# PROJECT ON VERIFICATION OF DIGITAL SYSTEMS

**TOPIC: LAYERED TESTBENCH FOR PRIORITY ENCODER** 

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#### **OBJECTIVE:**

THE OBJECTIVE OF A **PRIORITY ENCODER** IS TO CONVERT A BINARY INPUT WITH MULTIPLE BITS INTO A BINARY OUTPUT THAT REPRESENTS THE POSITION OF THE HIGHEST-ORDER BIT THAT IS SET TO 1. ADDITIONALLY, IT USUALLY PROVIDES A **VALID SIGNAL** TO INDICATE WHETHER ANY INPUT IS ACTIVE (NON-ZERO).

#### **INTRODUCTION:**

A **priority encoder** is a type of digital circuit that is used to convert a set of binary inputs into a binary output code that represents the position of the highest-order active input bit. It also provides an output signal that indicates whether any input is active or not.

In simple terms, it "encodes" the position of the highest set bit (1) from a set of inputs, with priority given to the higher-order bits. This makes it useful in applications where you need to know the highest active signal from a group of signals, such as in interrupt handling, data compression, and digital communication systems.

Truth table for 4 bit priority encoder:

	Input				Output		
13	12	l1	10	01	00	٧	
0	0	0	0	0	0	0	
0	0	0	1	0	0	1	
0	0	1	Х	0	1	1	
0	1	Χ	Х	1	0	1	
1	Χ	Χ	Х	1	1	1	

```
module priority_encoder (
     input bit [3:0] I, // 4-bit input
     output bit [1:0] Y, // 2-bit output (priority)
     output bit Valid // Valid flag
5);
      always @(*) begin
           case (I)
               4'b0000: begin Y = 2'b00; Valid = 0; end
8
               4'b0001: begin Y = 2'b00; Valid = 1; end
               4'b0010: begin Y = 2'b01; Valid = 1; end
10
              4'b0011: begin Y = 2'b01; Valid = 1; end
11
              4'b0100: begin Y = 2'b10; Valid = 1; end
12
              4'b0101: begin Y = 2'b10; Valid = 1; end
13
              4'b0110: begin Y = 2'b10; Valid = 1; end
14
              4'b0111: begin Y = 2'b10; Valid = 1; end
15
              4'b1000: begin Y = 2'b11; Valid = 1; end
16
              4'b1001: begin Y = 2'b11; Valid = 1; end
17
              4'b1010: begin Y = 2'b11; Valid = 1; end
18
              4'b1011: begin Y = 2'b11; Valid = 1; end
19
              4'b1100: begin Y = 2'b11; Valid = 1; end
20
              4'b1101: begin Y = 2'b11; Valid = 1; end
21
              4'b1110: begin Y = 2'b11; Valid = 1; end
22
               4'b1111: begin Y = 2'b11; Valid = 1; end
23
               default: begin Y = 2'b00: Valid = 0: end
24
           endcase
25
       end
26
  endmodule
27
28
```

SYSTEM
VERILOG
CODE FOR
PRIORITY
ENCODER

#### TRANSCATION CODE



```
class transaction;
rand bit [3:0] I;
bit[1:0] Y;
bit Valid;

function void display(string name);
$display("%s",name);
$display("I=%b",I);
$display("Y=%b",Valid=%0d",Y,Valid);
endfunction
endclass
```

#### **GENERATOR CODE**

```
testbench.sv
             transcation.sv
                             generator.sv
                                           monitor.sv
                          interface1.sv
                                         drive.sv
scoreboard.sv
               test.sv
            *
envirnoment.sv
      class generator;
        transaction trans;
        mailbox gen2driv;
        function new(mailbox gen2driv);
           this.gen2driv=gen2driv;
   6
        endfunction
    8
        task main();
           repeat(1)
   10
             begin
   11
               trans=new();
   12
               trans.randomize();
   13
               trans.display("Generator");
   14
               gen2driv.put(trans);
   15
             end
   16
        endtask
   17
   18 endclass
```

#### **DRIVER CODE**



```
class drive;
    virtual intf vif;
     mailbox gen2driv;
     function new(virtual intf vif, mailbox
   gen2driv);
       this.vif=vif;
       this.gen2driv=gen2driv;
6
     endfunction
8
       task main;
9
         repeat(1)
10
           begin
11
             transaction trans;
12
             gen2driv.get(trans);
13
             vif.I <= trans.I;</pre>
14
             trans.Y=vif.Y;
15
             trans.Valid=vif.Valid;
16
             trans.display("Driver");
17
18
           end
       endtask
19
   endclass.
```

