

Computation of Forces Arising from the Linear Poisson-Boltzmann Method in the Domain Decomposition Paradigm

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Joint work with M.Nottoli (Università di Pisa, Pisa), C. Quan (SUS Tech, China),
and B. Stamm (Universität Stuttgart, Stuttgart)

1 Solvation Models

2 ddLPB Method

3 Computation of Forces

4 Numerical Studies

5 Conclusions and Outlook

- Ionic Solvation Models¹

- Explicit Solvation Models

- Adopts molecular representation of both solute and solvent
 - Accurate results
 - Computationally expensive

¹ Zhang et. al.: JCTC, 13, 1034-1043, 2017

² Tomasci, Persico: CR 94, 2027-2094, 1994

³ Honig, Nicholls: Sci. 268, 1144-1149, 1995

- Ionic Solvation Models¹
 - Explicit Solvation Models
 - Adopts molecular representation of both solute and solvent
 - Accurate results
 - Computationally expensive
 - Implicit Solvation Models^{2,3}
 - Microscopic treatment of solute
 - Macroscopic treatment of solvent using physical properties
 - Less computational cost

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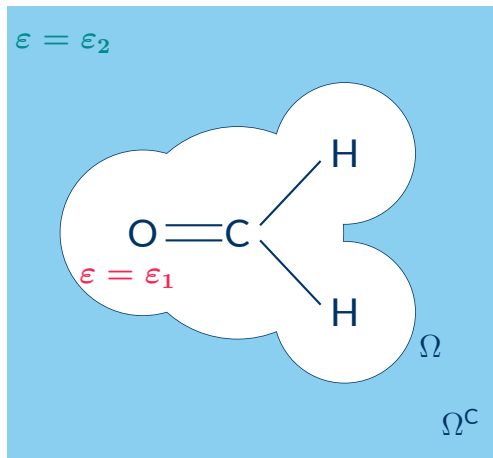


Figure 1: Formaldehyde molecule

- Linear Poisson-Boltzman (LPB) equation

$$-\nabla \cdot [\varepsilon(\mathbf{x}) \nabla \psi(\mathbf{x})] + \bar{\kappa}(\mathbf{x})^2 \psi(\mathbf{x}) = 4\pi \rho_M(\mathbf{x}) \quad \text{in } \mathbb{R}^3$$

- $\psi(\mathbf{x})$ – Electrostatic potential

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- $\psi(\mathbf{x})$ – Electrostatic potential
- $\varepsilon(\mathbf{x})$ – Space-dependent dielectric permittivity

$$\varepsilon(\mathbf{x}) = \begin{cases} \varepsilon_1 & \text{in } \Omega, \\ \varepsilon_2 & \text{in } \Omega^c := \mathbb{R}^3 \setminus \bar{\Omega} \end{cases}$$

- Ω – Solute Cavity

- $\bar{\kappa}(\mathbf{x})$ – Modified Debye-Hückel parameter

$$\bar{\kappa}(\mathbf{x}) = \begin{cases} 0 & \text{in } \Omega, \\ \sqrt{\varepsilon_2} \kappa & \text{in } \Omega^c \end{cases}$$

- κ – Debye-Hückel screening constant

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- κ – Debye-Hückel screening constant
- $\rho_M(\mathbf{x})$ – Solute charge distribution

$$\rho_M(\mathbf{x}) = \sum_{i=1}^M q_i \delta(\mathbf{x} - \mathbf{x}_i)$$

- M – Number of solute atoms
- q_i – Partial charge on the i^{th} atom

- **Boundary Element Method (BEM)** ¹

¹Yoon, Lehnoff: JCC 11, 1080–1086, 1990

²Madura et.al.: CPC 91, 57–95, 1995

³Chen, Holst, Xu: SINUM 45, 2295–2320, 2007

⁴Cancés, Maday, Stamm: JCP 139, 054111, 2013

⁵Lipparini et.al.: JCP 141, 184108, 2014

⁶Quan, Stamm, Maday: SISC 41, B320–B350, 2019

⁷Lebedev, Laikov: DM 59, 477–481, 1999

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- **Finite Difference Method (FDM)**²

