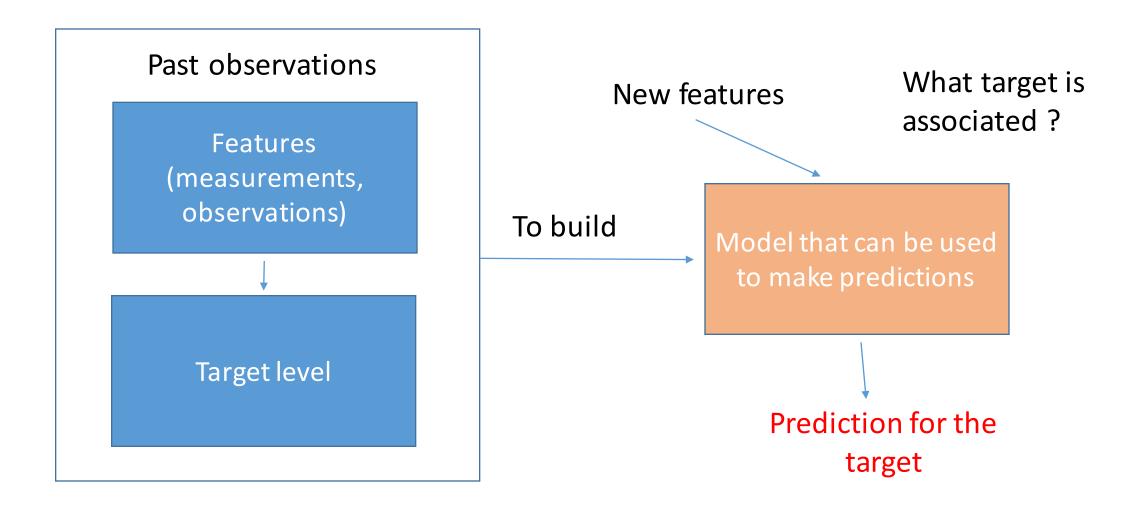
Machine learning with Bayes Naïve models

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Main idea



Rq.: in this chapter, the target is always 1D and discrete

One intuitive way to do it

The predicted "target" is the one that has the maximal probability given the features (observations) – *MAP estimator*

$$t_{opt} = argmax P[t|f_1, f_2, ..., f_n]$$

And we can use Bayes theorem

$$t_{opt} = argmax \ M(t) = argmax \ P[f_1, f_2, ..., f_n | t]P[t]$$

The denominator does not play a role (independent of t)

P[t] is a prior (usually very easy to determine – count the number of occurrences in the set of past observations

Case where f_i is discrete

One can count the ratio of the number of "features" in the set of past observations versus the number of total past observations ("brute force")

$$P[f_1, f_2, ..., f_n | t]$$

Or use the chain rule

$$P[f_1, f_2, ..., f_n | t] = P[f_1 | t] P[f_2 | t, f_1] ... P[f_n | t, f_1, f_2, ...,]$$

Problem: curse of dimensionality. When the number of features grow, it is difficult to have enough past observations to not end up with a 0.

One way to reduce the curse of dim. problem is to assume conditional independence

$$P[X|Y,Z] = P[X|Z]$$
 and $P[X,Y|Z] = P[X|Z]P[Y|Z]$

Condition less strong than strict independence. This condition is usually satisfies when X and Y are produced by Z.

This simplifies the chain rules

$$P[f_1, f_2, ..., f_n|t] = P[f_1|t]P[f_2|t] ... P[f_n|t]$$

And leads to a specific machine learning algorithm

Use the MAP estimator under the assumption of conditional independence of all the features

$$t_{opt} = argmax M(t) = argmax P[f_1|t] P[f_2|t] \dots P[f_n|t] P[t]$$

To "build" the model, we just need to determine the priors P[t] and all the conditional probability $P[f_i \mid t_j]$ for all targets t_j .

The conditional independence of all variables is quite strong but ... and the M(t) is not always very representative but the argmax is pretty insensitive to this change.

