Audio Processing With Deep Learning



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Problem Statement

Cornell Birdcall Identification

Objective: Challenge in this project is to identify which birds are calling in long recordings, given training data generated in

meaningfully different contexts.

Problem Link: https://www.kaggle.com/c/birdsong-recognition/data

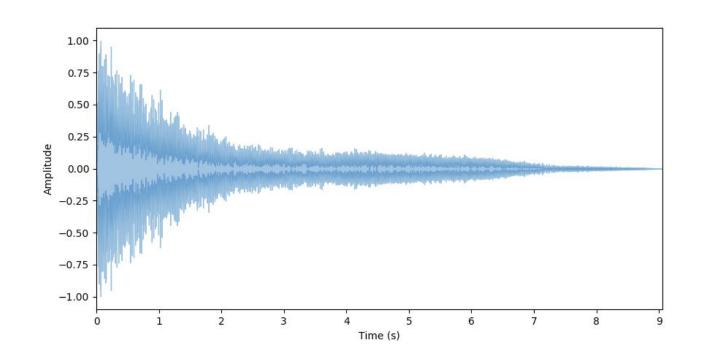
Code Link: https://github.com/abhinav8292/Deep_learning

Techstack: Python, Librosa, Numpy, Tensorflow, Matplotlib, Jupyter, VsCode

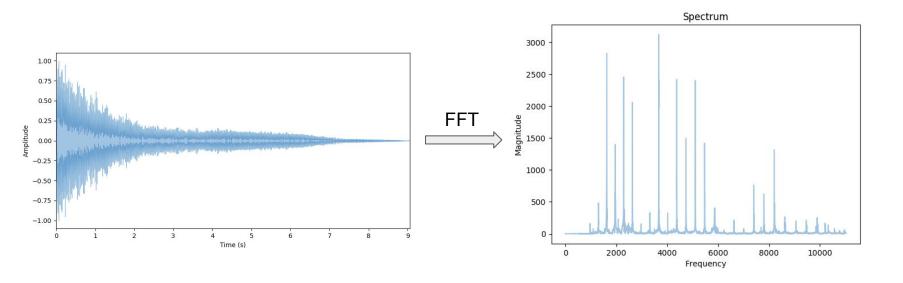
Understanding audio data for

deep learning

A real-world sound wave (piano key)

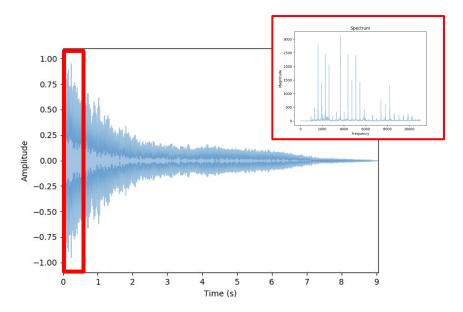


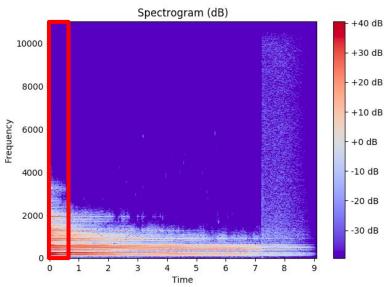
Fourier transform

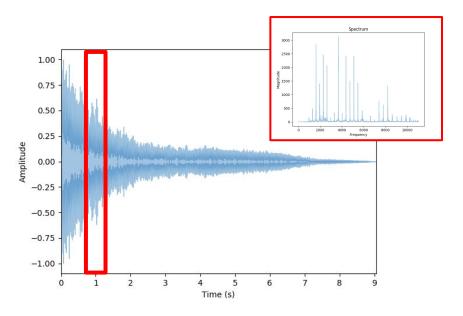


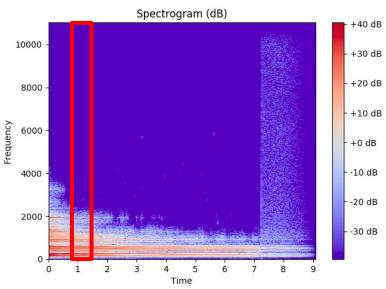
- From time domain to frequency domain
- No time information