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- **Boundary Element Method (BEM)**¹
- **Finite Difference Method (FDM)**²
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- **Domain Decomposition Methods**^{4,5,6}
 - Schwarz decomposition method
 - **Does not rely on mesh** but quadrature points⁷
 - Computation of forces becomes natural as spheres are centered at nucleus position

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- The LPB equation can be written in two equations

$$\begin{aligned} -\Delta \psi(\mathbf{x}) &= \frac{4\pi}{\varepsilon_1} \rho_M(\mathbf{x}) && \text{in } \Omega, \\ -\Delta \psi(\mathbf{x}) + \kappa^2 \psi(\mathbf{x}) &= 0 && \text{in } \Omega^c, \end{aligned}$$

with

$$\begin{aligned} \llbracket \psi(\mathbf{x}) \rrbracket &= 0 && \text{on } \Gamma, \\ \llbracket \partial_{\mathbf{n}} \psi(\mathbf{x}) \rrbracket &= 0 && \text{on } \Gamma \end{aligned}$$

- Using potential theory the final equations are

$$\begin{aligned}-\Delta\psi_r(x) &= 0 \quad \text{in } \Omega, \\ -\Delta\psi_e(x) + \kappa^2\psi_e(x) &= 0 \quad \text{in } \Omega,\end{aligned}$$

with

$$\begin{aligned}\psi_0 + \psi_r &= \psi_e \quad \text{on } \Gamma, \\ \sigma_e &= \partial_n \psi_e - \frac{\epsilon_1}{\epsilon_2} \partial_n (\psi_0 + \psi_r) \quad \text{on } \Gamma^1\end{aligned}$$

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where

- ψ_r – Reaction potential in Ω
- ψ_0 – Potential generated by ρ_M satisfying,

$$-\Delta\psi_0 = \frac{4\pi}{\varepsilon_1} \rho_M$$

¹Sauter, Schwab, Springer, Berlin-2011, Thm. 3.3.1

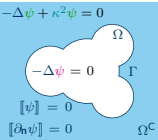
- ψ_e – Extended potential from Ω^C to Ω
- σ_e – Charge density generating ψ_e satisfying

$$S_{\kappa}\sigma_e(x) := \int_{\Gamma} \frac{\exp(-\kappa|x-y|)\sigma_e(y)}{4\pi|x-y|} = \psi_e \quad \forall x \in \Gamma$$

