```
% N = 10000;
% theta = rand(N,1);
% r =1;
% x = zeros(2,N);
 * x(1,:) = r*sin(2*pi*theta); 
% x(2,:) = r*cos(2*pi*theta);
% mu = sum(x,2)/N;
% Cov = zeros(2);
% for i = 1:N
     Cov = Cov + x(:,i)*x(:,i)';
% end
% Cov = Cov / N
clear;
clc;
rng(1000);
N = 10^5;
radius = 1;
x_sum = 0;
y_sum = 0;
covariance_help = zeros(2,2);
for i = 1:N
    theta = 2*pi*rand();
    x = radius*cos(theta);
    y = radius*sin(theta);
    x_sum = x_sum + x;
    y_sum = y_sum + y;
    X = [x; y] * [x y];
    covariance_help = covariance_help + X;
end
mean_matrix = [x_sum/N; y_sum/N];
covariance = covariance_help - mean_matrix*transpose(mean_matrix);
covariance = covariance/N;
mean_matrix
covariance
Ν
mean_matrix =
    0.0016
    0.0008
covariance =
```

0.5000 -0.0007 -0.0007 0.5000

N =

100000

Published with MATLAB® R2019b