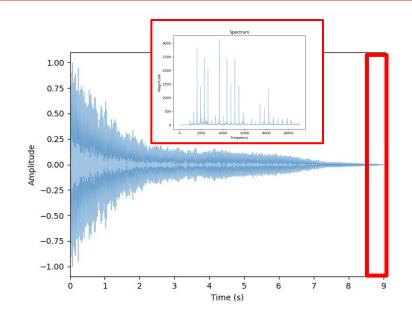
- Computes several FFT at different intervals
- Preserves time information
- Fixed frame size (e.g., 2048 samples)
- Gives a spectrogram (time + frequency + magnitude)

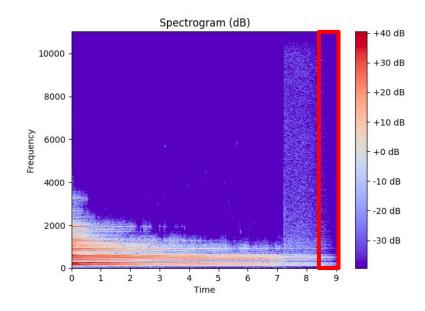




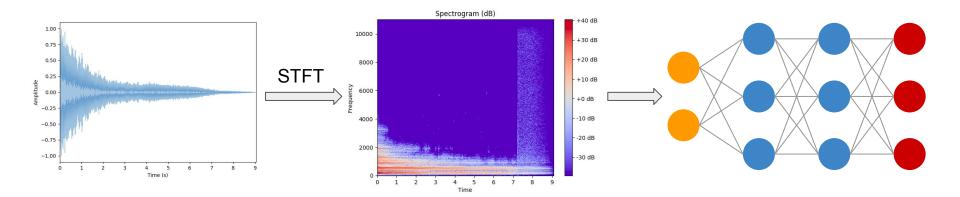








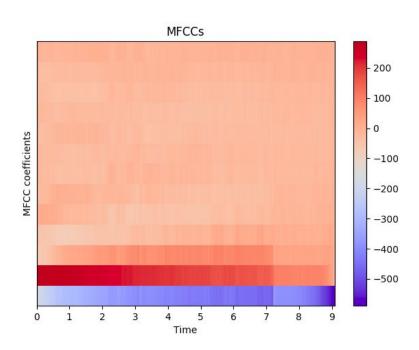
DL pre-proprocessing pipeline for audio data



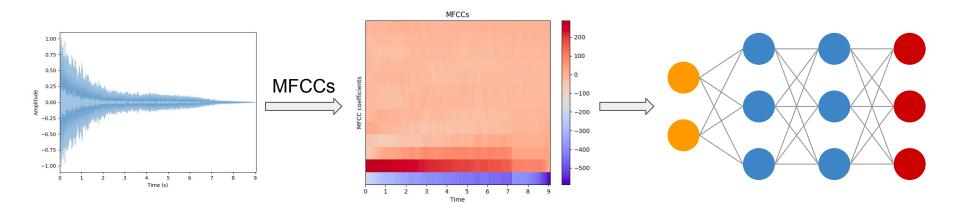
Mel Frequency Cepstral Coefficients (MFCCs)

- Capture timbral/textural aspects of sound
- Frequency domain feature
- Approximate human auditory system
- 13 to 40 coefficients
- Calculated at each frame

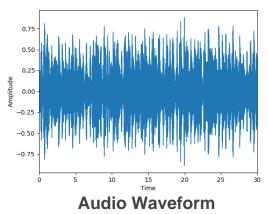
Mel Frequency Cepstral Coefficients (MFCCs)