- S_{κ} – Invertible single-layer potential operator¹

$$S_{\kappa} : H^{-1/2}(\Gamma) \rightarrow H^{1/2}(\Gamma)$$

¹Sauter, Schwab, Springer, Berlin-2011, 101-181



$-\Delta\psi + \kappa^2\psi = 0$

$-\Delta\psi = 0$

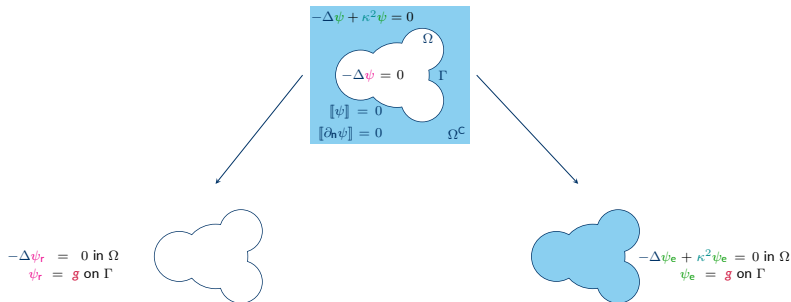
$[[\psi]] = 0$

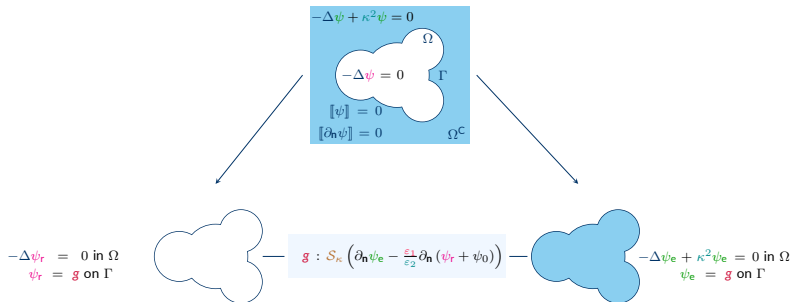
$[[\partial_n\psi]] = 0$

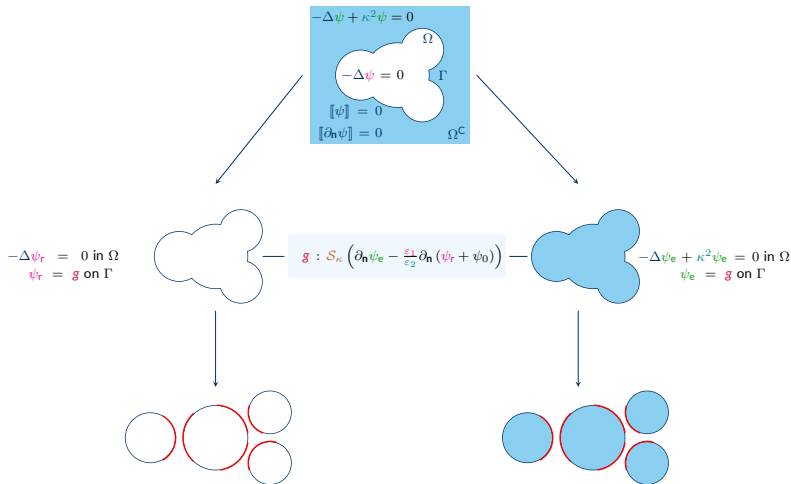
Ω

Γ

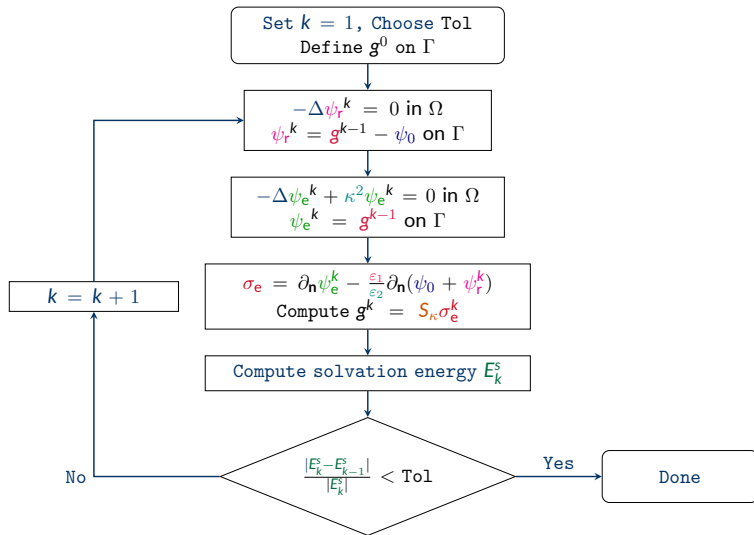
Ω^c







Global strategy



- Energy for LPB equations¹

$$E_s = \frac{1}{2} \langle \psi_r, \rho_M \rangle = \frac{1}{2} \sum_{j=1}^M \langle X, Q \rangle_j,$$

where,

$$[Q]_{j\ell m} = \begin{cases} q_j \delta_{\ell 0} \delta_{m 0}, & \text{if } 1 \leq j \leq M, \\ 0 & \text{if } M < j \leq 2M. \end{cases}$$

and

$$\langle X, Q \rangle_j = \sum_i [X]_{ji} [Q]_{ji}.$$

¹Fogolari, Brigo, Molinari: JMR 15, 2002

- Force with respect to λ

$$F_{\lambda} = \nabla^{\lambda} (E_s) = \frac{1}{2} \left(\langle \nabla^{\lambda} X, Q \rangle + \langle X, \nabla^{\lambda} Q \rangle \right) = \frac{1}{2} \langle \nabla^{\lambda} X, Q \rangle$$

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- Let $LX = g$ be the ddLPB system

$$\begin{aligned} \nabla^{\lambda} LX + L \nabla^{\lambda} X &= \nabla^{\lambda} g \\ \nabla^{\lambda} X &= L^{-1} \left(\nabla^{\lambda} g - \nabla^{\lambda} LX \right). \end{aligned}$$