Algorithm easy to understand and code, "computationally cheap" and producing good results in most cases

Constructing the model

- 1) Determine the priors P[t] (counting in the dataset)
- Determine P[f|t] (for all features and targets)
 - A) If f is discrete: counting in the dataset
 - B) If f is continuous: two possibilities
 - i) Use a continuous probability distribution function (pdf)
 - choose the form of the pdf (use an histogram)
 - determine the parameters from the pdf
 - ii) Use a binning -> come back to a discrete case

When counting, one may want to use a smoothing

Making prediction from new features:

1) Compute for all targets t_i the "score" $M(t_i)$ (not really a probability)

$$M(t_i) = P[f_1|t_i] P[f_2|t_i] ... P[f_n|t_i] P[t_i]$$

2) Choose the t_i with the largest score: this is the prediction!

Two possibilities when f_i is continuous

1) Introduce a probability distribution function (pdf)

$$P[x < f_i < x + dx] = p_{f_i}(x)dx$$

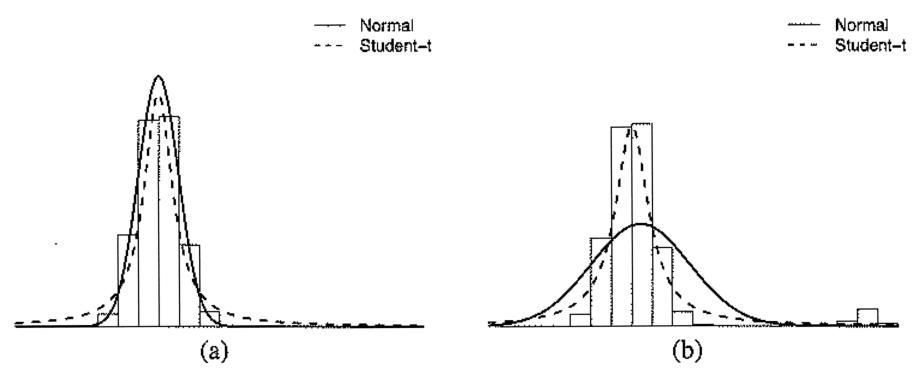
Rq.: Which dx to use is not really defined but in our case, it does not matter because it does not impact the "argmax"

$$t_{opt} = argmax \ P[f_1|t] \dots P[f_n|t]P[t] = argmax \ p_{f_1}(x_1)dx_1p_{f_2}(x_2)dx_2 \dots p_{f_1}(x_n)dx_nP[t]$$
$$= argmax \ p_{f_1}(x_1)p_{f_2}(x_2) \dots p_{f_1}(x_n)P[t]$$

2) Binning the continuous data

- 1) With 1 peak:
 - A) Normal pdf: light tails, very sensitive to outlier
 - B) Student-t pdf: fat tails, robust to outlier

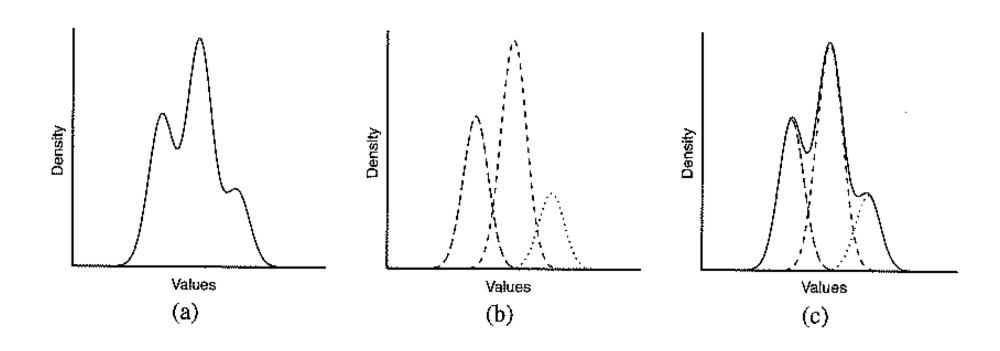
The parameters of the pdf can be determined from the mean and std