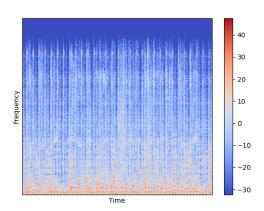


DL pre-proprocessing pipeline for audio data

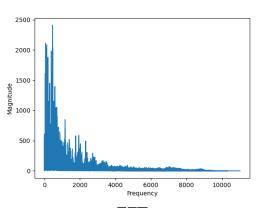


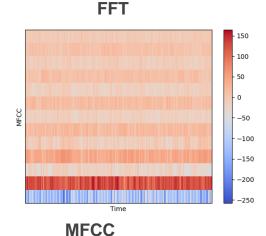
Birdsong Audio Features



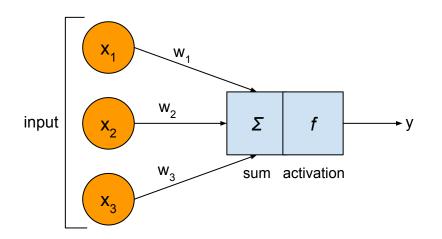


Spectrogram





The artificial neuron



$$h = \sum_{i} x_{i}w_{i} = x_{1}w_{1} + x_{2}w_{2} + x_{3}w_{3}$$

$$y = f(h) = f(x_{1}w_{1} + x_{2}w_{2} + x_{3}w_{3})$$

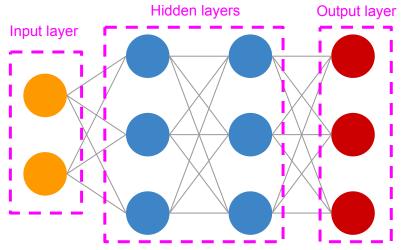
$$y = \frac{1}{1 + e^{-(x_{1}w_{1} + x_{2}w_{2} + x_{3}w_{3})}}$$

Why is a neural network needed?

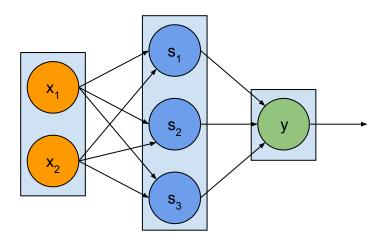
- A single neuron works for linear problems
- Real-world problems are complex
- ANNs can reproduce highly non-linear functions

The components of an artificial neural network (ANN)

- Neurons
- Input, hidden, output layers
- Weighted connections
- Activation function



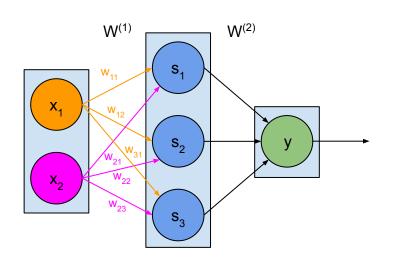
The multilayer perceptron (MLP)



Computation in MLP

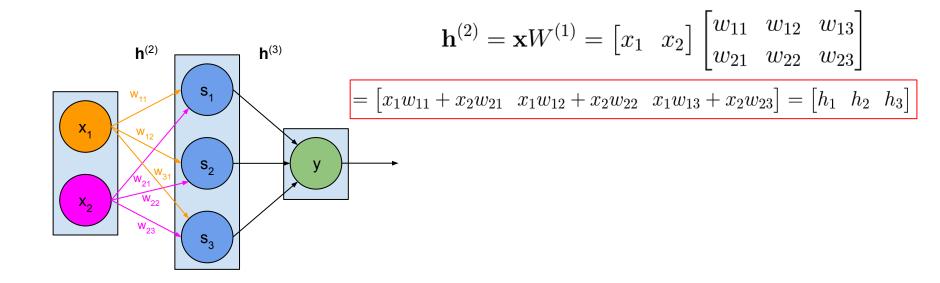
- Weights
- Net inputs (sum of weighted inputs)
- Activations (output of neurons to next layer)

Weights

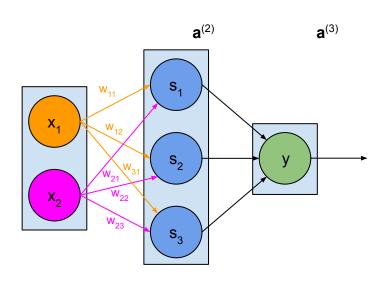


$$W^{(1)} = \begin{bmatrix} w_{11} & w_{12} & w_{13} \\ w_{21} & w_{22} & w_{23} \end{bmatrix}$$