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- Substituting $\nabla^{\lambda} X$

$$\begin{aligned} F_{\lambda} &= \frac{1}{2} \langle L^{-1} \left(\nabla^{\lambda} g - \nabla^{\lambda} LX \right), Q \rangle \\ &= \frac{1}{2} \langle \left(\nabla^{\lambda} g - \nabla^{\lambda} LX \right), (L^{-1})^* Q \rangle \\ &= \frac{1}{2} \langle \left(\nabla^{\lambda} g - \nabla^{\lambda} LX \right), X_{\text{adj}} \rangle \end{aligned}$$

- Linear System

$$\mathbf{L}\mathbf{x} = \mathbf{g},$$

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where

$$\mathbf{L} = \begin{bmatrix} \mathbf{A} & 0 \\ 0 & \mathbf{B} \end{bmatrix} + \begin{bmatrix} \mathbf{C}_1 & \mathbf{C}_2 \\ \mathbf{C}_1 & \mathbf{C}_2 \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} \mathbf{X}_r \\ \mathbf{X}_e \end{bmatrix}, \quad \text{and} \quad \mathbf{g} = \begin{bmatrix} \mathbf{G}_0 + \mathbf{F}_0 \\ \mathbf{F}_0 \end{bmatrix}$$

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- Using the global strategy

$$\begin{bmatrix} \mathbf{A} & 0 \\ 0 & \mathbf{B} \end{bmatrix} \begin{bmatrix} \mathbf{X}_r^k \\ \mathbf{X}_e^k \end{bmatrix} = - \begin{bmatrix} \mathbf{C}_1 & \mathbf{C}_2 \\ \mathbf{C}_1 & \mathbf{C}_2 \end{bmatrix} \begin{bmatrix} \mathbf{X}_r^{k-1} \\ \mathbf{X}_e^{k-1} \end{bmatrix} + \begin{bmatrix} \mathbf{G}_0 + \mathbf{F}_0 \\ \mathbf{F}_0 \end{bmatrix}$$

where

- k — Iteration
- \mathbf{F}_0 — Associated with $\partial_{\mathbf{n}}\psi_0$
- \mathbf{C}_1 — Associated with $\partial_{\mathbf{n}}\psi_r$
- \mathbf{C}_2 — Associated with $\partial_{\mathbf{n}}\psi_e$

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 - \mathbf{F}_0 – Associated with $\partial_{\mathbf{n}}\psi_0$
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 - \mathbf{C}_2 – Associated with $\partial_{\mathbf{n}}\psi_e$
- \mathbf{A}, \mathbf{B} are sparse
- $\mathbf{C}_1, \mathbf{C}_2$ are not sparse

- Comparison of Results
 - Adaptive Poisson-Boltzmann Solver¹
 - Energy
 - Memory

¹ Jurrus et. al. : Protein Sci. 27 (1), 112-128, 2018

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- Analytical Forces vs Finite Difference

$$D_h[E_s](\lambda) = \frac{E_s(\lambda + h) - E_s(\lambda)}{h}$$

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- Comparison of Results

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$$D_h[E_s](\lambda) = \frac{E_s(\lambda + h) - E_s(\lambda)}{h}$$

- ℓ^∞ error
- ℓ^2 error

$$\text{Err}_{j,\alpha}(h) = D_h[E_s](x_{j,\alpha}) - \frac{\partial E_s}{\partial x_{j,\alpha}},$$

with

$$\mathbf{x}_j = (x_{j,1}, x_{j,2}, x_{j,3})^T$$

¹ Jurrus et. al. : Protein Sci. 27 (1), 112-128, 2018

- Constants in the Model

- $\varepsilon_1 = 1, \varepsilon_2 = 78.54$

- $\kappa = 0.104 \text{ \AA}^{-1}$

¹ ddX: <https://github.com/ACoM-Computational-Mathematics/ddX>

² Berman et. al. : NAR 28, 235-242, 2000

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- Stopping Criteria¹

- GMRES Tol= 10^{-8}

- Tol= 10^{-10}

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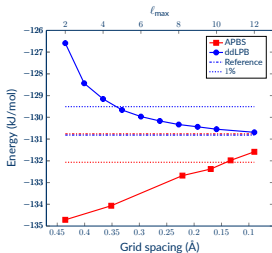
- Test Structure²