Kolmogorov-Smirnov test can help to decide between Normal and student

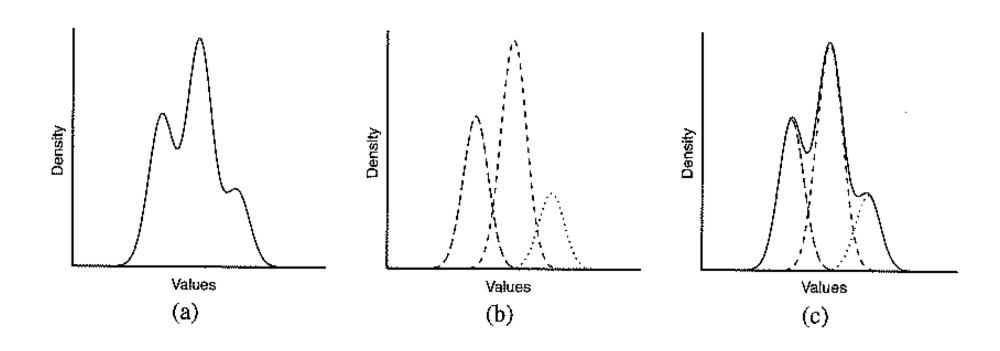
2) With multiple peaks: (multi mode) – sum of weighted normal pdf's (with the sum of the weights =1)

The parameters of the pdf needs to be determined by a fit (gradient algorithm)



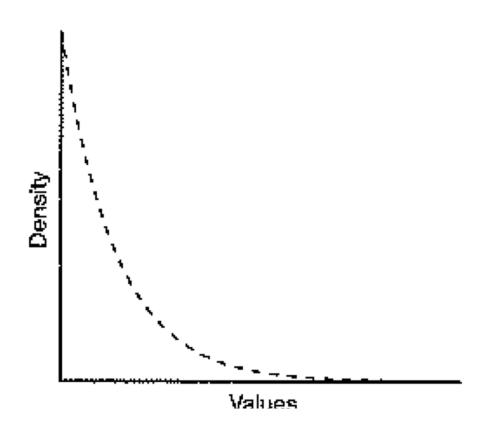
2) With multiple peaks: (multi mode) – sum of weighted normal pdf's (with the sum of the weights =1)

The parameters of the pdf needs to be determined by a fit (gradient algorithm)



2) Exponential pdf: depends on one parameter, the rate

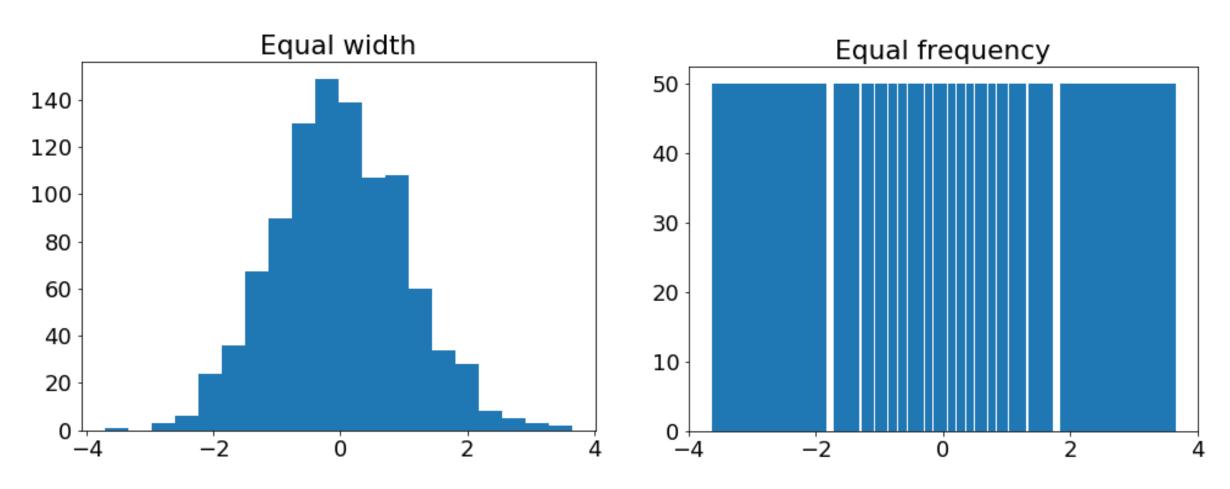
The parameter of the pdf can be determined as 1/mean



Often used to model waiting time, lifetime of components, ...

Two ways to bin a continuous distribution

- 1) equal-width binning
- 2) equal-frequency binning: much better to avoid bin with low number of occurences



Like a discrete distribution: count to determine P[f|t]

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2) Choose the t_i with the largest score: this is the prediction!