Net input

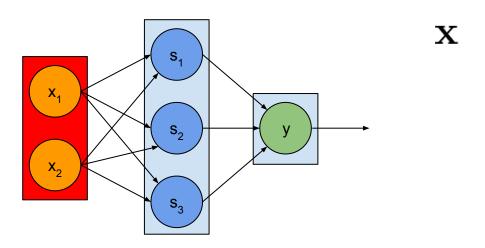


Activation

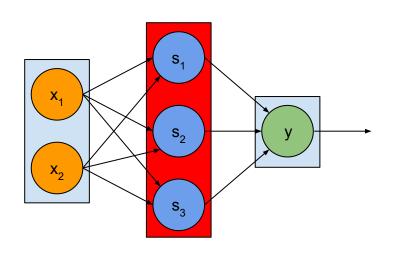


$$\mathbf{a}^{(2)} = f(\mathbf{h}^{(2)})$$

Computation in MLP (1st layer)



Computation in MLP (2nd layer)

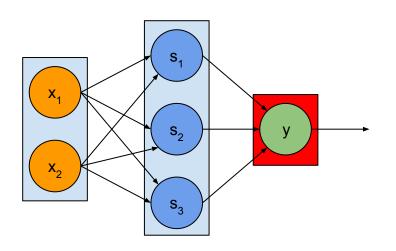


$$\mathbf{h}^{(2)} = \mathbf{x} W^{(1)}$$

$$\mathbf{h}^{(2)} = \mathbf{x} W^{(1)}$$

 $\mathbf{a}^{(2)} = f(\mathbf{h}^{(2)})$

Computation in MLP (3d layer)



$$\mathbf{h}^{(3)} = \mathbf{a}^{(2)} W^{(2)}$$
$$y = f(\mathbf{h}^{(3)})$$

Results using MLP

Train Accuracy: 32.27% Test Accuracy: 29.24%

```
Epoch 30/50
219/219 [=====
          219/219 [=====
           =========] - 5s 21ms/step - loss: 2.9821 - accuracy: 0.2604 - val loss: 2.9528 - val accuracy: 0.2543
Epoch 32/50
219/219 [=========] - 5s 21ms/step - loss: 2.9545 - accuracy: 0.2665 - val loss: 2.9373 - val accuracy: 0.2500
Epoch 34/50
219/219 [=====
           :========] - 5s 21ms/step - loss: 2.8836 - accuracy: 0.2741 - val loss: 2.8738 - val accuracy: 0.2664
Epoch 35/50
219/219 [======
          Epoch 36/50
219/219 [=====
           Epoch 37/50
Epoch 38/50
219/219 [===
              Epoch 39/50
219/219 [=====
             =========] - 5s 21ms/step - loss: 2.7143 - accuracy: 0.2927 - val loss: 2.6848 - val accuracy: 0.2810
Epoch 40/50
219/219 [====
           Epoch 41/50
Epoch 42/50
219/219 [====
           ==========] - 5s 21ms/step - loss: 2.6056 - accuracy: 0.3063 - val loss: 2.6051 - val accuracy: 0.2891
Epoch 43/50
219/219 [=======] - 5s 21ms/step - loss: 2.5809 - accuracy: 0.3034 - val loss: 2.5807 - val accuracy: 0.2881
Epoch 44/50
219/219 [====
          ==========] - 5s 21ms/step - loss: 2.5459 - accuracy: 0.3059 - val loss: 2.5477 - val accuracy: 0.2951
Epoch 45/50
219/219 [=======] - 5s 22ms/step - loss: 2.5165 - accuracy: 0.3107 - val loss: 2.5258 - val accuracy: 0.2887
Epoch 46/50
219/219 [===
           Fnoch 47/50
219/219 [=======] - 5s 21ms/step - loss: 2.4538 - accuracy: 0.3139 - val loss: 2.4737 - val accuracy: 0.2921
Fnoch 48/50
219/219 [===
           Epoch 49/50
Epoch 50/50
                ======] - 5s 22ms/step - loss: 2.3664 - accuracy: 0.3227 - val loss: 2.4033 - val accuracy: 0.2924
```

CNNs

- Mainly used for processing images
- Perform better than multilayer perceptron
- Less parameters than dense layers

Intuition

- Image data is structured
 - Edges, shapes
 - Translation invariance
 - Scale invariance
- CNN emulates human vision system
- Components of a CNN learn to extract different features