PDB Code	M	Name
1ay3	25	Nodularin
1etn	180	Enterotoxin
1qjt	9046	EH1 Domain

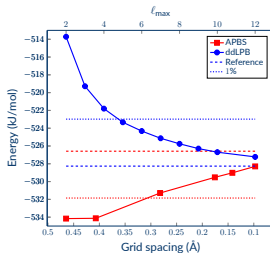
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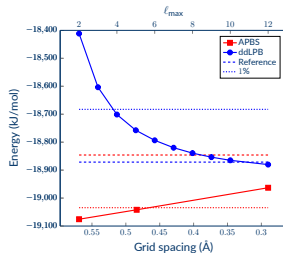
Energy



(a) 1ay3



(b) 1etn

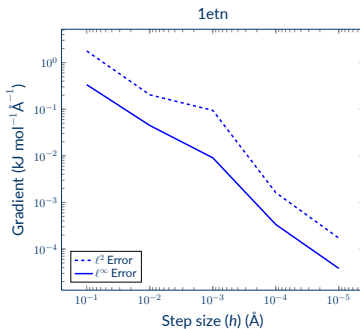
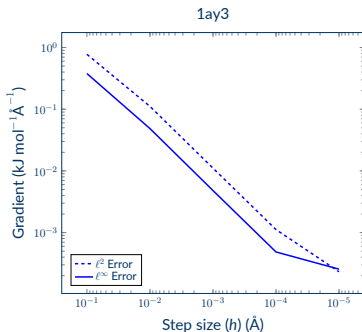


(c) 1qjt

- Memory

PDB Code	ddLPB					APBS			
	ℓ_{\max}	Energy (kJ/mol)	Rel. En.	Mem. (GB)	Iter.	h (Å)	Energy (kJ/mol)	Rel. En.	Mem. (GB)
1ay3 (25)	2	-126.5891	0.0323	0.0347	5	0.4353	-134.7127	0.0302	0.0215
	3	-128.4347	0.0182	0.0463	6	0.0127	-134.0656	0.0253	0.0218
	4	-129.1554	0.0127	0.0416	6	0.2213	-132.6796	0.0147	0.0638
	5	-129.6607	0.0088	0.0473	6	0.1697	-132.3780	0.0124	0.1244
	6	-129.9653	0.0065	0.0569	6	0.1333	-131.9791	0.0093	0.2448
	7	-130.1668	0.0050	0.0752	6	0.0900	-131.5849	0.0063	0.7906
	8	-130.3308	0.0037	0.0922	6				
	9	-130.4356	0.0029	0.1249	6				
	10	-130.5462	0.0021	0.1525	6				
	12	-130.6886	0.0010	0.2873	6				
1qjt (9046)	2	-18 411.4422	0.0244	1.2203	6	0.5690	-19 075.6126	0.0122	2.9358
	3	-18 603.4737	0.0142	3.1045	8	0.4840	-19 041.8281	0.0104	4.7910
	4	-18 701.0889	0.0090	6.9332	9	0.2900	-18 962.9862	0.0062	24.8033
	5	-18 757.4013	0.0060	13.7357	10				
	6	-18 793.3707	0.0041	24.7674	10				
	7	-18 819.8066	0.0027	41.5118	11				
	8	-18 839.1510	0.0017	65.6922	11				
	9	-18 853.5883	0.0009	99.2852	11				
	10	-18 864.8898	0.0003	144.5051	11				
	12	-18 880.1518	0.0005	279.6300	11				

- Analytical Forces vs Finite Difference



- **Conclusions**¹
 - **Derivation** of analytical forces for the ddLPB numerical method using the adjoint method

¹ J.,Nottoli, Quan, Stamm: arXiv : 2203.00552 , 2022

² ddX: <https://github.com/ACoM-Computational-Mathematics/ddX>

³ Mikhalev,Nottoli, Stamm: chemrxiv : 10.26434 , 2022

⁴ Geng,Kransy: JCP, 247, 62-78, 2013

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 - **Implementation** of the energy and forces validated by comparing results with APBS²

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 - Current implementation scales **quadratically** with number of atoms

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- **Outlook**
 - FMM implementation for **linear** scaling³
 - **Comparison** with other software⁴

¹ J., Nottoli, Quan, Stamm: arXiv : 2203.00552 , 2022

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