#### **MONITOR CODE**



```
class monitor;
    virtual intf vif;
    mailbox mon2scb;
3
    function new(virtual intf vif, mailbox
  mon2scb);
      this.vif=vif;
      this.mon2scb=mon2scb;
     endfunction
8
9
     task main;
10
      repeat(1)
11
         #5;
12
      begin
13
         transaction trans:
14
         trans=new();
15
         trans.I=vif.I;
16
         trans.Y=vif.Y:
17
         trans.Valid=vif.Valid;
18
         mon2scb.put(trans);
19
         trans.display("Monitor");
20
       end
21
     endtask
22
  endclass
```

#### SCOREBOARD CODE

```
class scoreboard:
     bit [3:0] I;
 2
     bit [1:0] Y;
bit Valid;
 3
 4
     mailbox mon2scb;
 5
 6
     function new(mailbox mon2scb);
 7
       this.mon2scb=mon2scb:
 8
     endfunction
 9
10
     task main:
11
       transaction trans;
12
       repeat(1)
13
14
         begin
15
            mon2scb.get(trans):
            if(I==4'b0000) assert (Y==2'b00 && Valid==0);
16
            else if (I==4'b0001) assert (Y==2'b00 && Valid==1);
17
            else if (I==4'b0010) assert (Y==2'b01 &&Valid==1);
18
            else if (I==4'b0011) assert (Y==2'b01 && Valid==1);
19
            else if (I==4'b0100) assert (Y==2'b10 && Valid==1);
20
            else if (I==4'b0101) assert (Y==2'b10 && Valid==1);
21
22
            else if (I==4'b0110) assert (Y==2'b10 && Valid==1);
            else if (I==4'b0111) assert (Y==2'b10 && Valid==1);
23
            else if (I==4'b1000) assert (Y==2'b11 && Valid==1);
24
            else if (I==4'b1001) assert (Y==2'b11 && Valid==1);
25
            else if (I==4'b1010) assert (Y==2'b11 && Valid==1);
else if (I==4'b1011) assert (Y==2'b11 && Valid==1);
26
27
            else if (I==4'b1100) assert (Y==2'b11 && Valid==1);
28
            else if (I==4'b1101) assert (Y==2'b11 && Valid==1);
29
            else if (I==4'b1110) assert (Y==2'b11 && Valid==1);
30
            else if (I==4'b1111) assert (Y==2'b11 && Valid==1);
31
            trans.display("Scoreboard");
32
33
         end
     endtask
34
   endclass
```

#### **INTERFACE CODE**



```
interface intf();
logic [3:0]I;
logic [1:0]Y;
logic Valid;
endinterface
```

#### **ENVIRONMENT CODE**

```
include
    include
   `include "drive.sv"
   include
   include
6
   class environment;
     generator gen;
8
     drive driv;
9
     monitor mon;
10
     scoreboard scb;
11
     mailbox m1;
12
13
     mailbox m2;
     virtual intf vif;
14
     function new(virtual intf vif);
15
       this.vif=vif;
16
       m1=new();
17
       m2=new();
18
       gen=new(m1);
19
       driv=new(vif,m1);
20
21
       mon=new(vif,m2);
22
       scb=new(m2);
     endfunction
23
24
25
     task test();
       fork
26
         gen.main();
27
         driv.main();
28
         mon.main();
29
         scb.main():
30
       join
31
     endtask
32
33
34
     task run;
35
       test();
       $finish;
36
37
     endtask
38
   endclass
```

#### **TEST CODE**

```
scoreboard.sv * test.sv * interface1.sv *
```

```
include "envirnoment.sv"
program test (intf i_intf);
environment env;
initial
begin
env=new(i_intf);
env.run();
end
endprogram
```

#### **TESTBENCH CODE**



```
include "interface1.sv"
include "test.sv"
module tbench_top;
intf i_intf();
test t1(i_intf);
priority_encoder h1(
    .I(i_intf.I),
    .Y(i_intf.Y),
    .Valid(i_intf.Valid)
);
endmodule
```

### **OUTPUT**

```
# Loading work.priority_encoder(fast)
# Loading work.intf(fast)
# run -all
# Generator
# I=0101
# Y=00 ,Valid=0
# Driver
# I=0101
# Y=00 ,Valid=0
# Monitor
# I=0101
# Y=10 ,Valid=1
# Scoreboard
# I=0101
# Y=10 ,Valid=1
# ** Note: $finish
                     : envirnoment.sv(37)
    Time: 5 ns Iteration: 0 Instance: /tbench_top/t1
# End time: 01:34:43 on Dec 02,2024, Elapsed time: 0:00:01
# Errors: 0, Warnings: 0
# *** Summary **********************
     qrun: Errors: 0, Warnings:
     vlog: Errors: 0, Warnings:
     vopt: Errors: 0, Warnings:
     vsim: Errors:
                     0, Warnings:
   Totals: Errors:
                     0, Warnings:
Done
```

**EDA PLAYGROUND LINK** 

https://www.edaplayground.com/x/RDTE

## THANKYOU