CNN components

- Convolution
- Pooling

Convolution

- Kernel = grid of weights
- Kernel is "applied" to the image
- Traditionally used in image processing

1	2	-1
0	1	2
-2	1	0

Convolution





5	2	3	1	2	4
2	4	1	0	3	1
5	1	0	2	8	3
0	2	1	5	2	4
2	7	0	0	2	1
1	3	2	8	7	0

Convolution: Zero padding

Image							
0	0	0	0	0	0	0	0
0	5	2	3	1	2	4	0
0	2	4	1	0	3	1	0
0	5	1	0	2	8	3	0
0	0	2	1	5	2	4	0
0	2	7	0	0	2	1	0
0	1	3	2	8	7	0	0
0	0	0	0	0	0	0	0

Kernel					
1	0	0			
2	1	0			
1	0	-1			

Output						
-1						
	18	10	-3	5		
	12	?	?	?		
	?	?	?	?		
	?	?	?	?		

Convolution

Image

0	0	0	0	0	0	0	0
0	5	2	3	1	2	4	0
0	2	4	1	0	3	1	0
0	5	1	0	2	8	3	0
0	0	2	1	5	2	4	0
0	2	7	0	0	2	1	0
0	1	3	2	8	7	0	0
0	0	0	0	0	0	0	0

Kernel

1	0	0
2	1	0
1	0	-1

Output

-1	?	?	?	?	?
?	18	10	-3	5	?
?	12	?	?	?	?
?	?	?	?	?	?
?	?	?	?	?	?
?	?	?	?	?	?

Kernels

- Feature detectors
- Kernels are learned

Oblique line detector

1	0	0
0	1	0
0	0	1

Vertical line detector

0	1	0
0	1	0
0	1	0

Architectural decisions for convolution

- Grid size
- Stride
- Depth
- Number of kernels

Grid size

- # of pixels for height/width
- Odd numbers

3 by 3					
1	2	9			
1	6	5			
2	2	3			

Grid size

- # of pixels for height/width
- Odd numbers

1	2	9	8	7
1	6	5	0	0
2	2	3	1	0
1	1	-3	0	-1
1	-2	2	2	3

Stride

- Step size used for sliding kernel on image
- Indicated in pixels

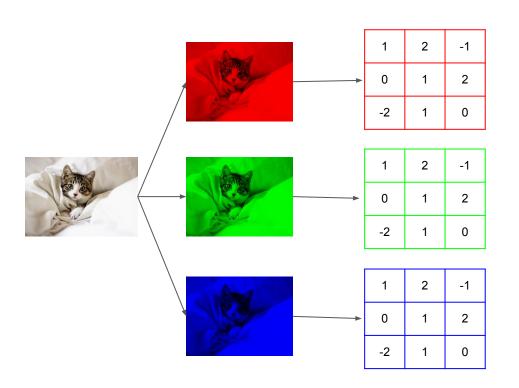
5	2	3	1	2	4
2	4	1	0	3	1
5	1	0	2	8	3
0	2	1	5	2	4
2	7	0	0	2	1
1	3	2	8	7	0

Stride

- Step size used for sliding kernel on image
- Indicated in pixels

5	2	3	1	2	4
2	4	1	0	3	1
5	1	0	2	8	3
0	2	1	5	2	4
2	7	0	0	2	1
1	3	2	8	7	0

Depth



Kernel = $3 \times 3 \times 3$ # weights = 27

of kernels

- A conv layer has multiple kernels
- Each kernel outputs a single 2D array
- Output from a layer has as many 2d arrays as # kernels

Pooling

- Downsample the image
- Overlaying grid on image
- Max/average pooling
- No parameters

Pooling settings

- Grid size
- Stride
- Type (e.g., max, average)

Max pooling (2x2, stride 2)

