

The logo of Galgotias University is a stylized 'G' composed of three concentric, curved segments in yellow, blue, and red. The text 'UNIT 4' is centered over this logo.

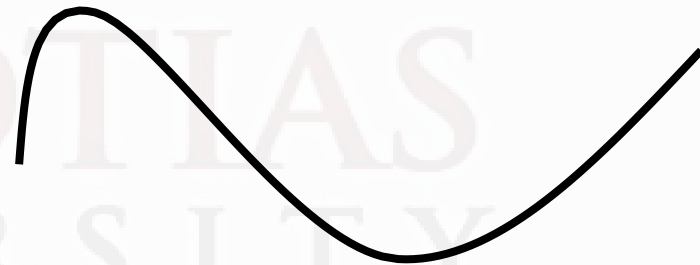
## UNIT 4

Spline: Interpolation and approximation spline

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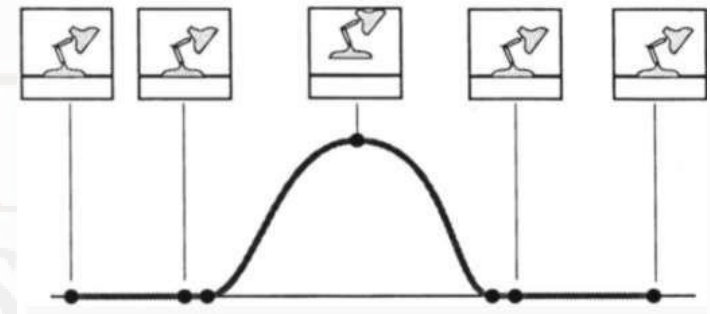
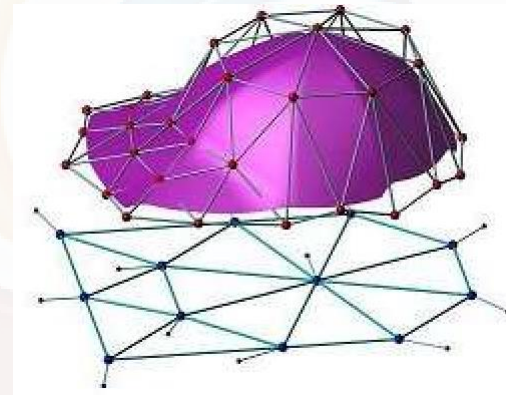
# Spline

- Drafting terminology
  - Spline is a flexible strip that is easily flexed to pass through a series of design points (control points) to produce a smooth curve.
- Spline curve – a piecewise polynomial (cubic) curve whose first and second derivatives are continuous across the various curve sections.



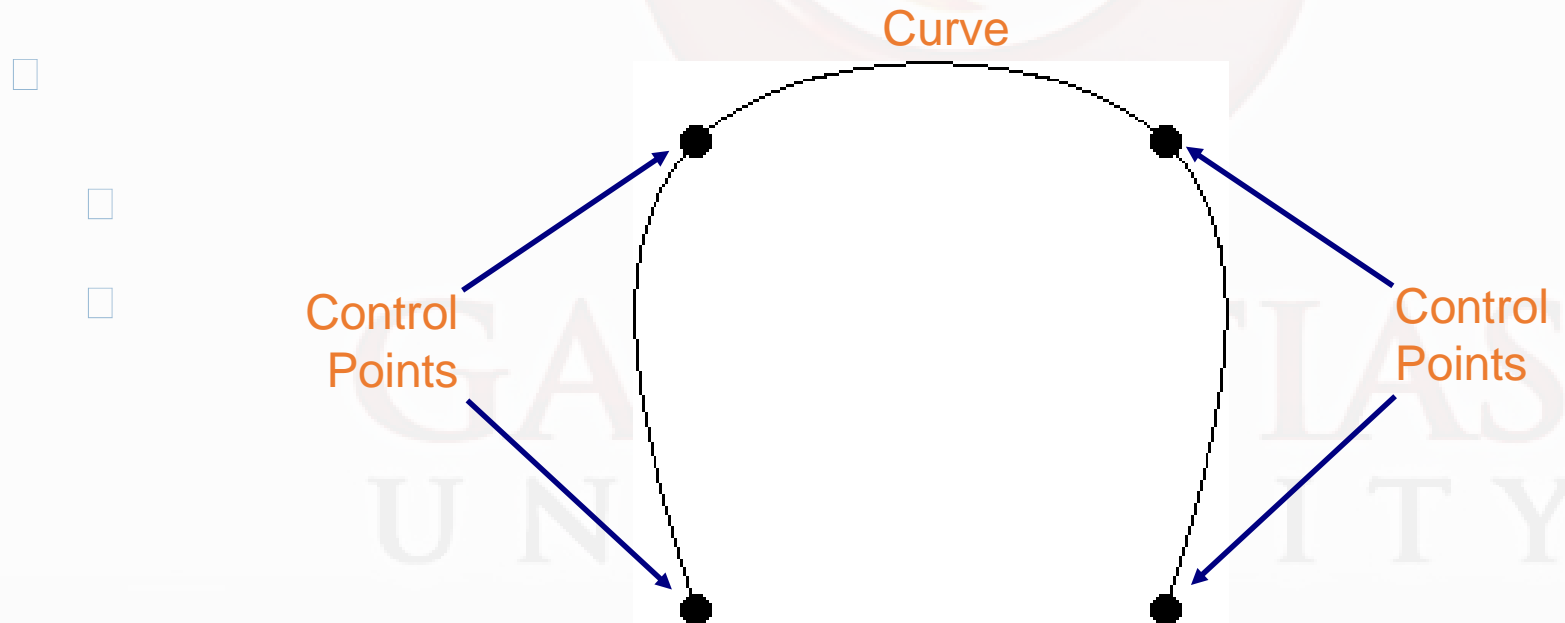
# Spline Representations

- Spline Representations defined mathematically using a set of constraints
- Splines have many uses:
  - 2D illustration
  - Fonts
  - 3D Modelling
  - Animation



