other values are } 0 \right]$$

$$= w_{ij}^{m+1} \frac{\partial f^m(z_j^m)}{\partial z_j^m} = w_{ij}^{m+1} f^m(z_j^m)$$

$$\frac{\partial z^{m+1}}{\partial z^m} = W^{m+1} \cdot F^m(z^m)$$

$$F^m(z^m) = \begin{bmatrix} f^m(z_1^m) & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & f^m(z_k^m) \end{bmatrix}$$

$$S^m = \left( \frac{\partial z^{m+1}}{\partial z^m} \right)^T \frac{\partial \hat{L}}{\partial z^{m+1}} = W^{m+1} \cdot F^m(z^m) \frac{\partial \hat{L}}{\partial z^{m+1}}$$

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$$S^m = W^{m+1} \cdot F^m(z^m) S_{k+1}^{m+1}$$

$$S^M \rightarrow S^{M-1} \rightarrow \dots \rightarrow S^1$$

$$S^M = \frac{\partial \hat{L}}{\partial z_i^M} = \frac{\partial}{\partial z_i^M} \sum_{j=1}^k (t_j - a_j)^2 = -2(t_i - a_i) \frac{\partial a_i^M}{\partial z_i^M} \quad [\text{for } i=j]$$



$$\frac{\partial a_i^M}{\partial z_i^M} = \dot{f}^M(z_i^M)$$

$$\therefore S^M = -2(t_i - a_i^M) \dot{f}^M(z_i^M)$$

$$S^M = -2 \dot{f}^M(z^M) (t - a^M)$$