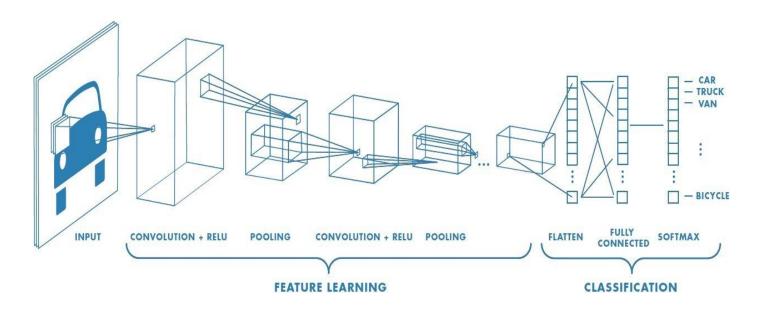
Input

-1	2	0	2
3	18	10	-3
2	12	5	2
1	3	7	4

Output

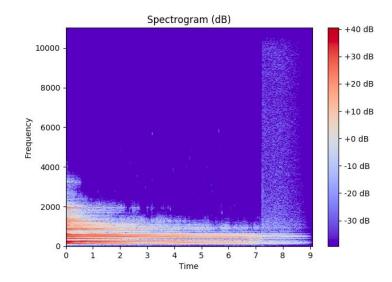
10	18
12	7

CNN architecture



How does convolution/pooling apply to audio?

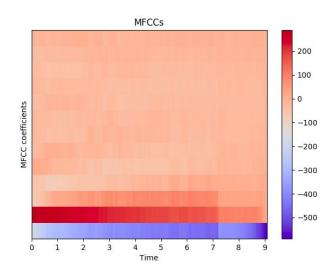
- Spectrogram/MFCC = image
- Time, frequency = x, y
- Amplitude = pixel value



Preparing MFCCs for a CNN

- 13 MFCCs
- Hop length = 512 samples
- # samples in audio file = 51200

Data shape = $100 \times 13 \times 1$



Results Using CNN

Train Accuracy: 74.29% Test Accuracy: 71.21%%

Problems output debug console terminal
Epoch 10/30
188/188 [===================================
Epoch 11/30
188/188 [===================================
188/188 [=======] - 6s 34ms/step - loss: 1.1256 - accuracy: 0.5981 - val loss: 1.0733 - val accuracy: 0.6222
Epoch 13/30
188/188 [========================] - 6s 33ms/step - loss: 1.1000 - accuracy: 0.6006 - val_loss: 1.0493 - val_accuracy: 0.6235
Epoch 14/30
188/188 [===================================
tpoci 13/30 188/188 [===================================
Epoch 16/30
188/188 [===================================
Epoch 17/30
188/188 [===================================
188/188 [===================================
Epoch 19/30
188/188 [===================] - 6s 33ms/step - loss: 0.9304 - accuracy: 0.6738 - val_loss: 0.9608 - val_accuracy: 0.6602
Epoch 26/30
188/188 [===================================
188/188 [============] - 6s 33ms/step - loss: 0.8945 - accuracy: 0.6874 - val loss: 0.9596 - val accuracy: 0.6595
Epoch 22/30
188/188 [===================================
Epoch 23/30 188/188 [===================================
160/160 [
188/188 [===================================
Epoch 25/30
188/188 [===================================
Epoch 26/30 188/188 [===================================
Tool 105 [
188/188 [===============================] - 6s 33ms/step - loss: 0.7670 - accuracy: 0.7276 - val_loss: 0.8711 - val_accuracy: 0.6949
Epoch 28/30
188/188 [========] - 6s 33ms/step - loss: 0.7701 - accuracy: 0.7311 - val_loss: 0.8691 - val_accuracy: 0.6943
Epoch 29/30 188/188 [===================================
1607.160 [
188/188 [===================================
79/79 - is - loss: 0.8288 - accuracy: 0.7121
Accuracy on test set is: 0.7120544910430908
Expected index: 4, Predicted index, [4]

Observation

Got 29.24% using MLP Got 71.21% using CNN CNN gave around 42% more accuracy than MLP

Refrences

```
Problem link: https://www.kaggle.com/c/birdsong-recognition/overview

Learn Data Science: https://www.youtube.com/watch?v=YJFnBPhTi0Y&t=2825s

Analytics Vidya: https://www.analyticsvidhya.com/blog/2021/05/convolutional-neural-networks-cnn/viso.ai:https://viso.ai/deep-learning/deep-neural-network-three-popular-types/
```