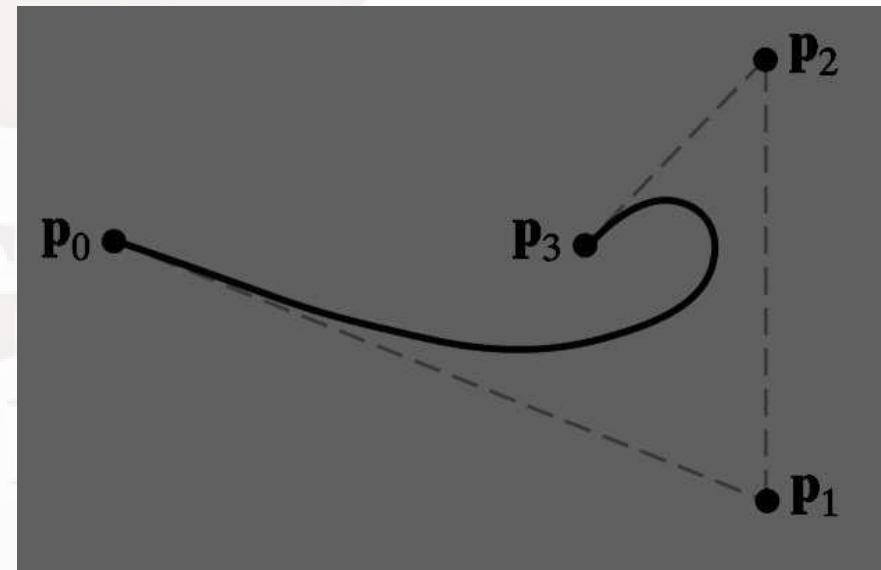
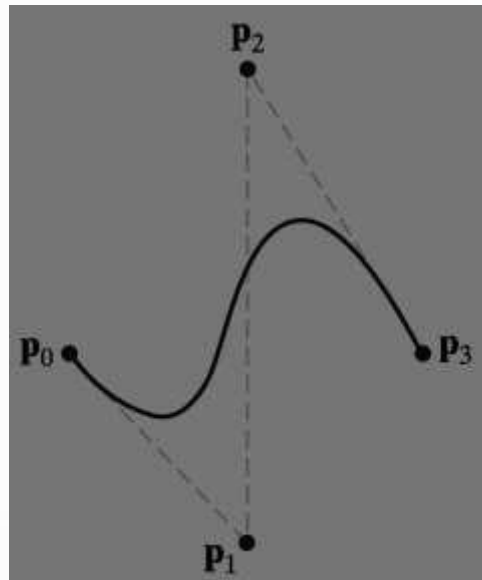
# Big Idea

- User specifies control points
- Defines a smooth curveThe boundary formed by the set of control points for a spline is known as a **convex hull**
- Think of an elastic band stretched around the control points



# Control Graphs

- A polyline connecting the control points in order is known as a
- **control graph**
- Usually displayed to help designers keep track of their splines



# Types of Curves

- A curve is an infinitely large set of points. Each point has two neighbors except endpoints. Curves can be broadly classified into three categories –
- **explicit, implicit, and parametric curves.**
- Implicit Curves



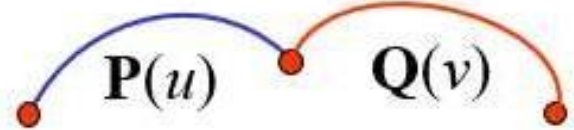
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# Implicit Curves

- Implicit curve representations define the set of points on a curve by employing a procedure that can test to see if a point is on the curve.
- Usually, an implicit curve is defined by an implicit function of the form –
- $f(x, y) = 0$
- Eg. A common example is the circle, whose implicit representation is
- $x^2 + y^2 - R^2 = 0$

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# Parametric curve

- The explicit and implicit curve representations can be used only when the function is known.
- Curves having parametric form are called parametric curves.
- In practice the parametric curves are used.
- Every point on the curve is having two neighbors (other than the end points). A two-dimensional parametric curve has the following form –
- $P(t) = f(t), g(t)$  or  $P(t) = x(t), y(t)$
- The functions  $f$  and  $g$  become the  $(x, y)$  coordinates of any point on the curve, **and the points are obtained when the parameter  $t$  (or  $u$ ) is varied over a certain interval  $[a, b]$ , normally  $[0, 1]$ .**



# Reference

Demo animation of metaballs

<http://www.youtube.com/watch?v=UWvGyKolkho&feature=related>

[http://www.youtube.com/watch?v=Nf\\_OlfWMRaA&NR=1](http://www.youtube.com/watch?v=Nf_OlfWMRaA&NR=1)

<http://www.nbb.cornell.edu/neurobio/land/OldStudentProjects/cs490-96to97/anson/BezierPatchApplet/>



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Thank You