The exercise

6 features, 3 targets + hypothesis that all P[f|t] are normally distributed

	COND	SED	Ss	COND	SED	Ss	
STATUS	-OUT	-OUT	-OUT	-IN	-IN	-IN	ID
ok	1,879	0.001	15	1,814	3	168	1
ok	1,425	0.01	14	1,358	3	156	2
ok	2,140	0.005	16	2,200	3.5	176	3
ok	2,700	0.2	27	2,070	3	256	4
settler	1,575	3.5	131	1,410	5	230	5
settler	1,221	0.06	104	1,238	3	116	6
settler	1,434	0.01	104	1,315	7	242	7
settler	1,374	0.02	78	1,183	4.5	242	8
settler	1,256	1.5	73	1,110	2.5	174	9
solids	33.3	1,172	81	1,218	35	1,004	10
solids	43.1	1,932	82.4	1,889	46	1,228	11
solids	1,966	1,030	20	2,120	17	964	12
solids	1,289	1,038	13	1,257	32	2,008	13

The exercise: the prior

6 features, 3 targets + hypothesis that all P[f|t] are normally distributed

	Ss	SED	COND	Ss	SED	COND		
ID	-In	-IN	-IN	-OUT	-OUT	-Out	STATUS	
1	168	3	1,814	15	0.001	1,879	ok	
2	156	3	1,358	14	0.01	1,425	ok	P[ok]=4/13
3	176	3.5	2,200	16	0.005	2,140	ok	P[UK]-4/13
4	256	3	2,070	27	0.2	2,700	ok	
5	230	5	1,410	131	3.5	1,575	settler	
6	116	3	1,238	104	0.06	1,221	settler	P[set]=5/13
7	242	7	1,315	104	0.01	1,434	settler	P[36t]-3/13
8	242	4.5	1,183	78	0.02	1,374	settler	
9	174	2.5	1,110	73	1.5	1,256	settler	
10	1,004	35	1,218	81	1,172	33.3	solids	
11	1,228	46	1,889	82.4	1,932	43.1	solids	P[sol]=4/13
12	964	17	2,120	20	1,030	1,966	solids	
13	2,008	32	1,257	13	1,038	1,289	solids	

The exercise: the conditional probabilities

6 features, 3 targets + hypothesis that all P[f|t] are normally distributed

	Ss	SED	COND	Ss	SED	COND	
ID	-IN	-In	-IN	-OUT	-OUT	-OUT	STATUS
1	168	3	1,814	15	0.001	1,879	ok
2	156	3	1,358	14	0.01	1,425	ok P[SS-IN OK] ~ N (189, 45.42)
3	176	3.5	2,200	16	0.005	2,140	ok
4	256	3	2,070	27	0.2	2,700	ok
5	230	5	1,410	131	3.5	1,575	settler
6	116	3	1,238	104	0.06	1,221	settler
7	242	7	1,315	104	0.01	1,434	settler P[ss-out set]~N(98,23.38)
8	242	4.5	1,183	78	0.02	1,374	settler
9	174	2.5	1,110	73	1.5	1,256	settler
10	1,004	35	1,218	81	1,172	33.3	solids
11	1,228	46	1,889	82.4	1,932	43.1	solids Etc 18 terms
12	964	17	2,120	20	1,030	1,966	solids
13	2,008	32	1,257	13	1,038	1,289	solids

The exercise: the prediction

For each target, we need to compute the "score"

$$M(t_i) = P[f_1|t_i] P[f_2|t_i] ... P[f_n|t_i] P[t_i]$$

Example

$$M(OK) = P[SS - in = 222|OK] ... P[C - OUT = 1642|OK]P[OK]$$

P[ss-in | set]~N(189,45.42)

P[ok]=4/13

The exercise: the prediction

We observe

$$Ss-In = 222$$
, $Sed-In = 4.5$, $Cond-In = 1,518$, $Ss-Out = 74$
 $Sed-Out = 0.25$, $Cond-Out = 1,642$

For each target, we need to compute the "score"

$$M(t_i) = P[f_1|t_i] P[f_2|t_i] ... P[f_n|t_i] P[t_i]$$

Example

M[ok]=3.4 E-36

M[settler]=1.5 E-13

M[solids]=1. E-21