view frames Result Recorded at time: 148.555 odom Broadcaster: /gazebo Average rate: 30.199 Buffer length: 4.967 Most recent transform: 148.538 Oldest transform: 143.571 base footprint Broadcaster: /robot\_state\_publisher Average rate:  $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.0 Buffer length: 0.0 Average rate: 10000.0 Average rate:  $1000\overline{0}.0$ Average rate:  $1000\overline{0}.0$ Average rate:  $30.\overline{205}$ Average rate:  $30.\overline{205}$ Buffer length: 4.933 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.933 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 148.539 Most recent transform: 148.539 Most recent transform: 0.0 Oldest transform: 143.606 Oldest transform: 143.606 wheel\_left\_link caster\_back\_link imu\_link wheel\_right\_link camera\_link base\_scan Broadcaster: /robot\_state\_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera\_rgb\_frame Broadcaster: /robot state publisher Average rate:  $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera\_rgb\_optical\_frame Broadcaster: /apriltag\_ros\_continuous\_node Average rate: 28.842 Buffer length: 4.958 Most recent transform: 148.524 Oldest transform: 143.566 tag\_0